

(1)

$$\text{Q1. } \text{(a) } V = \left\{ \begin{bmatrix} x \\ x \end{bmatrix} \in \mathbb{R}^2 : x \in \mathbb{R} \right\}$$

Let $\begin{bmatrix} x_1 \\ x_1 \end{bmatrix}$ & $\begin{bmatrix} x_2 \\ x_2 \end{bmatrix}$ be elements of V .

$$\begin{bmatrix} x_1 \\ x_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ x_1 + x_2 \end{bmatrix} \text{ is in } V.$$

— closure

For $\begin{bmatrix} x_i \\ x_i \end{bmatrix} \in V, i=1,2,3,$

$$\left(\begin{bmatrix} x_1 \\ x_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ x_2 \end{bmatrix} \right) + \begin{bmatrix} x_3 \\ x_3 \end{bmatrix}$$

$$= \begin{bmatrix} x_1 + x_2 \\ x_1 + x_2 \end{bmatrix} + \begin{bmatrix} x_3 \\ x_3 \end{bmatrix}$$

$$= \begin{bmatrix} (x_1 + x_2) + x_3 \\ (x_1 + x_2) + x_3 \end{bmatrix}$$

$$= \begin{bmatrix} x_1 + (x_2 + x_3) \\ x_1 + (x_2 + x_3) \end{bmatrix} \quad (\text{Using associativity of real numbers})$$

$$= \begin{bmatrix} x_1 \\ x_1 \end{bmatrix} + \begin{pmatrix} \begin{bmatrix} x_2 + x_3 \\ x_2 + x_3 \end{bmatrix} \end{pmatrix}$$

$$= \begin{bmatrix} x_1 \\ x_1 \end{bmatrix} + \left(\begin{bmatrix} x_2 \\ x_2 \end{bmatrix} + \begin{bmatrix} x_3 \\ x_3 \end{bmatrix} \right) \quad \text{— Associativity}$$

$$\begin{bmatrix} x_1 \\ x_1 \end{bmatrix} + \begin{bmatrix} x_2 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 + x_2 \\ x_1 + x_2 \end{bmatrix} = \begin{bmatrix} x_2 + x_1 \\ x_2 + x_1 \end{bmatrix}$$

$$= \begin{bmatrix} x_2 \\ x_2 \end{bmatrix} + \begin{bmatrix} x_1 \\ x_1 \end{bmatrix}$$

— Commutativity

(2)

$$*\begin{bmatrix} 0 \\ 0 \end{bmatrix} \in V.$$

$$*\text{ For } \begin{bmatrix} x \\ x \end{bmatrix} \in V, \text{ we have } \begin{bmatrix} -x \\ -x \end{bmatrix} \text{ such that}$$

$$\begin{bmatrix} x \\ x \end{bmatrix} + \begin{bmatrix} -x \\ -x \end{bmatrix} = \begin{bmatrix} x-x \\ x-x \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

$$*\text{ For } \alpha \in \mathbb{R} \text{ & } \begin{bmatrix} x \\ x \end{bmatrix} \in V,$$

$$\alpha \begin{bmatrix} x \\ x \end{bmatrix} = \begin{bmatrix} \alpha x \\ \alpha x \end{bmatrix} \in V.$$

$$*\alpha \left(\begin{bmatrix} x \\ x \end{bmatrix} + \begin{bmatrix} y \\ y \end{bmatrix} \right) = \alpha \begin{bmatrix} x+y \\ x+y \end{bmatrix} = \begin{bmatrix} \alpha x + \alpha y \\ \alpha x + \alpha y \end{bmatrix}$$

$$= \begin{bmatrix} \alpha x \\ \alpha x \end{bmatrix} + \begin{bmatrix} \alpha y \\ \alpha y \end{bmatrix}.$$

$$*(\alpha + \beta) \begin{bmatrix} x \\ x \end{bmatrix} = \begin{bmatrix} (\alpha + \beta)x \\ (\alpha + \beta)x \end{bmatrix} = \begin{bmatrix} \alpha x + \beta x \\ \alpha x + \beta x \end{bmatrix}$$

$$= \begin{bmatrix} \alpha x \\ \alpha x \end{bmatrix} + \begin{bmatrix} \beta x \\ \beta x \end{bmatrix}$$

