LAB MANUAL 9

HOMETASK

MUHAMMAD SIBGHAT RASOOL

4570355

```
HOMETASK 1:
#include <bits/stdc++.h>
using namespace std;
float calculateDeterminant2x2(float a, float b, float c, float d) {
  return (a * d - b * c);
}
float calculateDeterminant3x3(float matrix[3][3]) {
  float det = 0;
  for (int i = 0; i < 3; ++i) {
    det += matrix[0][i] * calculateDeterminant2x2(matrix[1][(i + 1) % 3], matrix[1][(i + 2) % 3],
                                 matrix[2][(i + 1) \% 3], matrix[2][(i + 2) \% 3]);
  }
  return det;
}
void calculateAdjoint(float matrix[3][3], float adjoint[3][3]) {
  for (int i = 0; i < 3; ++i) {
    for (int j = 0; j < 3; ++j) {
       float cofactor = calculateDeterminant2x2(matrix[(i + 1) % 3][(j + 1) % 3], matrix[(i + 1) % 3][(j + 2)
% 3],
                                matrix[(i + 2) \% 3][(j + 1) \% 3], matrix[(i + 2) \% 3][(j + 2) \% 3]);
       adjoint[j][i] = ((i + j) \% 2 == 0 ? 1 : -1) * cofactor;
```

```
}
  }
}
void calculateInverse(float matrix[3][3], float inverse[3][3]) {
  float det = calculateDeterminant3x3(matrix);
  if (det == 0) {
     cout << "The matrix is singular, and its inverse does not exist." << endl;</pre>
     return;
  }
  float adjoint[3][3];
  calculateAdjoint(matrix, adjoint);
  for (int i = 0; i < 3; ++i) {
    for (int j = 0; j < 3; ++j) {
       inverse[i][j] = adjoint[i][j] / det;
    }
  }
}
void displayMatrix(float matrix[3][3]) {
  for (int i = 0; i < 3; ++i) {
    for (int j = 0; j < 3; ++j) {
       cout << matrix[i][j] << " ";
     }
    cout << endl;
  }
}
```

```
int main() {
  float matrix[3][3];
  cout << "Enter the elements of the 3x3 matrix:" << endl;</pre>
  for (int i = 0; i < 3; ++i) {
    for (int j = 0; j < 3; ++j) {
       cin >> matrix[i][j];
    }
  }
  float inverse[3][3];
  calculateInverse(matrix, inverse);
  cout << "Original Matrix:" << endl;</pre>
  displayMatrix(matrix);
  cout << "\nInverse Matrix:" << endl;</pre>
  displayMatrix(inverse);
  return 0;
}
```

```
■ "L:\lab manual#9\bin\Debug\lab manual#9.exe"

Enter the elements of the 3x3 matrix:

112
24
46
78
76
68
98
24
46
Original Matrix:

112 24 46
78 76 68
98 24 46

Inverse Matrix:

0.0714286 -0 -0.0714286
-0.117872 0.0246781 0.154353
-0.213673 0.0128755 0.254445
```