

1. Fill in the blanks.

(a) If $A = \begin{bmatrix} 1 & 2 & 0 & 1 \\ 0 & a & b & 2 \\ 0 & 0 & c & 0 \end{bmatrix}$ is in RREF, then (2 pts.)

$a = \boxed{0}$ $b = \boxed{1}$ $c = \boxed{0}$

(b) If $A = \begin{bmatrix} 1 & 2 & 3 \\ 3 & 1 & 0 \\ 2 & \lambda & 6 \end{bmatrix}$, then the system $A\mathbf{x} = \mathbf{0}$ will have infinitely many solutions, if (1 pt.)

$\lambda = \boxed{4}$

(c) If $\begin{bmatrix} 1 & 3 & 0 \\ 2 & 5 & 1 \\ -3 & -9 & -1 \end{bmatrix}^{-1} = \begin{bmatrix} 4 & 3 & 3 \\ x & -1 & -1 \\ y & z & -1 \end{bmatrix}$, then (2 pts.)

$x = \boxed{-1}$ $y = \boxed{-3}$ $z = \boxed{0}$

(Partial mark for (a) and (c): 1 mark for only two correct answers.)

2. Let A be an $m \times n$ matrix with linearly independent columns.

- (a) Prove that $A^T A$ is invertible. (2 pts.)
- (b) Must AA^T also be invertible? Explain. (1 pt.)

Solution:

(a) Step 1. $x \in \text{null}(A^T A) \Rightarrow A^T A x = \mathbf{0} \Rightarrow x^T A^T A x = 0$
 $\Rightarrow (Ax)^T A x = 0 \Rightarrow Ax = \mathbf{0}$. (1 mark)

Step 2. $\Rightarrow x = \mathbf{0}$, since columns of A are LI. (1/2 mark)

Step 3. Hence $A^T A$, being a square matrix, is invertible. (1/2 mark)

Aliter to Step 1:

(1) A linear combination $A^T A y$ of columns of $A^T A$ is zero implies $A y$ is zero.

(2) The systems $A^T A x = \mathbf{0}$ and $A x = \mathbf{0}$ are equivalent.

(3) $\text{rank}(A^T A) = \text{rank}(A)$.

Marking: For any of the above: with justification 1 mark, without 1/2 mark.

(b) No.

If $m > n$, then $\text{rank}(AA^T) \leq n < m$. (1 mark)

Hence AA^T being an $m \times m$ matrix is not invertible.

Aliter: Take for example $A = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$.

Then $AA^T = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}$ is not invertible.

3. Consider the following subspaces of \mathbb{R}^3 :

$$\mathbb{U} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : x_1 = 2x_3 - x_2, 2x_2 = x_3 \right\} \text{ and } \mathbb{W} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} : x_1 = 2x_3 - x_2 \right\}.$$

(a) Find a vector \mathbf{u} such that $\text{span}\{\mathbf{u}\} = \mathbb{U}$. (1 pt.)

(b) Find a vector \mathbf{v} such that $\text{span}\{\mathbf{u}, \mathbf{v}\} = \mathbb{W}$. (1 pt.)

Solution:

(a) Solving the system $x_1 = 2x_3 - x_2$, $2x_2 = x_3$, we get $\mathbb{U} = \left\{ t \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix} : t \in \mathbb{R} \right\}$.

So, $\mathbf{u} = \begin{bmatrix} 3 \\ 1 \\ 2 \end{bmatrix}$ (or any scalar multiple of this). (1 mark)

(For giving a correct \mathbf{u} without any justification - 1/2 mark)

(b) $\mathbb{W} = \left\{ t \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} + s \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} : s, t \in \mathbb{R} \right\}$. (1/2 mark)

You can take $\mathbf{v} = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$ or $\begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ or any nonzero linear combination of these two vectors which is not a scalar multiple of \mathbf{u} . (1/2 mark)

(For giving a correct \mathbf{v} without any justification - 1/2 mark)

