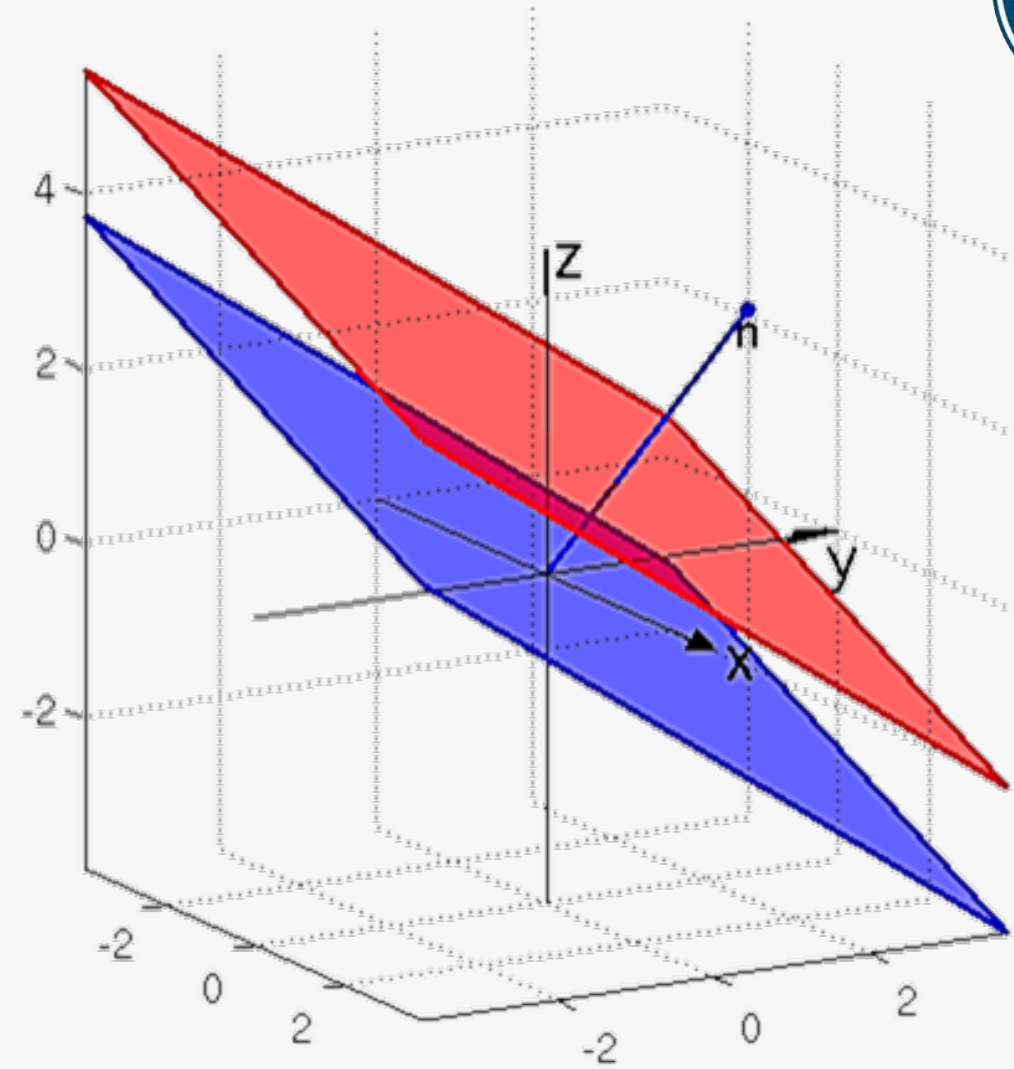


# Equations of Lines and Planes



Vector Calculus(MATH-243)  
Instructor: Dr. Naila Amir

# 12

## Vectors And The Geometry Of Space

**Book:** Thomas' Calculus Early Transcendentals (14th Edition) By George B. Thomas, Jr., Joel Hass, Christopher Heil, Maurice D. Weir.

**Section: 12.5**

**Book:** Calculus Early Transcendentals (6<sup>th</sup> Edition) By James Stewart.

**Section: 12.5**

# Lines in 2-D & 3-D

- A line in the  $xy$  –plane is determined when a point on the line and the direction of the line (its slope or angle of inclination) are given. The equation of the line can then be written using the point-slope form. Otherwise, we can determine equation of a line in 2-D if information about two points on the line is known.
- A line  $L$  in 3-D space is determined when we have information about a point  $P_0(x_0, y_0, z_0)$  on  $L$  and the direction of  $L$ , that can be determined with the help of a vector  $\mathbf{v} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ , that is parallel to  $L$ .

