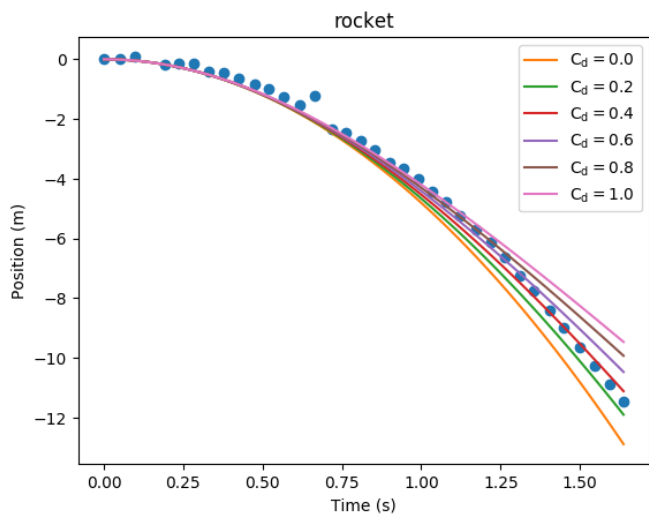
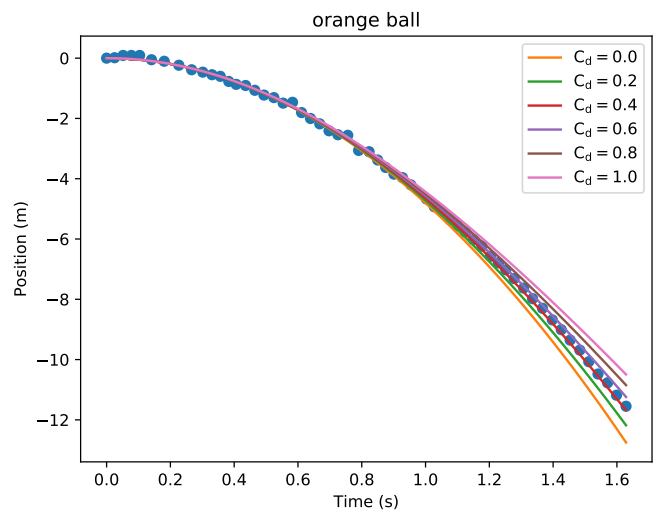
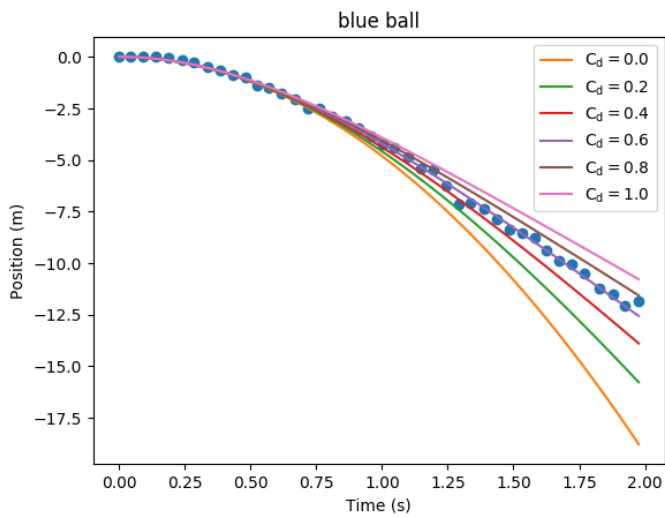
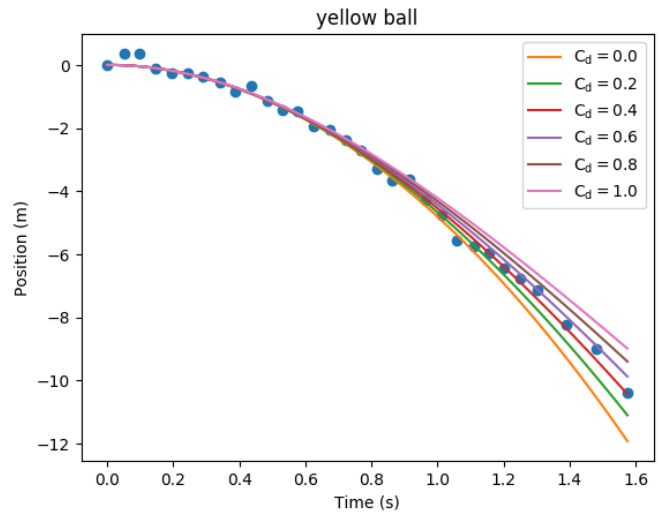