4. Prove or disprove: There exists a linear transformation T from $\mathbb{R}^4 \rightarrow \mathbb{R}^3$ such that (2 pts.)

$$\text{range}(T) = \{[x, y, z]^T : x + y + z = 0\} \text{ and } \ker(T) = \{[x, y, z, w]^T : x + y - 2z = 0\}.$$

Solution:

Step 1. $\text{rank}(T) = 2$ (with or without justification). (1/2 mark)

Step 2. $\text{nullity}(T) = 3$ (with or without justification). (1/2 mark)

Step 3. By rank-nullity theorem,

$$4 = \text{rank}(T) + \text{nullity}(T) = 5, \quad (1 \text{ mark})$$

which is not possible.

(No mark for just stating that the statement is FALSE. Wrong justification in any of the steps invites deduction of mark.)

5. Prove or disprove: If A and B are non-square matrices such that both AB and BA are defined, then either AB or BA has zero as an eigenvalue. (2 pts.)

Solution: Suppose A is an $m \times n$ matrix, where $m \neq n$. Then B is an $n \times m$ matrix. (1/2 mark)

Suppose $m > n$, then $\text{rank}(AB) \leq \min\{m, n\} = n < m$. (1 mark)

Hence, 0 is an eigenvalue of AB (because AB is $m \times m$ with $\text{rank} < m$.) (1/2 mark)

Similarly, if $n > m$, then 0 is an eigenvalue of BA .

6. Let $\mathbb{R}_4[x]$ be the vector space of all real polynomials of degree less than or equal to 4.

(a) Show that $\mathbb{W} = \{p(x) \in \mathbb{R}_4[x] : p''(0) = 2p(0)\}$ is a subspace of $\mathbb{R}_4[x]$. (1 pt.)

(b) Find the dimension of \mathbb{W} . (2 pts.)

Solution:

(a) $\mathbb{W} \neq \emptyset$, because the zero polynomial is in \mathbb{W} .

For $p_1, p_2 \in \mathbb{W}$, $\alpha, \beta \in \mathbb{R}$,

$$\begin{aligned} (\alpha p_1 + \beta p_2)''(0) &= \alpha p_1''(0) + \beta p_2''(0) \\ &= 2(\alpha p_1(0) + \beta p_2(0)) \\ &= 2(\alpha p_1 + \beta p_2)(0). \end{aligned} \quad (1 \text{ mark})$$

(Alternatively, you may show $p_1 + p_2 \in \mathbb{W}$ and $\alpha p \in \mathbb{W}$ for any $p_1, p_2 \in \mathbb{W}$ and $\alpha \in \mathbb{R}$. Then, 1/2 mark for each of these two steps is awarded.)

Thus, $\alpha p_1 + \beta p_2 \in \mathbb{W}$ and so \mathbb{W} is a subspace.

Aliter:

If you show $\mathbb{W} = \{p(x) = a_0(1 + x^2) + a_1x + a_3x^3 + a_4x^4 : a_0, a_1, a_3, a_4 \in \mathbb{R}\}$, as in part (b) below, and then justify that \mathbb{W} is a subspace using this.

(b) If $p(x) = a_0 + a_1x + a_2x^2 + a_3x^3 + a_4x^4$, then $p''(0) = 2p(0) \Rightarrow a_0 = a_2$. (1 mark)

Then $\mathbb{W} = \{p(x) = a_0(1 + x^2) + a_1x + a_3x^3 + a_4x^4 : a_0, a_1, a_3, a_4 \in \mathbb{R}\}$

Therefore $\dim(\mathbb{W}) = 4$. (1 mark)

Aliter:

(a) $T : \mathbb{R}_4[x] \rightarrow \mathbb{R}$ defined as $T(p) = p''(0) - 2p(0)$ is a LT. (1/2 mark)

$\mathbb{W} = \ker(T)$, and therefore is a subspace of $\mathbb{R}_4[x]$. (1/2 mark)

(b) $\text{rank}(T) = 1$, since $\text{range}(T) = \mathbb{R}$. (1 mark)

Since $\dim(\mathbb{R}_4[x]) = 5$, by rank-nullity theorem,

$\dim(\mathbb{W}) = \text{nullity}(T) = 4$. (1 mark)

7. Let $\mathcal{M}_2(\mathbb{R})$ denote the vector space of all 2×2 real matrices. Let $T : \mathcal{M}_2(\mathbb{R}) \rightarrow \mathcal{M}_2(\mathbb{R})$ be defined by $T(A) = A + A^T$.

