

# MA101 Mathematics I

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Jul – Nov 2013

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ver. 21 Sept 2013, 10:18 (bks)

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## Slides 5

### PLAN

- Linear Transformation, Kernel and Range
- Matrix of a Linear Transformation

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# Linear Transformations

- Suppose  $A \in \mathcal{M}_{m \times n}$ . Take  $\mathbf{v} \in \mathbb{R}^n$ . Then  $A\mathbf{v} \in \mathbb{R}^m$ . Thus, we have a map (function)  $F : \mathbb{R}^n \rightarrow \mathbb{R}^m$  given by  $F(\mathbf{v}) = A\mathbf{v}$ .
- Take  $F : \mathbb{R}[x] \rightarrow \mathbb{R}[x]$  given by  $F(p(x)) = p'(x)$ .
- Take  $F : \mathcal{C}[0, 1] \rightarrow \mathcal{C}[0, 1]$  given by  $(F(f))(x) = \int_0^x f(t)dt$ .
- Take  $F : \mathbb{R}[x] \rightarrow \mathbb{R}$  given by  $F(p(x)) = p(3)$ .

What is common in all of these? Well, they are maps (functions) with domains and codomains as VS's. What else? We have

$$F(\mathbf{u} + \mathbf{v}) = F(\mathbf{u}) + F(\mathbf{v}), \quad F(\alpha\mathbf{v}) = \alpha F(\mathbf{v}),$$

or, equivalently,  $F(\alpha\mathbf{u} + \beta\mathbf{v}) = \alpha F(\mathbf{u}) + \beta F(\mathbf{v})$ . Such functions are called **linear transformations (LT)**.

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## Definition

Let  $\mathbb{V}, \mathbb{W}$  be VS's over  $\mathbb{F}$ . A map  $T : \mathbb{V} \rightarrow \mathbb{W}$  is a **linear transformation (LT)** from  $V$  into  $W$  if  $\forall \mathbf{u}, \mathbf{v} \in \mathbb{V}, \alpha \in \mathbb{F}$

$$T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v}), \text{ and } T(\alpha\mathbf{v}) = \alpha T(\mathbf{v}), \text{ or}$$

equivalently,  $T(\alpha\mathbf{u} + \beta\mathbf{v}) = \alpha T(\mathbf{u}) + \beta T(\mathbf{v}), \forall \mathbf{u}, \mathbf{v} \in \mathbb{V}, \alpha, \beta \in \mathbb{F}$ .

**Obvious LT's:**

- $T_0 : \mathbb{V} \rightarrow \mathbb{W}, T_0(\mathbf{v}) = \mathbf{0}, \forall \mathbf{v} \in \mathbb{V}$  (**zero transformation**).  
Here,  $\mathbb{V}, \mathbb{W}$  are any VS's.
- $I_{\mathbb{V}} : \mathbb{V} \rightarrow \mathbb{V}, I_{\mathbb{V}}(\mathbf{v}) = \mathbf{v}, \forall \mathbf{v} \in \mathbb{V}$  (**identity transformation**).  
Here,  $\mathbb{V}$  is any VS.

## Exercise

Is  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ , where  $T([x, y]^T) = [2x, x + y]^T$  an LT? Yes,

check using definition, or observe that  $T\left(\begin{bmatrix} x \\ y \end{bmatrix}\right) = \begin{bmatrix} 2 & 0 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix}$ .

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## Result

Let  $T : \mathbb{V} \rightarrow \mathbb{W}$  be an LT. Then

- ①  $T(\mathbf{0}) = \mathbf{0}$ ;  $[T(\mathbf{0}) = T(\mathbf{0} + \mathbf{0}) = T(\mathbf{0}) + T(\mathbf{0}) \Rightarrow \mathbf{0} = T(\mathbf{0}).]$
- ②  $T(-\mathbf{v}) = -T(\mathbf{v})$  for all  $\mathbf{v} \in \mathbb{V}$ ;  $[T(-\mathbf{v}) + T\mathbf{v} = \mathbf{0}.]$
- ③  $T(\mathbf{u} - \mathbf{v}) = T(\mathbf{u}) - T(\mathbf{v})$  for all  $\mathbf{u}, \mathbf{v} \in \mathbb{V}$ .

## Exercise

Is  $T : \mathbb{R} \rightarrow \mathbb{R}$ , where  $T(x) = x + 1$  is an LT? No.  $T(0) \neq 0$ .