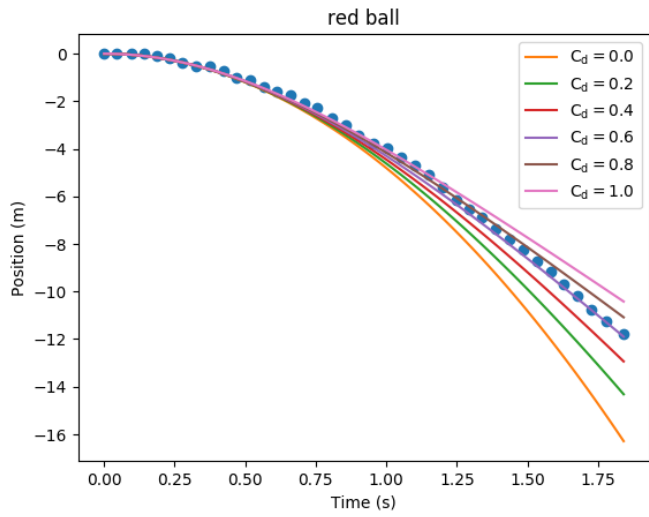
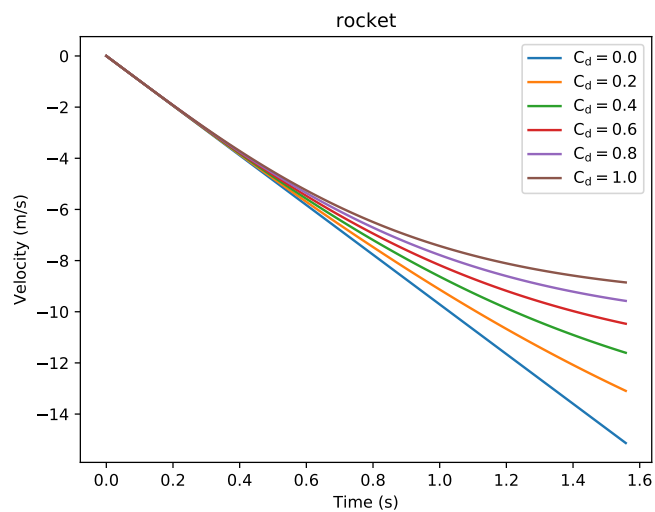
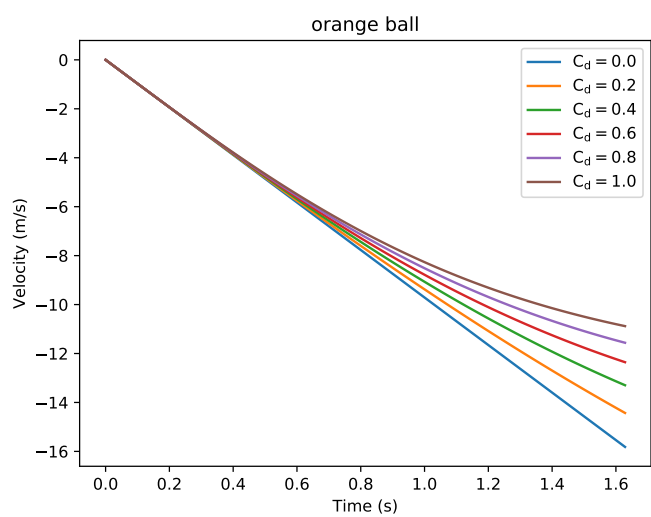
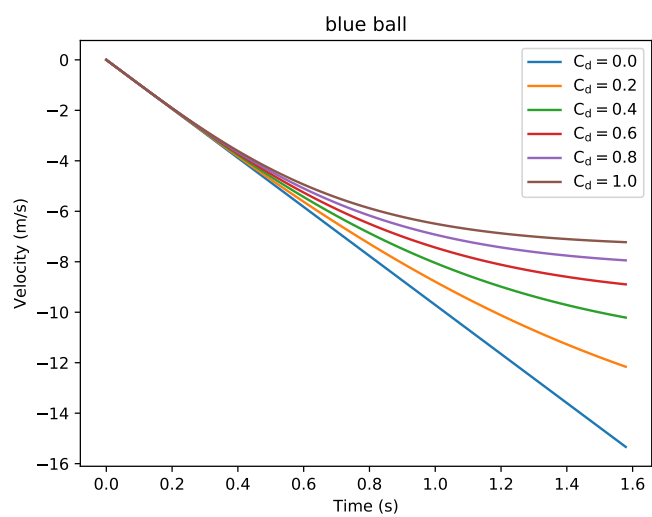