$$= \alpha \begin{bmatrix} x \\ x \end{bmatrix} + \beta \begin{bmatrix} x \\ x \end{bmatrix}.$$

$$*\alpha \beta \begin{bmatrix} x \\ x \end{bmatrix} = \begin{bmatrix} (\alpha \beta)x \\ (\alpha \beta)x \end{bmatrix} = \begin{bmatrix} \alpha(\beta x) \\ \alpha(\beta x) \end{bmatrix} = \alpha \begin{bmatrix} \beta x \\ \beta x \end{bmatrix} = \alpha \left(\beta \begin{bmatrix} x \\ x \end{bmatrix} \right)$$

$$*\begin{bmatrix} x \\ x \end{bmatrix} = \begin{bmatrix} 1 \cdot x \\ 1 \cdot x \end{bmatrix} = \begin{bmatrix} x \\ x \end{bmatrix}.$$

(3)

Q. 1 (b)

$$V = \left\{ \begin{bmatrix} z \\ \bar{z} \end{bmatrix} \in \mathbb{C}^2 : z \in \mathbb{C} \right\}.$$

Field of scalars = \mathbb{C} .

→ Exactly same as Q. 1 (a).

Q. 1 (c)

$$V = \left\{ \begin{bmatrix} x \\ y \end{bmatrix} \in \mathbb{R}^2 : x \geq y \right\}.$$

Note that the set V is closed w.r.t. usual addition. Commutativity & associativity also hold. $\begin{bmatrix} 0 \\ 0 \end{bmatrix} \in V$.

However, for $\begin{bmatrix} x \\ y \end{bmatrix} \in V$ the vector $\begin{bmatrix} -x \\ -y \end{bmatrix} \notin V$

as $x \geq y \Rightarrow -x \leq -y$.

Thus only the vectors of the type $\begin{bmatrix} x \\ x \end{bmatrix}$ have additive inverse.

Thus V is not a vector space.

(4)

Q.1 (d).

$$V = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : \begin{array}{l} a, b, c, d \in \mathbb{R} \\ a.d = 0 \end{array} \right\}.$$

Note that $ad = 0 \Rightarrow a=0$ or $d=0$.

Thus every element of V has atleast one diagonal entry to be zero.

Consider $A = \begin{bmatrix} 1 & b \\ c & 0 \end{bmatrix}$ & $B = \begin{bmatrix} 0 & b' \\ c' & 1 \end{bmatrix}$.

Then $A, B \in V$. But $A+B = \begin{bmatrix} 1 & b+b' \\ c+c' & 1 \end{bmatrix} \notin V$.

Thus V is not closed wrt usual addition.

$\therefore V$ is not a vector space.

Q.2

$$\text{IH} = \{a + bi + cj + dk : a, b, c, d \in \mathbb{R}\},$$

$i^2 = j^2 = k^2 = ijk = -1$

Remark:

Note this set is in one-to-one correspondence with $\mathbb{R}^4 = \{(a, b, c, d) : a, b, c, d \in \mathbb{R}\}$.

The relations $i^2 = j^2 = k^2 = ijk = -1$ do not play any role in the vector space structure of IH.

Check that IH satisfies all the axioms of a vector space.

The operations are defined as:

$$(a_1 + b_1 i + c_1 j + d_1 k) + (a_2 + b_2 i + c_2 j + d_2 k) \\ = (a_1 + a_2) + (b_1 + b_2)i + (c_1 + c_2)j + (d_1 + d_2)k.$$

For $\alpha \in \mathbb{R}$,

$$\alpha(a + bi + cj + dk) = (\alpha a) + (\alpha b)i + (\alpha c)j + (\alpha d)k$$

Q.3 (a)

$$V = M_{2,2}, \text{ & } W = \left\{ \begin{bmatrix} a & b \\ c & d \end{bmatrix} : ad \geq bc \right\}.$$

Consider

$$A = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \text{ & } B = \begin{bmatrix} 0 & 1 \\ 0 & 1 \end{bmatrix}$$

Note $A, B \in W$.

$$\text{But } A+B = \begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \notin W.$$

Thus W is not closed w.r.t. usual addition.

Q.3 (b) $V = M_{r,r}$. $W = \{A \in V : A \text{ is invertible}\}$.

Note 0 (zero matrix of V) is not invertible.

$\therefore W$ is not a subspace of V .

Q.3 (c) $V = F$, $W = \{f \in F : f(0) = 0\}$.