# Equation of a Line in 3-D

Let  $L$  be a line passing through the point  $P_0(x_0, y_0, z_0)$  and is parallel to the vector:  $\mathbf{v} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k} = \langle a, b, c \rangle$ . Let  $P(x, y, z)$  be an arbitrary point on  $L$ . Then  $L$  is the set of points  $P$  for which  $\mathbf{a} = \overrightarrow{P_0P}$  is parallel to  $\mathbf{v}$ . Since  $\mathbf{a}$  is parallel to  $\mathbf{v}$  so:

$$\mathbf{a} = \overrightarrow{P_0P} = t\mathbf{v}; \quad t \in \mathbb{R}. \quad (1)$$

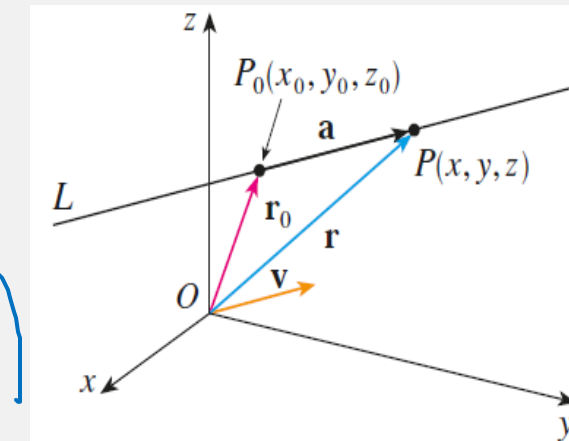
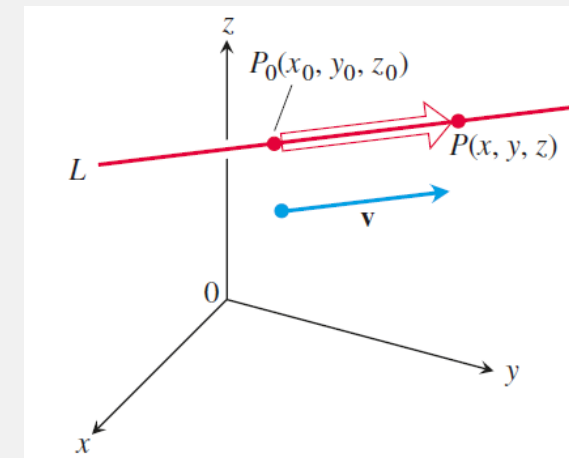
$\langle x-x_0, y-y_0, z-z_0 \rangle = t\langle a, b, c \rangle = \langle ta, tb, tc \rangle$

If  $\mathbf{r}$  is the position vector of a point  $P(x, y, z)$  on the line and  $\mathbf{r}_0$  is the position vector of the point  $P_0(x_0, y_0, z_0)$ , then by using head to tail rule we get:  $\mathbf{r} = \mathbf{r}_0 + \mathbf{a}$  and Equation (1) takes the form:

$$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}; \quad t \in \mathbb{R}, \quad (2)$$

$\langle x, y, z \rangle = \langle x_0, y_0, z_0 \rangle + t\langle a, b, c \rangle = \langle x_0 + at, y_0 + bt, z_0 + ct \rangle$

This is known as **vector equation** of a line in space



$$\hat{\mathbf{v}} = \frac{\mathbf{v}}{|\mathbf{v}|}$$

speed

# Equation of a Line in 3-D

Now the equation of line  $L$  in space that is passing through the point  $P_0(x_0, y_0, z_0)$  and is parallel to the vector:  $\mathbf{v} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k} = \langle a, b, c \rangle$  is given as:

$$\overrightarrow{P_0P} = t\mathbf{v}; \quad t \in \mathbb{R}, \quad (1)$$

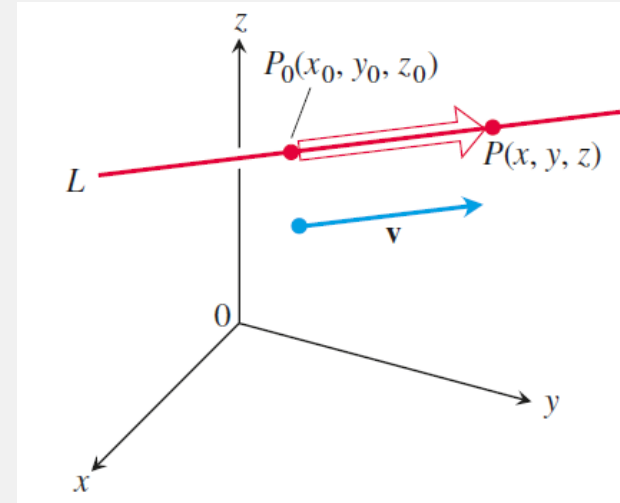
Since  $\overrightarrow{P_0P} = \langle x - x_0, y - y_0, z - z_0 \rangle$ , so above equation can be written as:

