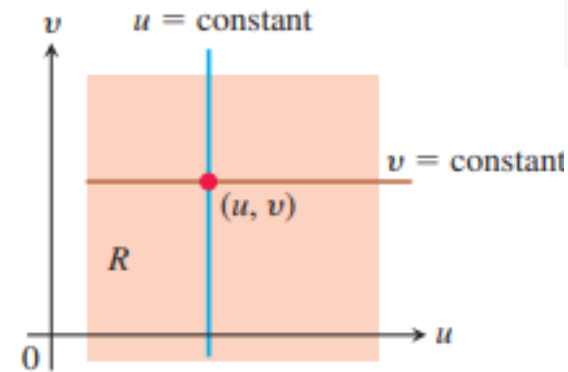
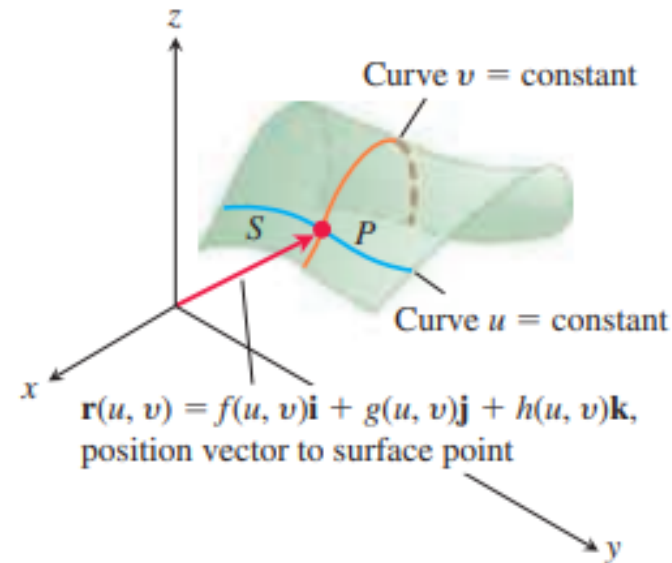


Parametrized Surfaces

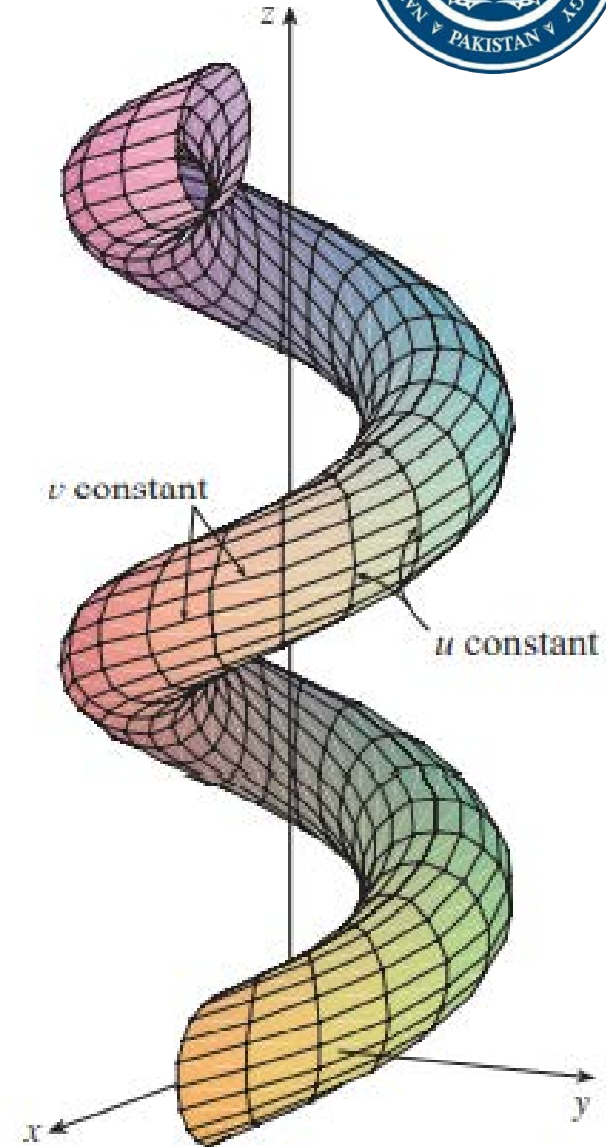
Vector Calculus(MATH-243)
Instructor: Dr. Naila Amir



Parametrization



A parametrized surface S expressed as a vector function of two variables defined on a region R .