Let $f, g \in W \Rightarrow f(0) = 0$ & $g(0) = 0$

then $(f+g)(0) = f(0) + g(0) = 0 \Rightarrow f+g \in W$.

$(\alpha f)(0) = \alpha \cdot f(0) = \alpha \cdot 0 = 0 \Rightarrow \alpha f \in W$.

$\therefore W$ is a subsp. of V .

(7)

Q.3(d)

$$V = \mathbb{F}, \quad W = \{f \in \mathbb{F} : f(1) = 0\}.$$

SAME as Q.3(c).

Q.3(e)

$$V = \mathbb{F} \quad W = \{f \in \mathbb{F} : f(0) = 1\}.$$

$$f, g \in W \Rightarrow f(0) = 1, g(0) = 1$$

$$(f+g)(0) = f(0) + g(0) = 1 + 1 = 2$$

$$\Rightarrow f+g \notin W.$$

Thus W is not a subsp. of V .

Q.3(f). $V = \mathbb{F}$, $V = \{f \in V : f \text{ is cont.}\}$.

Use the fact that addition of continuous functions is continuous.

What about scalar multiplication?

Q.3(g)

SAME AS Q.3(f).

Q.3(h) $f \in W \Rightarrow \int_{-\infty}^{\infty} f < \infty.$

Use arithmetic of integrable function

Q.3(i) $V = \mathbb{C}$, $W = \mathbb{R}$.

Usual properties of real numbers!

Note that an element of W is written as $a+0i$, which is equal to the real number a .

Q. 4(a) To prove zero element of V is unique ⁽⁹⁾

Suppose 0 & $0'$ are two zero elements of V .

Then by the property of additive identity of a vector space, we have,

$$\begin{aligned} 0 + 0' &= 0' \\ \& 0 + 0' = 0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \Rightarrow 0 = 0'.$$

Q. 4(b)

Can you apply same arguments as above?

Q. 5 (a) $V = \beta_1$
 $S = \{x, 1+x\}$

$$\alpha \cdot x + \beta(1+x) = 0$$

$$\Rightarrow \beta + (\alpha+\beta)x = 0.$$

Comparing coefficients, we get

$$\beta = 0 \Rightarrow \alpha = 0$$

Thus S is linearly independent.

Q. 5 (b) $V = \beta_2$

$$S = \{x, 2x-x^2, 3x+2x^2\}$$

$$\alpha x + \beta(2x-x^2) + \gamma(3x+2x^2) = 0$$

$$\Rightarrow (\alpha+2\beta+3\gamma)x + (-\beta+2\gamma)x^2 = 0$$

$$\Rightarrow \alpha+2\beta+3\gamma = 0$$

$$-\beta+2\gamma = 0$$

Solve this system! (for α, β, γ).

What can you say about

What is the relation of soln of this system & linear independence of S ?

Q. 5 (c)

~~If~~ Note that

$$P_1 \subseteq P_2 \subseteq P_3 \subseteq \dots \subseteq P_n \subseteq \dots$$

Then if a

Que If $W \subseteq V$ is a vector subspace,
 & $S \subseteq W$ is linearly independent in W
 then what happens to the linear
 independence of S when treated as
 a subset of V . ?

Q. 5 (d)

$$V = \mathbb{F} \quad S = \{1, \sin x, \cos x\}$$

$$\alpha \cdot 1(x) + \beta \sin x + \gamma \cos x = 0(x)$$

$$\therefore \alpha + \beta \sin x + \gamma \cos x = 0 \quad \forall x \in \mathbb{R}$$

Now As this holds for
 all real numbers x ,

take $x=0$ special values

of x & get relations between α, β, γ .

Then solve this system !

Note here $1 \in \mathbb{F}$
 means $1(x) = 1 \forall x$
 & $0 \in \mathbb{F}$ means
 $0(x) = 0 \forall x \in \mathbb{R}$.

Q.5(e) $V = F$, $S = \{\sin x, \sin 2x, \sin 3x\}$. (12)

Express $\sin 2x$ & $\sin 3x$ in terms of $\sin x$.

Now is the question similar to
Q. 5(d)?

Q. 6 ~~Prove~~

To prove: B is a basis for V .

