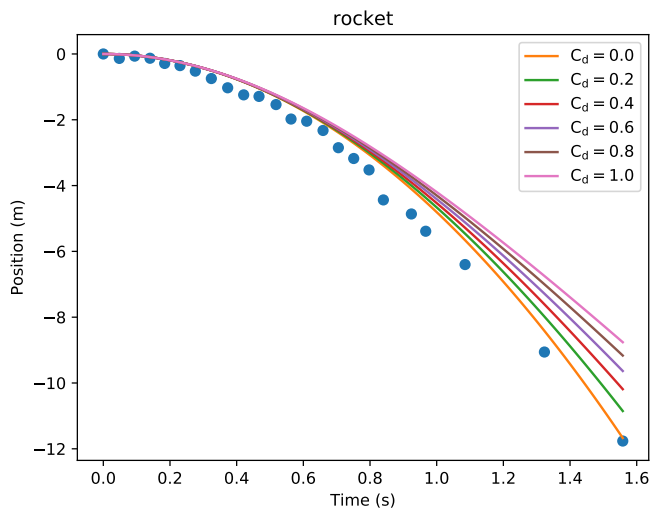
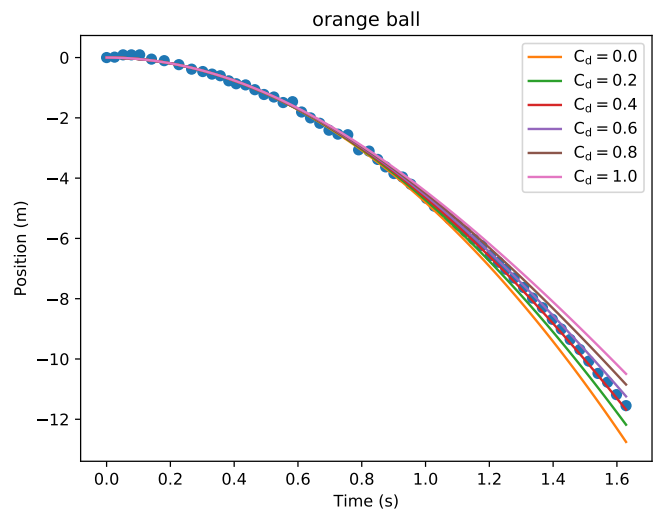
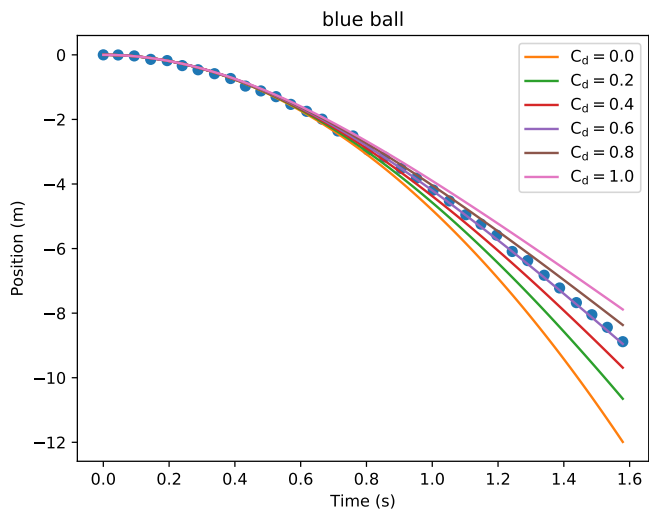
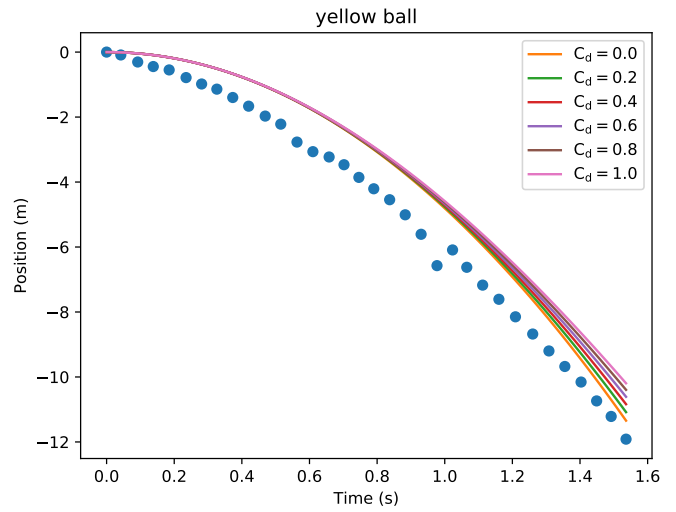