16

Vector Calculus

Book: Calculus Early Transcendentals (6th Edition) By James Stewart.

- **Chapter: 16**
 - **Section: 16.6**

Book: Thomas' Calculus Early Transcendentals (14th Edition) By George B. Thomas, Jr., Joel Hass, Christopher Heil, Maurice D. Weir.

- **Chapter: 16**
 - **Section: 16.5**

Parametric Surfaces

In much the same way that we describe a space curve by a vector function $\mathbf{r}(t)$ of a single parameter t , we can describe a surface by a vector function $\mathbf{r}(u, v)$ of two parameters u and v . We suppose that:

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}, \quad (1)$$

is a vector-valued function defined on a region D in the uv –plane.

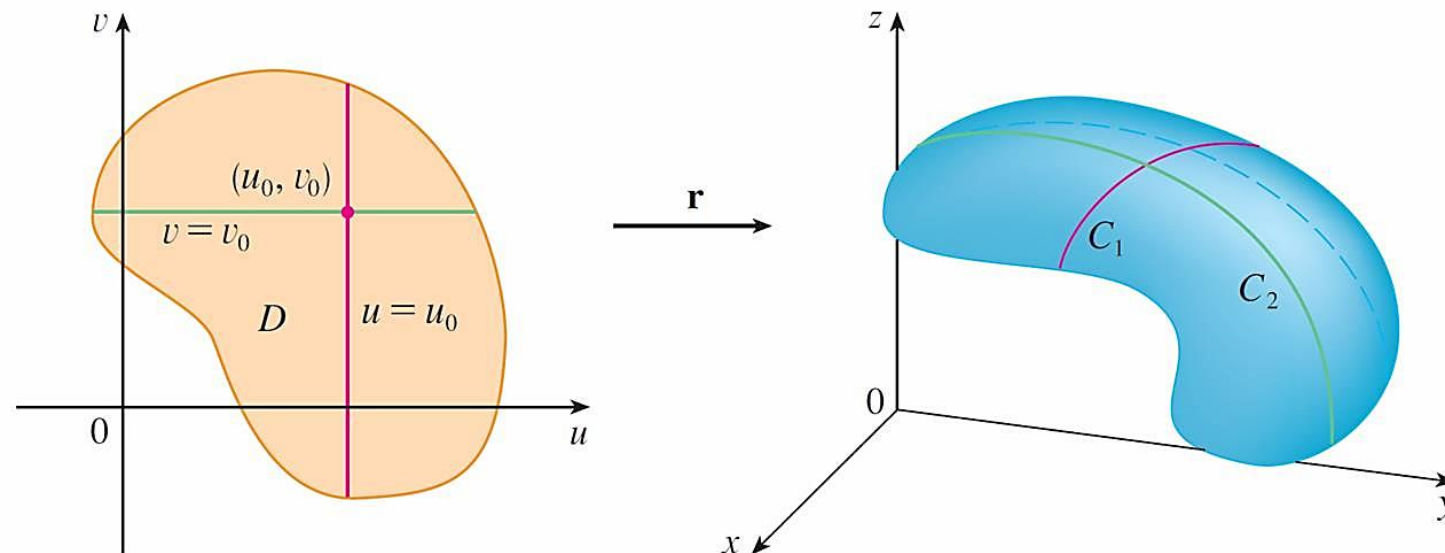
So, x , y , and z , the component functions of \mathbf{r} , are functions of the two variables u and v with domain D . The set of all points (x, y, z) in \mathbb{R}^3 such that:

$$x = x(u, v), \quad y = y(u, v), \quad z = z(u, v), \quad (2)$$

and (u, v) varies throughout D , is called a **parametric surface** S and Equations (2) are called **parametric equations** of S .

Parametric Surfaces: Families of Curves

If a parametric surface S is given by a vector function $\mathbf{r}(u, v)$, then there are two useful families of curves that lie on S , one family with u constant and the other with v constant. These families correspond to **vertical** and **horizontal lines** in the uv -plane. If we keep u constant by putting $u = u_0$, then $\mathbf{r}(u_0, v)$ becomes a vector function of the single parameter v and defines a curve C_1 lying on S . Similarly, if we keep v constant by putting $v = v_0$, we get a curve C_2 given by $\mathbf{r}(u, v_0)$ that lies on S . We call these curves **grid curves**. For instance, in previous example, the grid curves obtained by letting u be constant are horizontal lines whereas the grid curves with v constant are circles.