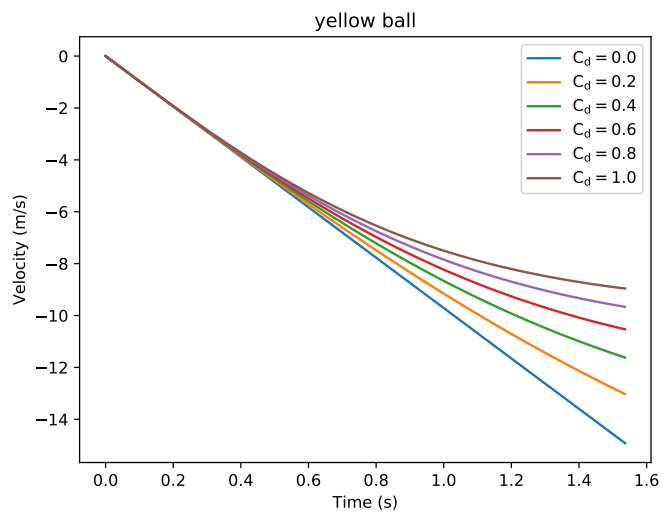
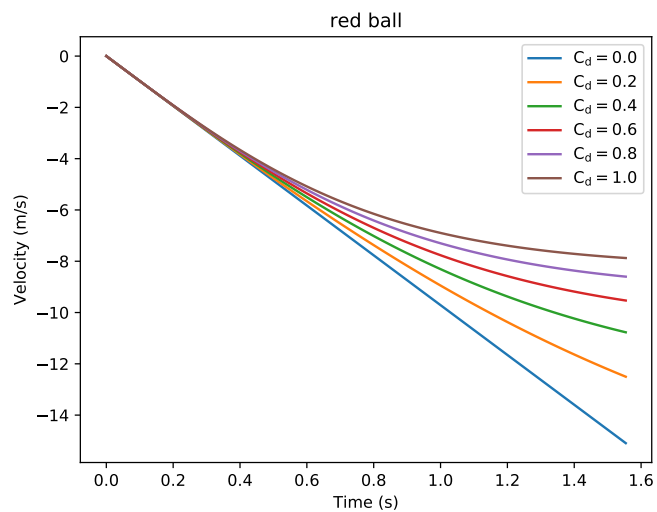


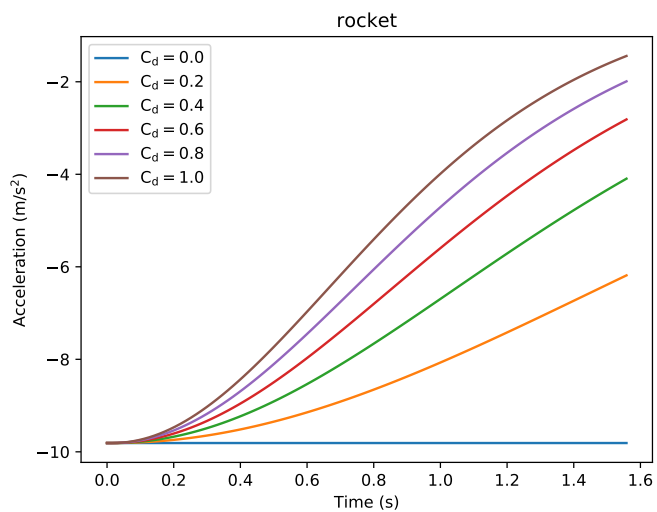
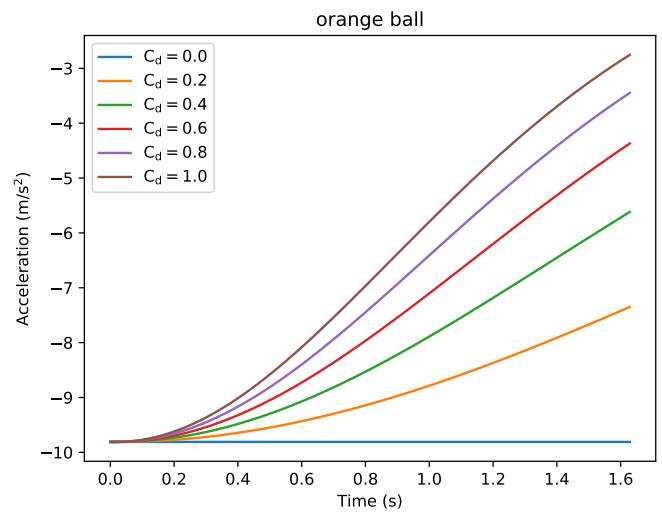
