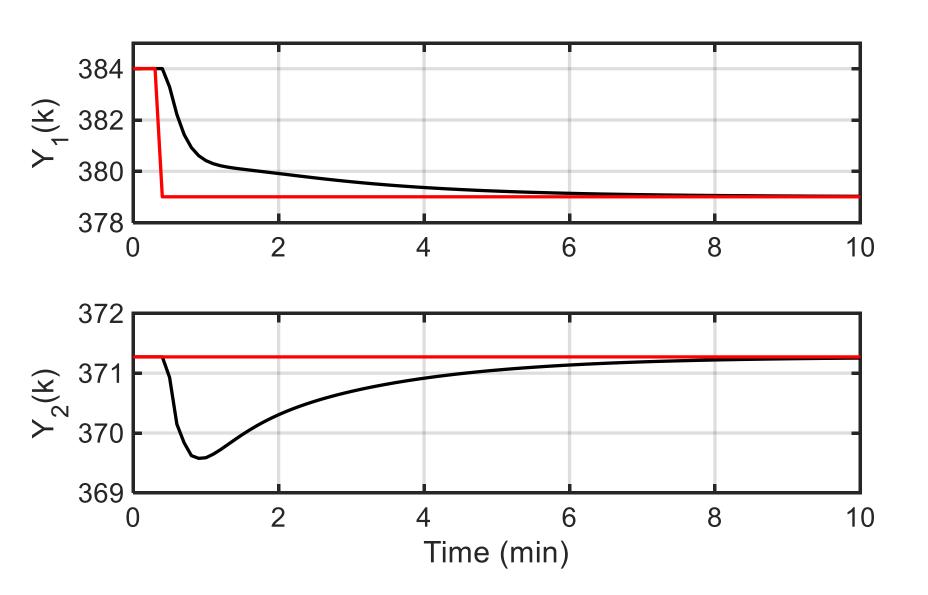
# Reactor System 1

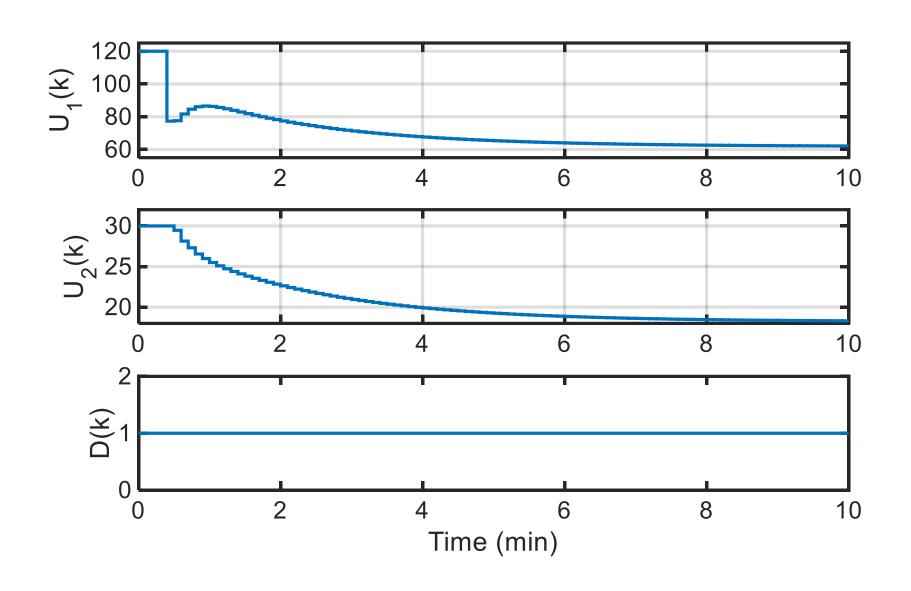
Servo and Regulatory Control using PID: Simulation Results

(with measurement noise and random input disturbance **set to zero**)