Parametric Surfaces

Note:

- In general, a surface given as the **graph of a function** of x and y , that is, with an equation of the form $z = f(x, y)$, can always be regarded as a parametric surface by taking x and y as parameters and writing the parametric equations as:

$$x = x, \quad y = y, \quad z = f(x, y).$$

- Parametric representations (also called parametrizations) of surfaces are not unique.
The next example shows two ways to parametrize a cone.

Tangent Planes

We now find the tangent plane to a parametric surface S traced out by a vector function:

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k},$$

at a point P_0 with position vector $\mathbf{r}(u_0, v_0)$.

If we keep u constant by putting $u = u_0$, then $\mathbf{r}(u_0, v)$ becomes a vector function of the single parameter v and defines a grid curve C_1 lying on S . The tangent vector to C_1 at P_0 is obtained by taking the partial derivative of \mathbf{r} with respect to v and is given as:

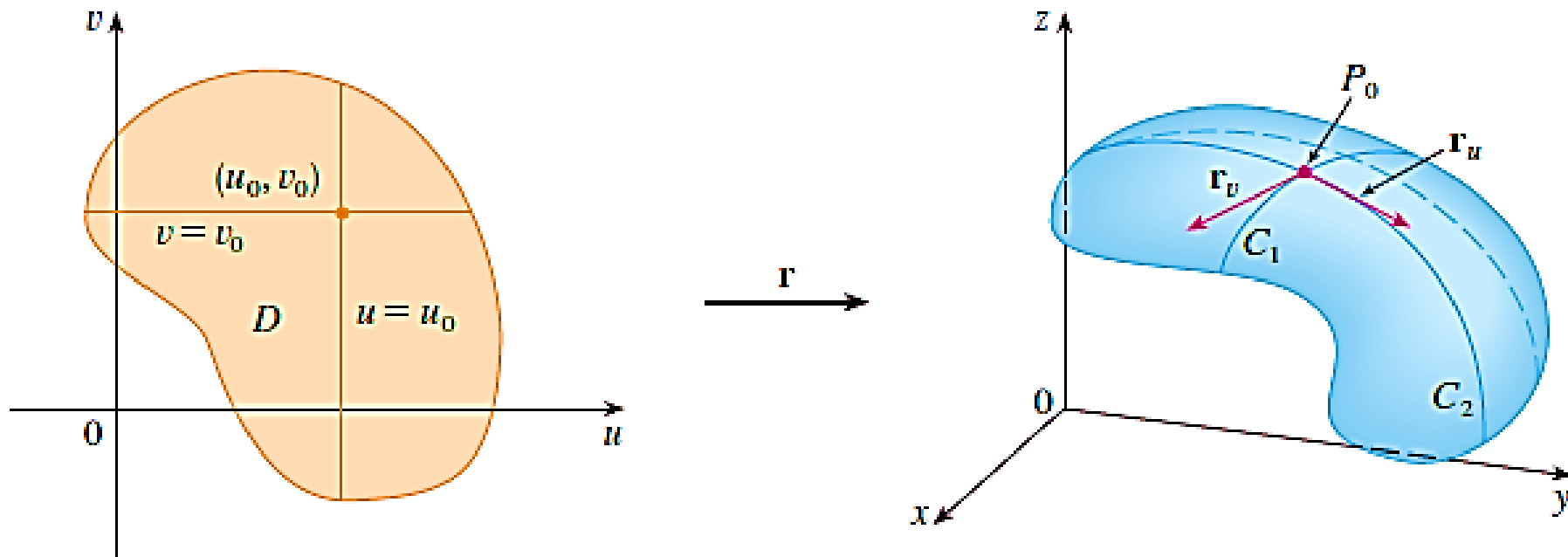
$$\mathbf{r}_v(u_0, v_0) = \frac{\partial x(u_0, v_0)}{\partial v}\mathbf{i} + \frac{\partial y(u_0, v_0)}{\partial v}\mathbf{j} + \frac{\partial z(u_0, v_0)}{\partial v}\mathbf{k}.$$

