Engineering Mechanics

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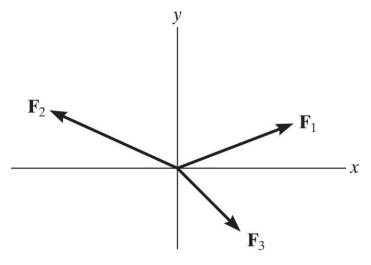
Research Interest: Photovoltaic systems, Power & Control, Sliding mode control (SMC)

Contents (Section 2.7-2.9)

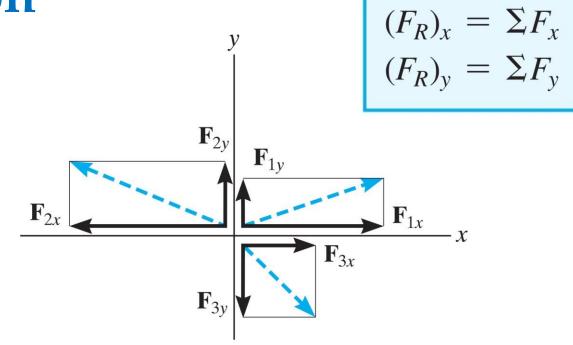
- Recap
- Position Vector
- Force along a line
- Dot Product

RECAP Engineering Mechanics

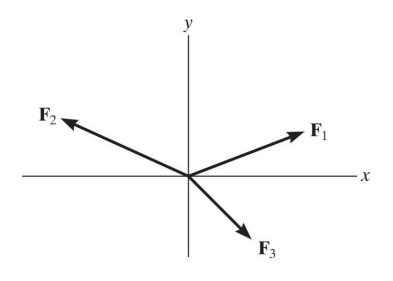
Cartesian Vector Notation







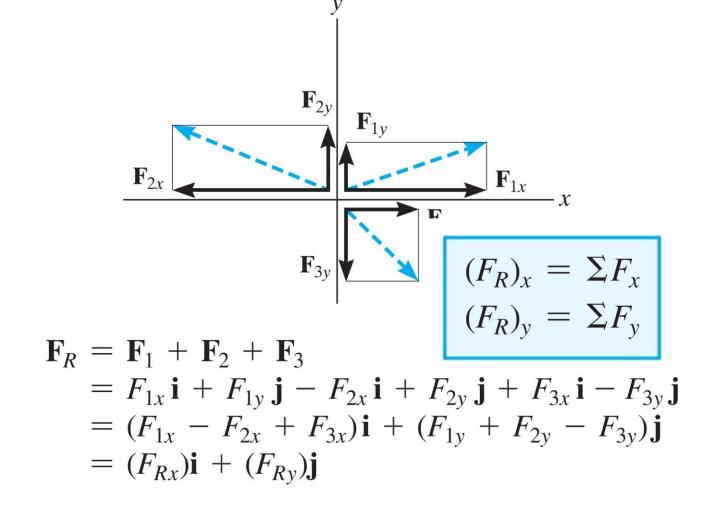
Cartesian Vector Notation



$$\mathbf{F}_1 = F_{1x} \mathbf{i} + F_{1y} \mathbf{j}$$

$$\mathbf{F}_2 = -F_{2x} \mathbf{i} + F_{2y} \mathbf{j}$$

$$\mathbf{F}_3 = F_{3x} \mathbf{i} - F_{3y} \mathbf{j}$$



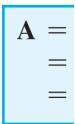
Cartesian Representation in 3D

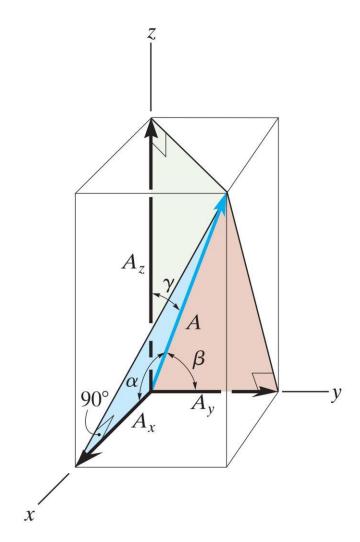
Magnitude

$$A =$$

Angles

$$\cos \alpha =$$