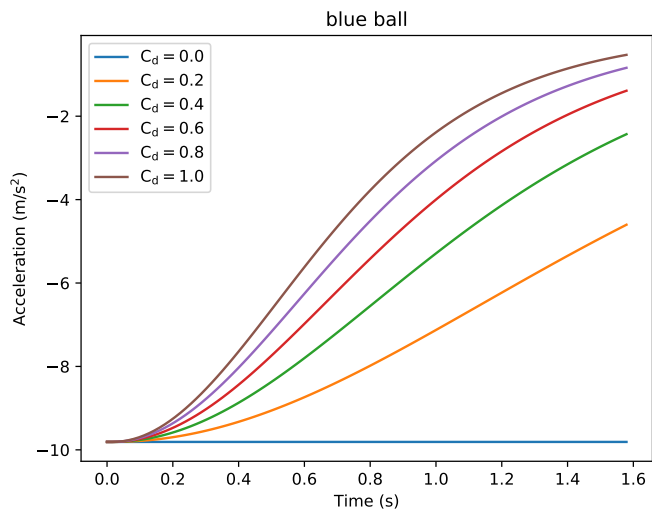
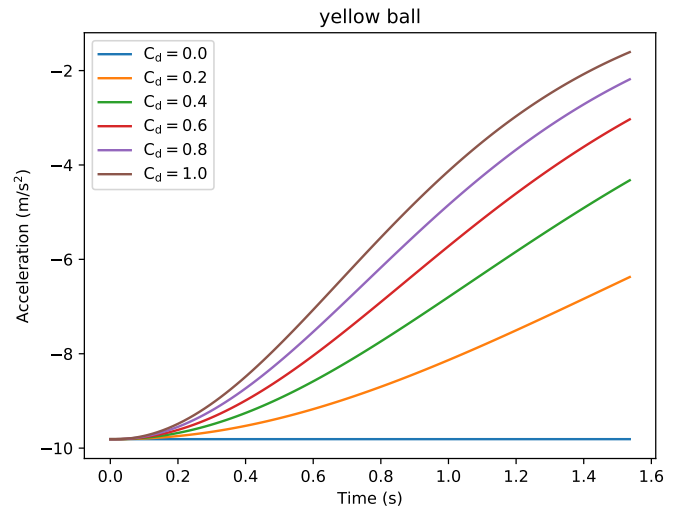
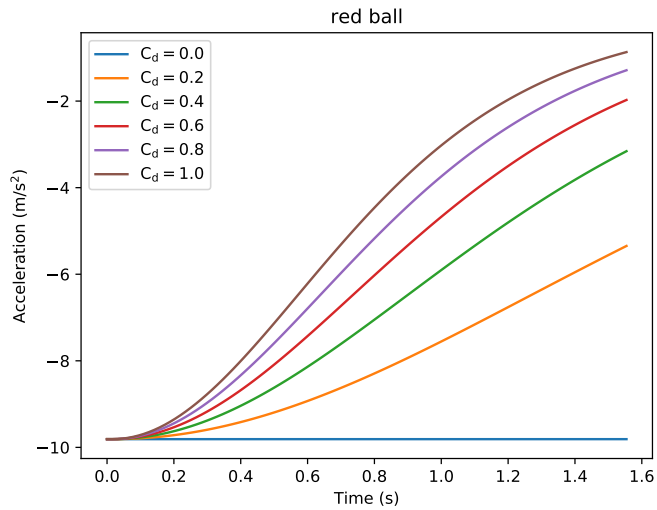
Modeled Position



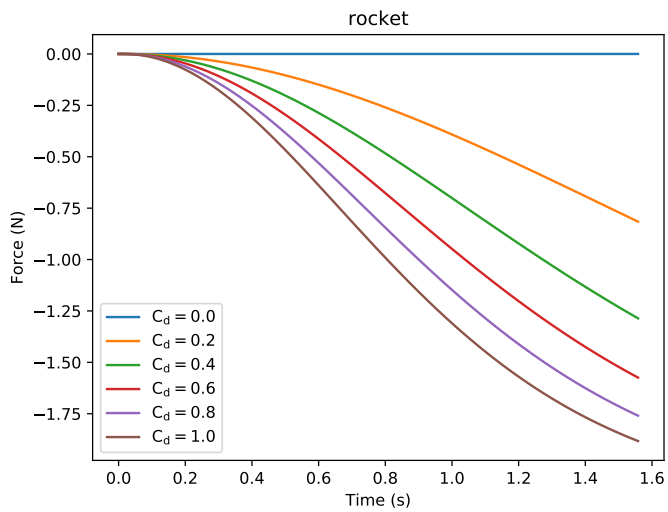
