## **FORMULA SHEET**

$$r = \sqrt{x^2 + y^2 + z^2}, \qquad \theta = \tan^{-1} \frac{\sqrt{x^2 + y^2}}{z}, \qquad \phi = \tan^{-1} \frac{y}{x}$$
$$x = r \sin \theta \cos \phi, \qquad y = r \sin \theta \sin \phi, \qquad z = r \cos \theta$$

$$\begin{bmatrix} A_r \\ A_\theta \\ A_\phi \end{bmatrix} = \begin{bmatrix} \sin\theta\cos\phi & \sin\theta\sin\phi & \cos\theta \\ -\cos\theta\cos\phi & \cos\theta\sin\phi & -\sin\theta \\ -\sin\phi & \cos\phi & 0 \end{bmatrix} \begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix}$$

$$\begin{bmatrix} A_{\rho} \\ A_{\phi} \\ A_{z} \end{bmatrix} = \begin{bmatrix} \cos \phi & \sin \phi & 0 \\ -\sin \phi & \cos \phi & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{bmatrix} A_{x} \\ A_{y} \\ A_{z} \end{bmatrix}$$

$$\begin{bmatrix} A_x \\ A_y \\ A_z \end{bmatrix} = \begin{bmatrix} \sin \theta \cos \phi & \cos \theta \cos \phi & -\sin \phi \\ \sin \theta \sin \phi & \cos \theta \sin \phi & \cos \phi \\ \cos \theta & -\sin \theta & 0 \end{bmatrix} \begin{bmatrix} A_r \\ A_{\theta} \\ A_{\phi} \end{bmatrix}$$

$$\rho = \sqrt{x^2 + y^2}, \qquad \phi = \tan^{-1} \frac{y}{x}, \qquad z = z$$

$$\varepsilon_0 = 8.854 \times 10^{-12} \simeq \frac{10^{-9}}{36\pi} \text{F/m}$$
or  $k = \frac{1}{4\pi\varepsilon} \simeq 9 \times 10^9 \text{ m/F}$ 

$$\mathbf{E} = \int \frac{\rho_L \, dl}{4\pi \varepsilon_0 R^2} \, \mathbf{a}_R \qquad \text{(line charge)}$$

$$\mathbf{E} = \int \frac{\rho_S dS}{4\pi\epsilon_0 R^2} \mathbf{a}_R \qquad \text{(surface charge)}$$

$$\mathbf{E} = \int \frac{\rho_v \, dv}{4\pi \varepsilon_0 R^2} \, \mathbf{a}_R \qquad \text{(volume charge)}$$

$$\mathbf{E} = \frac{\rho_L}{4\pi\varepsilon_0\rho} \left[ -(\sin\alpha_2 - \sin\alpha_1)\mathbf{a}_\rho + (\cos\alpha_2 - \cos\alpha_1)\mathbf{a}_z \right]$$

$$\mathbf{E} = \frac{\rho_L}{2\pi\epsilon_o\rho}\,\mathbf{a}_\rho$$

$$\nabla = \mathbf{a}_r \frac{\partial}{\partial r} + \mathbf{a}_\theta \frac{1}{r} \frac{\partial}{\partial \theta} + \mathbf{a}_\phi \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi}$$

$$\nabla V = \frac{\partial V}{\partial x} \, \mathbf{a}_x + \frac{\partial V}{\partial y} \, \mathbf{a}_y + \frac{\partial V}{\partial z} \, \mathbf{a}_z$$

$$\nabla V = \frac{\partial V}{\partial \rho} \mathbf{a}_{\rho} + \frac{1}{\rho} \frac{\partial V}{\partial \phi} \mathbf{a}_{\phi} + \frac{\partial V}{\partial z} \mathbf{a}_{z}$$

$$\nabla V = \frac{\partial V}{\partial r} \mathbf{a}_r + \frac{1}{r} \frac{\partial V}{\partial \theta} \mathbf{a}_{\theta} + \frac{1}{r \sin \theta} \frac{\partial V}{\partial \phi} \mathbf{a}_{\phi}$$

$$\nabla \cdot \mathbf{A} = \frac{\partial A_x}{\partial x} + \frac{\partial A_y}{\partial y} + \frac{\partial A_z}{\partial z}$$

$$\nabla \cdot \mathbf{A} = \frac{1}{\rho} \frac{\partial}{\partial \rho} (\rho A_{\rho}) + \frac{1}{\rho} \frac{\partial A_{\phi}}{\partial \phi} + \frac{\partial A_{z}}{\partial z}$$

$$W_E = \frac{1}{2} \int \mathbf{D} \cdot \mathbf{E} \, dv = \frac{1}{2} \int \varepsilon_0 E^2 \, dv$$

$$R = \frac{V}{I} = \frac{\int \mathbf{E} \cdot d\mathbf{l}}{\int \sigma \mathbf{E} \cdot d\mathbf{S}}$$

$$P = \int \mathbf{E} \cdot \mathbf{J} \, dv$$

$$w_P = \frac{dP}{dv} = \mathbf{E} \cdot \mathbf{J} = \sigma |\mathbf{E}|^2$$

$$ho_{ps} = \mathbf{p} \cdot \mathbf{a}_n$$
 $ho_{pv} = -\nabla \cdot \mathbf{P}$ 

$$\mathbf{D} = \boldsymbol{\varepsilon}_{o} \mathbf{E} + \mathbf{P}$$

$$\nabla \times \mathbf{A} = \begin{bmatrix} \frac{\partial A_t}{\partial y} & \frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_z + \begin{bmatrix} \frac{\partial A_s}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \begin{bmatrix} \frac{\partial A_t}{\partial y} & -\frac{\partial A_t}{\partial z} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t + \begin{bmatrix} \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial \rho} \end{bmatrix} \mathbf{a}_t \\ + \begin{bmatrix} \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t + \begin{bmatrix} \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial \rho} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial \rho} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial \rho} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial \rho} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial \rho} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial \phi} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial \phi} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial z} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial \phi} & -\frac{\partial A_t}{\partial z} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{1}{\rho} \begin{bmatrix} \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \\ \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t \\ + \frac{\partial A_t}{\partial z} & -\frac{\partial A_t}{\partial z} \end{bmatrix} \mathbf{a}_t$$

 $\mathbf{F}_{1} = \frac{\mu_{0}I_{1}I_{2}}{4\pi} \oint_{I} \oint_{I} \frac{d\mathbf{l}_{1} \times (d\mathbf{l}_{2} \times \mathbf{a}_{R_{21}})}{R_{21}^{2}}$