Cartesian Representation in 3D

Magnitude

$$A = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

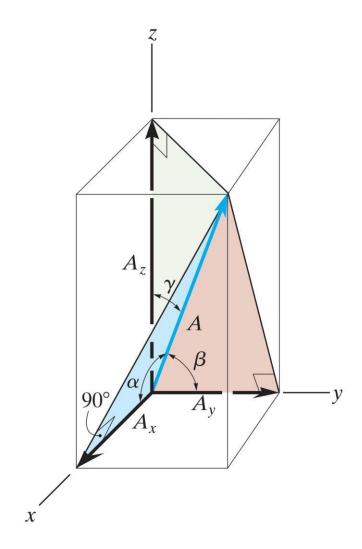
Angles

$$\cos \alpha = \frac{A_x}{A} \quad \cos \beta = \frac{A_y}{A} \quad \cos \gamma = \frac{A_z}{A}$$

$$\mathbf{A} = A \mathbf{u}_{A}$$

$$= A \cos \alpha \mathbf{i} + A \cos \beta \mathbf{j} + A \cos \gamma \mathbf{k}$$

$$= A_{x} \mathbf{i} + A_{y} \mathbf{j} + A_{z} \mathbf{k}$$



Transverse and Azimuth Angle Representation

Sometimes

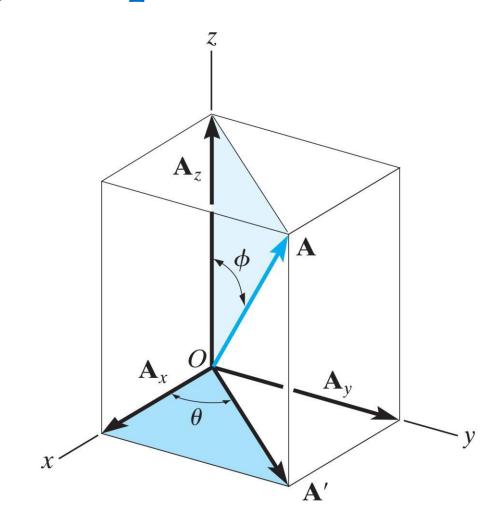
$$A_z = A \cos \phi$$

$$A' = A \sin \phi$$

$$A_x = A' \cos \theta = A \sin \phi \cos \theta$$

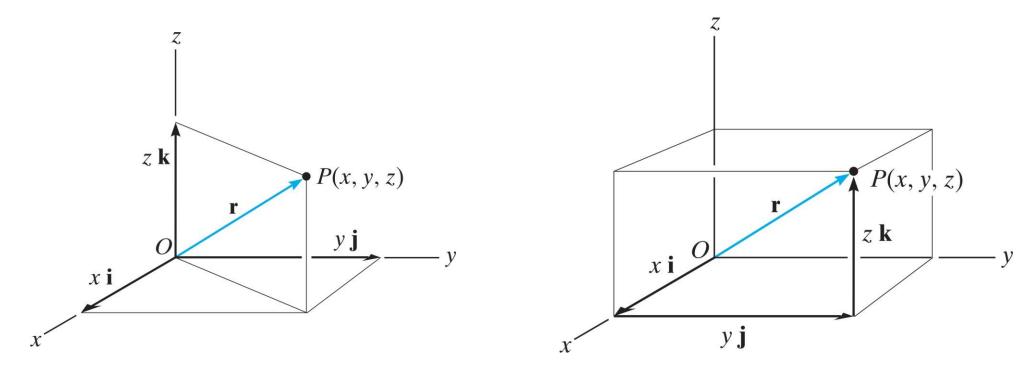
$$A_{y} = A' \sin \theta = A \sin \phi \sin \theta$$

 $\mathbf{A} = A \sin \phi \cos \theta \, \mathbf{i} + A \sin \phi \sin \theta \, \mathbf{j} + A \cos \phi \, \mathbf{k}$