Similarly, if we keep v constant by putting $v = v_0$, we get a grid curve C_2 given by $\mathbf{r}(u, v_0)$ that lies on S , and its tangent vector at P_0 is:

$$\mathbf{r}_u(u_0, v_0) = \frac{\partial x(u_0, v_0)}{\partial u}\mathbf{i} + \frac{\partial y(u_0, v_0)}{\partial u}\mathbf{j} + \frac{\partial z(u_0, v_0)}{\partial u}\mathbf{k}.$$

Tangent Planes

- If $\mathbf{r}_u \times \mathbf{r}_v$ is not $\mathbf{0}$, then the surface S is called **smooth** (it has no “corners”).
- For a smooth surface, the **tangent plane** is the plane that contains the tangent vectors \mathbf{r}_u and \mathbf{r}_v , and the vector $\mathbf{r}_u \times \mathbf{r}_v$ is a **normal vector** to the tangent plane.



Unit Normal Vector

For a smooth surface S , the **unit normal vector** to the tangent plane is:

$$\mathbf{n} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|}.$$

If the surface S is the graph of an equation $z = f(x, y)$ and if we let:

$$g(x, y, z) = z - f(x, y),$$

then S is also the graph of the equation $g(x, y, z) = 0$. Since the gradient of $g(x, y, z)$ is a normal vector to the graph of $g(x, y, z) = 0$ at the point (x, y, z) , a **unit normal vector** can be obtained as follows:

$$\mathbf{n} = \frac{\nabla g(x, y, z)}{|\nabla g(x, y, z)|} = \frac{\langle g_x, g_y, g_z \rangle}{|\langle g_x, g_y, g_z \rangle|} = \frac{\langle -f_x, -f_y, 1 \rangle}{\sqrt{1 + [f_x]^2 + [f_y]^2}}$$

Example:

Find the tangent plane to the surface with parametric equations:

$$x = u^2, \quad y = v^2, \quad z = u + 2v,$$

at the point $(1, 1, 3)$.

Solution:

We first compute the tangent vectors:

$$\mathbf{r}_u = \frac{\partial x}{\partial u} \mathbf{i} + \frac{\partial y}{\partial u} \mathbf{j} + \frac{\partial z}{\partial u} \mathbf{k} = 2u\mathbf{i} + \mathbf{k}.$$

$$\mathbf{r}_v = \frac{\partial x}{\partial v} \mathbf{i} + \frac{\partial y}{\partial v} \mathbf{j} + \frac{\partial z}{\partial v} \mathbf{k} = 2v\mathbf{j} + 2\mathbf{k}.$$

Thus, a normal vector to the tangent plane is given as:

$$\mathbf{n} = \mathbf{r}_u \times \mathbf{r}_v = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 2u & 0 & 1 \\ 0 & 2v & 2 \end{vmatrix} = \langle -2v, -4u, 4uv \rangle$$

Solution:

Notice that the point $(1, 1, 3)$ corresponds to the parameter values $u = 1$ and $v = 1$, so the normal vector at this point is given as:

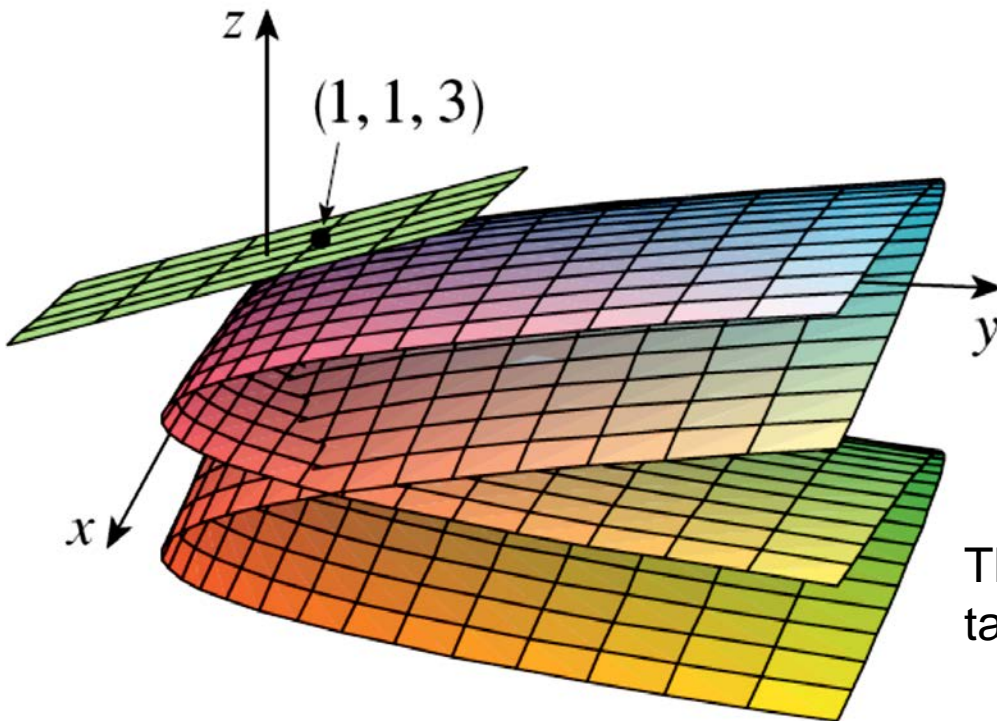
$$\mathbf{n} = \langle -2, -4, 4 \rangle.$$

