$$\vec{A} = \vec{A}_n + \vec{A}_y + \vec{A}_z$$

c)
$$\vec{A} + \vec{B} = (A_n + B_n)i + (A_u + B_u)\hat{i} + (A_u + B_u)\hat{i}$$

f) Define

1. Rigid Body: In which there is no deformation.

ii. Free Body Ding.: Forces on a system isolated from any enternal factor

iii Moment of Force. The measure of tendency of a body to rotate $M = r + \sin \theta \hat{h}$

in Moment of Couple, Special case of moment without any translation.

9) Mo= ?

$$\frac{2}{2} \frac{1}{2} \frac{1}$$

h) ax(b+c) = axb + axc i) (AyB2-AzBy)î - (AnB2-AzBn)ĵ + (AnBy-AyBn) k

= 334 Nm

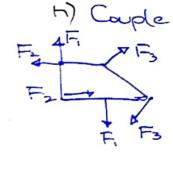


Fig. 1. Couple

Fig. 4Fi

Fig. 7F3

Fig. 7F3

$$F_1 = -(200)(4) + (450)(3) - (300)(5)$$

= -950 lb.ft

$$756$$
 $A = 8\hat{j}$
 756
 $A = 8\hat{j}$
 756
 $A = 5.12\hat{i} + 8\hat{j} - 3\hat{k}$
 $A = 76 \times (-28k) + 76 \times (-28k)$

$$M = r_A \times (-28R) + r_3 \times (28R)$$

$$= -200 \, \hat{c} - 14.9 \, + 200 \, \hat{c}$$

$$= -130 \, \hat{j} \quad \text{lb.in}$$