Plan

- Inner Product
- Gram-Schmidt Process

Let
$$\mathbf{u} = [u_1, u_2, \dots, u_n]^t$$
, $\mathbf{v} = [v_1, v_2, \dots, v_n]^t \in \mathbb{R}^n$ or \mathbb{C}^n .

 The dot product or the standard inner product u.v of u and v is defined by

$$\mathbf{u}.\mathbf{v} = \overline{u_1}v_1 + \overline{u_2}v_2 + \ldots + \overline{u_n}v_n = \mathbf{u}^*\mathbf{v}.$$

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• Observe that $\|\alpha \mathbf{u}\| = |\alpha| \|\mathbf{u}\|$.



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- \bigstar Let $\mathbf{u}, \mathbf{v}, \mathbf{w} \in \mathbb{C}^n$ and $\mathbf{c} \in \mathbb{C}$. Then
 - $\mathbf{0} \quad \mathbf{u}.\mathbf{v} = \overline{\mathbf{v}.\mathbf{u}};$

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 - $(c\mathbf{u}).\mathbf{v} = \overline{c}(\mathbf{u}.\mathbf{v});$
 - $\mathbf{0}$ $\mathbf{u}.\mathbf{u} \geq 0$ and $\mathbf{u}.\mathbf{u} = \mathbf{0}$ if and only if $\mathbf{u} = \mathbf{0}$.

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If $S = \{v_1, v_2, ..., v_k\}$ is an orthogonal set of non-zero vectors, then S is linearly independent.

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If $S = \{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ is an orthogonal set of non-zero vectors, then S is linearly independent.

Orthogonal Basis: An orthogonal basis of a subspace *W* is a basis for *W* that is an orthogonal set.

Notice that $\{[2,1,-1]^t,[0,1,1]^t,[1,-1,1]^t\}$ is an orthogonal basis for \mathbb{R}^3 . Take $[1,1,1]^t \in \mathbb{R}^3$. Find a,b,c such that $[1,1,1]^t = a[2,1,-1]^t + b[0,1,1]^t + c[1,-1,1]^t$.

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Result

Let $\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_k\}$ be an orthogonal basis for a subspace W and let $\mathbf{w} \in W$. Then the unique scalars $\mathbf{c}_1, \mathbf{c}_2, \dots, \mathbf{c}_k$ such that $\mathbf{w} = \mathbf{c}_1 \mathbf{v}_1 + \mathbf{c}_2 \mathbf{v}_2 + \dots + \mathbf{c}_k \mathbf{v}_k$ are given by

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- A vector v is said to be orthogonal to W if v is orthogonal to every vector in W.
- The orthogonal complement of W, denoted W^{\perp} , is defined as

$$W^{\perp} = \{ \mathbf{v} \in \mathbb{C}^n : \mathbf{v}.\mathbf{w} = 0 \text{ for all } \mathbf{w} \in W \}.$$

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- Let $A = [\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k]$. Let T be an invertible matrix such that $TA = \begin{bmatrix} \frac{l_k}{0} \end{bmatrix}$. Then the last n k columns of T^* will form a basis for W^{\perp} .

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$$W = \left\{ \begin{bmatrix} x \\ y \\ z \end{bmatrix} \in \mathbb{R}^3 : x + y + z = 0 \right\}$$
. A basis for W is $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$. A basis for W^{\perp} is $\left\{ \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} \right\}$.

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 then $\mathbf{w}_1 - \mathbf{w}_2 = \mathbf{w}_2' - \mathbf{w}_1' \in W \cap W^{\perp}.$ Hence $\mathbf{w}_1 = \mathbf{w}_2$ and $\mathbf{w}_1' = \mathbf{w}_2'.$

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- Thus v can be written as a sum of a vector in W and a vector in W[⊥] uniquely.
- Consider $\mathbf{v} = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}$. Find (somehow) $\mathbf{w} \in W$ and $\mathbf{w}' \in W^{\perp}$ such that $\mathbf{v} = \mathbf{w} + \mathbf{w}'$. This \mathbf{w} is called the orthogonal projection of \mathbf{v} on W.



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Exercise

Let A and B be two $m \times n$ matrices and let the consistent linear systems $A\mathbf{x} = \mathbf{c}$ and $B\mathbf{x} = \mathbf{d}$ have the same solution set. Show that the matrix A is row equivalent to B.