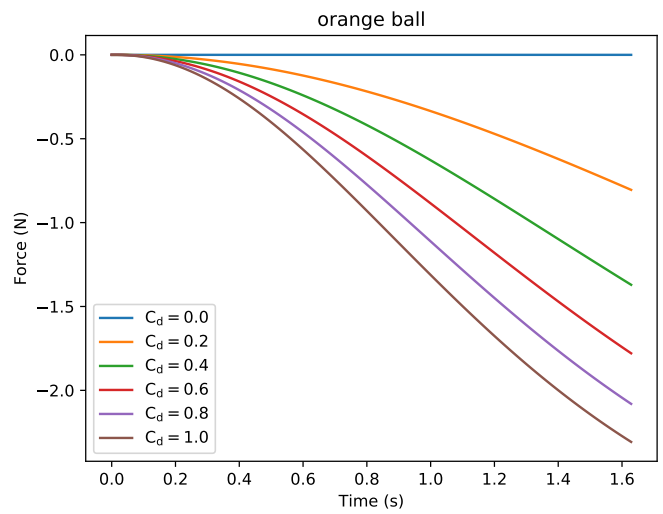
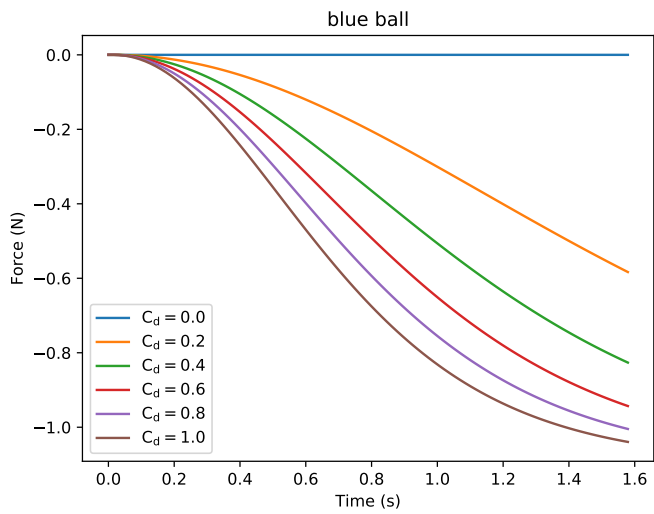
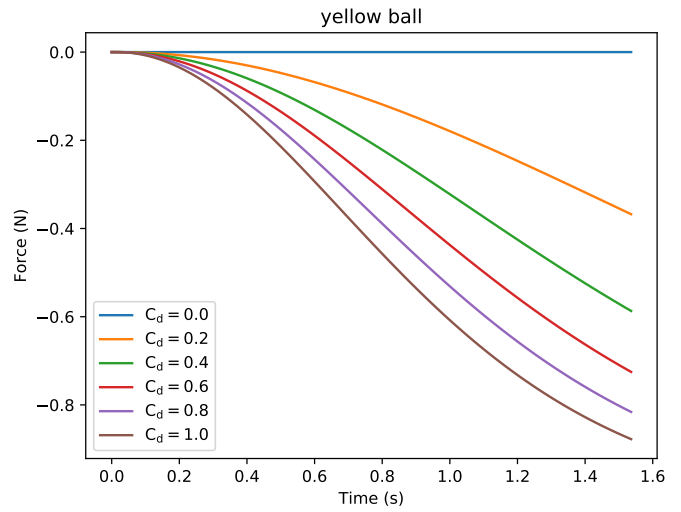
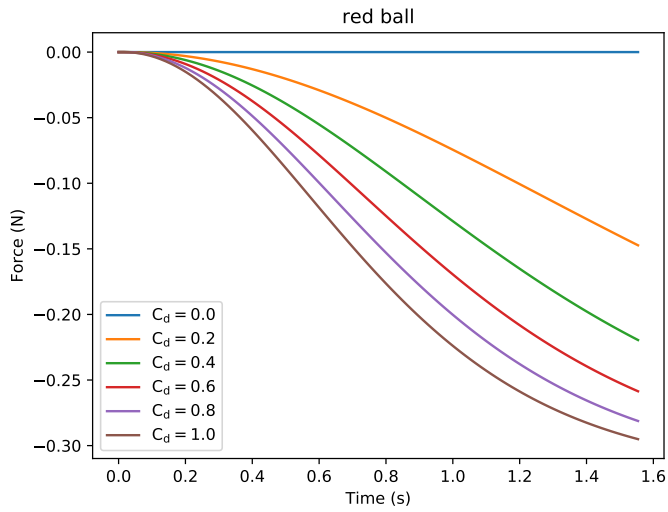
