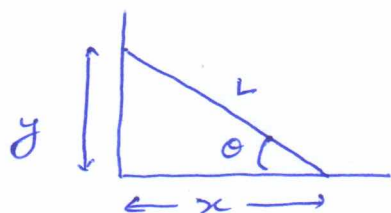


1.

(a)



$$x^2 + y^2 = L^2$$

$$\Rightarrow 2x\dot{x} + 2y\dot{y} = 0$$

$$\Rightarrow \dot{x}^2 + x\ddot{x} + \dot{y}^2 + y\ddot{y} = 0$$

When the pole is at rest  $\dot{x} = 0 = \dot{y}$

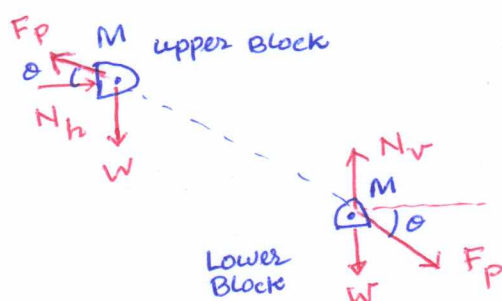
At rest the condition becomes:

$$x\ddot{x} + y\ddot{y} = 0$$

$$\Rightarrow \ddot{x} = -\frac{y}{x}\ddot{y} = -(\tan\theta)\ddot{y} \rightarrow (i)$$

(b)

Take the pole to be massless  $\Rightarrow$  net force on the pole must be 0.



Upper Block:  $M\ddot{y} = F_p \sin\theta - W \rightarrow (ii)$

Lower Block:  $M\ddot{x} = F_p \cos\theta \rightarrow (iii)$

Solving ~~(i)~~ (ii) and (iii) and using (i) one can obtain:

$$\ddot{x} = g \sin\theta \cos\theta \quad \ddot{y} = -g \cos^2\theta$$

2.

(a)

The block to remain motionless  
 $\Rightarrow$  it has 0 acceleration

(2)



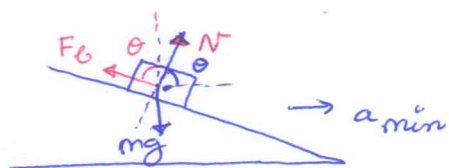
$$N - mg \cos \theta = 0$$

$$mg \sin \theta - F_a = 0$$

$$F_a = \mu N$$

$$\therefore mg \sin \theta = \mu N = \mu mg \cos \theta \Rightarrow \boxed{\mu = \tan \theta} //$$

(b) Minimum acceleration



Block's horizontal acceleration is

$$ma_{\min} = N \cos \theta - F_b \sin \theta \rightarrow (i)$$

$$\text{In the limit } F_b = \mu N \rightarrow (ii)$$

The block has zero vertical acceleration:

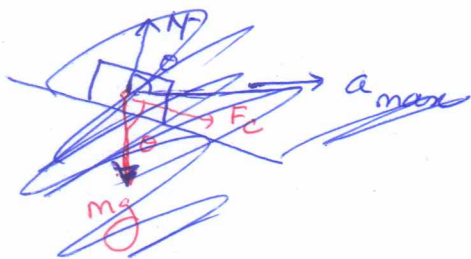
$$N \sin \theta + F_b \cos \theta - mg = 0 \rightarrow (iii)$$

Using combining ~~the~~ (i), (ii) and (iii), it is straightforward to show:

$$\boxed{a_{\min} = \left( \frac{\cos \theta - \mu \sin \theta}{\sin \theta + \mu \cos \theta} \right) g}$$

Caution  
 This ' $\theta$ ' is different from inclined wedge angle  $\theta$

(This  $\theta = 90^\circ - \theta_{\text{wedge}}$ )

(c) Maximum acc<sup>n</sup>

$$ma_{\max} = N \cos \theta + F_c \sin \theta \rightarrow (i)$$

no vertical acc<sup>n</sup> $\Rightarrow$ 

$$N \sin \theta - F_c \cos \theta - mg = 0 \rightarrow (ii)$$

In the limiting case

$$F_c = \mu N \rightarrow (iii)$$

Using (i), (ii) and (iii) one can get:

$$\boxed{a_{\max} = \left( \frac{\cos \theta + \mu \sin \theta}{\sin \theta - \mu \cos \theta} \right) g}$$

3.