## Exercise

Can there be an LT  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  such that

$$T([0, 1]^T) = [2, 3]^T, \quad T([1, 0]^T) = [3, 2]^T \text{ and} \\ T([1, 1]^T) = [3, 3]^T?$$

No,  $[3, 3]^T = T([1, 1]^T) = T(\mathbf{e}_1) + T(\mathbf{e}_2) = [5, 5]^T$ , not possible.

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## Exercise

Suppose  $T : \mathbb{R}^2 \rightarrow \mathbb{R}_2[x]$  is an LT. Given that

$$T([1, 0]^T) = 2 - 3x + x^2 \text{ and } T([0, 1]^T) = 1 - x^2. \text{ What is} \\ T([2, 3]^T)? \quad T([2, 3]^T) = T(2\mathbf{e}_1 + 3\mathbf{e}_2) = 2T(\mathbf{e}_1) + 3T(\mathbf{e}_2) = \\ 2(2 - 3x + x^2) + 3(1 - x^2) = 7 - 6x - x^2. \text{ What is } T([a, b]^T)?$$

## Result

Let  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  be a basis of  $\mathbb{V}$  ( $\dim(\mathbb{V}) = n$ ). Let  $\mathbf{u}_1, \dots, \mathbf{u}_n$  be arbitrarily chosen in  $\mathbb{W}$ . Then there is a unique LT  $T : \mathbb{V} \rightarrow \mathbb{W}$  such that  $T(\mathbf{v}_i) = \mathbf{u}_i$ .

**PROOF.** Let  $\mathbf{v} \in \mathbb{V}$ . Then  $\mathbf{v}$  equals a unique linear combination  $\alpha_1\mathbf{v}_1 + \dots + \alpha_n\mathbf{v}_n$ . Define  $T\mathbf{v} = \alpha_1\mathbf{u}_1 + \dots + \alpha_n\mathbf{u}_n \in \mathbb{W}$ . The resulting map  $T$  is the LT we are looking for. ■

**REMARK:** To define (know) an LT, it is enough to define (know) the images of vectors in any basis of the domain.

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## Example

Consider  $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$  given by  $T(\mathbf{x}) = A\mathbf{x}$ , where  $A \in \mathcal{M}_{m \times n}$ .

What is the range of  $T$ ? It is  $\{T(\mathbf{x}) \in \mathbb{R}^m \mid \mathbf{x} \in \mathbb{R}^n\}$

$= \{A\mathbf{x} \mid \mathbf{x} \in \mathbb{R}^n\} = \text{col}(A)$ . Note that the range is a subspace of  $\mathbb{R}^m$ . On the other hand,

$\text{null}(A) = \{\mathbf{x} \in \mathbb{R}^n \mid A\mathbf{x} = \mathbf{0}\} = \{\mathbf{x} \in \mathbb{R}^n \mid T(\mathbf{x}) = \mathbf{0}\}$  is a subspace of  $\mathbb{R}^n$ .

**Kernel and Range:** For an LT  $T : \mathbb{V} \rightarrow \mathbb{W}$  we define:

- Kernel (or null space) of  $T$ :  $\ker(T) := \{\mathbf{v} \in \mathbb{V} \mid T(\mathbf{v}) = \mathbf{0}\}$ ;
- range of  $T$ :  $\text{range}(T) := \{T(\mathbf{v}) \in \mathbb{W} \mid \mathbf{v} \in \mathbb{V}\}$ .

It is easy to see that  $\ker(T) \preceq \mathbb{V}$  and  $\text{range}(T) \preceq \mathbb{W}$ . Moreover,

If  $B = \{\mathbf{v}_1, \dots, \mathbf{v}_k\}$  spans  $V$ , then  $T(B) = \{T(\mathbf{v}_1), \dots, T(\mathbf{v}_k)\}$  spans  $\text{range}(T)$ .

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## Exercise

Let  $D : \mathbb{R}_3[x] \rightarrow \mathbb{R}_3[x]$  be defined by  $D(p(x)) = p'(x)$ . Find  $\ker(D)$ ,  $\text{range}(D)$  and their dimensions.

## Definition

For an LT  $T : \mathbb{V} \rightarrow \mathbb{W}$  we define

- $\text{rank}(T) :=$  dimension of  $\text{range}(T)$ ; and
- $\text{nullity}(T) :=$  dimension of  $\ker(T)$ .

## Example

For the previous example,  $\text{rank}(D) = 3$  and  $\text{nullity}(D) = 1$ .