Position Vector

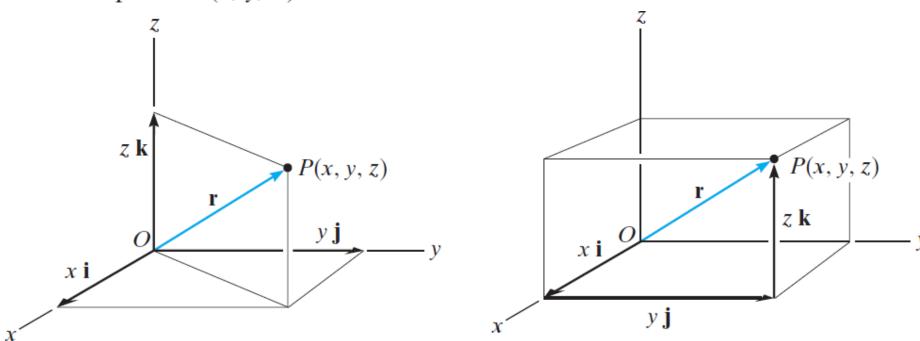
A fixed vector which locates a point in space relative to another point



Position Vector. A position vector \mathbf{r} is defined as a fixed vector which locates a point in space relative to another point. For example, if \mathbf{r} extends from the origin of coordinates, O, to point P(x, y, z), Fig. 2–35a, then \mathbf{r} can be expressed in Cartesian vector form as

$$\mathbf{r} = x\mathbf{i} + y\mathbf{j} + z\mathbf{k}$$

Note how the head-to-tail vector addition of the three components yields vector \mathbf{r} , Fig. 2–35b. Starting at the origin O, one "travels" x in the $+\mathbf{i}$ direction, then y in the $+\mathbf{j}$ direction, and finally z in the $+\mathbf{k}$ direction to arrive at point P(x, y, z).



Position Vector (General Case)

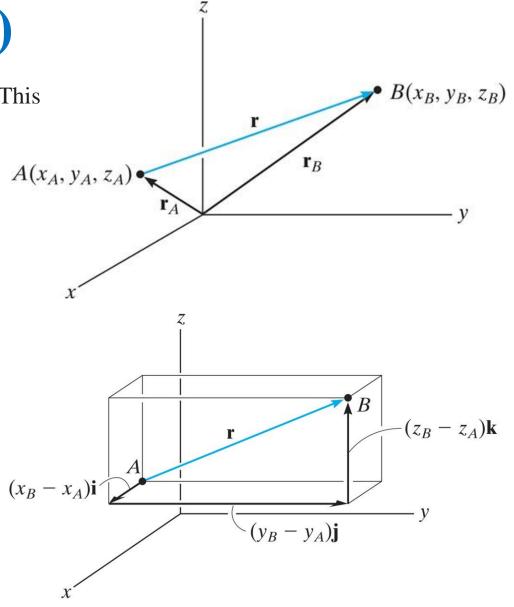
The position vector may be directed from point A to point B in space, Fig. This vector is also designated by the symbol \mathbf{r} .

$$\mathbf{r}_A + \mathbf{r} = \mathbf{r}_B$$

$$\mathbf{r} = \mathbf{r}_B - \mathbf{r}_A = (x_B \mathbf{i} + y_B \mathbf{j} + z_B \mathbf{k}) - (x_A \mathbf{i} + y_A \mathbf{j} + z_A \mathbf{k})$$

$$\mathbf{r} = (x_B - x_A)\mathbf{i} + (y_B - y_A)\mathbf{j} + (z_B - z_A)\mathbf{k}$$

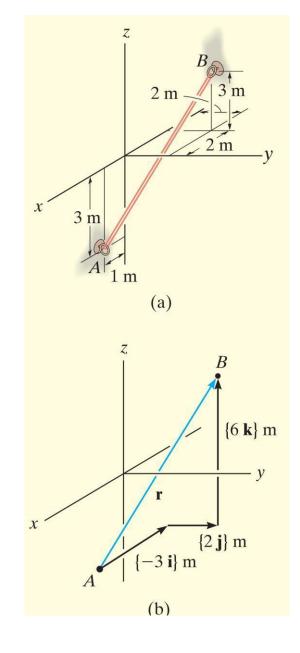
We can also form these components *directly*, Fig. 2–36*b*, by starting at *A* and moving through a distance of $(x_B - x_A)$ along the positive *x* axis $(+\mathbf{i})$, then $(y_B - y_A)$ along the positive *y* axis $(+\mathbf{j})$, and finally $(z_B - z_A)$ along the positive *z* axis $(+\mathbf{k})$ to get to *B*



