



## **EE-222: Microprocessor Systems**

### **Project Proposal**

# **Web-Controlled Multifunctional Car**



### **Group Members**

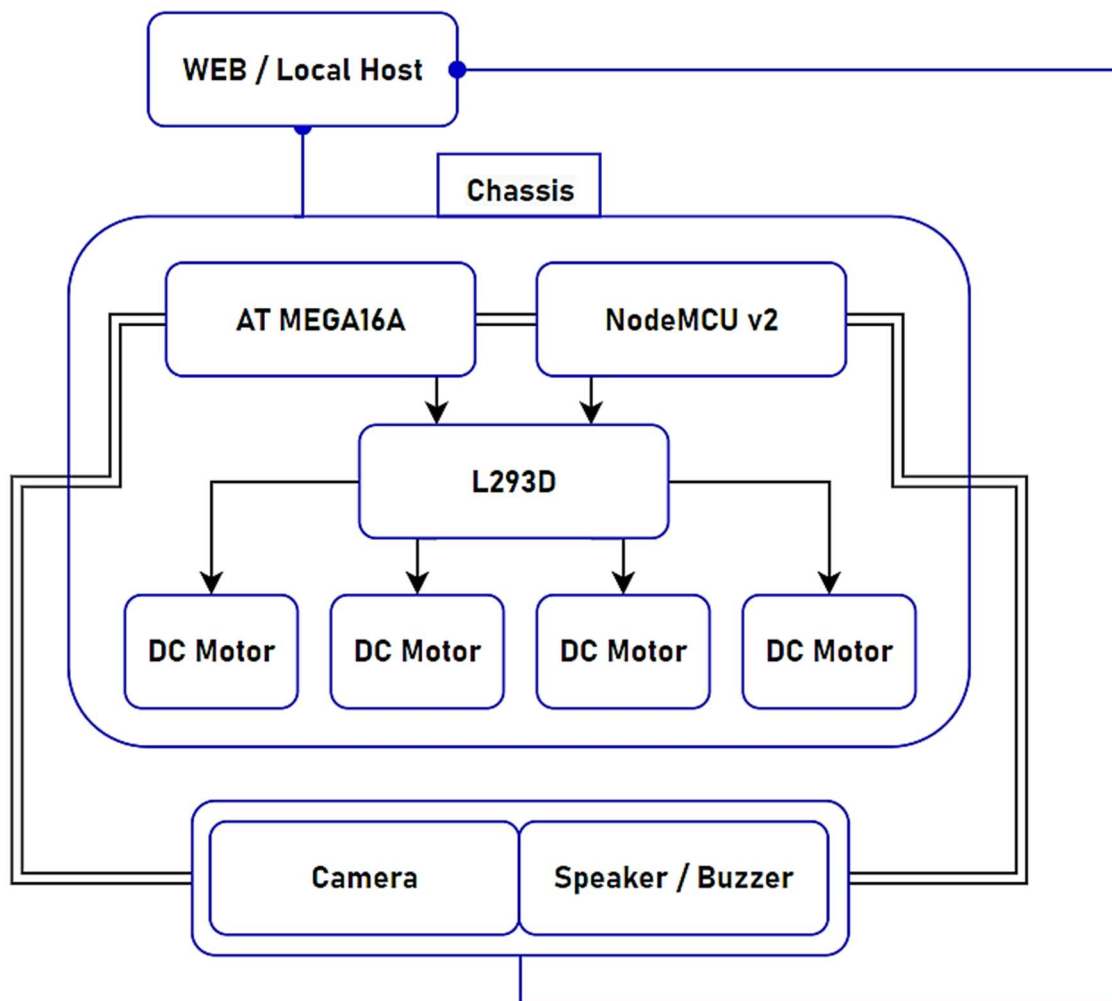
<b>Name</b>	<b>Reg. No</b>
Muhammad Ahmed Mohsin	333060
Muhammad Umer	345834
Tariq Umar	334943

## Abstract

In this project, we aim to develop a Web-Controlled Multifunctional Car. We hope to implement features such as line following, obstacle detection etc. along with some specialized features such as camera, light sensors and speakers. All of this will be implemented with AT MEGA16 as the heart of our project.

Other hardware components will include NodeMCU (ESP8266 Wifi-Module) along with L293D Motor Driver. Moreover, we also aim to develop a mobile app or a website to control the car. Our objective is to develop skills to use microprocessor to implement advanced functions on hardware. This will give us an insight on how to implement the theoretical knowledge on hardware and what are the difficulties faced during the process. We can further extend our functionality from detection to identification in order to make our car as an information gathering device over a long-ranged WiFi network.

## Block Diagram



## Functionality

Line Following

Web – Controlled Movement

Obstacle Detection & Avoidance

Real – Time Camera Footage to Local Host

Playing Banger Music

## Components

AT MEGA16A

NodeMCU V2 (ESP8266)

2 x L298N Motor Driver / L293D Motor Driver

4 x DC Motors

Camera (To Interface with NodeMCU)

12V Battery

Breadboards

Car Chassis

Speaker

Light Sensors

## Relevant Industries

LRRC Robotics

IoT (Internet of Things)

Information Nodes