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## **Remedial UTS**

### **Project Case Study:**

Edge Detection Displaying the contours of objects in the image using an edge detection algorithm.

### **Step by Step :**

#### **1. Installation and Library Import**

Steps:

Ensure the required Python libraries (OpenCV, NumPy, and Matplotlib) are installed.

OpenCV: Used for image manipulation and analysis.

NumPy: Used for numerical data manipulation.

Matplotlib: Used for result visualization.

code :

```
!pip install opencv-python-headless matplotlib numpy
```

#### **2. Reading and Converting the Image**

Objective:

To read an image from the file path and convert it into grayscale format. Grayscale format simplifies analysis by reducing the RGB color dimensions into a single channel (intensity of gray shades).

Process:

- `cv2.imread()`: Reads the image.
- `cv2.cvtColor()`: Converts the image to grayscale.

code :

```
import cv2
```

```

import numpy as np

import matplotlib.pyplot as plt

# Path ke gambar

image_path = '/content/WIN_20240627_13_59_47_Pro.jpg' # Ganti dengan
path gambar

# Fungsi untuk membaca gambar dan mengubah ke format grayscale

def read_and_convert_image(image_path):

    # Membaca gambar

    img = cv2.imread(image_path)

    # Konversi ke skala abu-abu

    gray_img = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

    return img, gray_img

```

### 3. Edge Detection with the Canny Algorithm

Objective:

To detect edges in the image based on intensity changes using the Canny algorithm.

Process:

- cv2.Canny() takes the grayscale image and two threshold parameters (lower\_threshold and upper\_threshold) to detect significant pixel intensity changes.
- These parameters can be adjusted for optimal results based on the image's level of detail.

code :

```

# Fungsi untuk mendeteksi tepi menggunakan Canny

def detect_edges(gray_img, lower_threshold=50, upper_threshold=150):

    edges = cv2.Canny(gray_img, lower_threshold, upper_threshold)

    return edges

```

## 4. Finding and Analyzing Contours

Objective:

To identify contours in the image based on detected edges and analyze the properties of each contour.

Process:

1. `cv2.findContours()`: Finds all contours in the edge-detected image.
2. The analysis includes calculations for:
  - Area: Using `cv2.contourArea()`.
  - Bounding Box: Using `cv2.boundingRect()`.
  - Centroid: The center point of the bounding box, calculated as  $(x + w // 2, y + h // 2)$ .

code :

```
# Fungsi untuk menemukan dan menganalisis kontur

def find_and_analyze_contours(edges):

    # Menemukan kontur

    contours, _ = cv2.findContours(edges, cv2.RETR_EXTERNAL,
cv2.CHAIN_APPROX_SIMPLE)

    contour_data = []

    for contour in contours:

        # Menghitung luas dan koordinat bounding box

        area = cv2.contourArea(contour)

        x, y, w, h = cv2.boundingRect(contour)

        contour_data.append({

            "Area": area,

            "Bounding Box": (x, y, w, h),

            "Centroid": (x + w // 2, y + h // 2)

        })

    return contours, contour_data
```

## 5. Drawing Contours on the Original Image

Objective:

To visualize the detected contours by overlaying them on the original image.

Process:

- `cv2.drawContours()`: Draws all contours in green with a specified line thickness.

code :

```
# Fungsi untuk menggambar kontur pada gambar asli
def draw_contours(img, contours):
    result_img = img.copy()

    cv2.drawContours(result_img, contours, -1, (0, 255, 0), 2) # Hijau
    untuk kontur

    return result_img
```

## 6. Creating and Running a process Function

Objective:

To encapsulate the entire program into a single function named process for easier execution.

code :

```
# Fungsi utama untuk deteksi dan analisis
def process_image(image_path):
    img, gray_img = read_and_convert_image(image_path)
    edges = detect_edges(gray_img)
    contours, contour_data = find_and_analyze_contours(edges)
    result_img = draw_contours(img, contours)

    return result_img, edges, contour_data, contours # Return contours
here

# Proses gambar
```

```
original_img, gray_img = read_and_convert_image(image_path)

result_img, edges, contour_data, contours = process_image(image_path) #
Assign contours here
```

## 7. Visualizing Results

Objective:

To display the original image, the edge-detected image, and the image with contours side by side for better understanding of the analysis.

Process:

- `plt.subplot()`: Splits the view into three sections for parallel visualization of images.

code :

```
# fungsi Visualisasi

def visualize_results(img, edges, result_img):

    plt.figure(figsize=(15, 5))

    plt.subplot(1, 3, 1)

    plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))

    plt.title("Gambar Asli")

    plt.axis("off")


    plt.subplot(1, 3, 2)

    plt.imshow(edges, cmap="gray")

    plt.title("Deteksi Tepi")

    plt.axis("off")


    plt.subplot(1, 3, 3)

    plt.imshow(cv2.cvtColor(result_img, cv2.COLOR_BGR2RGB))

    plt.title("Kontur pada Gambar")

    plt.axis("off")
```

```
plt.show()

# Visualisasi hasil
visualize_results(original_img, edges, result_img)
```

## The results obtained



## 8. Analysis Information

Objective:

To display the properties of the detected contours, such as:

- Number of objects in the image.
- Area: The size of each object.
- Bounding Box: Coordinates (x, y) and dimensions (w, h).
- Centroid: The center point of each object.

code :

```
# Menampilkan informasi objek
print(f"Jumlah objek terdeteksi: {len(contours)}")
print("Informasi tiap objek:")
for i, data in enumerate(contour_data):
    print(f"Objek {i + 1}:")
    print(f" - Area: {data['Area']:.2f}")
    print(f" - Bounding Box (x, y, w, h): {data['Bounding Box']}")
    print(f" - Centroid: {data['Centroid']}")
```

## The analysis information that has been gathered



Informasi tiap objek:

Objek 1:

- Area: 107.00
- Bounding Box (x, y, w, h): (304, 714, 58, 6)
- Centroid: (333, 717)

Objek 2:

- Area: 0.00
- Bounding Box (x, y, w, h): (0, 712, 7, 2)
- Centroid: (3, 713)

Objek 3:

- Area: 0.00
- Bounding Box (x, y, w, h): (473, 705, 3, 15)
- Centroid: (474, 712)

Objek 4:

- Area: 0.50
- Bounding Box (x, y, w, h): (472, 705, 2, 2)
- Centroid: (473, 706)

## Complete information is available at this link:

[https://github.com/muhamadazz/PengolahanCitraDigital/blob/main/Remedial%20UTS/Analisis\\_data.csv](https://github.com/muhamadazz/PengolahanCitraDigital/blob/main/Remedial%20UTS/Analisis_data.csv)