$$\langle x - x_0, y - y_0, z - z_0 \rangle = t\langle a, b, c \rangle,$$

From which we get three scalar equations:

$$x = x_0 + at, \quad y = y_0 + bt, \quad z = z_0 + ct; \quad t \in \mathbb{R}. \quad (3)$$

These equations are called **parametric equations** of the line  $L$ .



# Equation of a Line in 3-D

Another way of describing a line is to eliminate the parameter from Equations (3). If none of  $a, b$ , or  $c$  is 0, we can solve each of these equations for the parameter  $t$ , equate the results, and obtain:

$$\frac{x - x_0}{a} = \frac{y - y_0}{b} = \frac{z - z_0}{c} \quad \text{or} \quad \frac{x - x_0}{x_1 - x_0} = \frac{y - y_0}{y_1 - y_0} = \frac{z - z_0}{z_1 - z_0}. \quad (4)$$

These equations are called **symmetric equations** of the line  $L$ . Notice that the numbers  $a, b$ , and  $c$  that appear in the denominators of Equations (4) are direction numbers of  $L$ , that is, components of a vector parallel to  $L$ . If one of  $a, b$ , or  $c$  is 0, we can still eliminate  $t$ . For instance, if  $a = 0$ , we could write the equations of  $L$  as:

$$x = x_0, \quad \frac{y - y_0}{b} = \frac{z - z_0}{c}. \quad (5)$$

This means that  $L$  lies in the vertical plane  $x = x_0$ .

# Equation of a Line in 3-D

The vector form of a line in space:

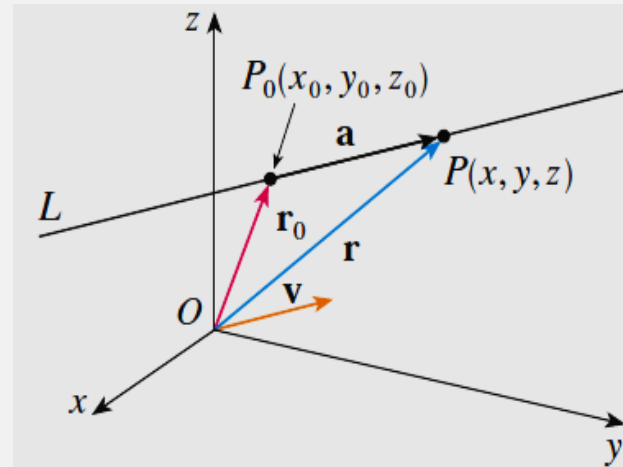
$$\mathbf{r} = \mathbf{r}_0 + t\mathbf{v}; \quad t \in \mathbb{R}, \quad (2)$$

is more revealing if we think of a line as the path of a particle starting at position  $P_0(x_0, y_0, z_0)$  and moving in the direction of vector  $\mathbf{v}$ . Rewriting Equation (2), we have:

$$\mathbf{r} = \mathbf{r}_0 + t|\mathbf{v}| \left( \frac{\mathbf{v}}{|\mathbf{v}|} \right); \quad t \in \mathbb{R}, \quad (6)$$

Initial position      Time      Speed      Direction

In other words, the position of the particle at time  $t$  is its initial position plus its distance moved (speed  $\times$  time) in the direction  $\frac{\mathbf{v}}{|\mathbf{v}|}$  of its straight-line motion.



# Example:

A helicopter is to fly directly from a helipad at the origin in the direction of the point  $(1, 1, 1)$  at a speed of 60 ft/sec. What is the position of the helicopter after 10 sec?

