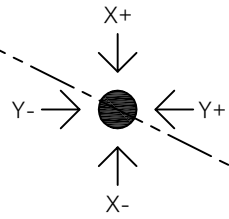
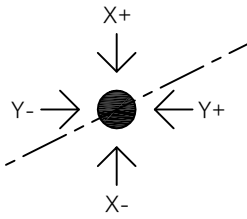


Calibration Graph for Freenove Quadrupe Robot



Leg 1



Leg 2

Print this graph on A4 paper with the proportion of 100%

100mm

USB port
is here



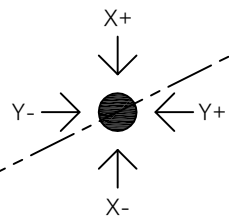
Put
quadrupe robot
here



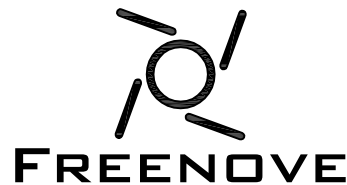
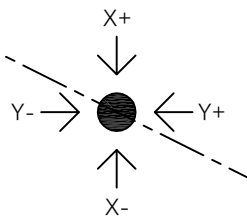
Align the bottom of
robot to this shape

Z+: perpendicular to this paper and upward
Z-: Perpendicular to this paper and down

Leg 3



Leg 4



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