

Fourier transform & Convolution:

On view of the duality between time and frequency domains, there are two convolution results involving the Fourier transform.

Convolution in time: Suppose that $F[f(t)] = F(j\omega)$, $F[g(t)] = G(j\omega)$

$$\text{and } y(t) = f(t) * g(t) = \int_{-\infty}^{+\infty} f(\tau) g(t-\tau) d\tau$$

$$\begin{aligned} F[y(t)] &= Y(j\omega) = \int_{-\infty}^{+\infty} \left[\int_{-\infty}^{+\infty} f(\tau) g(t-\tau) d\tau \right] e^{-j\omega t} dt \\ &= \int_{-\infty}^{+\infty} f(\tau) \left[\int_{-\infty}^{+\infty} e^{-j\omega t} g(t-\tau) dt \right] d\tau. \end{aligned}$$

$$\text{Let } t-\tau = u \Rightarrow t = u+\tau, dt = du$$

$$\begin{aligned} Y(j\omega) &= \int_{-\infty}^{+\infty} f(\tau) \left[\int_{-\infty}^{+\infty} g(u) e^{-j\omega(u+\tau)} du \right] d\tau \\ &= \int_{-\infty}^{+\infty} f(\tau) e^{-j\omega\tau} d\tau \int_{-\infty}^{+\infty} g(u) e^{-j\omega u} du = F(j\omega) G(j\omega) \end{aligned}$$

$$\text{hence, } F[f(t) * g(t)] = F(j\omega) G(j\omega).$$

Convolution in frequency: $f(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} F(j\omega) e^{j\omega t} d\omega$, $g(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} G(j\omega) e^{j\omega t} d\omega$

$$F(j\omega) * G(j\omega) = \int_{-\infty}^{+\infty} F(y) G(\omega-y) dy$$

$$F^{-1}[F(\omega) * G(\omega)] = \frac{1}{2\pi} \int_{-\infty}^{+\infty} \left[\int_{-\infty}^{+\infty} F(y) G(\omega-y) dy \right] e^{j\omega t} d\omega$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} F(y) \left[\int_{-\infty}^{+\infty} G(\omega-y) e^{j\omega t} d\omega \right] dy \quad \begin{matrix} \omega-y = u \\ \omega = y+u \end{matrix}$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} F(y) \left[\int_{-\infty}^{+\infty} G(u) e^{j(y+u)t} du \right] dy$$

$$= \frac{1}{2\pi} \int_{-\infty}^{+\infty} F(y) e^{jyt} dy \int_{-\infty}^{+\infty} G(u) e^{jut} du = 2\pi f(t) g(t)$$

$$\text{giving, } F[f(t)g(t)] = \frac{1}{2\pi} F(j\omega) * G(j\omega).$$

Ex:- A relaxed causal LTI system is described by the following ordinary differential equation

$$\frac{d^2 y}{dt^2} + 3 \frac{dy}{dt} + 2y(t) = \frac{dx}{dt} \quad \text{--- (i)}$$

Where $x(t)$ is the input and $y(t)$ is the output. Using Fourier transform techniques, determine the output $y(t)$ when the input $x(t) = u(t)$, the unit step signal.

Sol:- Taking Fourier transform of (i), we get

$$(j\omega)^2 Y(j\omega) + 3(j\omega)Y(j\omega) + 2Y(j\omega) = (j\omega)X(j\omega)$$

$$\text{or } \frac{Y(j\omega)}{X(j\omega)} = H(j\omega) = \frac{j\omega}{(j\omega)^2 + 3j\omega + 2} \quad \text{--- (ii)}$$

$$Y(j\omega) = \left[\frac{j\omega}{(j\omega+2)(j\omega+1)} \right] X(j\omega) \quad \text{--- (iii)}$$

$$x(t) = u(t) \longleftrightarrow x(\omega) = \pi \delta(\omega) + \frac{1}{j\omega} \quad \text{--- (iv)}$$

Using (iv) in (iii), we have

$$Y(\omega) = \left[\frac{j\omega}{(j\omega+2)(j\omega+1)} \right] \left[\pi \delta(\omega) + \frac{1}{j\omega} \right]$$

$$= \frac{1}{(j\omega+2)(j\omega+1)} \quad \text{--- (v)}$$

The second term is zero.