It is already given that every vector of V can be written as a linear combination of elements of B .

$$\therefore \text{span}(B) = V.$$

To check/prove: B is linearly independent.

$$\text{Let } B = \{v_1, \dots, v_n\}.$$

$$\text{Suppose } a_1v_1 + \dots + a_nv_n = 0.$$

But $0 \in V$ & the property that such a linear combination has to be unique.

$$\Rightarrow a_i = 0 \quad \forall i$$

$\Rightarrow \{v_1, \dots, v_n\}$ is linearly independent.

$\therefore B$ is a basis.

7. (a) let $p(x) = a + bx + cx^2$ s.t. $p(1) = 0$

$$\therefore a + b + c = 0 \Rightarrow c = - (a + b)$$

$$\therefore p(x) = a + bx - (a + b)x^2 \\ = a(1 - x^2) + b(x - x^2)$$

Clearly, $1 - x^2$ and $x - x^2$ span

$$\{p(x) \mid p(1) = 0\}$$

Also, $c_1(1 - x^2) + c_2(x - x^2) = 0$

$$\Rightarrow c_1 + c_2 x - (c_1 + c_2)x^2 = 0$$

$$\therefore c_1 = c_2 = 0$$

$\therefore \{1 - x^2, x - x^2\}$ is a basis.

(b) let $U = \left\{ \begin{bmatrix} a & b \\ 0 & c \end{bmatrix} \mid a, b, c \in \mathbb{R} \right\}$

Clearly, $\begin{bmatrix} a & b \\ 0 & c \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}$

and $c_1 \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + c_2 \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c_3 \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$

$$\therefore c_1 = c_2 = c_3 = 0$$

$\therefore \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$ spans U and is linearly independent.

\therefore it is a basis.

$$7. \text{ Consider } D = \left\{ \begin{bmatrix} a & b & c \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} \mid a, b, c \in \mathbb{R} \right\}$$

Clearly,

$$\begin{bmatrix} a & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & c \end{bmatrix} = a \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

and $c_1 D_1 + c_2 D_2 + c_3 D_3 = 0$

$$\Rightarrow c_1 = c_2 = c_3 = 0 \quad (\text{by } \text{lin. ind.})$$

$\therefore \{D_1, D_2, D_3\}$ is a basis.

Consider

$$(1) \quad z = a + ib \in \mathbb{C}.$$

Then $z = a \cdot 1 + b \cdot i$ $(i = \sqrt{-1})$

ie, $\{1, i\}$ spans \mathbb{C} over \mathbb{R} .

Also, $c_1 \cdot 1 + c_2 i = 0 \quad (c_1, c_2 \in \mathbb{R})$

$$\Rightarrow c_1 = 0, c_2 = 0 \quad (\text{by equating real and imaginary parts})$$

$\therefore \{1, i\}$ is lin. ind.

$\therefore \{1, i\}$ is a basis of \mathbb{C} over \mathbb{R} .

$$\begin{aligned}
 8. \quad (a) \quad & T \left(2 \begin{bmatrix} a & b \\ c & d \end{bmatrix} + \begin{bmatrix} a & b \\ c & d \end{bmatrix} \right) \\
 &= T \left(\begin{bmatrix} 2a+a & 2b+b \\ 2c+c & 2d+d \end{bmatrix} \right) \\
 &= \begin{bmatrix} 2a+a+2b+b & 0 \\ 0 & 2c+c+2d+d \end{bmatrix} \\
 &= 2 \begin{bmatrix} a+b & 0 \\ 0 & c+d \end{bmatrix} + \begin{bmatrix} a+b & 0 \\ 0 & c+d \end{bmatrix} \\
 &= 2 T \begin{bmatrix} a & b \\ c & d \end{bmatrix} + T \begin{bmatrix} a & b \\ c & d \end{bmatrix}
 \end{aligned}$$

$\therefore T$ is a lin trans.

$$\begin{aligned}
 (b) \quad & T \left(2 \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \right) = T \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} = 2^1 + 2 T \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} \\
 & \therefore T \text{ is not a L.T.}
 \end{aligned}$$

$$(c) \quad T \left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right) = T \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = 1$$

$$\text{But } T \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = \cancel{T} \left(\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = 0 + 0 = 0$$

$\therefore T$ is not a lin trans.