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Find a basis for
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, where $W = span(\begin{bmatrix} 1\\-3\\5\\0\\5\end{bmatrix}, \begin{bmatrix} -1\\1\\2\\-2\\3\end{bmatrix}, \begin{bmatrix} 0\\-1\\4\\-1\\5\end{bmatrix})$.

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• Let W be a subspace of \mathbb{C}^n . Assume $\{\mathbf{w}_1, \dots, \mathbf{w}_n\}$ is an orthonormal basis for \mathbb{C}^n such that $\{\mathbf{w}_1, \mathbf{w}_2, \dots, \mathbf{w}_k\}$ is a basis for W and $\{\mathbf{w}_{k+1}, \dots, \mathbf{w}_n\}$ is a basis for W^{\perp} .



• Let $\mathbf{v} \in \mathbb{C}^n$. Then

$$\begin{split} \boldsymbol{v} &= \big(\boldsymbol{w}_1.\boldsymbol{v}\big)\boldsymbol{w}_1 + \ldots + \big(\boldsymbol{w}_n.\boldsymbol{v}\big)\boldsymbol{w}_n \\ &= [(\boldsymbol{w}_1.\boldsymbol{v})\boldsymbol{w}_1 + \ldots + (\boldsymbol{w}_k.\boldsymbol{v})\boldsymbol{w}_k] + [(\boldsymbol{w}_{k+1}.\boldsymbol{v})\boldsymbol{w}_{k+1} + \ldots + (\boldsymbol{w}_n.\boldsymbol{v})\boldsymbol{w}_n] = \boldsymbol{w} + \boldsymbol{w}'. \end{split}$$

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Orthogonal Projection: Let W be a subspace of \mathbb{C}^n and let $\{\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_k\}$ be an orthogonal basis for W. If $\mathbf{v} \in \mathbb{C}^n$, then the orthogonal projection of \mathbf{v} onto W is defined as

$$\text{proj}_{\mathcal{W}}(\textbf{v}) = \frac{\textbf{u}_1.\textbf{v}}{\textbf{u}_1.\textbf{u}_1} \textbf{u}_1 + \frac{\textbf{u}_2.\textbf{v}}{\textbf{u}_2.\textbf{u}_2} \textbf{u}_2 + \ldots + \frac{\textbf{u}_k.\textbf{v}}{\textbf{u}_k.\textbf{u}_k} \textbf{u}_k.$$

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The component of v orthogonal to W is the vector

$$perp_{W}(\mathbf{v}) = \mathbf{v} - proj_{W}(\mathbf{v}).$$

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• If U_i is the subspace spanned by the vector u_i , then

$$\operatorname{proj}_{W}(\mathbf{v}) = \operatorname{proj}_{U_{b}}(\mathbf{v}) + \operatorname{proj}_{U_{b}}(\mathbf{v}) + \ldots + \operatorname{proj}_{U_{b}}(\mathbf{v}).$$



Let W be a subspace of \mathbb{C}^n and let $\mathbf{v} \in \mathbb{C}^n$. Then there are unique vectors $\mathbf{w} \in W$ and $\mathbf{w}^{\perp} \in W^{\perp}$ such that $\mathbf{v} = \mathbf{w} + \mathbf{w}^{\perp}$. That is, $W \oplus W^{\perp} = \mathbb{C}^n$.

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Let S be a subspace of \mathbb{C}^n . Let $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ form a basis for S^{\perp} . Consider the $k \times n$ matrix A whose i-th row is \mathbf{v}_i^* . Show that S = null(A).

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Result

Let A be an $m \times n$ matrix. Then rank(A) + nullity(A) = n.



$$\mathbf{v}_1 = \mathbf{x}_1,$$
 $W_1 = span(\mathbf{x}_1);$

$$\begin{aligned} \mathbf{v}_1 &= \mathbf{x}_1, & W_1 &= \textit{span}(\mathbf{x}_1); \\ \mathbf{v}_2 &= \mathbf{x}_2 - \left(\frac{\mathbf{v}_1.\mathbf{x}_2}{\mathbf{v}_1.\mathbf{v}_1}\right)\mathbf{v}_1, & W_2 &= \textit{span}(\mathbf{x}_1,\mathbf{x}_2); \end{aligned}$$