## **Solution:**

We place the origin at the starting position (helipad) of the helicopter. Then the unit vector:  $\mathbf{u} = \left\langle \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right\rangle$  gives the flight direction of the helicopter. From Equation (5), the position of the helicopter at any time  $t$  is given as:

$$\mathbf{r} = \mathbf{r}_0 + t(\text{speed})\mathbf{u} = \mathbf{0} + t(60) \left\langle \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}}, \frac{1}{\sqrt{3}} \right\rangle = (20\sqrt{3} t) \langle 1, 1, 1 \rangle.$$

At  $t = 10$  sec:  $\mathbf{r} = 200\sqrt{3} \langle 1, 1, 1 \rangle$ . After 10 sec of flight from the origin toward  $(1, 1, 1)$ , the helicopter is located at the point  $(200\sqrt{3}, 200\sqrt{3}, 200\sqrt{3})$  in space. It has traveled a distance of  $(60 \text{ ft/sec})(10 \text{ sec}) = 600 \text{ ft}$ , which is the length of the vector  $\mathbf{r}$ .



# Example:

Find the parametric equations of the line passing through the points  $(1, 2, -2)$  and  $(3, -2, 5)$ .

**Solution:**

First, we need to determine the direction vector and then by considering either of the points, simply use the parametric form to obtain the required line. Direction vector is obtained as:

$$\mathbf{v} = \langle 3 - 1, -2 - 2, 5 - (-2) \rangle = \langle 2, -4, 7 \rangle.$$

Parametric equations of the line passing through the points  $(1, 2, -2)$  and  $(3, -2, 5)$  are given as:

$$x = 1 + 2t, \quad y = 2 - 4t, \quad z = -2 + 7t; \quad t \in \mathbb{R}.$$

# Example:

- 
- a) Find the symmetric equations of the line that is passing through the points  $A(2, 4, -3)$  and  $B(3, -1, 1)$ .
- b) Determine at what point this line will intersect the  $xy$  -plane.

## Solution:

- a) For the present case, the direction vector  $\mathbf{v} = \langle a, b, c \rangle$ , is obtained as:
- $$\mathbf{v} = \langle 3 - 2, -1 - 4, 1 - (-3) \rangle = \langle 1, -5, 4 \rangle.$$

Taking the point  $(2, 4, -3)$  as the initial point, we see that the symmetric equations are given as:

$$\frac{x - 2}{1} = \frac{y - 4}{-5} = \frac{z + 3}{4}.$$

# Example:

- 
- a) Find the symmetric equations of the line that is passing through the points  $A(2, 4, -3)$  and  $B(3, -1, 1)$ .
- b) Determine at what point this line will intersect the  $xy$  -plane.

## Solution:

- b) The line intersects the  $xy$  -plane when  $z = 0$ . So, we put  $z = 0$  in the symmetric equations and obtain:

$$\frac{x - 2}{1} = \frac{y - 4}{-5} = \frac{3}{4} \Rightarrow x = \frac{11}{4} \quad \text{and} \quad y = \frac{1}{4}.$$

Thus, the line intersects the  $xy$  -plane at the point  $\left(\frac{11}{4}, \frac{1}{4}, 0\right)$ .

# Equation of Plane in Space

- 
- Although a line in space is determined by a point and a direction, a plane in space is more difficult to describe.
  - A single vector parallel to a plane is not enough to convey the “direction” of the plane, but a vector perpendicular to the plane does completely specify its direction.
  - Thus, a plane in space is determined by a point in the plane and a vector that is orthogonal to the plane. This orthogonal vector is called a **normal vector**.

# Equation of Plane in Space

Let the plane  $M$  is passing through an arbitrary point  $P_0(x_0, y_0, z_0)$ , and is normal to the vector  $\mathbf{n} = a\mathbf{i} + b\mathbf{j} + c\mathbf{k}$ . Then  $M$  is the set of all points  $P(x, y, z)$  for which  $\overrightarrow{P_0P}$  is perpendicular to  $\mathbf{n}$ . Means the normal vector  $\mathbf{n}$  is orthogonal to every vector in the given plane, i.e.,