$$\begin{aligned}
 (d) \quad & T(A_1 + A_2) = (A_1 + A_2)B = A_1 B + A_2 B \\
 &= 2 T(A_1) + T(A_2) \\
 &\therefore T \text{ is a L.T.}
 \end{aligned}$$

$$\begin{aligned}
 (e) \quad & T(2A) = 2A + B \neq 2(A + B) = 2T(A) \\
 & \text{unless } B = 0.
 \end{aligned}$$

If $B = 0$, $T(A) = A$ is a L.T.

$$(f) \quad T(x) = 1+x+x^2 \neq 0 \quad \therefore T \text{ is not a L.T.}$$

$$9. \quad T(1+x) + T(x+x^2) + T(1+x^2) = 1+x^2 + x - x^2 + 1+x+x^2$$

$$\Rightarrow T(2+2x+2x^2) = 2+2x+x^2$$

$$\Rightarrow T(1+x+x^2) = 1+x+\frac{x^2}{2}$$

$$\begin{aligned} \therefore T(1) &= T(1+x+x^2 - (x+x^2)) \\ &= 1+x+\frac{x^2}{2} - (x+x^2) \\ &= 1+\frac{3x^2}{2} \end{aligned}$$

$$\begin{aligned} T(x) &= T(1+x+x^2 - (1+x^2)) \\ &= 1+x+\frac{x^2}{2} - (1+x+x^2) \\ &= -\frac{x^2}{2} \end{aligned}$$

$$\begin{aligned} T(x^2) &= T(1+x+x^2 - (1+x)) \\ &= 1+x+\frac{x^2}{2} - (1+x) \\ &= x-\frac{x^2}{2} \end{aligned}$$

$$\begin{aligned} \therefore T(1-x+3x^2) &= 4T(1) - T(x) + 3T(x^2) \\ &= 4\left(1+\frac{3x^2}{2}\right) + \frac{x^2}{2} + 3\left(x-\frac{x^2}{2}\right) \\ &= 4+3x-5x^2 \end{aligned}$$

$$\begin{aligned} T(ax+bx+cx^2) &= a\left(1+\frac{3x^2}{2}\right) + b\left(-\frac{x^2}{2}\right) + c\left(x-\frac{x^2}{2}\right) \\ &= a + cx + \frac{3a-b-c}{2}x^2 \end{aligned}$$

16. $\mathcal{L}(V, W) = \{ T: V \rightarrow W , T \text{ a lin. map} \}$

Define $(T_1 + T_2)(v) = T_1 v + T_2 v \quad \forall v \in V$

(i) and $(cT)(v) = c T(v) \quad \forall v \in V, c \in F$
 Clearly $(T_1 + T_2)(cv + w) = c_1(T_1 + T_2)v + (T_1 + T_2)w \stackrel{T_1 + T_2 \in \mathcal{L}(V, W)}{=} T_1 + T_2 \in \mathcal{L}(V, W)$
 (ii) Now, the map $T_0: V \rightarrow W$ similarly, $cT \in \mathcal{L}(V, W)$
 $v \mapsto 0 \quad \forall v \in V$

is the identity of $\mathcal{L}(V, W)$, ~~is~~.

$$\begin{aligned} (T + T_0)(v) &= T(v) + T_0(v) \\ &= T(v) + 0 \\ &= T(v) \end{aligned}$$

Similarly $(T_0 + T)(v) = T(v) \quad \forall v \text{ and } T_0 + T = T$.

$$\begin{aligned} (i) \quad ((T_1 + T_2) + T_3)(v) &= (T_1 + T_2)(v) + T_3(v) \\ &= (T_1(v) + T_2(v)) + T_3(v) \\ &= T_1(v) + (T_2(v) + T_3(v)) \\ &= T_1(v) + (T_2 + T_3)(v) \\ &= (T_1 + (T_2 + T_3))(v) \quad \forall v \in V \\ \therefore + \text{ is an addition on } \mathcal{L}(V, W) \end{aligned}$$

$$\begin{aligned} (ii) \quad (T_1 + T_2)(v) &= T_1 v + T_2 v = T_2 v + T_1 v = (T_2 + T_1)v \\ &\Rightarrow T_1 + T_2 = T_2 + T_1 \end{aligned}$$