An elastic rubber band is attached to points *A* and *B*. Determine its length and its direction measured from *A* toward *B*.

$$r =$$





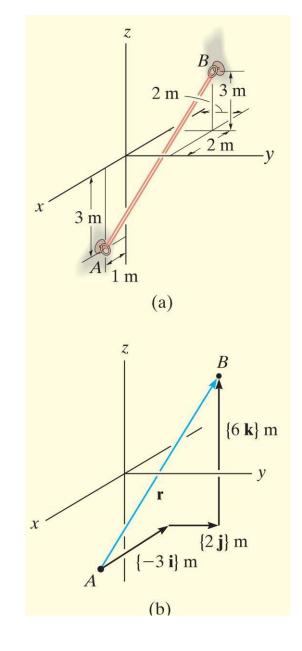
An elastic rubber band is attached to points *A* and *B*. Determine its length and its direction measured from *A* toward *B*.

$$\mathbf{r} = [-2 \text{ m} - 1 \text{ m}]\mathbf{i} + [2 \text{ m} - 0]\mathbf{j} + [3 \text{ m} - (-3 \text{ m})]\mathbf{k}$$

= $\{-3\mathbf{i} + 2\mathbf{j} + 6\mathbf{k}\} \text{ m}$

$$r = \sqrt{(-3 \text{ m})^2 + (2 \text{ m})^2 + (6 \text{ m})^2} = 7 \text{ m}$$

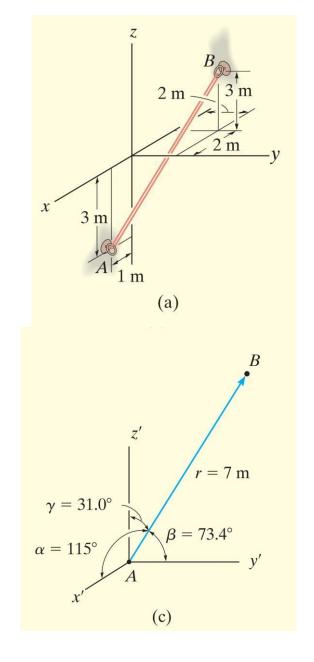
$$\mathbf{u} = \frac{\mathbf{r}}{r} = -\frac{3}{7}\mathbf{i} + \frac{2}{7}\mathbf{j} + \frac{6}{7}\mathbf{k}$$





$$3 =$$

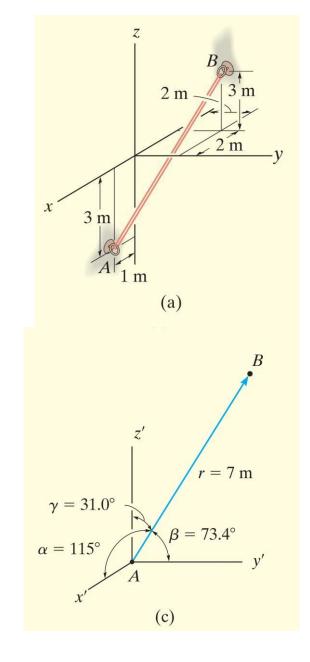
$$\gamma =$$



$$\alpha = \cos^{-1}\left(-\frac{3}{7}\right) = 115^{\circ}$$

$$\beta = \cos^{-1}\left(\frac{2}{7}\right) = 73.4^{\circ}$$

$$\gamma = \cos^{-1}\left(\frac{6}{7}\right) = 31.0^{\circ}$$



Force Vector Directed Along a Line

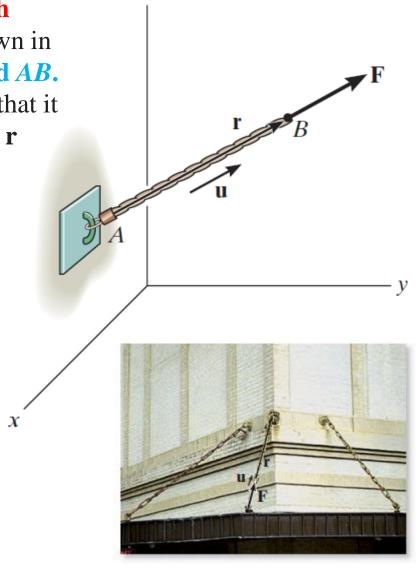
Quite often in three-dimensional statics problems, the direction of a force is specified by two points through which its line of action passes. Such a situation is shown in Fig. 2–38, where the force F is directed along the cord AB. We can formulate F as a Cartesian vector by realizing that it has the *same direction* and *sense* as the position vector r