(3)

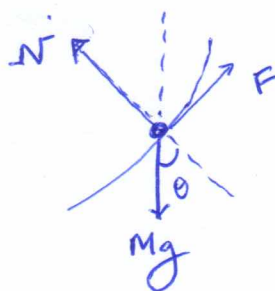
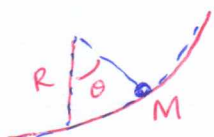
Here, it is assumed,  $r = R = \text{constant}$

$$\therefore \dot{r} = 0$$

$$\Rightarrow \ddot{r} = 0$$

$$\dot{\theta} = v/R = \text{constant}$$

$$\Rightarrow \ddot{\theta} = 0$$



Radial  $E_2^n$  of motion:

$$M \frac{v^2}{R} = N - Mg \cos \theta \rightarrow (i)$$

Tangential  $E_2^n$  of motion:

$$F - Mg \sin \theta = 0 \rightarrow (ii)$$

The automobile begins to skid when, tangential force  $F - Mg \sin \theta \leq 0$

Now, the  $\text{max}^m$  value of  $F$  is  $\mu N$ . In the limiting case,  $\mu N = Mg \sin \theta$

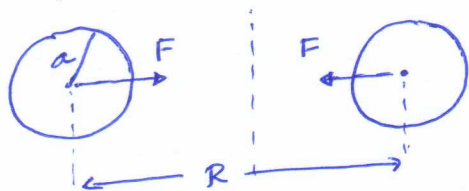
From (i)

$$M \frac{v^2}{R} = Mg \left( \frac{\sin \theta}{\mu} - \cos \theta \right)$$

$$\Rightarrow \boxed{\frac{\sin \theta}{\mu} - \cos \theta = \frac{v^2}{Rg}}$$

4.

4



Each sphere orbits in a circle of radius  $R/2$  and experiences a radial gravitational attraction  $F$ :

$$F = \frac{GMM}{R^2}$$

Radial eq<sup>n</sup> of motion:

$$M \frac{R}{2} \omega^2 = \frac{GM^2}{R^2} \Rightarrow \omega = \sqrt{\frac{2GM}{R^3}}$$

$$T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{R^3}{2GM}}$$

Say,  $\rho$  is the density, then  $M = \frac{4}{3}\pi a^3 \rho$

$a_{\max} = R/2$  (spheres touching)  $T$  can be made smaller by making  $M$  larger; we can make  $a$  large. However,  $a_{\max} = R/2$  (sphere touching)

$$\therefore T_{\min} = 2\pi \sqrt{\frac{R^3}{2G\rho \frac{4}{3}\pi (R/2)^3}}$$

$$= 2\pi \sqrt{\frac{3}{G\rho\pi}}$$

$$= \sqrt{\frac{12\pi}{G\rho}}$$

$$G = 6.67 \times 10^{-11} \text{ kg}^{-1} \text{ m}^3 \text{ s}^{-2}$$

$$\rho = 21.5 \text{ g cm}^{-3} = 21.5 \times 10^3 \text{ kg m}^{-3}$$

One should get

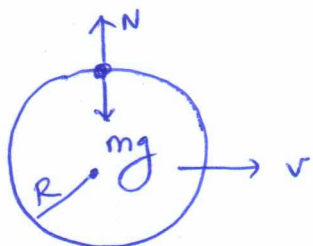
$$T_{\min} = 85.5 \text{ mins}$$



5.

(5)

The speed of the pebble is  $v_p = v_w$ , speed of the wheel as long as the pebble is in contact with wheel.



$$v_p = R\omega \\ = v_w$$

(a) From the force diagram above,

$$m \frac{v^2}{R} = mg - N, \quad v = v_p = v_w$$

where,  $N \geq 0$

The pebble flies off when  $N = 0$ .

$$\therefore \frac{mv^2}{R} > mg \Rightarrow \boxed{v > \sqrt{Rg}} \text{ is the}$$

required condition for the pebble to fly off the wheel immediately.