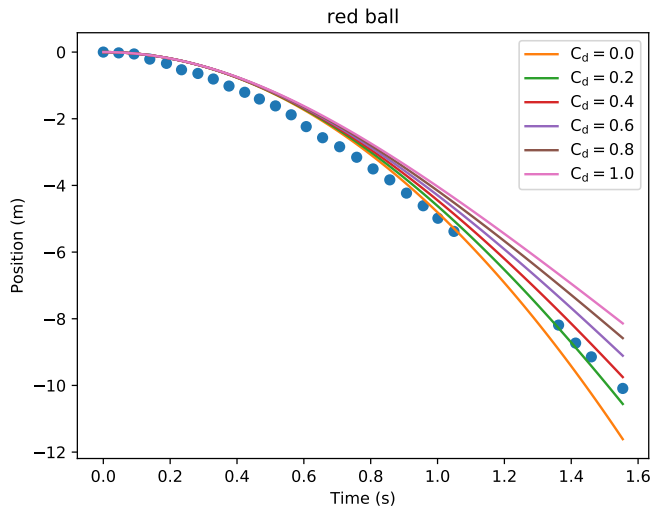
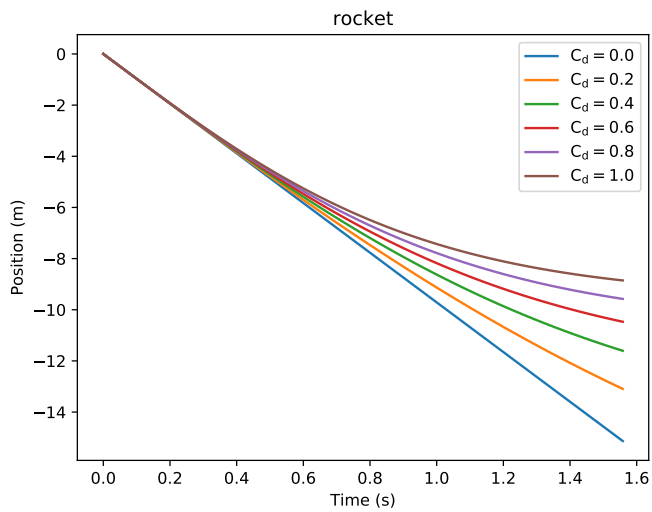
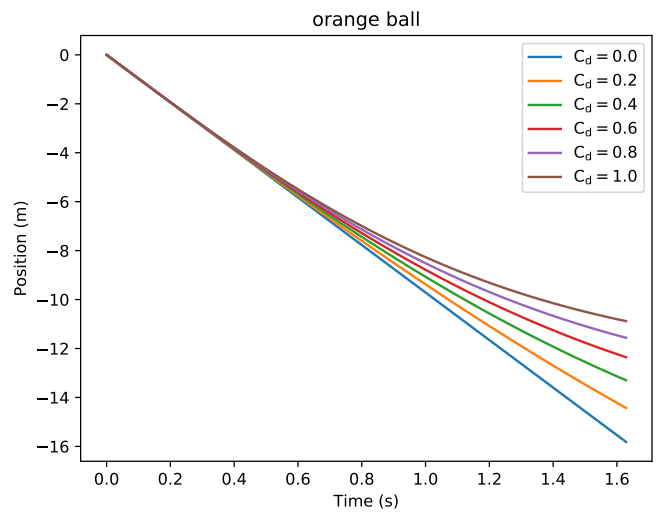
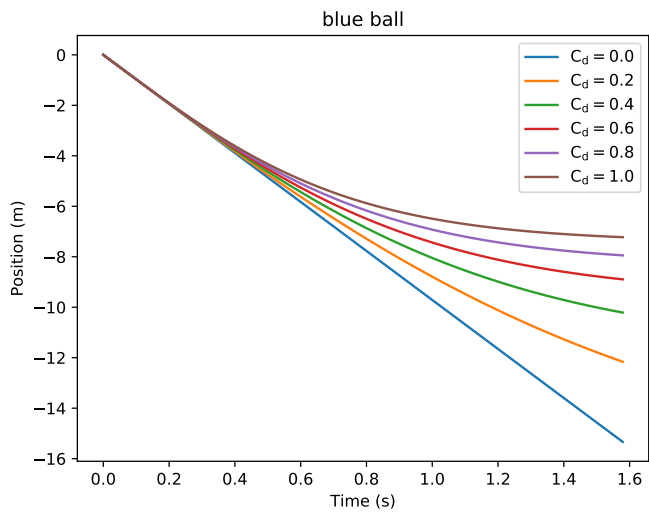