Therefore, an equation of the tangent plane at $(1, 1, 3)$ is:

$$-2(x - 1) - 4(y - 1) + 4(z - 3) = 0$$

or

$$x + 2y - 2z + 3 = 0.$$



The figure shows the self-intersecting surface and its tangent plane at $(1, 1, 3)$.

Surface Area

Now we define the surface area of a general parametric surface. Suppose a smooth parametric surface S is given by equation:

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}; \quad (u, v) \in D,$$

and S is covered just once as (u, v) ranges throughout the parameter domain D . Then, the surface area of S is given as:

$$\text{Surface Area} = A(S) = \iint_D |\mathbf{r}_u \times \mathbf{r}_v| dA$$

where,

$$\mathbf{r}_u = \frac{\partial x}{\partial u}\mathbf{i} + \frac{\partial y}{\partial u}\mathbf{j} + \frac{\partial z}{\partial u}\mathbf{k} \quad \text{and} \quad \mathbf{r}_v = \frac{\partial x}{\partial v}\mathbf{i} + \frac{\partial y}{\partial v}\mathbf{j} + \frac{\partial z}{\partial v}\mathbf{k}.$$

Example:

Find the surface area of a sphere of radius a .

Solution:

The parametric representation of sphere of radius a is:

$$x = a \sin \varphi \cos \theta, \quad y = a \sin \varphi \sin \theta, \quad z = a \cos \varphi,$$

where the parameter domain is:

$$D = \{(\varphi, \theta) | 0 \leq \varphi \leq \pi, 0 \leq \theta \leq 2\pi\}.$$

For the present case:

$$\mathbf{r}(\varphi, \theta) = \langle a \sin \varphi \cos \theta, a \sin \varphi \sin \theta, a \cos \varphi \rangle.$$

We first compute the tangent vectors:

$$\mathbf{r}_\varphi = \langle a \cos \varphi \cos \theta, a \cos \varphi \sin \theta, -a \sin \varphi \rangle.$$

and

$$\mathbf{r}_\theta = \langle -a \sin \varphi \sin \theta, a \sin \varphi \cos \theta, 0 \rangle.$$

Solution:

We then compute the cross product of the tangent vectors \mathbf{r}_φ and \mathbf{r}_θ as:

$$\begin{aligned}\mathbf{n} = \mathbf{r}_\varphi \times \mathbf{r}_\theta &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a \cos \varphi \cos \theta & a \cos \varphi \sin \theta & -a \sin \varphi \\ -a \sin \varphi \sin \theta & a \sin \varphi \cos \theta & 0 \end{vmatrix} \\ &= \langle a^2 \sin^2 \varphi \cos \theta, a^2 \sin^2 \varphi \sin \theta, a^2 \sin \varphi \cos \varphi \rangle.\end{aligned}$$

Thus,

$$|\mathbf{r}_\varphi \times \mathbf{r}_\theta| = a^2 \sin \varphi.$$

since $\sin \varphi \geq 0$ for $0 \leq \varphi \leq \pi$. Hence, the area of the sphere is:

$$A(S) = \iint_D |\mathbf{r}_\varphi \times \mathbf{r}_\theta| dA = \int_0^{2\pi} \int_0^\pi a^2 \sin \varphi d\varphi d\theta = 4\pi a^2.$$