(b)

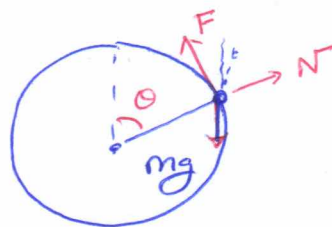
When in contact, the radial eq<sup>n</sup> of motion for the pebble is

$$\frac{mv^2}{R} = mg \cos \theta - N \rightarrow (i)$$

Now,  $N \geq 0$

$$\Rightarrow \cos \theta_{\max} = \frac{v^2}{Rg}$$

However, there is a more stringent criterion based on the frictional force  $F$ , as follows. There is no tangential acceleration:



$$0 = mg \sin \theta - F \Rightarrow F = mg \sin \theta \rightarrow (ii)$$

$$F \leq \mu N \rightarrow (iii)$$

From (i), (ii) and (iii) one can obtain:

(6)

$$g \sin \theta \leq \mu g \cos \theta - \mu v^2/R$$

For  $\mu = 1$

$$g \sin \theta \leq g \cos \theta - \frac{v^2}{R}$$

$$\Rightarrow \sin \theta \leq \cos \theta - \frac{v^2}{Rg}$$

$$\frac{v^2}{Rg} = \cos \theta_{\max} - \sin \theta_{\max}$$

$$= \sqrt{2} \cos \left( \theta_{\max} + \frac{\pi}{4} \right)$$

$$\Rightarrow \cos \left( \theta_{\max} + \frac{\pi}{4} \right) = \frac{v^2}{\sqrt{2} Rg}$$

$$\Rightarrow \theta_{\max} = \cos^{-1} \left( \frac{v^2}{\sqrt{2} Rg} \right) - \frac{\pi}{4}$$

6.

$$m \frac{dv}{dt} = -kv^2$$

$$\Rightarrow \int_{v_0}^v \frac{dv}{v^2} = -\frac{k}{m} \int_0^t dt$$

$$\Rightarrow \frac{1}{v} = \frac{1}{v_0} + \frac{kt}{m}$$

$$= \frac{1}{v_0} \left( 1 + \frac{kv_0 t}{m} \right)$$

$$= \frac{1}{v_0} \left( 1 + \frac{t}{\tau} \right),$$

$$\tau = \frac{m}{kv_0},$$

is a characteristic time

$$d = \int v dt$$

$$= \int_0^t \left( \frac{v_0}{1 + t/\tau} \right) dt = v_0 \tau \ln(1 + t/\tau)$$

$$\boxed{d = v_0 \tau \ln(1 + t/\tau)}.$$

For short time,  $t \ll \tau$ ,  
using  $\ln(1+x) \approx x$  we obtain

$$d \approx v_0 \tau (t/\tau) = v_0 t //$$

7.

(7)

$$[h] = ML^2 T^{-1}$$

$$[G] = M^{-1} L^3 T^{-2}$$

$$[c] = LT^{-1}$$

(a) Planck length  $L_p = h^\alpha G^\beta c^\gamma$

~~$$[L_p] = [h^\alpha]$$~~

$$L = (ML^2 T^{-1})^\alpha (M^{-1} L^3 T^{-2})^\beta (LT^{-1})^\gamma$$

$$= M^{\alpha-\beta} L^{2\alpha+3\beta+\gamma} T^{-(\alpha+2\beta+\gamma)}$$

$$\Rightarrow \begin{aligned} \alpha - \beta &= 0 \\ 2\alpha + 3\beta + \gamma &= 1 \\ \alpha + 2\beta + \gamma &= 0 \end{aligned}$$

$$\Downarrow$$

$$\begin{aligned} \alpha &= 1/2 \\ \beta &= 1/2 \\ \gamma &= -3/2 \end{aligned}$$

$$L_p = \sqrt{\frac{hG}{c^3}} \approx 4.1 \times 10^{-35} \text{ m}$$

to Similar way one can find

(b)  $M_p = \sqrt{\frac{hc}{G}} \approx 5.4 \times 10^{-8} \text{ kg}$

(c)  $T_p = \sqrt{\frac{hG}{c^5}} \approx 1.3 \times 10^{-43} \text{ s}$

//