## Result (THE RANK-NULLITY THEOREM)

If  $\mathbb{V}$  is *finite dimensional*, then for any LT  $T : \mathbb{V} \rightarrow \mathbb{W}$ ,

$$\text{rank}(T) + \text{nullity}(T) = \dim(V).$$

**PROOF.** Take a basis  $B = \{\mathbf{v}_1, \dots, \mathbf{v}_k\}$  of  $\ker(T)$ . Extend it to a basis  $B \cup \{\mathbf{v}_{k+1}, \dots, \mathbf{v}_n\}$  of  $\mathbb{V}$ . Then  $\{T(\mathbf{v}_{k+1}), \dots, T(\mathbf{v}_n)\}$  spans  $\text{range}(T)$ . Moreover,  $\{T(\mathbf{v}_{k+1}), \dots, T(\mathbf{v}_n)\}$  is LI.

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## Result

Let  $T : \mathbb{V} \rightarrow \mathbb{W}$  be an LT. Then

- $T$  is **one-one** iff  $\ker(T) = \{\mathbf{0}\}$ .
- $\dim(\mathbb{V}) = \dim(\mathbb{W}) = n$ , then  $T$  is **onto** iff  $\ker(T) = \{\mathbf{0}\}$ .

## Definition

For linear transformations  $T : \mathbb{V} \rightarrow \mathbb{W}$ ,  $S : \mathbb{V} \rightarrow \mathbb{W}$  and  $\alpha \in \mathbb{F}$  we define  $T + S : \mathbb{V} \rightarrow \mathbb{W}$ ,  $\alpha T : \mathbb{V} \rightarrow \mathbb{W}$  by

$$(T + S)(\mathbf{v}) = T(\mathbf{v}) + S(\mathbf{v}), (\alpha T)(\mathbf{v}) = \alpha(T(\mathbf{v})), \quad \mathbf{v} \in \mathbb{V}.$$

## Exercise

Show that  $T + S$  and  $\alpha T$  are **linear transformations**.

## Result (Composition of Linear Transformations )

Suppose  $T : \mathbb{U} \rightarrow \mathbb{V}$  and  $S : \mathbb{V} \rightarrow \mathbb{W}$  are LT's. Then the **composition**  $S \circ T : \mathbb{U} \rightarrow \mathbb{W}$  is also an LT.

PROOF. Note:  $(S \circ T)(\mathbf{u}) = S(T\mathbf{u})$  for all  $\mathbf{u} \in \mathbb{U}$ . Now,

$$(S \circ T)(\alpha \mathbf{u} + \beta \mathbf{v}) = S(\alpha T\mathbf{u} + \beta T\mathbf{v}) = \alpha(S \circ T)\mathbf{u} + \beta(S \circ T)\mathbf{v}. \quad \blacksquare$$

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## Coordinates

Suppose  $\mathbb{V}$  is a VS of **dimension**  $n$ . Fix an **ordered** basis

$B = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  (i.e., a basis with a specific order of its elements). For  $\mathbf{v} \in \mathbb{V}$  we have unique way of writing

$\mathbf{v} = \alpha_1 \mathbf{v}_1 + \alpha_2 \mathbf{v}_2 + \dots + \alpha_n \mathbf{v}_n$ ,  $\alpha_i \in \mathbb{F}$ . Define

$T(\mathbf{v}) = [\alpha_1, \alpha_2, \dots, \alpha_n]^T$ . Then, we have a map  $T : \mathbb{V} \rightarrow \mathbb{F}^n$ .

## Definition

Consider the above map  $T : \mathbb{V} \rightarrow \mathbb{F}^n$ .  $T(\mathbf{v})$  is called the **coordinate vector** of  $\mathbf{v}$  w.r.t. the **ordered** basis  $B$ .  $T(\mathbf{v})$  is denoted by  $[\mathbf{v}]_B$ . The scalars  $\alpha_i$  are called the **coordinates** of  $\mathbf{v}$  w.r.t.  $B$ .

## Remark

- $[\mathbf{v}]_B$  depends not only on  $B$ ; but also on the order in which  $\mathbf{v}_i$  chosen.
- $T : \mathbb{V} \rightarrow \mathbb{F}^n$ , where  $T(\mathbf{v}) = [\mathbf{v}]_B$  is an LT. Indeed,

$$[\mathbf{u} + \mathbf{v}]_B = [\mathbf{u}]_B + [\mathbf{v}]_B \quad \text{and} \quad [c\mathbf{u}]_B = c[\mathbf{u}]_B.$$

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# Isomorphism

## Example

Take the standard (ordered) basis  $B = \{1, x, x^2\}$  of  $\mathbb{R}_2[x]$ . Then,

$$[a + bx + cx^2]_B = \begin{bmatrix} a \\ b \\ c \end{bmatrix}. \text{ Note that the LT } T : \mathbb{R}_2[x] \rightarrow \mathbb{R}^3,$$

$T(p(x)) = [p(x)]_B$  is **one-one** and **onto** (i.e., **invertible**).