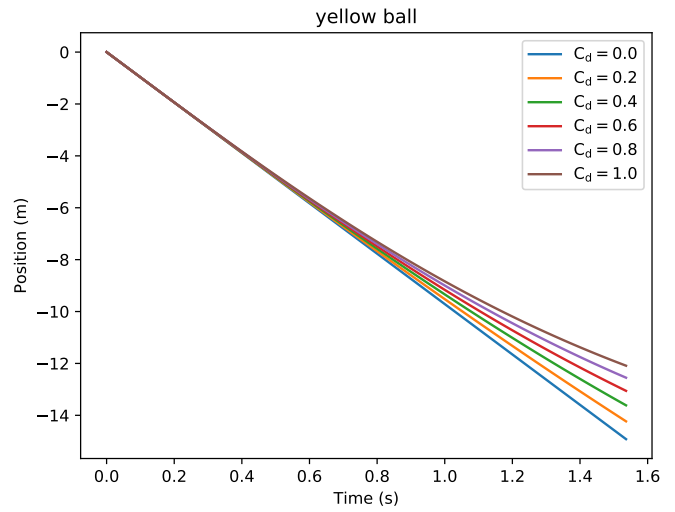
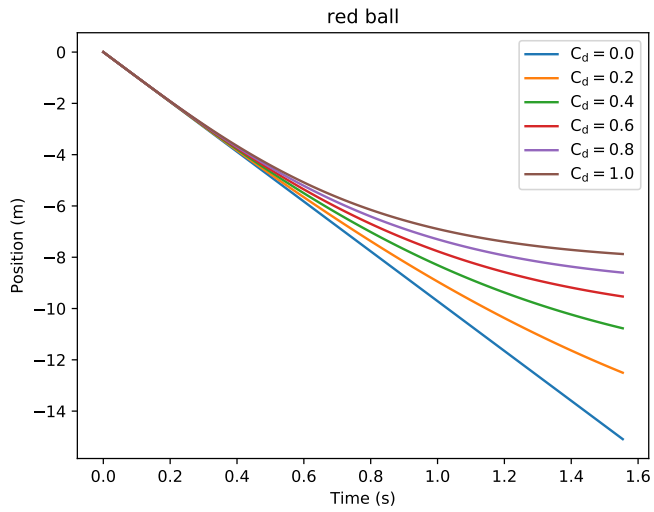


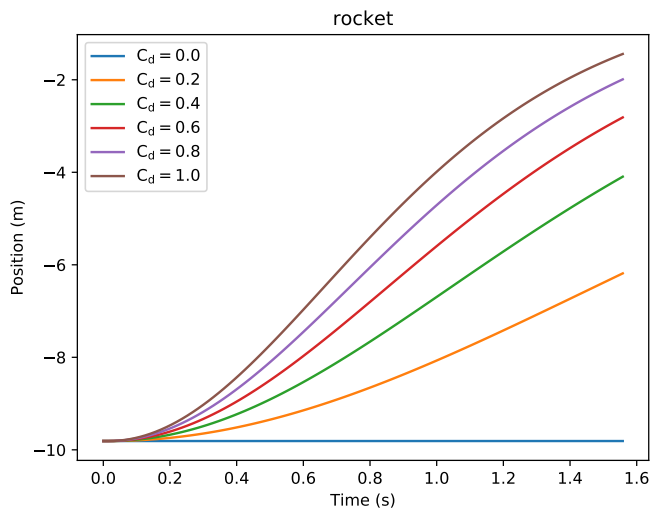
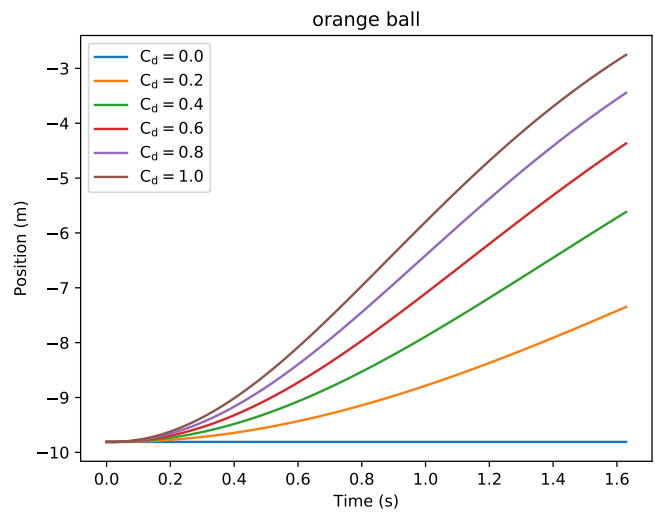