$$\mathbf{F} = F\mathbf{u}$$

$$\mathbf{u} = \mathbf{r}/r$$

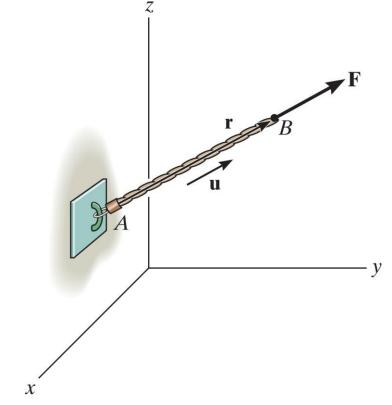
$$\mathbf{F} = F\mathbf{u} = F\left(\frac{\mathbf{r}}{r}\right)$$

$$F\left(\frac{(x_B - x_A)\mathbf{i} + (y_B - y_A)\mathbf{j} + (z_B - z_A)\mathbf{k}}{\sqrt{(x_B - x_A)^2 + (y_B - y_A)^2 + (z_B - z_A)^2}}\right)$$



Force Vector Directed Along A Line

$$\mathbf{F} = F \mathbf{u} = F \left(\frac{\mathbf{r}}{r} \right) = F \left(\frac{(x_B - x_A)\mathbf{i} + (y_B - y_A)\mathbf{j} + (z_B - z_A)\mathbf{k}}{\sqrt{(x_B - x_A)^2 + (y_B - y_A)^2 + (z_B - z_A)^2}} \right)$$



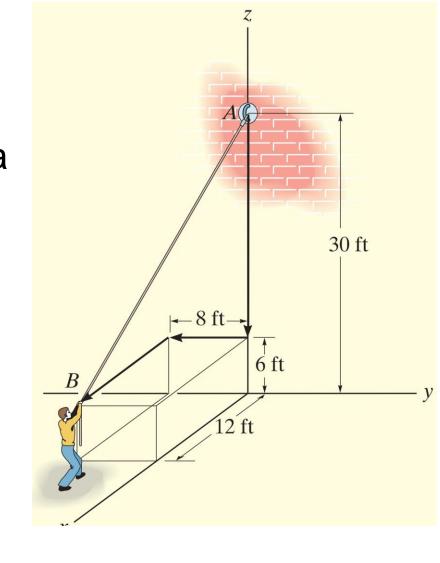
The man pulls on the cord with a force of 70 lb. represent this force acting on the support A as a Cartesian vector and determine its direction.

$$\mathbf{r} =$$

$$r =$$

u =

 $\mathbf{F} =$



The man pulls on the cord with a force of 70 lb. represent this force acting on the support A as a Cartesian vector and determine its direction.

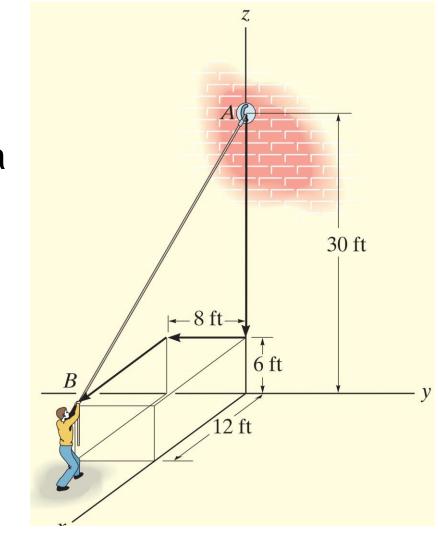
$$r = \{12i - 8j - 24k\} ft$$

$$r = \sqrt{(12 \text{ ft})^2 + (-8 \text{ ft})^2 + (-24 \text{ ft})^2} = 28 \text{ ft}$$