$$Y(\omega) = \frac{1}{j\omega+1} - \frac{1}{j\omega+2} \quad \text{--- (vi)}$$

By taking inverse Fourier transform on both sides of (vi), we have

$$y(t) = \left[\frac{-t}{e} - \frac{-2t}{e} \right] u(t).$$

Energy & Power Signals:-

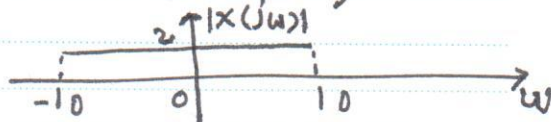
The idea of the "size" of a signal is crucial to many applications. It is nice to know, for example, how much electricity can be used in a defibrillator without ill effects or the amount of the signal driving a set of headphones. So, we use the concept of energy and power. Defibrillation is the process of applying a controlled shock to allow restoration of the normal rhythm in a serious cardiac arrest.

$$E = \int_{-\infty}^{+\infty} [f(t)]^2 dt, \quad P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} [f(t)]^2 dt$$

Using Parseval's relation, $E = \int_{-\infty}^{+\infty} [f(t)]^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |F(j\omega)|^2 d\omega$.

EX:- Determine the energy of the signal $f(t) = \frac{2 \sin 10(t - \frac{\pi}{10})}{10(t - \frac{\pi}{10})}$

$$F(j\omega) = 2 \text{Rect}\left(\frac{\omega}{20}\right) e^{-\frac{j\omega\pi}{10}}$$



$$E = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |F(j\omega)|^2 d\omega = \frac{1}{2\pi} \int_{-10}^{10} (2)^2 d\omega = \frac{1}{2\pi} (4)(20) = \frac{40}{\pi} \text{ J}$$

There are important signals $f(t)$, defined in general for $-\infty < t < \infty$, for which the integral $\int_{-\infty}^{+\infty} [f(t)]^2 dt$ is either unbounded (i.e.,

it becomes infinite) or does not converge to a finite limit. For such signals we calculate average power P of the signal.

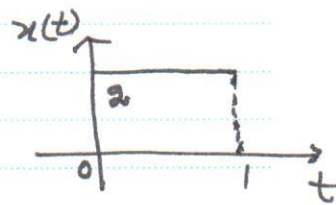
$$f(t) = \cos(\omega_0 t), \quad E = \int_{-\infty}^{+\infty} \cos^2 \omega_0 t dt \text{ is unbounded.}$$

$$P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} \cos^2 \omega_0 t dt = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} \frac{1 + \cos(2\omega_0 t)}{2} dt$$
$$= \lim_{T \rightarrow \infty} \frac{1}{T} \left[\frac{t}{2} + \frac{1}{2\omega_0} \sin(2\omega_0 t) \right]_{-T/2}^{T/2} = 1/2$$

Thus while the signal has unbounded energy associated with it, its power content is $1/2$.

Signals whose associated energy is finite are sometimes called energy signals, while those whose associated energy is unbounded but whose total power is finite are known as power signals.

Ex: For the CTS (Continuous time signal) shown in figure, determine whether it is an energy signal or power signal?



$$E = \int_{-\infty}^{+\infty} x^2(t) dt = \int_0^1 4 dt = 4, \quad P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_{-T/2}^{T/2} x^2(t) dt = \lim_{T \rightarrow \infty} \frac{1}{T} [4] = 0$$

Hence, $x(t)$ is an energy signal and not a power signal.

Exercise: Determine the values of power and energy, state whether each of the following signals is a power or energy signal.

(i) $x(t) = e^{-2t} u(t)$ (ii) $x(t) = \cos^2 t$ (iii) $x(t) = 2 \operatorname{rect}(t/4)$

(iv) $x(t) = e^{j(2t + \pi/6)}$ (v) $x(t) = \cos(3\pi t) + 2 \sin\left(\frac{2\pi}{3}\right)$

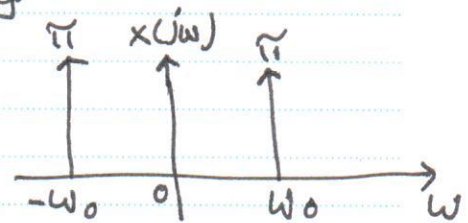
(vi) $x(t) = \begin{cases} t, & t > 0 \\ 0, & t < 0 \end{cases}$ (vii) $x(t) = \begin{cases} 1, & t > 0 \\ 0, & t < 0 \end{cases}$

Modulation:- Fourier transform is widely used in communication systems. Some of the fundamental idea is modulation (Amplitude, frequency etc).