Surface Area of the Graph of a Function

Now, consider the special case of a surface S with equation $z = f(x, y)$, where (x, y) lies in D and f has continuous partial derivatives. Here, we take x and y as parameters. The parametric equations are:

$$x = x, \quad y = y, \quad z = f(x, y).$$

Thus,

$$\mathbf{r}(x, y) = x\mathbf{i} + y\mathbf{j} + f(x, y)\mathbf{k}, \quad \mathbf{r}_x = \mathbf{i} + f_x\mathbf{k}, \quad \mathbf{r}_y = \mathbf{j} + f_y\mathbf{k},$$

and

$$\mathbf{r}_x \times \mathbf{r}_y = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & f_x \\ 0 & 1 & f_y \end{vmatrix} = \langle -f_x, -f_y, 1 \rangle.$$

Thus, we have:

$$|\mathbf{r}_x \times \mathbf{r}_y| = \sqrt{1 + [f_x]^2 + [f_y]^2} = \sqrt{1 + [z_x]^2 + [z_y]^2}.$$

Then, the surface area formula can be rewritten as:

$$A(S) = \iint_D |\mathbf{r}_x \times \mathbf{r}_y| dA = \iint_D \sqrt{1 + [z_x]^2 + [z_y]^2} dA.$$

Surface Area of the Graph of a Function

Similarly, if we consider the surface S with equation $y = h(x, z)$, we have:

$$A(S) = \iint_D |\mathbf{r}_x \times \mathbf{r}_z| dA = \iint_D \sqrt{1 + [h_x]^2 + [h_z]^2} dA == \iint_D \sqrt{1 + [y_x]^2 + [y_z]^2} dA.$$

and if we consider the surface S with equation $x = k(y, z)$, we have:

$$A(S) = \iint_D |\mathbf{r}_y \times \mathbf{r}_z| dA = \iint_D \sqrt{1 + [k_y]^2 + [k_z]^2} dA == \iint_D \sqrt{1 + [x_y]^2 + [x_z]^2} dA.$$

Example:

Find the area of the part of the paraboloid $z = x^2 + y^2$ that lies under the plane $z = 9$.

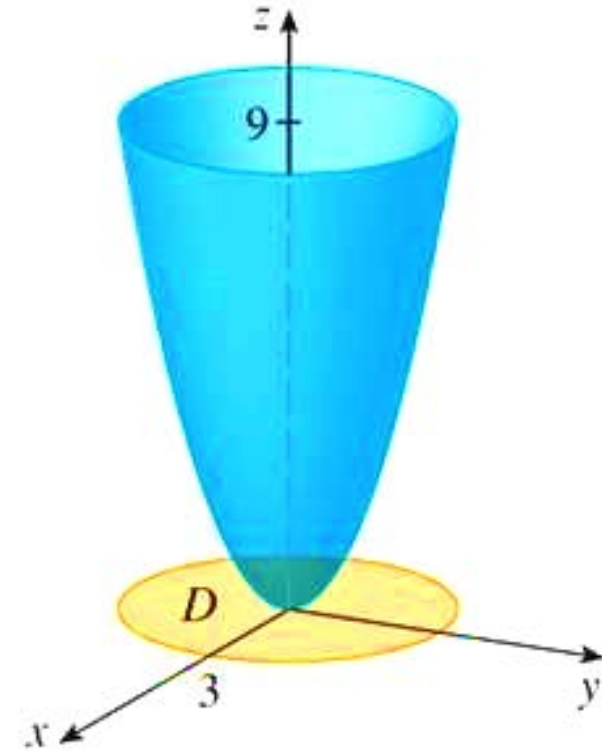
Solution:

The plane intersects the paraboloid in the circle $x^2 + y^2 = 9$, $z = 9$. Therefore, the given surface lies above the disk D with center the origin and radius 3. Hence, the surface area is:

$$\begin{aligned} A(S) &= \iint_D \sqrt{1 + [z_x]^2 + [z_y]^2} dA \\ &= \iint_D \sqrt{1 + [2x]^2 + [2y]^2} dA \\ &= \iint_D \sqrt{1 + 4(x^2 + y^2)} dA. \end{aligned}$$

Using polar coordinates, we obtain:

$$A(S) = \int_0^{2\pi} \int_0^3 \sqrt{1 + 4r^2} r dr d\theta = \frac{(37\sqrt{37} - 1)\pi}{6}.$$



Practice Questions

Book: Calculus Early Transcendentals (6th Edition) By James Stewart.