$$\mathbf{u} = \frac{\mathbf{r}}{r} = \frac{12}{28}\mathbf{i} - \frac{8}{28}\mathbf{j} - \frac{24}{28}\mathbf{k}$$

$$\mathbf{F} = F\mathbf{u} = 70 \, \text{lb} \left(\frac{12}{28} \mathbf{i} - \frac{8}{28} \mathbf{j} - \frac{24}{28} \mathbf{k} \right)$$

$$= \{30\mathbf{i} - 20\mathbf{j} - 60\mathbf{k}\}\$$
1b

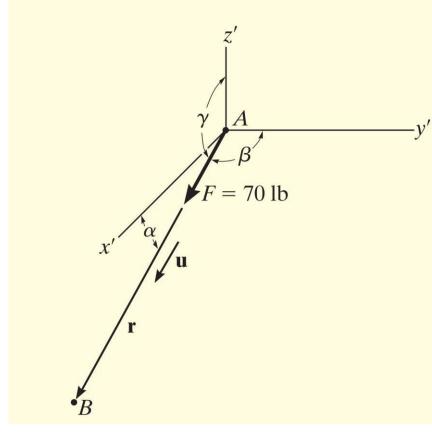


The man pulls on the cord with a force of 70 lb. represent this force acting on the support A as a Cartesian vector and determine its direction.

$$\alpha =$$

$$\beta =$$

$$\gamma =$$

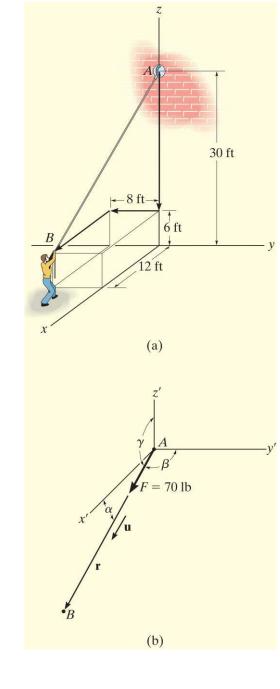


The man pulls on the cord with a force of 70 lb. represent this force acting on the support A as a Cartesian vector and determine its direction.

$$\alpha = \cos^{-1}\left(\frac{12}{28}\right) = 64.6^{\circ}$$

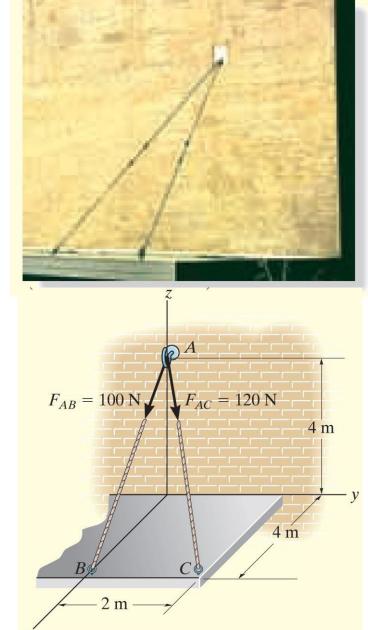
$$\beta = \cos^{-1}\left(\frac{-8}{28}\right) = 107^{\circ}$$

$$\gamma = \cos^{-1}\left(\frac{-24}{28}\right) = 149^{\circ}$$



The roof is supported by cables as shown in the photo. If the cables exert forces $F_{AB} = 100 \text{ N}$ and $F_{AC} = 120 \text{ N}$ on the wall hook at A, determine the resultant force acting at A. Express the result as a Cartesian vector.

$$\mathbf{r}_{AB} =$$
 $r_{AB} =$
 $\mathbf{F}_{AB} =$



The roof is supported by cables as shown in the photo. If the cables exert forces $F_{AB} = 100 \text{ N}$ and $F_{AC} = 120 \text{ N}$ on the wall hook at A, determine the resultant force acting at A. Express the result as a Cartesian vector.