## Definition

A linear transformation  $T : \mathbb{V} \rightarrow \mathbb{W}$  is called an **isomorphism** of  $\mathbb{V}$  onto  $\mathbb{W}$ , if it is **one-one** and **onto**. In that case, we say that  $\mathbb{V}$  is **isomorphic to**  $\mathbb{W}$  and we write  $\mathbb{V} \cong \mathbb{W}$ .

## Example

The LT  $T : \mathbb{V} \rightarrow \mathbb{F}^n$ , where  $T(\mathbf{v}) = [\mathbf{v}]_B$ , is an isomorphism. Thus, any VS of dimension  $n$  over  $\mathbb{F}$  is isomorphic to  $\mathbb{F}^n$ .

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## The Matrix of a Linear Transformation

Suppose  $\dim(\mathbb{V}) = n$ ,  $\dim(\mathbb{W}) = m$ ,  $B = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  an ordered basis of  $\mathbb{V}$ ,  $C = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_m\}$  an ordered basis of  $\mathbb{W}$  and  $T : V \rightarrow W$  an LT. Then the  $m \times n$  matrix  $A$  defined by

$$A = \left[ [T(\mathbf{v}_1)]_C, [T(\mathbf{v}_2)]_C, \dots, [T(\mathbf{v}_n)]_C \right]$$

is called the **matrix of  $T$  with respect to the bases  $B$  and  $C$** .

The matrix  $A$  is written as  $[T]_{C \leftarrow B}$ .

## Example

Let  $T : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  be defined by

$$T([x, y, z]^T) = [x - 2y, x + y - 3z]^T.$$

Consider the bases  $B = \{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3\}$  and  $C = \{\mathbf{e}_1, \mathbf{e}_2\}$  for  $\mathbb{R}^3$  and  $\mathbb{R}^2$ , respectively. Then

$$A = [T]_{C \leftarrow B} = [T(\mathbf{e}_1), T(\mathbf{e}_2), T(\mathbf{e}_3)] = \begin{bmatrix} 1 & -2 & 0 \\ 1 & 1 & -3 \end{bmatrix}.$$

What is  $T([1, 2, 3]^T)$ ? In general  $T([x, y, z]^T) = A[x, y, z]^T$ .

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### Remark

If  $\mathbb{V} = \mathbb{W}$  and  $B = C$ , then  $[T]_{C \leftarrow B}$  is written as  $[T]_B$ .

### Example

Consider  $D : \mathbb{R}_3[x] \rightarrow \mathbb{R}_3[x]$  defined by  $D(p(x)) = p'(x)$ . Take the standard (ordered) basis  $B = \{1, x, x^2, x^3\}$  of  $\mathbb{R}_3[x]$ . Since  $D(1) = 0$ ,  $D(x) = 1$ ,  $D(x^2) = 2x$ ,  $D(x^3) = 3x^2$ , we get

$$[D]_B = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 2 & 0 \\ 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

Consider  $p(x) = a_0 + a_1x + a_2x^2 + a_3x^3$ . Then  $D(p(x)) = a_1 + 2a_2x + 3a_3x^2$ . Note that

$$[p(x)]_B = \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix}, \quad [D]_B[p(x)]_B = \begin{bmatrix} a_1 \\ 2a_2 \\ 3a_3 \\ 0 \end{bmatrix} = [D(p(x))]_B.$$

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### Result

Let  $A = [T]_{C \leftarrow B}$ . Then, for all  $\mathbf{v} \in \mathbb{V}$ ,

$$A[\mathbf{v}]_B = [T(\mathbf{v})]_C, \quad \text{i.e.,} \quad \left\{ \begin{array}{ccc} \mathbf{v} \in \mathbb{V} & \xrightarrow{T} & T(\mathbf{v}) \in \mathbb{W} \\ \downarrow & & \downarrow \\ [\mathbf{v}]_B \in \mathbb{F}^n & \xrightarrow{T_A} & [T(\mathbf{v})]_C = A[\mathbf{v}]_B \in \mathbb{F}^m \end{array} \right\}$$

Here  $T_A : \mathbb{F}^n \rightarrow \mathbb{F}^m$  is the LT given by  $T_A(\mathbf{x}) = A\mathbf{x}$ .