(iii) Clearly, $(-T)(v) = -T(v)$ defines inverse of $-T$:

$$(T + (-T))(v) = T(v) \quad \forall v \in V.$$

$$\begin{aligned} (iv) \quad (c(T_1 + T_2))v &= \cancel{c(T_1 v + T_2 v)} - \cancel{(cT_1 + cT_2)(v)} \\ &= c(T_1 + T_2)v = cT_1(v) + cT_2(v) = (cT_1 + cT_2)(v) \\ &\Rightarrow c(T_1 + T_2) = cT_1 + cT_2 \end{aligned}$$

$$\textcircled{v.1} \quad (c_1 + c_2) \tau(v) = c_1 \tau(v) + c_2 \tau(v) \\ = (c_1 \tau + c_2 \tau)(v) = v(c_1 + c_2)$$

$$\therefore (c_1 + c_2) \tau = c_1 \tau + c_2 \tau$$

$$\textcircled{v.1} \quad ((c_1 c_2) \tau)(v) = c_1 c_2 \tau(v) \\ = c_1 (c_2 (\tau(v))) \\ = c_1 (c_2 \tau)(v) \\ \therefore (c_1 c_2) \tau = c_1 (c_2 \tau)$$

$$\textcircled{v.1.1} \quad 1 \cdot \tau(v) = \tau(v) \\ \therefore 1 \tau = \tau \quad \forall \tau \in L(v, w)$$

$\therefore L(v, w)$ is a vector space.

11. (a) $T: M_{3,2} \rightarrow M_{2,2}$

$$T\left(\begin{bmatrix} a & b \\ c & d \end{bmatrix}\right) = \begin{bmatrix} a & 0 \\ 0 & d \end{bmatrix}$$

~~Def~~ $\therefore \text{ker } T = \left\{ \begin{bmatrix} 0 & b \\ c & 0 \end{bmatrix} \mid b, c \in \mathbb{R} \right\}$

and it has basis $\{M_1 = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, M_2 = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}\}$

$$\text{rank}(T) = \left\{ a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + d \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \mid a, d \in \mathbb{R} \right\}$$

has basis $\{M_3 = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, M_4 = \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix}\}$

$\therefore \text{rk}(T) = 2, \text{ nullity}(T) = 2$

and $\dim(M_{2,2}) = 4 = 2 + 2 = \text{rk}(T) + \text{nullity}(T)$

(b) $T: M_{2,2}(\mathbb{R}) \rightarrow \mathbb{R}$

$$T(A) = \text{tr}(A)$$

$\therefore \begin{bmatrix} a & b \\ c & d \end{bmatrix} \mapsto a+d$

$\therefore A \in \text{ker}(T) \iff A = \begin{bmatrix} a & b \\ c & -a \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} + c \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$

$\therefore \text{ker}(T)$ has dim 3. ($\{A_1, A_2, A_3\}$ span $\text{ker } T$, and lin ind)

$$\text{rank}(T) = \mathbb{R} \quad \left(\text{by } \begin{bmatrix} a & 0 \\ 0 & 0 \end{bmatrix} \xrightarrow{\text{tr}} a \right)$$

and $\text{rank}(T) + \text{nullity}(T) = 1 + 3 = 4 = \dim M_{2,2}(\mathbb{R})$

11. (c) $\text{ker } T : M_{2,2}(\mathbb{R}) \rightarrow \mathbb{R}^2$

$$T \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} a-b \\ c-d \end{bmatrix}$$

$\therefore \text{ker}(T) = \left\{ \begin{bmatrix} a & a \\ c & c \end{bmatrix} \right\}$ hat dim 2
(basis $\left\{ \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 1 & 1 \end{bmatrix} \right\}$)

and

$$\text{range}(T) \ni \begin{bmatrix} 1 \\ 0 \end{bmatrix} = T \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$$

$$\text{and } \begin{bmatrix} 0 \\ 1 \end{bmatrix} = T \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

$\therefore \text{rank}(T)$ hat dim 2.

$\therefore \text{rank}(T) + \text{nullity}(T) = 2 + 2 = 4 = \dim M_{2,2}(\mathbb{R})$

(d) $T : P_2 \rightarrow \mathbb{R}^2$ $T(p(x)) = \begin{bmatrix} p(0) \\ p'(1) \end{bmatrix}$

$$T(a+bx+cx^2) = 0 \Rightarrow a=0, \quad a+b+c=0 \\ \text{d.h. } b=-c$$

$$\therefore a+bx+cx^2 \in \text{ker } T \Rightarrow a+bx+cx^2 = h(x-x^2)$$

$\therefore \text{nullity}(T) = 1$.

