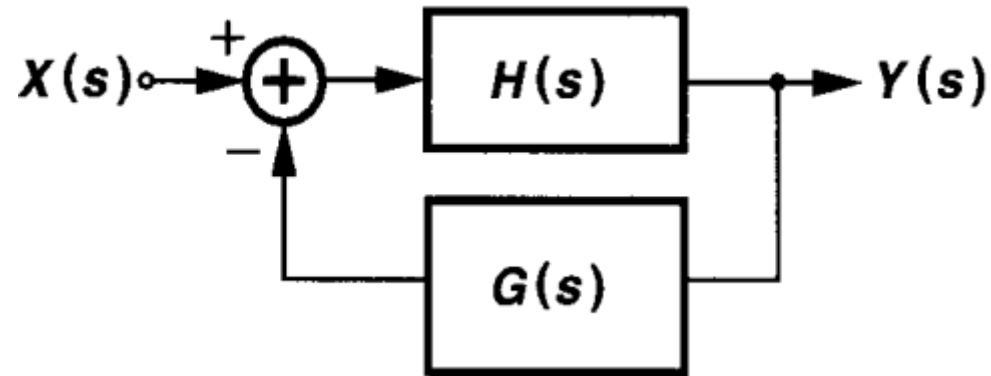

EE223 Analog Integrated Circuits

Fall 2018

Lecture 20: Feedback

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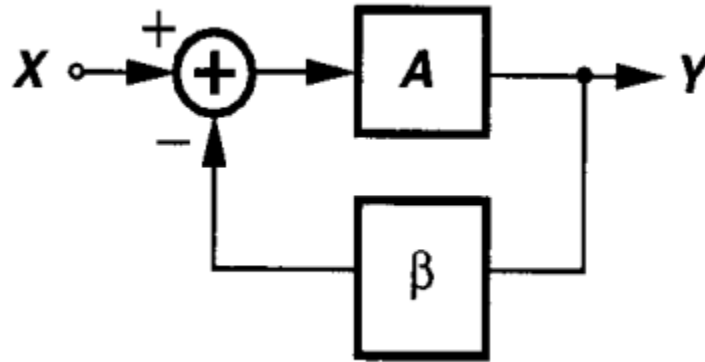
General Feedback System



$$Y(s) = H(s)[X(s) - G(s)Y(s)]$$

$$\frac{Y(s)}{X(s)} = \frac{H(s)}{1 + G(s)H(s)}$$

Simple Feedback System

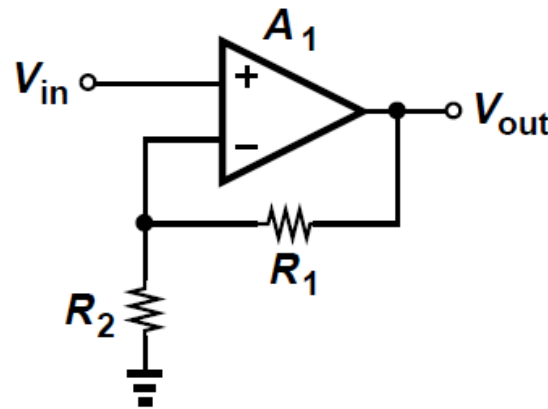


$$\frac{Y}{X} = \frac{A}{1 + \beta A}$$
$$\approx \frac{1}{\beta} \left(1 - \frac{1}{\beta A} \right)$$

where we have assumed $\beta A \gg 1$

OPAMP Gain Requirement

The circuit has a nominal gain of 10. i.e., $1 + R_1/R_2 = 10$.
Determine the minimal value of A_1 for a gain error 1%:



Solution:

$$\begin{aligned}\frac{V_{out}}{V_{in}} &= \frac{A_1}{1 + \frac{R_2}{R_1 + R_2} A_1} \\ &= \frac{R_1 + R_2}{R_2} \frac{A_1}{\frac{R_1 + R_2}{R_2} + A_1}\end{aligned}$$

$$\frac{V_{out}}{V_{in}} \approx \left(1 + \frac{R_1}{R_2}\right) \left(1 - \frac{R_1 + R_2}{R_2} \frac{1}{A_1}\right)$$

$$\text{Gain error} = \frac{1}{\beta A}$$

Properties of Feedback System

- Gain Desensitization
- Bandwidth Modification
- Terminal Impedance Modification
- Nonlinearity Reduction