$$\begin{split} \mathbf{v}_1 &= \mathbf{x}_1, & W_1 &= \textit{span}(\mathbf{x}_1); \\ \mathbf{v}_2 &= \mathbf{x}_2 - \left(\frac{\mathbf{v}_1.\mathbf{x}_2}{\mathbf{v}_1.\mathbf{v}_1}\right)\mathbf{v}_1, & W_2 &= \textit{span}(\mathbf{x}_1,\mathbf{x}_2); \\ \mathbf{v}_3 &= \mathbf{x}_3 - \left(\frac{\mathbf{v}_1.\mathbf{x}_3}{\mathbf{v}_1.\mathbf{v}_1}\right)\mathbf{v}_1 - \left(\frac{\mathbf{v}_2.\mathbf{x}_3}{\mathbf{v}_2.\mathbf{v}_2}\right)\mathbf{v}_2, & W_3 &= \textit{span}(\mathbf{x}_1,\mathbf{x}_2,\mathbf{x}_3); \end{split}$$

$$\begin{aligned} \mathbf{v}_{1} &= \mathbf{x}_{1}, & W_{1} &= span(\mathbf{x}_{1}); \\ \mathbf{v}_{2} &= \mathbf{x}_{2} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{2}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1}, & W_{2} &= span(\mathbf{x}_{1},\mathbf{x}_{2}); \\ \mathbf{v}_{3} &= \mathbf{x}_{3} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{3}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1} - \left(\frac{\mathbf{v}_{2}.\mathbf{x}_{3}}{\mathbf{v}_{2}.\mathbf{v}_{2}}\right)\mathbf{v}_{2}, & W_{3} &= span(\mathbf{x}_{1},\mathbf{x}_{2},\mathbf{x}_{3}); \\ \vdots &\vdots &\vdots &\vdots &\vdots \\ \vdots &\vdots &\vdots &\vdots &\vdots \\ \mathbf{v}_{k} &= \mathbf{x}_{k} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{k}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1} - \left(\frac{\mathbf{v}_{2}.\mathbf{x}_{k}}{\mathbf{v}_{2}.\mathbf{v}_{2}}\right)\mathbf{v}_{2} - \dots - \left(\frac{\mathbf{v}_{k-1}.\mathbf{x}_{k}}{\mathbf{v}_{k-1}.\mathbf{v}_{k-1}}\right)\mathbf{v}_{k-1}, \\ & & W_{k} &= span(\mathbf{x}_{1}, \dots, \mathbf{x}_{k}). \end{aligned}$$

Let $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k\}$ be a basis for a subspace W of \mathbb{C}^n . Define

$$\begin{aligned} \mathbf{v}_{1} &= \mathbf{x}_{1}, & W_{1} &= span(\mathbf{x}_{1}); \\ \mathbf{v}_{2} &= \mathbf{x}_{2} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{2}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1}, & W_{2} &= span(\mathbf{x}_{1},\mathbf{x}_{2}); \\ \mathbf{v}_{3} &= \mathbf{x}_{3} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{3}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1} - \left(\frac{\mathbf{v}_{2}.\mathbf{x}_{3}}{\mathbf{v}_{2}.\mathbf{v}_{2}}\right)\mathbf{v}_{2}, & W_{3} &= span(\mathbf{x}_{1},\mathbf{x}_{2},\mathbf{x}_{3}); \\ \vdots &\vdots &\vdots &\vdots &\vdots &\vdots \\ \vdots &\vdots &\vdots &\vdots &\vdots &\vdots \\ \mathbf{v}_{k} &= \mathbf{x}_{k} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{k}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1} - \left(\frac{\mathbf{v}_{2}.\mathbf{x}_{k}}{\mathbf{v}_{2}.\mathbf{v}_{2}}\right)\mathbf{v}_{2} - \dots - \left(\frac{\mathbf{v}_{k-1}.\mathbf{x}_{k}}{\mathbf{v}_{k-1}.\mathbf{v}_{k-1}}\right)\mathbf{v}_{k-1}, \\ & & W_{k} &= span(\mathbf{x}_{1}, \dots, \mathbf{x}_{k}). \end{aligned}$$

Then $\{\mathbf{v}_1, \dots, \mathbf{v}_i\}$ is an orthogonal basis for W_i , for $1 \le i \le k$.