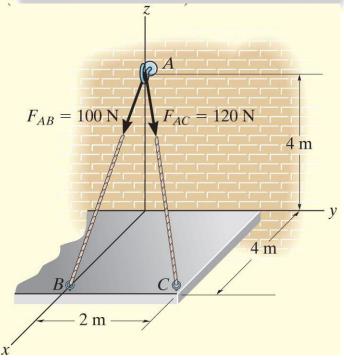
$$\mathbf{r}_{AB} = \{4\mathbf{i} - 4\mathbf{k}\} \text{ m}$$

$$r_{AB} = \sqrt{(4 \text{ m})^2 + (-4 \text{ m})^2} = 5.66 \text{ m}$$

$$\mathbf{F}_{AB} = F_{AB} \left(\frac{\mathbf{r}_{AB}}{r_{AB}}\right) = (100 \text{ N}) \left(\frac{4}{5.66}\mathbf{i} - \frac{4}{5.66}\mathbf{k}\right)$$

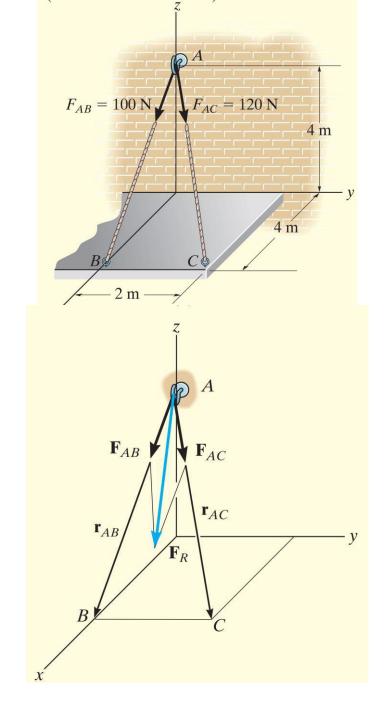
$$\mathbf{F}_{AB} = \{70.7\mathbf{i} - 70.7\mathbf{k}\} \text{ N}$$





$$\mathbf{r}_{AC} =$$
 $r_{AC} =$
 $\mathbf{F}_{AC} =$

$$\mathbf{F}_{R} = \mathbf{F}_{AB} + \mathbf{F}_{AC} =$$



$$\mathbf{r}_{AC} = \{4\mathbf{i} + 2\mathbf{j} - 4\mathbf{k}\} \text{ m}$$

$$r_{AC} = \sqrt{(4 \text{ m})^2 + (2 \text{ m})^2 + (-4 \text{ m})^2} = 6 \text{ m}$$

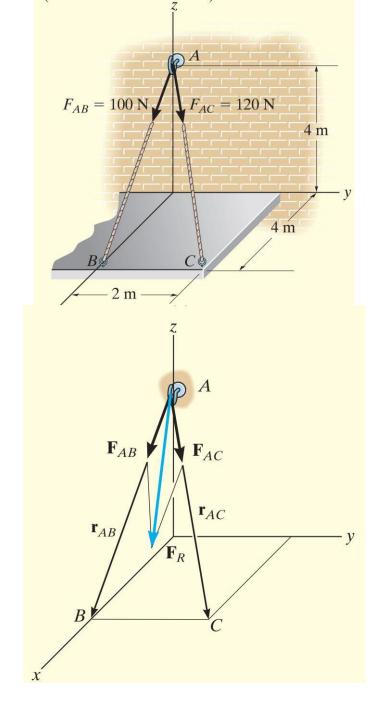
$$\mathbf{F}_{AC} = F_{AC} \left(\frac{\mathbf{r}_{AC}}{r_{AC}}\right) = (120 \text{ N}) \left(\frac{4}{6}\mathbf{i} + \frac{2}{6}\mathbf{j} - \frac{4}{6}\mathbf{k}\right)$$

$$= \{80\mathbf{i} + 40\mathbf{j} - 80\mathbf{k}\} \text{ N}$$

The resultant force is therefore

$$\mathbf{F}_R = \mathbf{F}_{AB} + \mathbf{F}_{AC} = \{70.7\mathbf{i} - 70.7\mathbf{k}\} \text{ N} + \{80\mathbf{i} + 40\mathbf{j} - 80\mathbf{k}\} \text{ N}$$

$$= \{151\mathbf{i} + 40\mathbf{j} - 151\mathbf{k}\} \text{ N} \qquad Ans.$$



Home Assignment

• Example 2.14