Modeled Velocity



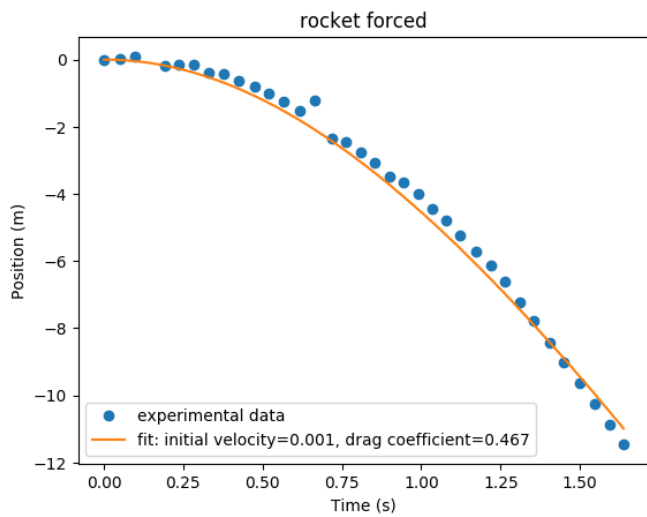
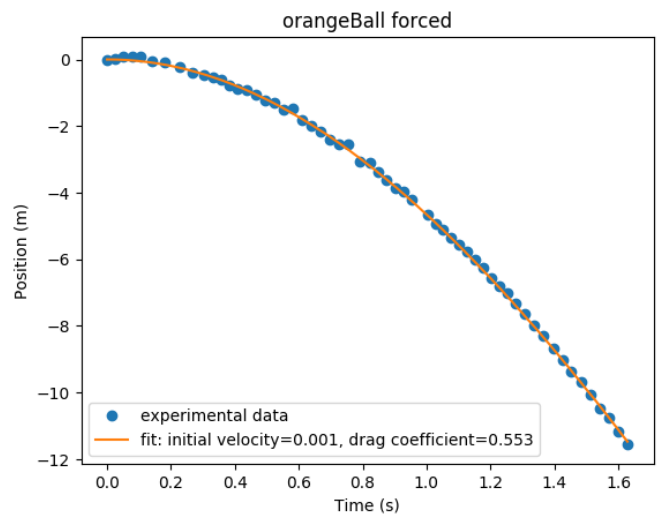
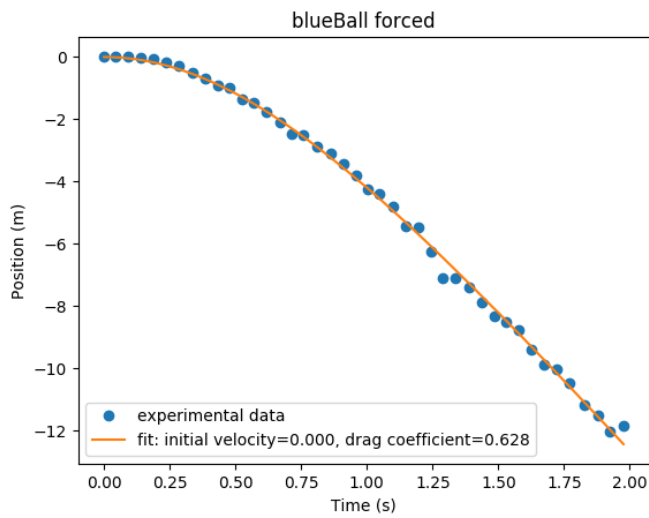
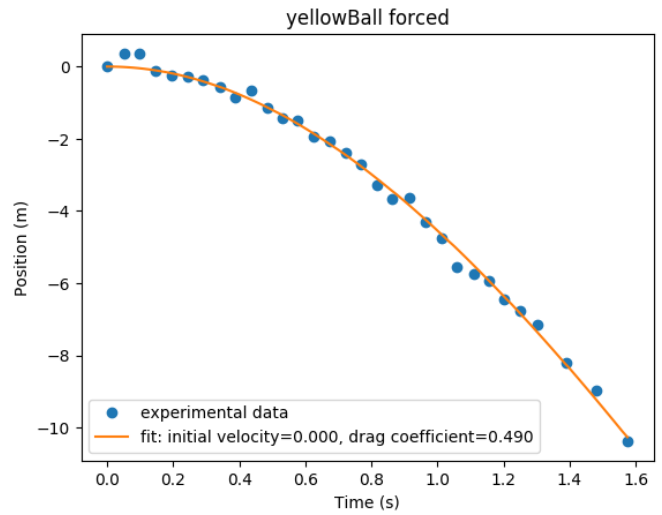