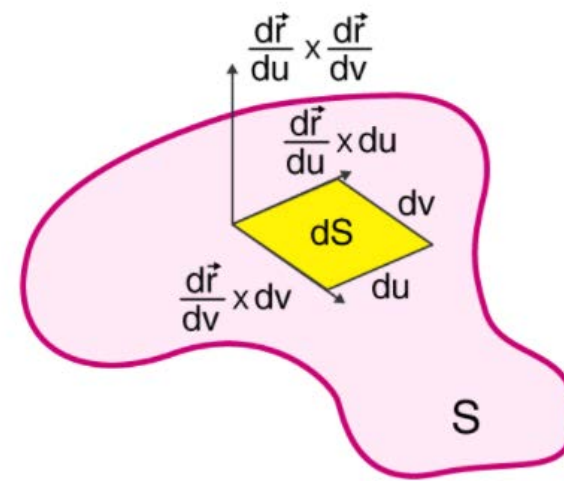
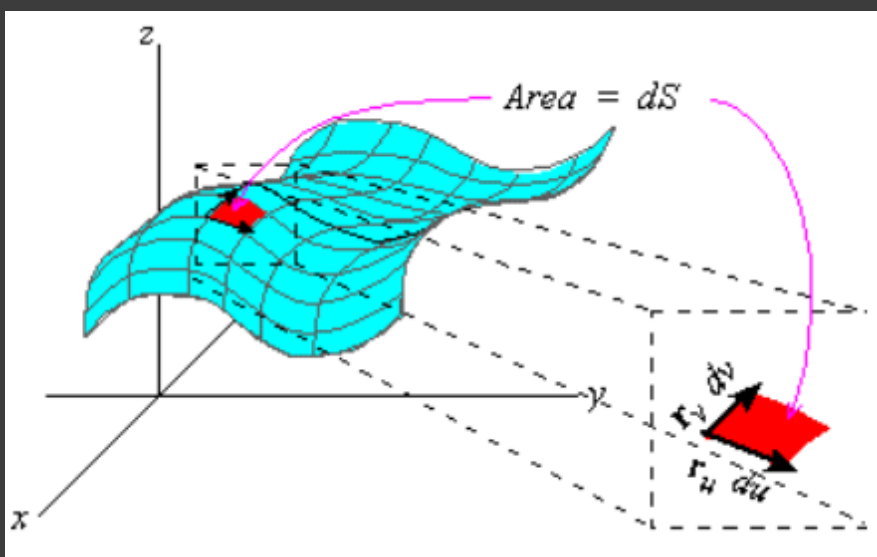
Chapter: 16

Exercise-16.6: Q – 1 to 26, Q – 33 to 47, Q – 56 to 57.

Book: Thomas' Calculus Early Transcendentals (14th Edition) By George B. Thomas, Jr., Joel Hass, Christopher Heil, Maurice D. Weir.

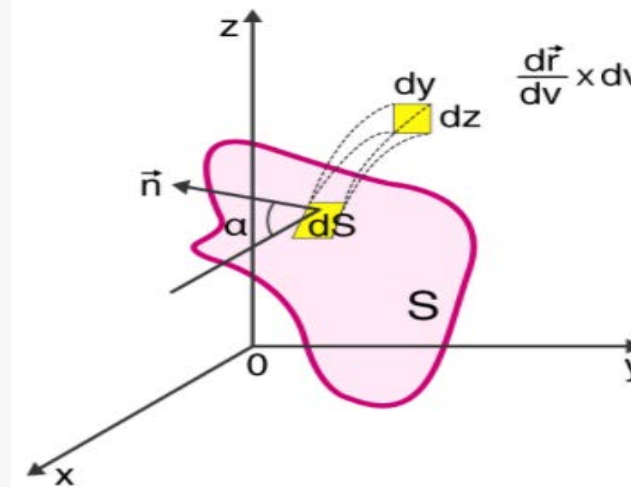
Chapter: 16

Exercise-16.5: Q – 1 to 30, Q – 33 to 56.