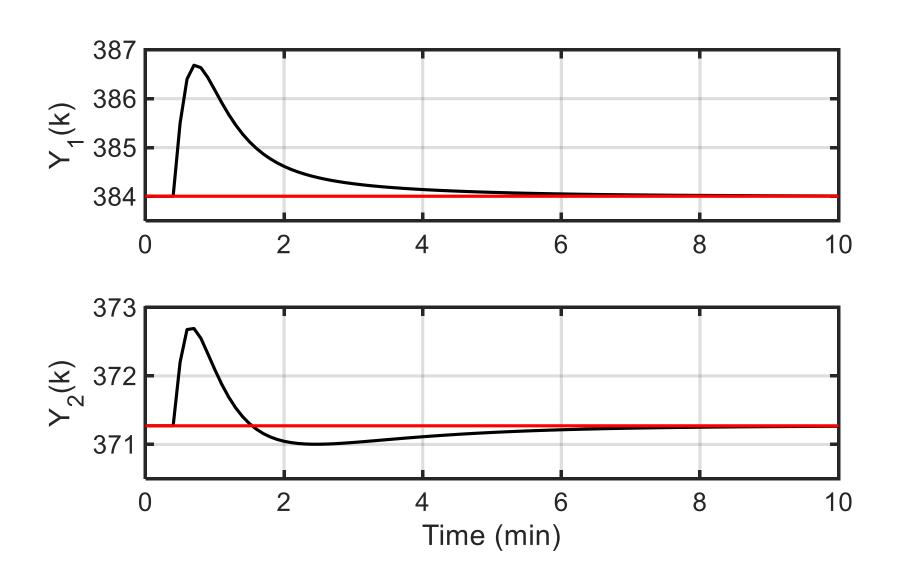
#### Servo Problem: Controlled Outputs



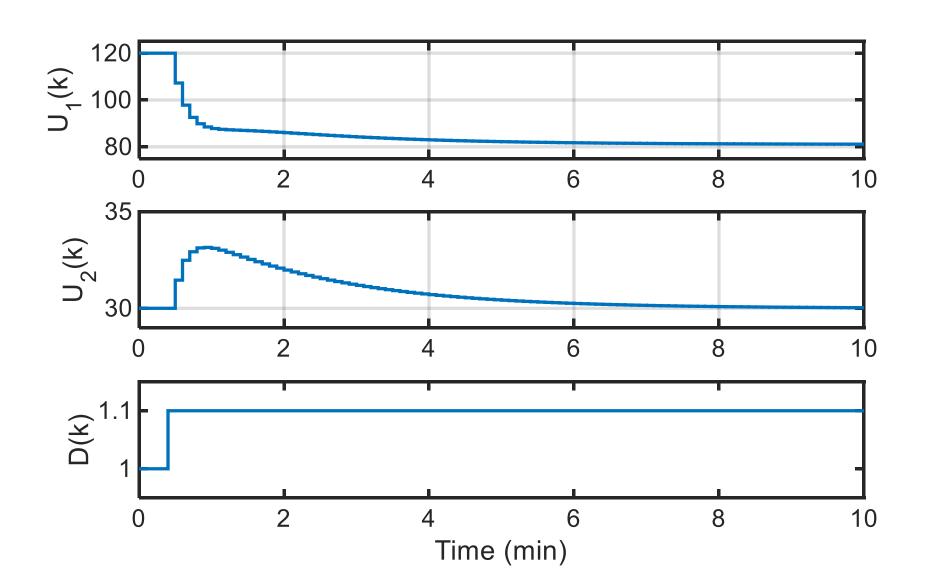
## Servo Problem: Input Trajectories



### Regulatory Problem: Controlled Outputs



## Regulatory Problem: Input Trajectories

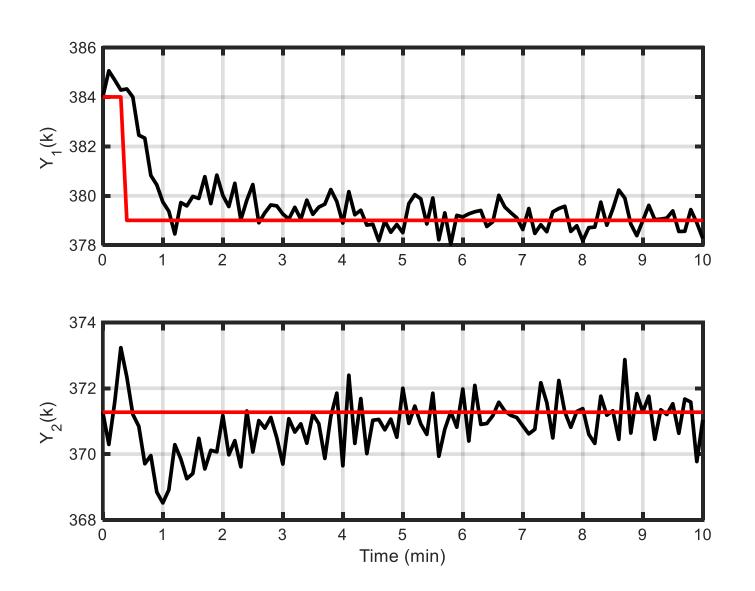


# Reactor System 1

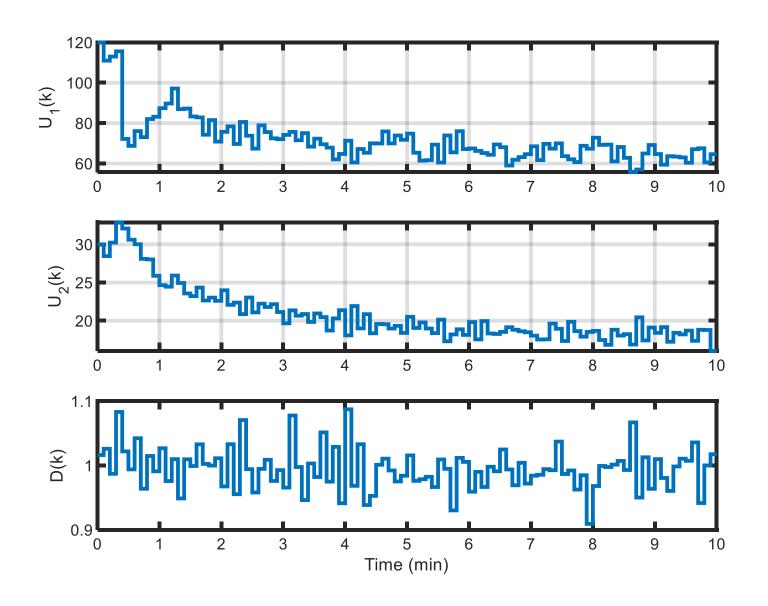
