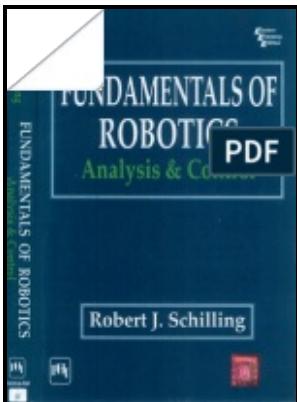


Mobile robots II - 5-6 November 1987, Cambridge, Massachusetts

The Society - Dual arm coordination and control



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