$$\checkmark \quad \vec{n} \cdot \vec{r} = \vec{n} \cdot \vec{r}_0$$

$$\mathbf{n} \cdot \overrightarrow{P_0P} = 0. \quad (1)$$

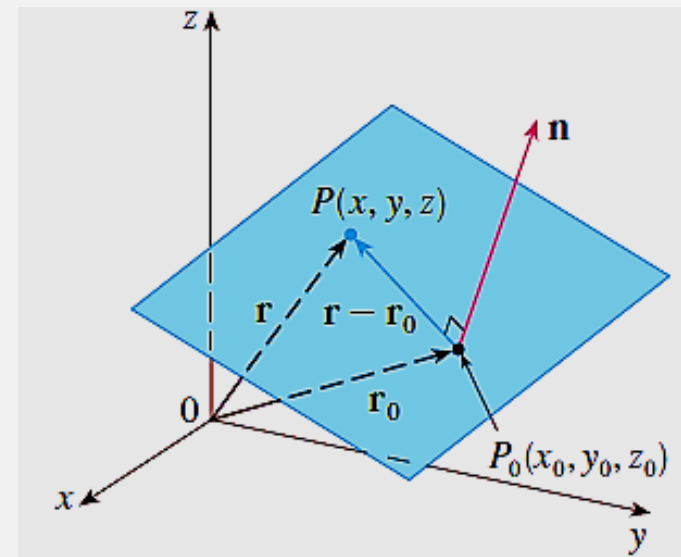
$$\begin{array}{l} \vec{r}_0 \rightarrow P_0 \\ \vec{r} \rightarrow P \end{array}$$

Equation (1) is the **vector equation** of plane. This equation can be written as:

$$(a\mathbf{i} + b\mathbf{j} + c\mathbf{k}) \cdot [(x - x_0)\mathbf{i} + (y - y_0)\mathbf{j} + (z - z_0)\mathbf{k}] = 0$$

$$\Rightarrow a(x - x_0) + b(y - y_0) + c(z - z_0) = 0. \quad (2)$$

This is the **scalar equation** or **standard form** of the plane through  $P_0(x_0, y_0, z_0)$  with normal vector  $\mathbf{n}$ .



# Equation of Plane in Space

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## Note:

The equation (2)

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0. \quad (2)$$

can be simplified by using the distributive property and collecting like terms. This results in the **general form** given as:

$$ax + by + cz + d = 0. \quad (3)$$

$$d = -(ax_0 + by_0 + cz_0)$$

# Example:

Given the normal vector,  $\langle 3, 1, -2 \rangle$  to the plane containing the point  $(2, 3, -1)$ , write the equation of the plane in both standard form and general form.

## Solution:

Standard form of plane:

$$\vec{n} = \langle a, b, c \rangle = \langle 3, 1, -2 \rangle$$
$$P_0 (x_0, y_0, z_0) = (2, 3, -1)$$

$$a(x - x_0) + b(y - y_0) + c(z - z_0) = 0,$$
$$\Rightarrow 3(x - 2) + 1(y - 3) - 2(z + 1) = 0.$$

General form of plane:

$$ax + by + cz + d = 0,$$
$$\Rightarrow 3x + y - 2z - 11 = 0.$$

# Example:

Given the points  $(1, 2, -1)$ ,  $(4, 0, 3)$  and  $(2, -1, 5)$  in a plane, find the equation of the plane in general form.

**Solution:**

**Hint:**

To write the equation of the plane we need a point (we have three) and a vector normal to the plane. So, we need to find a vector normal to the plane. First find two vectors in the plane, then recall that their cross product will be a vector normal to both those vectors and thus normal to the plane. Using all this information in the general equation of plane we will finally get:

**Equation of the plane in general form:**

$$2y + z - 3 = 0.$$

$(x_0, y_0, z_0) \leftarrow P$

$\vec{PQ}$

$\vec{PR}$

$\vec{n} = \langle a, b, c \rangle$

$= \vec{PQ} \times \vec{PR}$



# Some Properties of Lines and Planes

- 
- Two lines are **parallel** if and only if they have the same direction.
  - Two lines **intersect** at a point if they are lying in the same plane.
  - The lines that do not intersect each other and are not parallel (and therefore do not lie in the same plane) are called **skew lines**.
  - Intersection of a line and a plane is a point.
  - Two planes are **parallel** if and only if their normals are parallel, i.e.,
$$\mathbf{n}_1 = k\mathbf{n}_2; \quad \text{for some scalar } k.$$
  - Two planes that are not parallel intersect in a line.

# Intersecting Planes

Any two planes that are not parallel or identical will intersect in a line and to find the line, solve the equations simultaneously.



# Example:

Find the line of intersection for the planes  $x + 3y + 4z = 0$  and  $x - 3y + 2z = 0$ .

