

Lecture 29: Auto Encoders

CNN-1D

Application of CNN

→ task related image (videos)

- computer vision applications
 - (1) semantic segmentation
 - (2) image classification
 - (3) object detect
 - (4) object recognition

input image → convolutional layer → pooling layer → flattened → fully connected → output
CNN is good for images

Neural Network ⇒ Auto Encoders

Type of neural network designed for data compression, anomaly detection, dimensionality reduction and feature learning

why

↳ To get crux of information (summary)

.. (compressed representation)

- structured manner so that we can that expand later.

↳ less computational power

Compressed representation → actual input re-create

Auto Encoder

(function like which give the same input as like input)

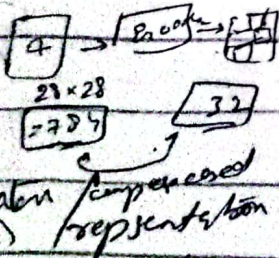
Primary goal

[To encode data into a compact representation and then decode it for re-constructs]

Auto encoders

encoder

- converts original data into secret code
- use rules/transform to hide the message



latent space/hidden

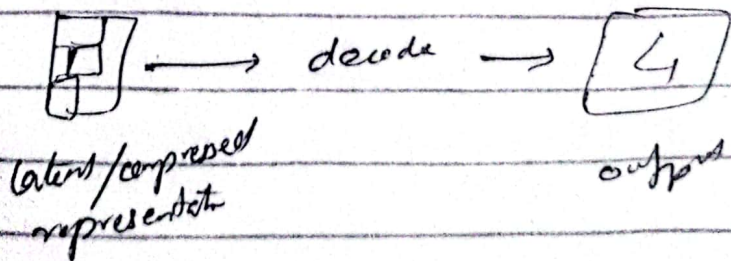
The encoder is like detective that learn to capture most important features.

feature.

- This part is responsible for compressing the input data.

decoder

- like an artist that take compact representation (encoding) from encoder and re-create the original data.
- it is second part of auto-encoder & responsible for generating output from encoding



- Reverts the secret code back to original data
- understand the rules to reverse the encoding.

encoder

→ Training of auto-encoder
(if we are unable to
create the output from
input)

encode is like as a
funnel that squeeze a
long picture into smaller
representation

Decoder

enable understanding of
hidden message.

It transform the encoding from
latent space back into a
reconstructed output enabling the
decoder network to reconstruct the
original input as closely as possible.

Encoding Process

Step 1: input data-like image is fed into encoder.

Step 2: encoder consists of layer of neurons that
learn patterns and features in the data.

Step 3, Pattern are combined and transformed
into compact representation in Low
Dimensional Space (Latent Space)

with so two thing happens

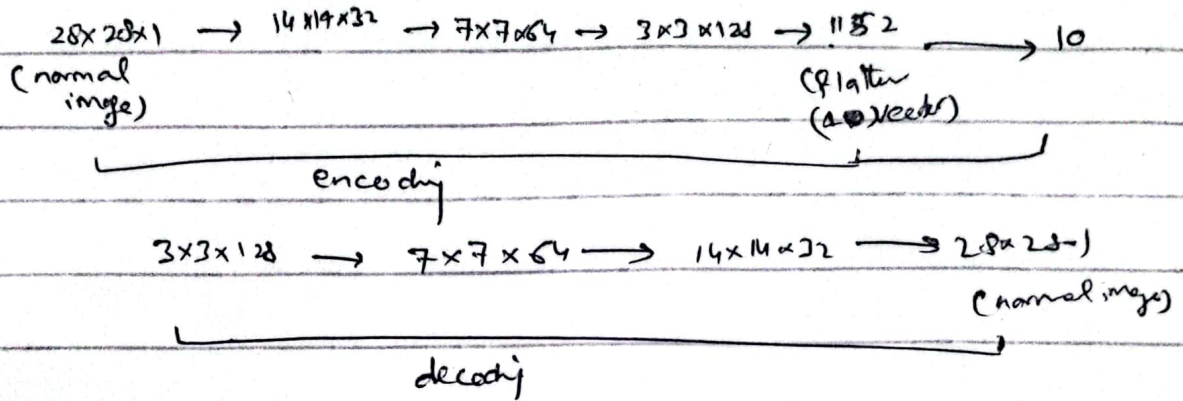
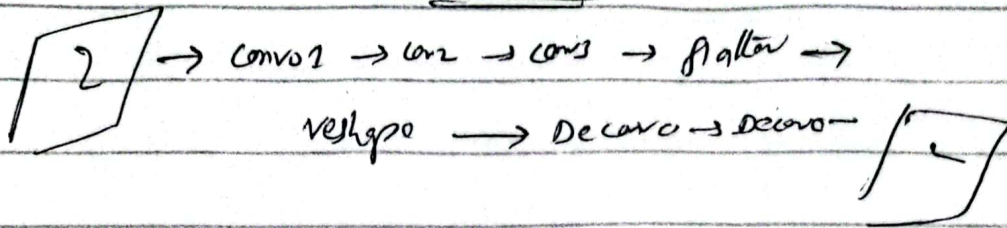
- ① Feature Learning
($2 \times 2 \times W \times H$)
- ② Compression
(reduces)
(\therefore pooling layer)

Convolution $2 \times 2, 3 \times 3$
etc (feature extract) etc

Some we can use CNN (convolutional +
pooling layer)
2D: 2D

Q

Auto-Encoder



Deconvolution

- Takes the **compressed** feature maps from encoder and expands their **spatial dimension**
- reverse of convolution (feature \rightarrow image (deconvolts))
(image \rightarrow feature)

Decoding step

- ① The **encoded data** (latent space repr) feed into decoder
- ② The decoder consists of layer that learn to **reverse the compression** process
- ③ constructed features combined to reconstruct original data.

\Rightarrow we can either use encoder and decoder \rightarrow combine
 \rightarrow separately

\Rightarrow when we can generate something we can create variator
like from old, blurry image to clear image

- \rightarrow Types of auto encoder
- \rightarrow use cases of auto encoder
- \rightarrow modifier of auto encoder

As homework