Surface Integral of Scalar Field

$$\iint_S f(x, y, z) dS = \iint_{D(u,v)} f[x(u, v), y(u, v), z(u, v)] \cdot \left| \frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v} \right| du dv$$



Surface Integral of Vector Field

- If the surface "S" oriented is outward, then the surface integral of the vector field is given as:

$$\iint_S \mathbf{F}(x, y, z) \cdot d\mathbf{S} = \iint_S \mathbf{F}(x, y, z) \cdot \mathbf{n} dS = \iint_{D(u,v)} \mathbf{F}[x(u, v), y(u, v), z(u, v)] \cdot \left[\frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v} \right] du dv$$

- If the surface "S" oriented is inward, then the surface integral of the vector field is given as:

$$\iint_S \mathbf{F}(x, y, z) \cdot d\mathbf{S} = \iint_S \mathbf{F}(x, y, z) \cdot \mathbf{n} dS = \iint_{D(u,v)} \mathbf{F}[x(u, v), y(u, v), z(u, v)] \cdot \left[\frac{\partial \mathbf{r}}{\partial v} \times \frac{\partial \mathbf{r}}{\partial u} \right] du dv$$

Where $d\mathbf{S} = \mathbf{n} dS$ is known as the vector element of the surface.

Surface Integrals

Vector Calculus(MATH-243)

Instructor: Dr. Naila Amir

16

Vector Calculus

Book: Calculus Early Transcendentals (6th Edition) By James Stewart.

- **Chapter: 16**
 - **Section: 16.7**

Book: Thomas' Calculus Early Transcendentals (14th Edition) By George B. Thomas, Jr., Joel Hass, Christopher Heil, Maurice D. Weir.

- **Chapter: 16**
 - **Section: 16.6**

Surface Integrals for Scalar Fields

- The relationship between surface integrals and surface area is much the same as the relationship between line integrals and arc length.
- Suppose f is a function of three variables whose domain includes a surface S .
- We will define the surface integral of f over S such that the value of the surface integral is equal to the surface area of S in the case where $f(x, y, z) = 1$.
- If S is a smooth surface defined parametrically as:

$$\mathbf{r}(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}; \quad (u, v) \in D,$$

and $f(x, y, z)$ is a continuous function defined on S , then the **integral of f over S** is:

$$\iint_S f(x, y, z) dS = \iint_D f(\mathbf{r}(u, v)) |\mathbf{r}_u \times \mathbf{r}_v| dA.$$

- When using this formula, remember that $f(\mathbf{r}(u, v))$ is evaluated by writing $x = x(u, v)$, $y = y(u, v)$, $z = z(u, v)$ in the formula for $f(x, y, z)$. Moreover, observe that:

$$\iint_S 1 dS = \iint_D |\mathbf{r}_u \times \mathbf{r}_v| dA = A(S).$$

Example:

Compute the surface integral

$$\iint_S x^2 dS,$$

where S is the unit sphere $x^2 + y^2 + z^2 = 1$.

Solution:

We use the parametric representation for the unit sphere:

$$x = \sin \varphi \cos \theta, \quad y = \sin \varphi \sin \theta, \quad z = \cos \varphi,$$

where, $D = \{(\varphi, \theta) | 0 \leq \varphi \leq \pi, 0 \leq \theta \leq 2\pi\}$. That is,

$$\mathbf{r}(\varphi, \theta) = \langle \sin \varphi \cos \theta, \sin \varphi \sin \theta, \cos \varphi \rangle.$$

For the present case: $|\mathbf{r}_\varphi \times \mathbf{r}_\theta| = \sin \varphi$. Therefore, the surface integral can be calculated as:

$$\iint_S x^2 dS = \iint_D (\sin \varphi \cos \theta)^2 |\mathbf{r}_\varphi \times \mathbf{r}_\theta| dA = \int_0^{2\pi} \int_0^\pi (\sin \varphi \cos \theta)^2 \sin \varphi d\varphi d\theta = \frac{4\pi}{3}.$$

Graphs of a Function

Any surface S with equation $z = g(x, y)$ can be regarded as a parametric surface with parametric equations:

$$x = x, \quad y = y, \quad z = g(x, y).$$

So, we have:

$$\iint_S f(x, y, z) dS = \iint_D f(x, y, g(x, y)) \sqrt{1 + [z_x]^2 + [z_y]^2} dA.$$

Similar formulas apply when it is more convenient to project S onto the yz –plane or xy –plane.

Example:

Evaluate

$$\iint_S y dS,$$

where S is the surface $z = x + y^2, 0 \leq x \leq 1, 0 \leq y \leq 2$.

Solution:

For the present case we have: $x = x, y = y, z = x + y^2$. Thus,

$$\iint_S y dS = \iint_D y \sqrt{1 + [z_x]^2 + [z_y]^2} dA = \int_0^1 \int_0^2 y \sqrt{1 + [1]^2 + [2y]^2} dy dx = \frac{13\sqrt{2}}{3}.$$