## Solution:

To find the common intersection, solve the equations simultaneously. Multiply the first equation by  $-1$  and add the two to eliminate  $x$ .

$$\begin{array}{rcl} -1 \cdot (x + 3y + 4z = 0) & \Rightarrow & -x - 3y - 4z = 0 \\ x - 3y + 2z = 0 & \Rightarrow & +x - 3y + 2z = 0 \\ \hline & & -6y - 2z = 0 \end{array} \quad \left. \vphantom{\begin{array}{rcl} -1 \cdot (x + 3y + 4z = 0) & \Rightarrow & -x - 3y - 4z = 0 \\ x - 3y + 2z = 0 & \Rightarrow & +x - 3y + 2z = 0 \end{array}} \right\} \text{Add}$$
$$\text{or} \quad y = \frac{-1}{3}z$$

Back substitute  $y$  into one of the first equations and solve for  $x$ .

# Example:

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$$\begin{aligned}x + 3 \cdot \left( \frac{-1}{3} z \right) + 4z &= 0 \\x - z + 4z &= 0 \\x &= -3z.\end{aligned}$$

Finally, if we let  $z = t$ , the parametric equations for the line are:

$$x = -3t, \quad y = \frac{-1}{3}t \quad \text{and} \quad z = t.$$

# Practice Questions

**Book:** Thomas' Calculus Early Transcendentals (14th Edition) By George B. Thomas, Jr., Joel Hass, Christopher Heil, Maurice D. Weir.

**Chapter: 12**

**Exercise-12.5:** Q – 1 to 12, Q – 21 to 26, Q – 57 to 64.

**Book:** Calculus Early Transcendentals (6<sup>th</sup> Edition)  
By James Stewart.

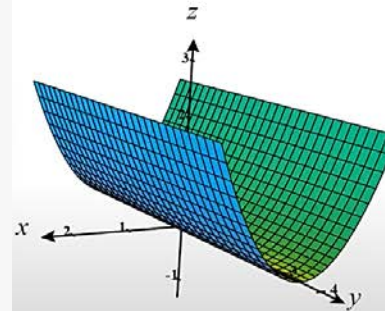
**Chapter: 12**

**Exercise-12.5:** Q – 1 to 12, Q – 19 to 36, Q – 43 to 45.

# Cylinders & Quadric Surfaces

## Parabolic Cylinder

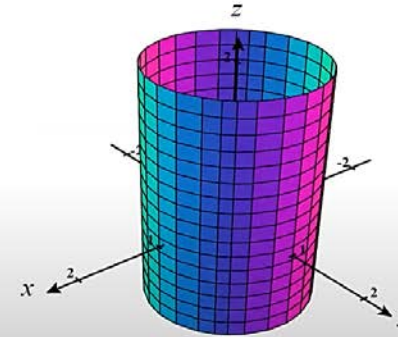
$$z = x^2 \text{ is shown}$$



y is missing in the equation,  
so axis parallel to y-axis

## Circular Cylinder

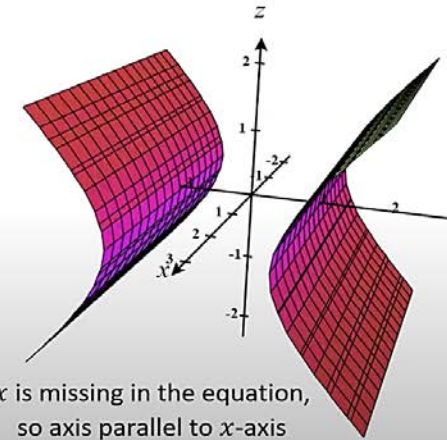
$$x^2 + y^2 = 1 \text{ is shown}$$



z is missing in the equation,  
so axis parallel to z-axis

## Hyperbolic Cylinder

$$y^2 - z^2 = 1 \text{ is shown}$$



x is missing in the equation,  
so axis parallel to x-axis

## Quadratic Surfaces

Quadratic Surfaces – General Form:  $Ax^2 + By^2 + Cz^2 + Dxy + Eyz + Fxz + Gx + Hy + Jz + K = 0$

Parabolic Cylinder $y = x^2$	Elliptical Cylinder $x^2 + 4z^2 = 4$	Hyperbolic Cylinder $y^2 - z^2 = 1$	Ellipsoid $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$	Elliptical Paraboloid $\frac{x^2}{a^2} + \frac{y^2}{b^2} = z$
Elliptical Cone $\frac{x^2}{a^2} + \frac{y^2}{b^2} = \frac{z^2}{c^2}$	Hyperboloids		Hyperbolic Paraboloid (with saddle point) $\frac{y^2}{b^2} - \frac{z^2}{c^2} = \frac{x^2}{a^2}$	

# 12

## Vectors And The Geometry Of Space

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**Section: 12.6**

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