(a) Show that T is a linear transformation. (1 pt.)

(b) Find a basis for $\text{range}(T)$ and a basis for $\ker(T)$. (2 pts.)

Solution:

(a) For $A, B \in \mathcal{M}_2(\mathbb{R})$ and $\alpha \in \mathbb{R}$,

$$\begin{aligned} T(A + B) &= (A + B) + (A + B)^T = (A + A^T) + (B + B^T) \\ &= T(A) + T(B). \end{aligned} \quad (1/2 \text{ mark})$$

$$T(\alpha A) = \alpha A + (\alpha A)^T = \alpha(A + A^T) = \alpha T(A). \quad (1/2 \text{ mark})$$

(Alternatively, showing $T(\alpha A + \beta B) = \alpha T(A) + \beta T(B)$. (1 mark))

Hence T is a LT.

(b) If $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, then $T(A) = A + A^T = \begin{bmatrix} 2a & b+c \\ b+c & 2d \end{bmatrix}$. Therefore,

$$\text{range}(T) = \left\{ \begin{bmatrix} 2a & b+c \\ b+c & 2d \end{bmatrix} : a, b, c, d \in \mathbb{R} \right\}.$$

Thus, $A \in \text{range}(T) \Leftrightarrow A$ is symmetric. (1/2 mark)

A basis for $\text{range}(T) = \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 \\ 0 & 1 \end{bmatrix} \right\}$. (1/2 mark)

(For writing the basis without any justification also gets full 1 mark.)

$\dim(\ker(T)) = 1$ (by rank nullity theorem). (1/2 mark)

A basis for $\ker(T) = \left\{ \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix} \right\}$. (1/2 mark)

(For writing the basis without any justification also gets full 1 mark.)

8. Consider the 10×10 matrix $A = \mathbf{xy}^T$, where $\mathbf{x} = \begin{bmatrix} 1 \\ 2 \\ \vdots \\ 9 \\ 10 \end{bmatrix}$ and $\mathbf{y} = \begin{bmatrix} -1 \\ -1 \\ \vdots \\ -1 \\ -1 \end{bmatrix}$.

- (a) Show that A is diagonalizable. (2 pts.)
- (b) Find two eigenvectors corresponding to two distinct eigenvalues of A . (2 pts.)

Solution:

- (a) $\text{rank}(A) = 1$, and hence $\text{nullity}(A) = 9$. (1/2 mark)

So 0 is an eigenvalue of A with geometric multiplicity 9 (i.e., A has 9 LI eigenvectors corresponding to the eigenvalue 0). (1/2 mark)

$\mathbf{y}^T \mathbf{x} \neq 0$ is another eigenvalue of A . (1/2 mark)

Thus, for each eigenvalue of A , geometric multiplicity equals its algebraic multiplicity. (1/2 mark)

(i.e., A has ten LI eigenvectors.)

Hence, A is diagonalizable.

(Alternatively, one can actually find a matrix P (e.g., finding ten LI eigenvectors) and a diagonal matrix D such that $AP = PD$. One can take P as

$$P = \begin{bmatrix} 1 & 1 & \dots & 1 & 1 \\ -1 & 0 & \dots & 0 & 2 \\ 0 & -1 & \dots & 0 & 3 \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \dots & -1 & 10 \end{bmatrix}.$$

(Appropriate marks are awarded.)