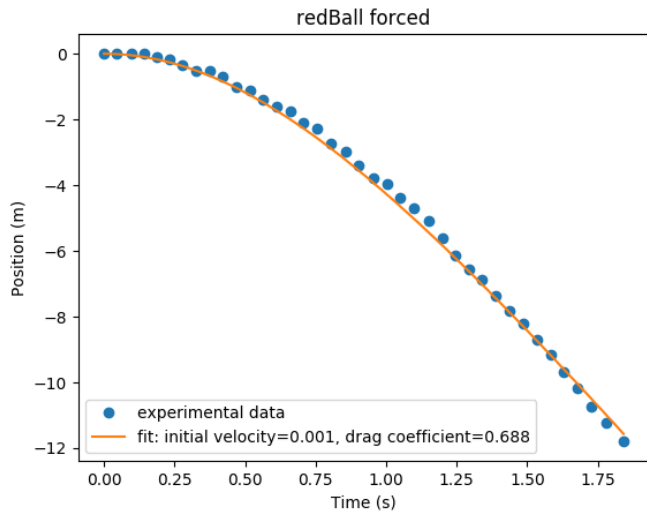
Modeled Acceleration



Modeled Drag Force



Fitting Routine Forced (Velocity Bounds: [0, 0.001])



Fitting Routine Open