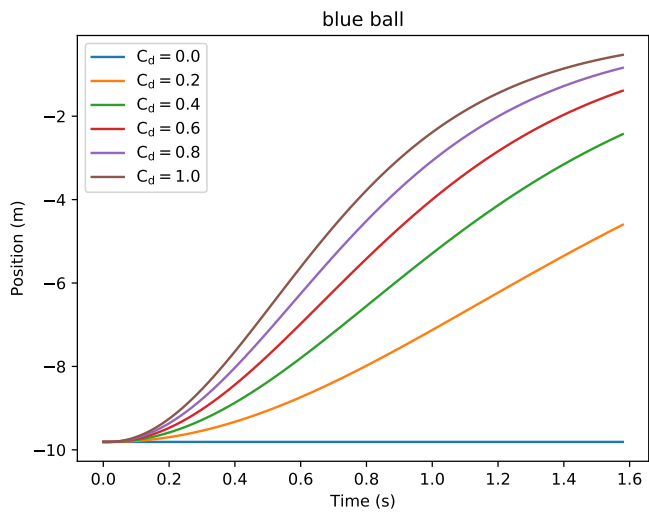
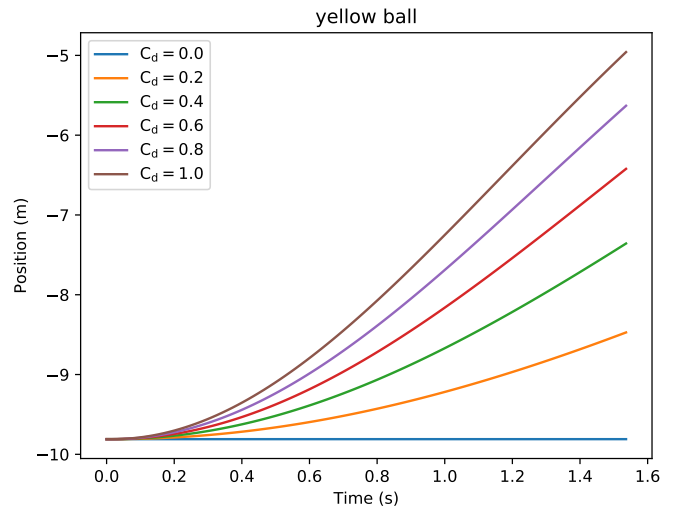
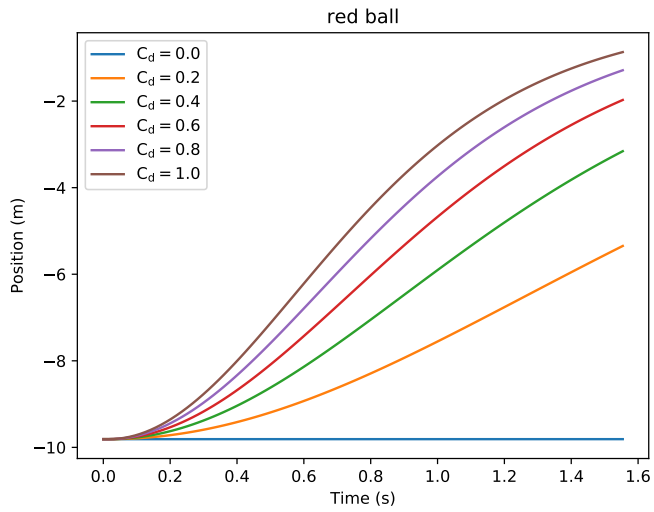
Modeled Position



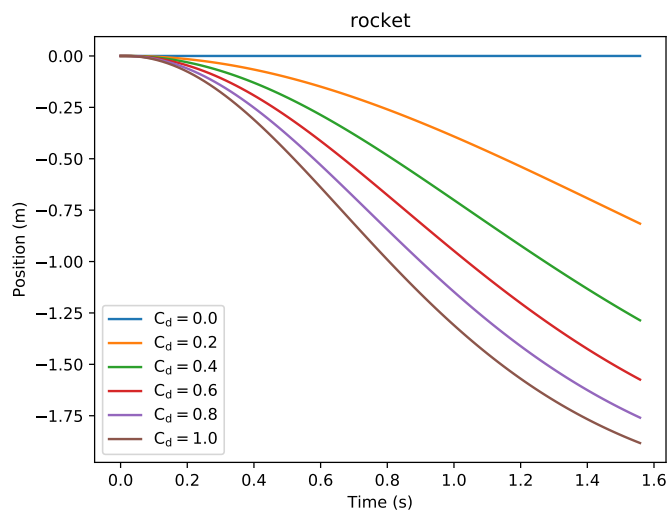