### Remark

The above result means:

Suppose we know  $[T]_{C \leftarrow B}$  w.r.t. given bases  $B$  and  $C$ . Then we know  $T$  in the following sense:

$$\text{If } \mathbf{v} = \sum_{i=1}^n a_i \mathbf{v}_i \text{ and } [T]_{C \leftarrow B} \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{bmatrix}, \text{ then } T(\mathbf{v}) = \sum_{j=1}^m b_j \mathbf{u}_j.$$

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## Result

Let  $\mathbb{U}, \mathbb{V}$  and  $\mathbb{W}$  be three vector spaces with bases  $B, C$  and  $D$ , respectively. Let  $T : \mathbb{U} \rightarrow \mathbb{V}$  and  $S : \mathbb{V} \rightarrow \mathbb{W}$  be linear transformations. Then  $[S \circ T]_{D \leftarrow B} = [S]_{D \leftarrow C} [T]_{C \leftarrow B}$ .

**PROOF.** We have

$$[S \circ T]_{D \leftarrow B} = \left[ [(S \circ T)(\mathbf{v}_1)]_D, [(S \circ T)(\mathbf{v}_2)]_D, \dots, [(S \circ T)(\mathbf{v}_n)]_D \right].$$

Now, the  $i$ -th column of  $[S \circ T]_{D \leftarrow B}$  is

$$\begin{aligned} [(S \circ T)(\mathbf{v}_i)]_D &= [(S(T(\mathbf{v}_i)))_D] = [S]_{D \leftarrow C} [T(\mathbf{v}_i)]_C \\ &= [S]_{D \leftarrow C} [T]_{C \leftarrow B} [\mathbf{v}_i]_B = [S]_{D \leftarrow C} [T]_{C \leftarrow B} \mathbf{e}_i, \end{aligned}$$

the  $i$ -th column of  $[S]_{D \leftarrow C} [T]_{C \leftarrow B}$ . ■

## Result

Let  $\mathbb{V}$  be VS with basis  $B$ , resp., and  $T, S : \mathbb{V} \rightarrow \mathbb{V}$  are linear transformations. Then,  $[S \circ T]_B = [S]_B [T]_B$ .

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## Change of Basis:

Let  $B = \{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_n\}$  and  $C = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  be two bases for a vector space  $\mathbb{V}$  with dimension  $n$ . For  $\mathbf{v} \in \mathbb{V}$ , both  $[\mathbf{v}]_B$  and  $[\mathbf{v}]_C$  are in  $\mathbb{R}^n$ . How are they related?

Let  $P_{C \leftarrow B} := [[\mathbf{u}_1]_C, [\mathbf{u}_2]_C, \dots, [\mathbf{u}_n]_C]$ , (called the **change of basis matrix** from  $B$  to  $C$ .) Then

- ①  $P_{C \leftarrow B} [\mathbf{x}]_B = [\mathbf{x}]_C$  for all  $\mathbf{x} \in V$ ;
- ②  $P_{C \leftarrow B}$  is **unique such matrix**;
- ③  $P_{C \leftarrow B}$  is invertible and  $(P_{C \leftarrow B})^{-1} = P_{B \leftarrow C}$ .

## Example

Find the change of basis matrix  $P_{C \leftarrow B}$  and  $P_{B \leftarrow C}$  for the bases  $B = \{1, x, x^2\}$  and  $C = \{1 + x, x + x^2, 1 + x^2\}$  of  $\mathbb{R}_2[x]$ . Then find the coordinate vector of  $p(x) = 1 + 2x - x^2$  w.r.t. respect to the basis  $C$ .