Recall the FT of the complex exponential is

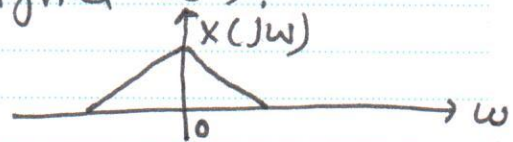
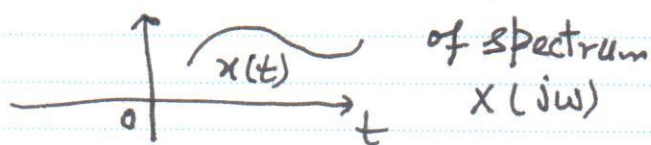
$$F[e^{j\omega_0 t}] = 2\pi \delta(\omega - \omega_0)$$

$$\text{Let } x(t) = \cos(\omega_0 t) = \frac{1}{2} e^{j\omega_0 t} + \frac{1}{2} e^{-j\omega_0 t}$$



$$X(j\omega) = F[x(t)] = \pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)$$

Now let us consider a generic signal $x(t)$.



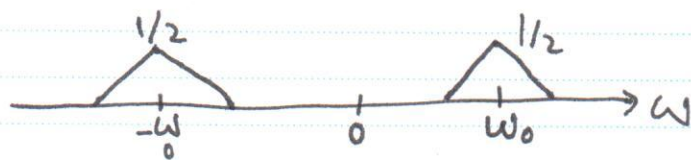
and let us multiply this by $\cos(\omega_0 t)$

$$F[x(t) \cos(\omega_0 t)] = X(j\omega) * [\pi \delta(\omega - \omega_0) + \pi \delta(\omega + \omega_0)]$$

$$= X(j\omega) * \pi \frac{1}{2\pi} \delta(\omega - \omega_0) + X(j\omega) * \pi \frac{1}{2\pi} \delta(\omega + \omega_0)$$

$$= \frac{1}{2} X(j(\omega - \omega_0)) + \frac{1}{2} X(j(\omega + \omega_0))$$

So, the effect is that of creating two replicas of the spectrum of $x(t)$ and to shift them in frequency, placing them at $\omega = \pm \omega_0$ each scaled by a factor $1/2$.



This operation is called modulation.

Ex:- The message signal $x(t) = 5 + 2\cos 100t \cos 200t$ modulates a carrier signal $\cos(1000t)$ to produce the AM signal, $y(t) = x(t)\cos(1000t)$. Determine & sketch the spectrum of (a) $x(j\omega)$ (b) $y(j\omega)$.

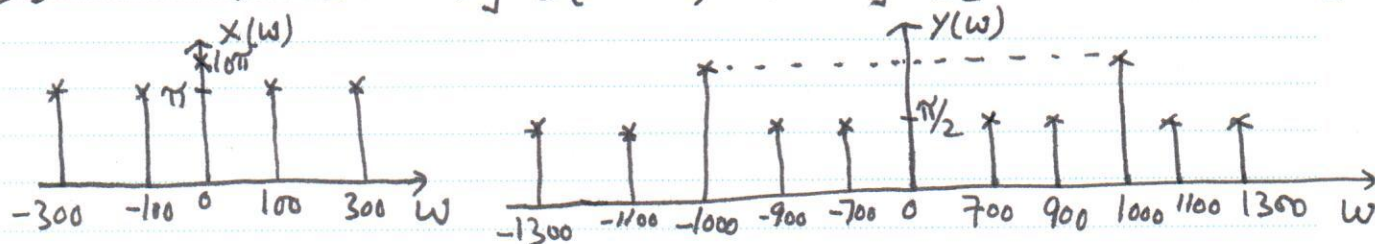
Solution:- $\cos 200t \cos 100t = \frac{1}{2} [\cos(200t+100t) + \cos(200t-100t)]$

$$x(t) = 5 + \cos 300t + \cos 100t$$

$$(a) \quad X(j\omega) = \mathcal{F}[x(t)] = (5)(2\pi\delta(\omega)) + \pi[\delta(\omega-100) + \delta(\omega+100)] + \pi[\delta(\omega-300) + \delta(\omega+300)]$$