- (b) Note that $\mathbf{y}^T \mathbf{x}$ is a scalar, and therefore, $(\mathbf{xy}^T)\mathbf{x} = \mathbf{x}(\mathbf{y}^T \mathbf{x}) = (\mathbf{y}^T \mathbf{x})\mathbf{x}$, i.e., \mathbf{x} is an eigenvector of A corresponding to eigenvalue $\mathbf{y}^T \mathbf{x} \neq 0$. (1 mark)

For an eigenvector corresponding to 0, any \mathbf{z} such that $\sum_{i=1}^{10} z_i = 0$ will be an eigenvector.

For example $\mathbf{z} = [1, -1, 0, \dots, 0]^T$. (1 mark)

9. Applying Gram-Schmidt process to $\left\{ \mathbf{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \mathbf{v}_2 = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}, \mathbf{v}_3 = \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$ find an orthonormal basis of \mathbb{R}^3 . (2 pts.)

Solution:

$$\mathbf{w}_1 = \frac{\mathbf{v}_1}{\|\mathbf{v}_1\|} = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}. \quad (1/2 \text{ mark})$$

$$\mathbf{u}_2 = \mathbf{v}_2 - (\mathbf{w}_1 \cdot \mathbf{v}_2) \mathbf{w}_1.$$

$$= \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \quad (1/2 \text{ mark})$$

$$\text{Therefore } \mathbf{w}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}.$$

$$\mathbf{u}_3 = \mathbf{v}_3 - (\mathbf{w}_1 \cdot \mathbf{v}_3) \mathbf{w}_1 - (\mathbf{w}_2 \cdot \mathbf{v}_3) \mathbf{w}_2. \quad (1/2 \text{ mark})$$

$$= \frac{1}{2} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix}.$$

$$\mathbf{w}_3 = \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ -\frac{1}{\sqrt{2}} \end{bmatrix}. \quad (1/2 \text{ mark})$$

(For finding an **orthogonal** basis in stead of **orthonormal** only partial mark is awarded.)

10. Let $T : \mathbb{R}^5 \rightarrow \mathbb{R}^5$ be defined by $T \begin{pmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \end{pmatrix} = \begin{pmatrix} x_2 \\ x_3 \\ x_4 \\ x_5 \\ 0 \end{pmatrix}$. Consider the ordered bases

$\mathcal{B} = \{\mathbf{e}_1, \mathbf{e}_2, \mathbf{e}_3, \mathbf{e}_4, \mathbf{e}_5\}$ and $\mathcal{C} = \{\mathbf{e}_5, \mathbf{e}_4, \mathbf{e}_3, \mathbf{e}_2, \mathbf{e}_1\}$ of \mathbb{R}^5 .

- (a) Find the matrix $[T]_{\mathcal{C} \leftarrow \mathcal{B}}$ of T with respect to the bases \mathcal{B} and \mathcal{C} . (2 pts.)
- (b) Find the change of basis matrix (also known as transition matrix) $P_{\mathcal{C} \leftarrow \mathcal{B}}$. (1 pt.)
- (c) Find $\text{rank}(T)$ and $\text{nullity}(T)$. (1 pt.)

Solution:

(a) $[T]_{\mathcal{C} \leftarrow \mathcal{B}} = [[T(\mathbf{e}_1)]_{\mathcal{C}}, \dots, [T(\mathbf{e}_5)]_{\mathcal{C}}]$. (1 mark)

$$= \begin{bmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \end{bmatrix}. \quad (1 \text{ mark})$$

(If only the matrix $[T]_{\mathcal{C} \leftarrow \mathcal{B}}$ is written correctly without doing the first step (that is without writing the form), then also gets full 2 marks.)

(b) $P_{\mathcal{C} \leftarrow \mathcal{B}} = \begin{bmatrix} 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 1 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 \end{bmatrix}$. (1 mark)

(c) $\text{rank}(T) = 4$. (1/2 mark)

$\text{nullity}(T) = 1$. (1/2 mark)