Let $\{\mathbf{x}_1, \mathbf{x}_2, \dots, \mathbf{x}_k\}$ be a basis for a subspace W of \mathbb{C}^n . Define

$$\begin{aligned} \mathbf{v}_{1} &= \mathbf{x}_{1}, & W_{1} &= span(\mathbf{x}_{1}); \\ \mathbf{v}_{2} &= \mathbf{x}_{2} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{2}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1}, & W_{2} &= span(\mathbf{x}_{1},\mathbf{x}_{2}); \\ \mathbf{v}_{3} &= \mathbf{x}_{3} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{3}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1} - \left(\frac{\mathbf{v}_{2}.\mathbf{x}_{3}}{\mathbf{v}_{2}.\mathbf{v}_{2}}\right)\mathbf{v}_{2}, & W_{3} &= span(\mathbf{x}_{1},\mathbf{x}_{2},\mathbf{x}_{3}); \\ \vdots &\vdots &\vdots &\vdots &\vdots \\ \vdots &\vdots &\vdots &\vdots &\vdots \\ \mathbf{v}_{k} &= \mathbf{x}_{k} - \left(\frac{\mathbf{v}_{1}.\mathbf{x}_{k}}{\mathbf{v}_{1}.\mathbf{v}_{1}}\right)\mathbf{v}_{1} - \left(\frac{\mathbf{v}_{2}.\mathbf{x}_{k}}{\mathbf{v}_{2}.\mathbf{v}_{2}}\right)\mathbf{v}_{2} - \dots - \left(\frac{\mathbf{v}_{k-1}.\mathbf{x}_{k}}{\mathbf{v}_{k-1}.\mathbf{v}_{k-1}}\right)\mathbf{v}_{k-1}, \\ & & W_{k} &= span(\mathbf{x}_{1}, \dots, \mathbf{x}_{k}). \end{aligned}$$

Then $\{\mathbf{v}_1, \dots, \mathbf{v}_i\}$ is an orthogonal basis for W_i , for $1 \le i \le k$. In particular, $\{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ is an orthogonal basis for W.

$$\bullet \mathbf{v}_1 = \mathbf{x}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix},$$

$$\bullet \mathbf{v}_2 = \mathbf{x}_2 - \left(\frac{\mathbf{v}_1.\mathbf{x}_2}{\mathbf{v}_1.\mathbf{v}_1}\right)\mathbf{v}_1$$

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$$ullet$$
 $\mathbf{v}_2 = \mathbf{x}_2 - \left(\frac{\mathbf{v}_1 \cdot \mathbf{x}_2}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 = \mathbf{x}_2 - \left(\frac{-6}{3}\right) \mathbf{v}_1 =$

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$$\mathbf{v}_{1} = \mathbf{x}_{1} = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}$$
,
• $\mathbf{v}_{2} = \mathbf{x}_{2} - \left(\frac{\mathbf{v}_{1} \cdot \mathbf{x}_{2}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}}\right) \mathbf{v}_{1} = \mathbf{x}_{2} - \left(\frac{-6}{3}\right) \mathbf{v}_{1} = \begin{bmatrix} 0 \\ 3 \\ -3 \end{bmatrix} + \begin{bmatrix} 2 \\ -2 \\ 2 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix}$,
• $\mathbf{v}_{3} = \mathbf{x}_{3} - \left(\frac{\mathbf{v}_{1} \cdot \mathbf{x}_{3}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}}\right) \mathbf{v}_{1} - \left(\frac{\mathbf{v}_{2} \cdot \mathbf{x}_{3}}{\mathbf{v}_{2} \cdot \mathbf{v}_{2}}\right) \mathbf{v}_{2}$

$$= \mathbf{x}_{3} - \left(\frac{3}{2}\right) \mathbf{v}_{1} - \left(\frac{6}{6}\right) \mathbf{v}_{2}$$

$$\bullet \mathbf{v}_2 = \mathbf{x}_2 - \left(\frac{\mathbf{v}_1 \cdot \mathbf{x}_2}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 = \mathbf{x}_2 - \left(\frac{-6}{3}\right) \mathbf{v}_1 = \begin{bmatrix} 0\\3\\-3 \end{bmatrix} + \begin{bmatrix} 2\\-2\\2 \end{bmatrix} = \begin{bmatrix} 2\\1\\-1 \end{bmatrix},$$