$$(b) \quad y(t) = x(t)\cos(1000t), \mathcal{F}[y(t)] = Y(j\omega) = \frac{1}{2}[X(\omega-1000) + X(\omega+1000)]$$

$$Y(j\omega) = 5\pi[\delta(\omega-1000) + \delta(\omega+1000)] + \frac{\pi}{2}[\delta(\omega-1100) + \delta(\omega-900)] + \frac{\pi}{2}[\delta(\omega+1100) + \delta(\omega+900)] + \frac{\pi}{2}[\delta(\omega-700) + \delta(\omega-1300)] + \frac{\pi}{2}[\delta(\omega+700) + \delta(\omega+1300)]$$



Ex:- Let $f(t) = 10\cos t$, $g(t) = 2\delta(t+4)$, $y = f * g$, Calculate $Y(\omega)$.

Sol:- $f(t) * g(t) = \int_{-\infty}^{+\infty} 10\cos(t-\tau) \cdot 2\delta(\tau+4) d\tau = 20\cos(t-(-4))$

$$f * g = 20\cos(t+4), Y(\omega) = \mathcal{F}[y(t)] = \mathcal{F}[20\cos(t+4)]$$

$$Y(\omega) = 20[\pi\delta(\omega+1) + \pi\delta(\omega-1)] e^{4j\omega} \quad (i)$$

OR Convolution theorem:

$$F(j\omega) = \mathcal{F}[f(t)] = \mathcal{F}[10\cos t] = 10[\pi\delta(\omega-1) + \pi\delta(\omega+1)]$$

$$G(j\omega) = \mathcal{F}[g(t)] = \mathcal{F}[2\delta(t+4)] = 2e^{4j\omega}$$

$$Y(j\omega) = F(j\omega) \times G(j\omega) = 10[\pi\delta(\omega-1) + \pi\delta(\omega+1)] \cdot 2e^{4j\omega} \text{ same as (i).}$$

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Q. Determine & sketch the magnitude & phase spectra of the signal $x(t)$ given by:

$$x(t) = \frac{2 \sin(200\pi(t - 1/100))}{\pi(t - 1/100)} \cos(200\pi t).$$

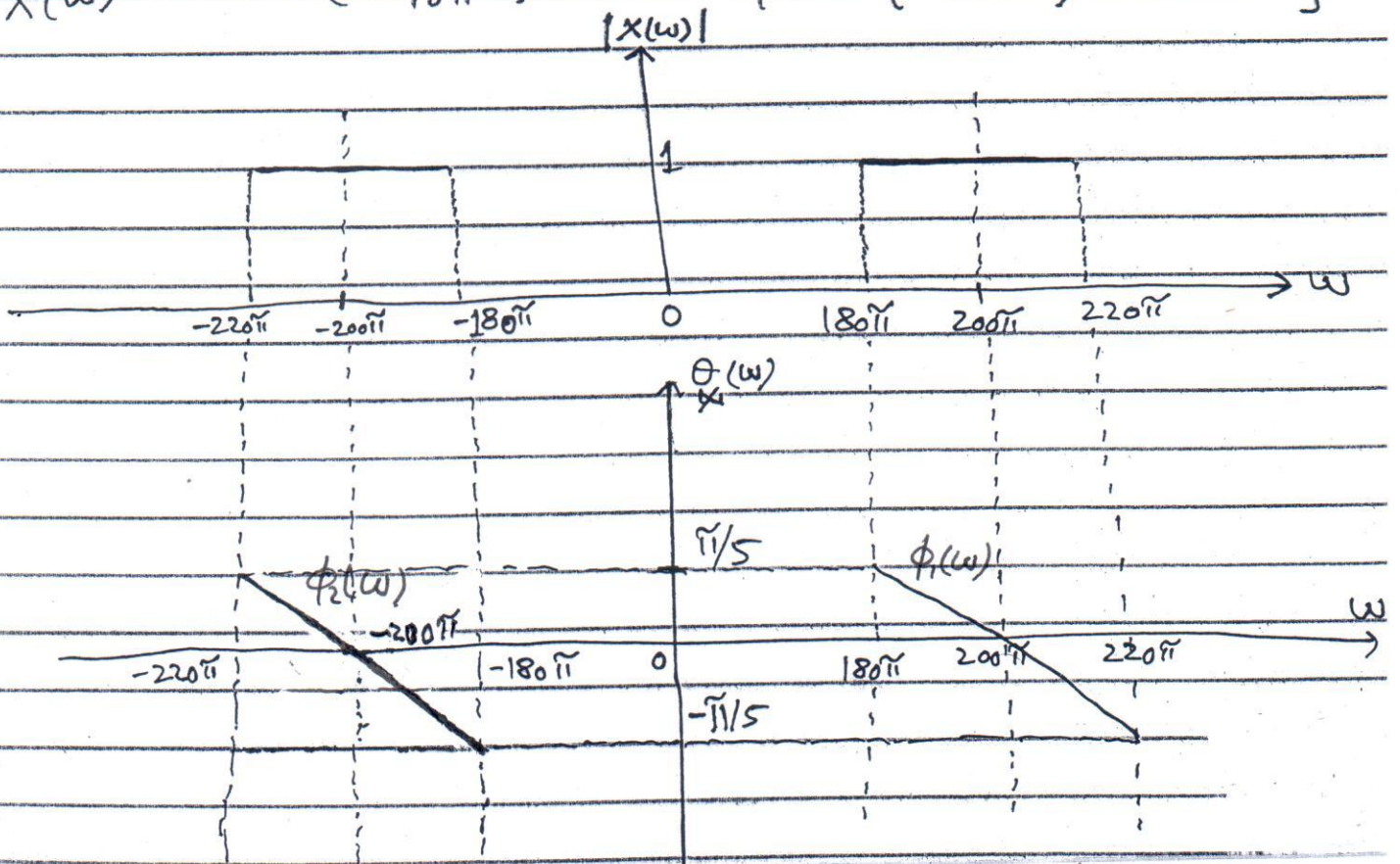
$$x(t) = x_1(t) \cos(200\pi t), \text{ where } x_1(t) = x_2(t - \frac{1}{100}).$$

