Recorded at time: 1627295850.219 world Broadcaster: /manequin/robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1627295850.219 sec old) Buffer length: 0.000 sec chair\_base Broadcaster: /manequin/robot\_state\_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1627295850.219 sec old) Buffer length: 0.000 sec body\_hip Broadcaster: /manequin/robot\_state\_publisher Broadcaster: /manequin/robot\_state\_publisher Broadcaster: /manequin/robot\_state\_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 ( 1627295850.219 sec old) Most recent transform: 0.000 ( 1627295850.219 sec old) Most recent transform: 0.000 ( 1627295850.219 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec body\_Lleg body\_Rleg body\_chest Broadcaster: /manequin/robot\_state\_publisher Broadcaster: /manequin/robot\_state\_publisher Broadcaster: 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right\_palm\_sensor

left\_palm\_sensor

view\_frames Result