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## Exercises

- Check whether the following are linear transformations, one-one and onto.
  - $T : \mathbb{R} \rightarrow \mathbb{R}^2$  defined by  $T(x) = [x, 0]^T$ ,  $x \in \mathbb{R}$ .
  - $T : \mathbb{R}^2 \rightarrow \mathbb{R}$  defined by  $T[x, y]^T = x$ , for  $[x, y]^T \in \mathbb{R}^2$ .
  - $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $T[x, y]^T = [-x, -y]^T$ , for  $[x, y]^T \in \mathbb{R}^2$ .
- Let  $T : \mathbb{V} \rightarrow \mathbb{W}$  be a linear transformation,  $\mathbf{v}_1, \dots, \mathbf{v}_k$  be in  $\mathbb{V}$  such that  $T(\mathbf{v}_1), \dots, T(\mathbf{v}_k)$  are linearly independent. Can  $\mathbf{v}_1, \dots, \mathbf{v}_k$  be linearly dependent? Justify?
- Let an LT  $T : \mathbb{V} \rightarrow \mathbb{W}$  is given to be one-one. If  $S = \{\mathbf{v}_1, \dots, \mathbf{v}_k\}$  is an LI subset of  $\mathbb{V}$  then show that  $T(S) = \{T(\mathbf{v}_1), \dots, T(\mathbf{v}_k)\}$  is LI in  $\mathbb{W}$ .

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## Exercises

- Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  and  $S : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be defined by  $T[x, y]^T = [x - y, -3x + 4y]^T$  and  $S[x, y]^T = [4x + y, 3x + y]^T$  for  $[x, y]^T \in \mathbb{R}^2$ . Compute  $T \circ S$  and  $S \circ T$ . What is your observation?
- Let  $\mathbb{V}$  and  $\mathbb{W}$  be vector spaces over  $\mathbb{F}$ .
  - If  $T : \mathbb{V} \rightarrow \mathbb{W}$  is an one-one and onto (i.e., invertible). linear transformation, then show that  $T^{-1} : \mathbb{W} \rightarrow \mathbb{V}$  is an LT.
  - Argue that if  $\mathbb{V}$  is isomorphic to  $\mathbb{W}$ , then  $\mathbb{W}$  is isomorphic to  $\mathbb{V}$ .
- Let  $\dim(\mathbb{V}) = \dim(\mathbb{W})$ . Then show that a linear transformation  $T : \mathbb{V} \rightarrow \mathbb{W}$  is one-one iff  $T$  is onto.
- Let  $\dim(\mathbb{V}) = \dim(\mathbb{W})$ . Then a one-one linear transformation  $T : \mathbb{V} \rightarrow \mathbb{W}$  maps a basis for  $\mathbb{V}$  onto a basis for  $\mathbb{W}$ .

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## Exercises

- Let  $\mathbb{V}$  and  $\mathbb{W}$  be two finite dimensional vector spaces. Then  $\mathbb{V}$  is **isomorphic** to  $\mathbb{W}$  iff  $\dim(\mathbb{V}) = \dim(\mathbb{W})$ .
- Show that
  - $\mathbb{R}^3$  and  $\mathbb{R}_2[x]$  are **isomorphic**.
  - The vector spaces  $\mathbb{R}^n$  and  $\mathbb{R}_n[x]$  are **not** isomorphic.
- Let  $B = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_n\}$  be a basis for a vector space  $\mathbb{V}$ , and let  $\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k$  be vectors in  $\mathbb{V}$ . Then  $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$  is linearly independent in  $\mathbb{V}$  if and only if  $\{[\mathbf{u}_1]_B, [\mathbf{u}_2]_B, \dots, [\mathbf{u}_k]_B\}$  is linearly independent in  $\mathbb{R}^n$ .
- Suppose  $T, S : \mathbb{V} \rightarrow \mathbb{W}$  are LT's, and  $B$  and  $C$  are ordered bases of  $\mathbb{V}$  and  $\mathbb{W}$ , resp. Show that

$$[T + S]_{C \leftarrow B} = [T]_{C \leftarrow B} + [S]_{C \leftarrow B},$$

$$[\alpha T]_{C \leftarrow B} = \alpha [T]_{C \leftarrow B}.$$

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## Exercises

- Let  $\mathbb{V}, \mathbb{W}$  be  $n$  dimensional with bases  $B$  and  $C$ , resp., and  $T : \mathbb{V} \rightarrow \mathbb{W}$  an LT. Then  **$T$  is invertible if and only if** the matrix  $[T]_{C \leftarrow B}$  **is invertible**. In that case,

$$([T]_{C \leftarrow B})^{-1} = [T^{-1}]_{B \leftarrow C}.$$

- Let  $T : \mathbb{R}^2 \rightarrow \mathbb{R}_1[x]$  be defined by  $T([a, b]^T) = a + (a + b)x$  for  $[a, b]^T \in \mathbb{R}^2$ . Find  $[T]_{C \leftarrow B}$  w.r.t. standard bases, show that  **$T$  is invertible**, and thus find  $T^{-1}$ .

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