$$\text{where } x_2(t) = \frac{2 \sin(200\pi t)}{200\pi t} \longleftrightarrow X_2(\omega) = 2 \text{rect}\left(\frac{\omega}{400\pi}\right)$$

$$\Rightarrow X_1(\omega) = X_2(\omega) e^{-j\omega(1/100)} = 2 \text{rect}\left(\frac{\omega}{400\pi}\right) e^{-j(\frac{\omega}{100})}.$$

$$x(t) = x_1(t) \cos(200\pi t) \longleftrightarrow X(\omega) = \frac{1}{2} [X(\omega - 200\pi) + X(\omega + 200\pi)]$$

$$X(\omega) = \text{rect}\left(\frac{\omega - 200\pi}{400\pi}\right) e^{-j(\frac{\omega - 200\pi}{100})} + \text{rect}\left(\frac{\omega + 200\pi}{400\pi}\right) e^{-j(\frac{\omega + 200\pi}{100})}.$$



$$\phi_1(\omega) = -\frac{\omega - 200\pi}{100}$$

$$\text{When } \omega = 180\pi, \phi_1 = -\frac{180\pi + 200\pi}{100} = -\frac{\pi}{5}$$

$$\text{When } \omega = 200\pi, \phi_1 = -\frac{200\pi + 200\pi}{100} = 0$$

$$\text{When } \omega = 220\pi, \phi_1 = -\frac{220\pi + 200\pi}{100} = \frac{\pi}{5}$$

$$\phi_2(\omega) = -\frac{(\omega + 200\pi)}{100}$$

$$\text{When } \omega = -180\pi, \phi_2 = -\frac{(-180\pi + 200\pi)}{100} = \frac{20\pi}{100} = \frac{\pi}{5}$$

$$\text{When } \omega = -200\pi, \phi_2 = -\frac{(-200\pi + 200\pi)}{100} = 0$$

$$\text{When } \omega = -220\pi, \phi_2 = -\frac{(-220\pi + 200\pi)}{100} = -\frac{\pi}{5}$$

NUST School of Electrical Engineering & Computer Science
Complex Variables and transforms-

Q-1.

Let $f(t) = \cos(2t-3)$, $g(t) = U(t)$, $U(t)$ be the unit-step function. Calculate $\mathcal{F}[f(t)g(t)]$ using convolution in the frequency domain.

Q-2.