Servo and Regulatory Control using PID: Simulation Results

(with measurement noise and random input disturbance)

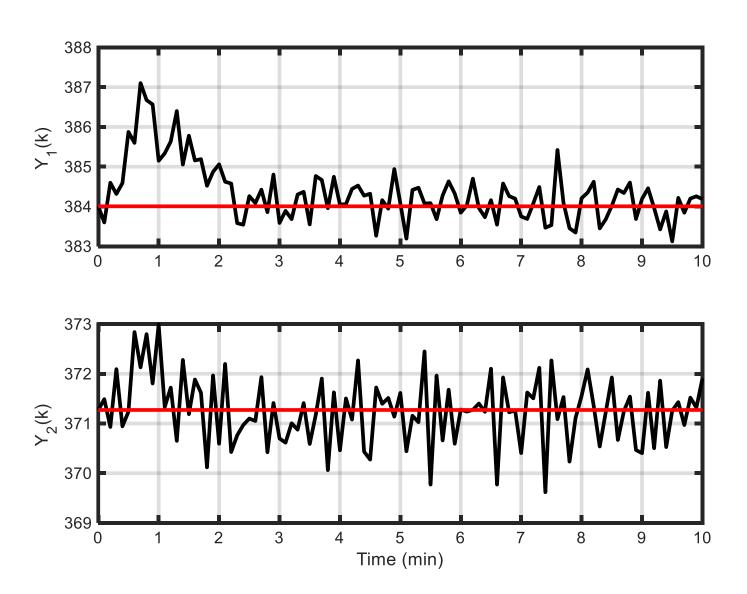
### Servo Problem: Controlled Outputs



### Servo Problem: Input Trajectories



### Regulatory Problem: Controlled Outputs



#### Regulatory Problem: Input Trajectories