$\text{range}(T)$ contains $T(x) = \underbrace{\begin{bmatrix} 0 \\ 1 \end{bmatrix}}_{\text{in }} \text{ and } T(1) = \overbrace{\begin{bmatrix} 1 \\ 0 \end{bmatrix}}^{\text{in }} \text{ (1 ist ein v.a.)}$

$\therefore \text{rank}(T) = 2$.

$\therefore \text{rk } T + \text{nullity}(T) = 1 + 2 = 3 = \dim P_2$

(e) $\tau: \mathbb{C} \rightarrow \mathbb{R}$

$$\tau(2) = 2, \quad \tau(1+i) = 1$$

$$\begin{aligned} a+ib \in \ker \tau &\Rightarrow \tau(a+ib) = 0 \\ &\Rightarrow \tau(a-b + (1+i)b) = 0 \\ &\Rightarrow \cancel{\tau(a-b)} + (a-b)\tau(1) + b\tau(1+i) = 0 \\ &\Rightarrow \frac{a-b}{2}, \tau(2) + b, 1 = 0 \\ &\Rightarrow a-b + b = 0 \\ &\Rightarrow a = 0 \end{aligned}$$

$\therefore \ker \tau = \text{span } \{i\} \therefore \text{nullity } \tau_1 = 1$

$$\text{rank } (\tau) \neq 0 \therefore \text{rank } \tau_1 = 1$$

$$\text{rank } (\tau_1 + \text{nullity } \tau_1) = 1+1 = 2 = \dim_{\mathbb{R}} \mathbb{C}$$

$$\begin{aligned} (b) \quad \tau(A) = 0 &\Rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \\ &\Rightarrow \begin{bmatrix} a-b & -a+b \\ c-d & -c+d \end{bmatrix} = \begin{bmatrix} a-c & b-d \\ -a+c & -b+d \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \\ &= 1 \begin{bmatrix} c-b & d-a \\ a-d & b-c \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \quad \text{ab} - \text{ac} \cancel{- \text{ad} + \text{bd}} \cancel{- \text{cb} + \text{cd}} \cancel{- \text{ca} + \text{da}} \cancel{- \text{db} + \text{bc}} \\ &\quad \Rightarrow \cancel{b-c} \cancel{d-a} \cancel{c-d} \cancel{-a+c} \cancel{b-d} \cancel{a-d} \cancel{c+d} \cancel{-b+d} \cancel{1} \cancel{0} \\ &\therefore A = \begin{bmatrix} a & b \\ b & a \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \\ &\quad = \text{nullity } \tau_1 = 2. \end{aligned}$$

$$\text{rank } (\tau) \text{ contains } \tau \left(\begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \right) = \underbrace{\begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix}}_{\text{lin. ind.}} \text{ and } \tau \left(\begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \right) = \underbrace{\begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix}}_{\text{lin. ind.}}$$

$$\text{and } \tau \begin{bmatrix} a & b \\ c & d \end{bmatrix} = (a-b) \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} + (a-d) \begin{bmatrix} 0 & -1 \\ 1 & 0 \end{bmatrix} \quad \therefore \text{rank } \tau_1 = 2$$

12. linear independence of $\{x, Tx, \dots, T^{n-1}x\}$:

Consider

$$c_0 x + c_1 Tx + \dots + c_{n-1} T^{n-1} x = 0 \quad (*) \quad (c_i \in \mathbb{R})$$

Applying T^{n-1} on both sides,

$$T^{n-1}(c_0 x + c_1 Tx + \dots + c_{n-1} T^{n-1} x) = T^{n-1}(0)$$

Noting that T^{n-1} is a linear transformation

$$\text{or } T^{n-1} c_0 x + c_1 T^{n-1} x + \dots + c_{n-1} T^{2n-2} x = 0$$

$$\Rightarrow c_0 T^{n-1} x = 0$$

$$\Rightarrow c_0 = 0 \quad \text{as } T^{n-1} x \neq 0$$

Next, apply T^{n-2} to obtain $c_1 = 0$ (from *)

$\therefore \{x, Tx, \dots, T^{n-1}x\}$ is lin. ind.

Since $\dim V = n$, $\{x, \dots, T^{n-1}x\}$ must be a basis of V .