For a function $f(t)$, $F(j\omega) = \left[\text{sinc}\left(\frac{\omega}{2}\right) \right]^2$, find $f(t)$. [Hint: Convolution].

Q-3.

Consider the signal $f(t) = \begin{cases} 3, & 0 \leq t < 2 \\ -5, & 2 \leq t < 4 \end{cases}$.

Express $f(t)$ using $\text{rect}(t)$ function, compute the Fourier transform of $f(t)$, using the properties and the rect function.

Q-4.

Use the integral definition of convolution to evaluate $y(t)$, where $y = x * h$ and $x(t) = e^{-(t-2)} U(t-2)$, $h(t) = \begin{cases} 1, & -1 \leq t < 3 \\ 0, & \text{otherwise} \end{cases}$.

Q-5.

Consider the functions $f(t) = \begin{cases} 1, & -2 \leq t < 0 \\ -2, & 0 \leq t < 3 \\ 0, & \text{otherwise} \end{cases}$, $g(t) = \begin{cases} 1, & -1 \leq t < 0 \\ 0, & \text{otherwise} \end{cases}$.

and $h(t) = (f * g)(t)$. Use integral & graphical approach to calculate $h(t)$. Find $H(j\omega)$.

Q-6.

Determine whether the following signals are energy signals, power signals, or neither.

(a) $x(t) = e^{-at} U(t)$, $a > 0$ (b) $x(t) = A \cos(\omega_0 t + \theta)$, (c) $x(t) = t U(t)$.

Solution manual

Q-1. $f(t) = \cos(2t-3)$, $g(t) = U(t)$. $F(j\omega) = \frac{1}{j\omega} e^{-\frac{3j}{2}} [\delta(\omega+2) + \delta(\omega-2)]$

$G(j\omega) = \frac{1}{j\omega} + \pi \delta(\omega)$.

$F[f(t)g(t)] = \frac{1}{2\pi} F(j\omega) * G(j\omega) = \frac{1}{2\pi} \frac{1}{j\omega} e^{-\frac{3j}{2}} [\delta(\omega+2) + \delta(\omega-2)] * (\frac{1}{j\omega} + \pi \delta(\omega))$

$= 0.5 e^{-\frac{3j}{2}} \delta(\omega+2) * \frac{1}{j\omega} + 0.5 \pi e^{-\frac{3j}{2}} \delta(\omega+2) * \delta(\omega)$

$+ 0.5 e^{-\frac{3j}{2}} \delta(\omega-2) * \frac{1}{j\omega} + 0.5 \pi e^{-\frac{3j}{2}} \delta(\omega-2) * \delta(\omega)$

$= 0.5 e^{-\frac{3j}{2}(-2)} \frac{1}{j(\omega+2)} + 0.5 \pi e^{-\frac{3j}{2}(-2)} \delta(\omega+2) + 0.5 e^{-\frac{3j}{2}(2)} \frac{1}{j(\omega-2)} + 0.5 \pi e^{-\frac{3j}{2}(2)} \delta(\omega-2)$

$= \frac{0.5 e^{3j}}{j(\omega+2)(\omega-2)} + \frac{0.5 \pi e^{3j}}{e^{3j}} \delta(\omega+2) + \frac{0.5 e^{-3j}}{j(\omega-2)} + 0.5 \pi e^{-3j} \delta(\omega-2)$

Thus,

$F[\cos(2t-3)U(t)] = \frac{j\omega \cos(3) + 2 \sin(3)}{4 - \omega^2} + 0.5 \pi [e^{3j} \delta(\omega+2) + e^{-3j} \delta(\omega-2)]$

Q-2 $F(j\omega) = [\text{sinc}(\frac{\omega}{2})]^2 \Rightarrow f(t) \leftrightarrow \text{sinc}(\frac{\omega}{2}) \text{sinc}(\frac{\omega}{2})$

We know that $\text{rect}(t) \leftrightarrow \text{sinc}(\frac{\omega}{2})$, $f(t) = \text{rect}(t) * \text{rect}(t)$

$f(t) = \int_{-\infty}^{+\infty} \text{rect}(t) \text{rect}(t-u) du = \int_{t-1/2}^{t+1/2} \text{rect}(u) du = \begin{cases} 0, & -\infty < t \leq -1 \\ t+1, & -1 < t \leq 0 \\ 1-t, & 0 < t \leq 1 \\ 0, & 1 < t < \infty \end{cases}$