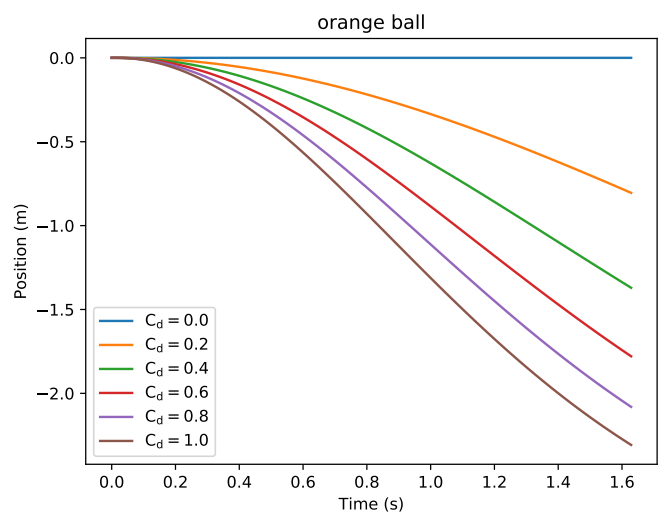
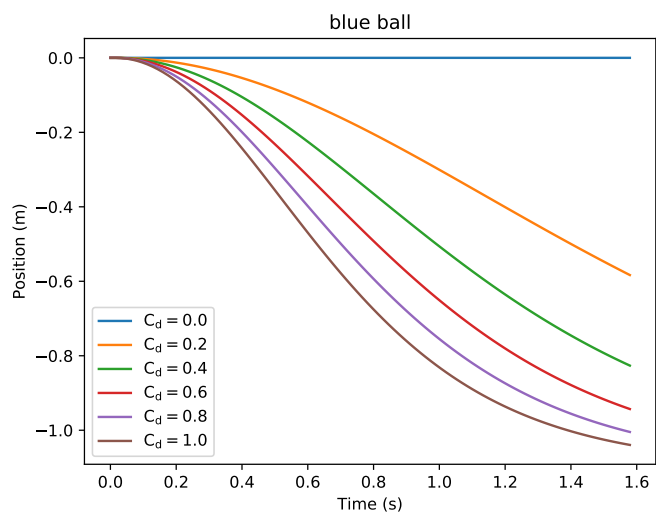
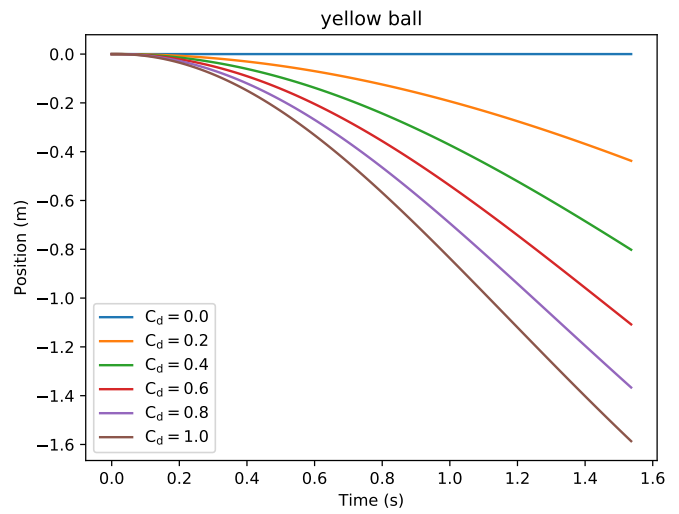
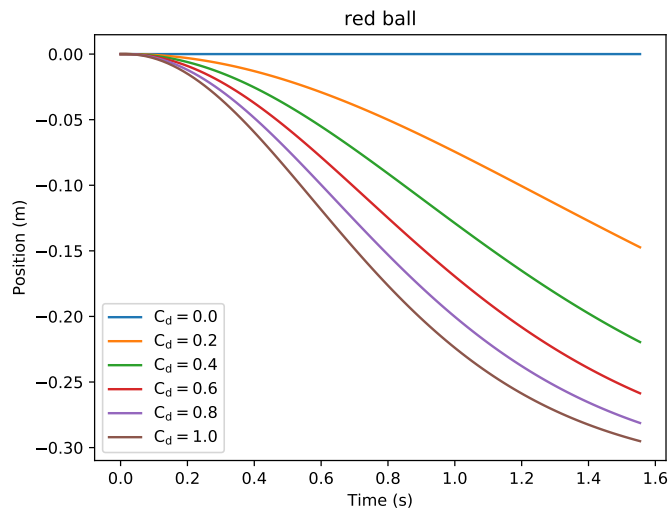
Modeled Velocity