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$$\bullet \quad \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|} = \begin{bmatrix} 1/\sqrt{3} \\ -1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}$$

$$\bullet \mathbf{v}_2 = \mathbf{x}_2 - \left(\frac{\mathbf{v}_1 \cdot \mathbf{x}_2}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 = \mathbf{x}_2 - \left(\frac{-6}{3}\right) \mathbf{v}_1 = \begin{bmatrix} 0\\3\\-3 \end{bmatrix} + \begin{bmatrix} 2\\-2\\2 \end{bmatrix} = \begin{bmatrix} 2\\1\\-1 \end{bmatrix},$$

$$\mathbf{v}_{3} = \mathbf{x}_{3} - \left(\frac{\mathbf{v}_{1} \cdot \mathbf{x}_{3}}{\mathbf{v}_{1} \cdot \mathbf{v}_{1}}\right) \mathbf{v}_{1} - \left(\frac{\mathbf{v}_{2} \cdot \mathbf{x}_{3}}{\mathbf{v}_{2} \cdot \mathbf{v}_{2}}\right) \mathbf{v}_{2}$$

$$= \mathbf{x}_{3} - \left(\frac{3}{3}\right) \mathbf{v}_{1} - \left(\frac{6}{6}\right) \mathbf{v}_{2} = \begin{bmatrix} 3 \\ 2 \\ 2 \end{bmatrix} - \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix} - \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 2 \\ 2 \end{bmatrix}.$$

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$$\bullet \ \ \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|} = \begin{bmatrix} 1/\sqrt{3} \\ -1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}, \ \ \frac{\mathbf{v}_2}{\|\mathbf{v}_2\|} = \begin{bmatrix} 2/\sqrt{6} \\ 1/\sqrt{6} \\ -1/\sqrt{6} \end{bmatrix}, \ \ \frac{\mathbf{v}_3}{\|\mathbf{v}_3\|} = \begin{bmatrix} 0 \\ 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}.$$

Apply the Gram-Schmidt process to find an orthonormal basis of the subspace spanned by $\mathbf{x}_1 = [1, -1, 1]^t$, $\mathbf{x}_2 = [0, 3, -3]^t$ and $\mathbf{x}_3 = [3, 2, 2]^t$.

$$\bullet \mathbf{v}_1 = \mathbf{x}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix},$$

$$\bullet \mathbf{v}_2 = \mathbf{x}_2 - \left(\frac{\mathbf{v}_1 \cdot \mathbf{x}_2}{\mathbf{v}_1 \cdot \mathbf{v}_1}\right) \mathbf{v}_1 = \mathbf{x}_2 - \left(\frac{-6}{3}\right) \mathbf{v}_1 = \begin{bmatrix} 0\\3\\-3 \end{bmatrix} + \begin{bmatrix} 2\\-2\\2 \end{bmatrix} = \begin{bmatrix} 2\\1\\-1 \end{bmatrix},$$

$$\begin{aligned} \bullet & \mathbf{v}_3 = \mathbf{x}_3 - \left(\frac{\mathbf{v}_1.\mathbf{x}_3}{\mathbf{v}_1.\mathbf{v}_1}\right) \mathbf{v}_1 - \left(\frac{\mathbf{v}_2.\mathbf{x}_3}{\mathbf{v}_2.\mathbf{v}_2}\right) \mathbf{v}_2 \\ &= \mathbf{x}_3 - \left(\frac{3}{3}\right) \mathbf{v}_1 - \left(\frac{6}{6}\right) \mathbf{v}_2 = \begin{bmatrix} 3\\2\\2 \end{bmatrix} - \begin{bmatrix} 1\\-1\\1 \end{bmatrix} - \begin{bmatrix} 2\\1\\-1 \end{bmatrix} = \begin{bmatrix} 0\\2\\2 \end{bmatrix}. \end{aligned}$$

$$\bullet \quad \frac{\textbf{v}_1}{\|\textbf{v}_1\|} = \begin{bmatrix} 1/\sqrt{3} \\ -1/\sqrt{3} \\ 1/\sqrt{3} \end{bmatrix}, \quad \frac{\textbf{v}_2}{\|\textbf{v}_2\|} = \begin{bmatrix} 2/\sqrt{6} \\ 1/\sqrt{6} \\ -1/\sqrt{6} \end{bmatrix}, \quad \frac{\textbf{v}_3}{\|\textbf{v}_3\|} = \begin{bmatrix} 0 \\ 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix}.$$

• Orthonormal basis is $\left\{ \begin{array}{c} 1/\sqrt{3} \\ -1/\sqrt{3} \\ 1/\sqrt{3} \end{array}, \begin{array}{c} 2/\sqrt{6} \\ 1/\sqrt{6} \\ -1/\sqrt{6} \end{array} \right[\begin{bmatrix} 0 \\ 1/\sqrt{2} \\ 1/\sqrt{2} \end{bmatrix} \right\}.$



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- The vectors in S corresponding to the elements of B are linearly independent.