Q-3 $f(t) = 3 \text{rect}(\frac{t-1}{2}) - 5 \text{rect}(\frac{t-3}{2})$

We know that $\text{rect}(t) \leftrightarrow \text{sinc}(\frac{\omega}{2})$. Using linearity, time shifting and scaling,

$F(j\omega) = 3 \left\{ 2 e^{-j\omega} \text{sinc}(\frac{\omega}{2}) \right\} - 5 \left\{ 2 e^{-j3\omega} \text{sinc}(\frac{\omega}{2}) \right\}$

$= 2 (3 e^{-j\omega} - 5 e^{-j3\omega}) \text{sinc}(\omega)$, $-\infty < \omega < +\infty$.

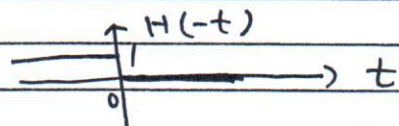
Q-4. $y(t) = (x * h)(t) = \int_{-\infty}^{+\infty} x(t-\tau)h(\tau)d\tau = \int_{-\infty}^{+\infty} e^{-(t-\tau-2)} u(t-\tau-2)h(\tau)d\tau$
 $= \int_{-\infty}^{t-2} e^{-(t-\tau-2)} h(\tau)d\tau$. Using the definition of h we have

If $t-2 < -1$, i.e., $t < 1$, then $h(\tau) = 0$, and so $y(t) = 0$.

If $-1 < t-2 < 3$, i.e., $1 < t < 5$, $y(t) = \int_{-1}^{t-2} e^{-(t-\tau-2)} d\tau = 1 - e^{1-t}$

If $t-2 > 3$, i.e., $t > 5$, $y(t) = \int_{-1}^3 e^{-(t-\tau-2)} d\tau = e^{t-2} [e^{-3} - e^{-1}]$

So, $y(t) = \begin{cases} 0, & t < 1 \\ 1 - e^{1-t}, & 1 < t < 5 \\ e^{t-2}(e^{-3} - e^{-1}), & t > 5 \end{cases}$



$h(-t) = \begin{cases} 0, & -t < 0 \\ 1, & -t \geq 0 \end{cases} = \begin{cases} 0, & t > 0 \\ 1, & t \leq 0 \end{cases}$

Q-6. (a). $E = \int_{-\infty}^{+\infty} [x(t)]^2 dt = \int_0^{\infty} e^{-2at} dt = \left[\frac{e^{-2at}}{-2a} \right]_0^{\infty} = -\frac{1}{2a} [0 - 1] = \frac{1}{2a}$ Energy signal

(b). $E = \int_{-\infty}^{+\infty} [x(t)]^2 dt$ is not finite. Power = $\lim_{T \rightarrow \infty} \left[\frac{1}{T} \int_{-T/2}^{T/2} A^2 \cos^2(\omega_0 t + \theta) dt \right]$
 $= \lim_{T \rightarrow \infty} \left[\frac{1}{T} A^2 \int_{-T/2}^{T/2} \left(\frac{1 + \cos 2(\omega_0 t + \theta)}{2} \right) dt \right] = \frac{A^2}{2} \lim_{T \rightarrow \infty} \left[t + \frac{\sin 2(\omega_0 t + \theta)}{2\omega_0} \right]_{-T/2}^{T/2}$
 $= \frac{A^2}{2} \lim_{T \rightarrow \infty} \left[\left(\frac{T}{2} + \frac{\sin 2(\omega_0 \frac{T}{2} + \theta)}{2\omega_0} \right) - \left(-\frac{T}{2} + \frac{\sin 2(\omega_0 \cdot -T/2 + \theta)}{2\omega_0} \right) \right]$
 $= \frac{A^2}{2} \lim_{T \rightarrow \infty} \frac{1}{T} (T/2 - (-T/2)) = A^2/2$, Power signal.

(c). $E = \int_0^{\infty} t^2 dt = \infty$, $P = \lim_{T \rightarrow \infty} \frac{1}{T} \int_0^{T/2} t^2 dt = \lim_{T \rightarrow \infty} \frac{1}{T} \left(\frac{t^3}{3} \right)_0^{T/2} = \infty$
 $x(t)$ is neither Energy nor Power signal.