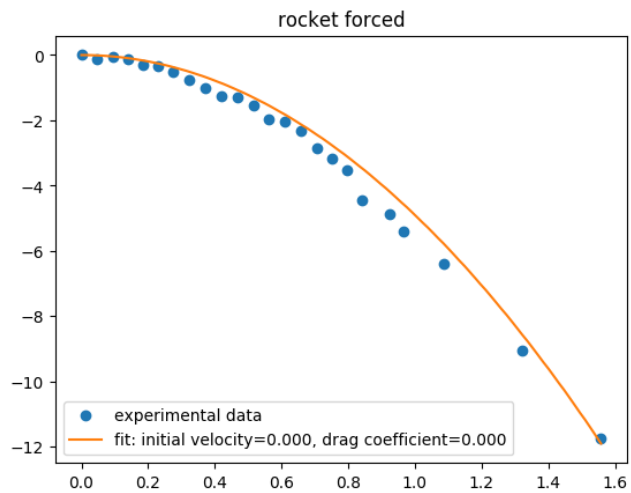
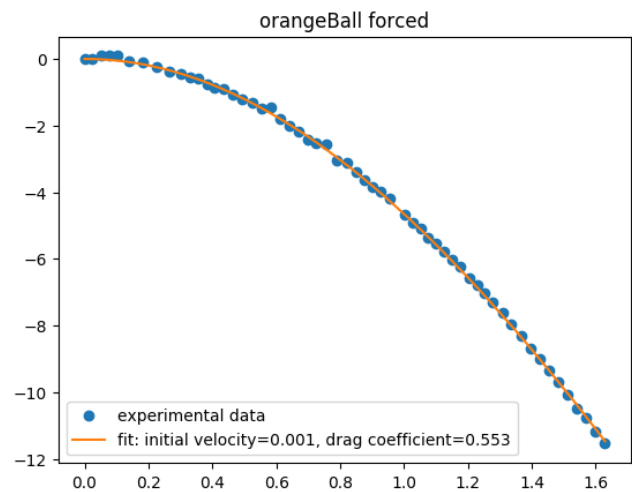
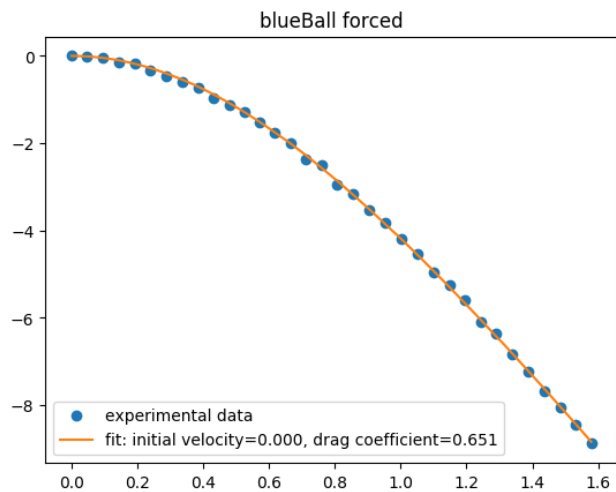
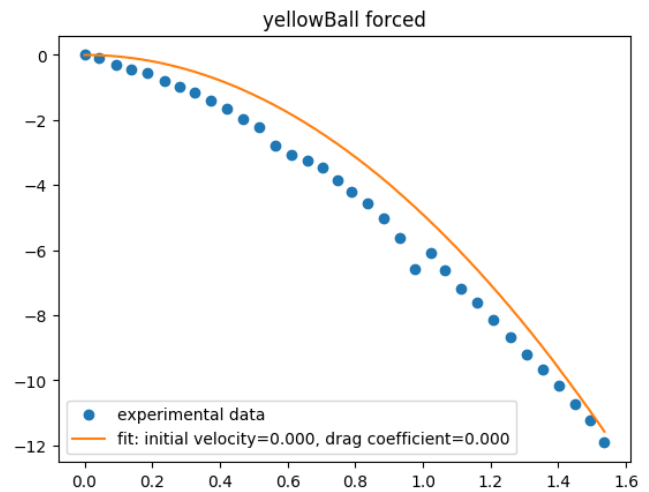
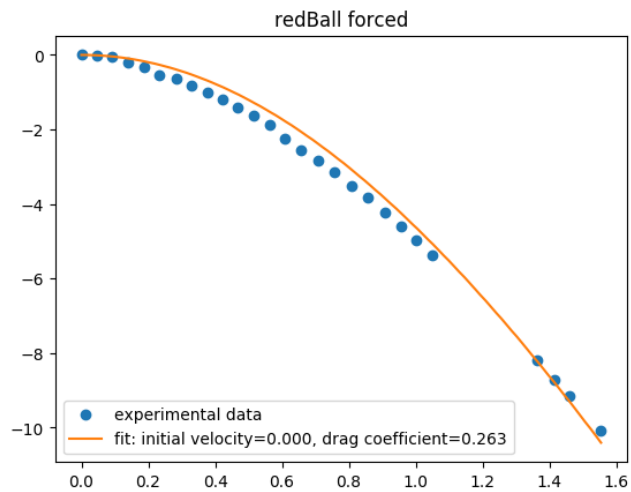
Modeled Acceleration



Modeled Drag Force



Fitting Routine Forced (Velocity Bounds: $[0, 0.001]$)



Fitting Routine Open

