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INDIAN INSTITUTE OF TECHNOLOGY GUWAHATI
MA101 MATHEMATICS-I
Solutions to Tutorial - 5
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1. Show that any two similar matrices have the same trace.

Solution: Let A and B are similar matrices. Therefore, \exists an invertible matrix P such that

$$P^{-1}AP = B.$$

We know that for any two $n \times n$ matrix X, Y

$$\text{tr}(XY) = \text{tr}(YX).$$

Therefore,

$$\text{tr}(B) = \text{tr}(P^{-1}AP) = \text{tr}(AP^{-1}P) = \text{tr}(A).$$

Alter: Since similar matrices have the same characteristic polynomial, so all the eigenvalues are equal for both A and B . Suppose $\{\lambda_1, \dots, \lambda_n\}$ (not necessarily distinct) be the set of eigenvalues for both A and B . Then we have

$$\text{tr}(A) = \sum_i \lambda_i = \text{tr}(B).$$

2. Let A be an invertible matrix. Prove that if A is diagonalizable, then so is A^{-1} .

Solution: Let A be an $n \times n$ matrix with eigenvalues $\lambda_1, \dots, \lambda_n$ (need not be all distinct). Since A is invertible, so $\lambda_i \neq 0 \forall i$ and hence λ_i^{-1} exists for all i . A is diagonalizable $\Rightarrow \exists$ a non-singular matrix P such that

$$\begin{aligned} P^{-1}AP &= D = \text{diag}\{\lambda_1, \dots, \lambda_n\} \\ \Rightarrow (P^{-1}AP)^{-1} &= D^{-1} = \text{diag}\{\lambda_1^{-1}, \dots, \lambda_n^{-1}\} \\ \Rightarrow P^{-1}A^{-1}P &= D^{-1}. \end{aligned}$$

So A^{-1} is similar to a diagonal matrix D^{-1} i.e. A^{-1} is diagonalizable.

3. Let A be a diagonalizable matrix such that characteristic polynomial of A has only one root. Then find out the diagonal matrix D such that $A \sim D$. Is such a matrix D unique?

Solution: Since A is diagonalizable so there exists an invertible matrix P such that

$$P^{-1}AP = D = \text{diag}\{\lambda_1, \dots, \lambda_n\}.$$

Also since the characteristic polynomial has only one root (λ^* say), so

$$P^{-1}AP = D = \text{diag}\{\lambda^*, \dots, \lambda^*\} = \lambda^* I_n,$$

which is unique. (assuming A to be an $n \times n$ matrix)
(Note that, $A = \lambda^* I_n$. Such matrix is called **Scalar Matrix**.)

4. With the help of diagonalization, calculate A^{2015} where

$$A = \begin{bmatrix} -1 & 0 & 1 \\ 3 & 0 & -3 \\ 1 & 0 & -1 \end{bmatrix}.$$

Solution: On solving the characteristic equation, we get the eigenvalues of A to be: $0, 0$ and -2 . Also the eigenvectors corresponding to these eigenvalues are respectively

$$\left\{ \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 3 \\ 1 \end{bmatrix} \right\}.$$

So A is diagonalizable and for $P = \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 3 \\ 0 & 1 & 1 \end{bmatrix}$ we have

$$P^{-1}AP = \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -2 \end{bmatrix} \Rightarrow A = PDP^{-1} \Rightarrow A^{2015} = PD^{2015}P^{-1}.$$

Since $P^{-1} = \begin{bmatrix} \frac{3}{2} & 1 & -\frac{3}{2} \\ \frac{1}{2} & 0 & \frac{1}{2} \\ -\frac{1}{2} & 0 & \frac{1}{2} \end{bmatrix}$, so we have

$$A^{2015} = P \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -2 \end{bmatrix} P^{-1} = \begin{bmatrix} -2^{2014} & 0 & 2^{2014} \\ 3 \cdot 2^{2014} & 0 & -3 \cdot 2^{2014} \\ 2^{2014} & 0 & -2^{2014} \end{bmatrix}.$$

5. Let A be an $n \times n$ matrix and let $P(\lambda) = \lambda^n + a_{n-1}\lambda^{n-1} + \dots + a_0$ be the characteristic polynomial of A . Then show that $P(A) = A^n + a_{n-1}A^{n-1} + \dots + a_0I_n$ is the zero matrix if

- (a) A is a diagonal matrix.
- (b) A is a diagonalizable matrix.

[Cayley Hamilton theorem states, this statement holds for any square matrix.]

Solution:

- (a) Suppose $A = \text{diag}\{a_1, \dots, a_n\}$ is a diagonal matrix with characteristic polynomial $P(\lambda)$. Then a_i (for $i = 1, \dots, n$) being roots of the characteristic polynomial, $P(a_i) = 0$ for all $1 \leq i \leq n$. Therefore we have

$$P(A) = \text{diag}\{P(a_1), \dots, P(a_n)\} = \text{diag}\{0, \dots, 0\} = \mathbf{0}.$$

- (b) Suppose A is diagonalizable. Then $A \sim D$, where $D = \text{diag}\{\lambda_1, \dots, \lambda_n\}$ is a diagonal matrix. Therefore \exists a non-singular matrix X such that $X^{-1}AX = D \Rightarrow A = XDX^{-1}$. But since similar matrices have the same characteristic polynomial, and the same set of eigenvalues therefore

$$P(A) = P(XDX^{-1}) = XP(D)X^{-1} = \mathbf{0}.$$

(Note that, $A^k = (XDX^{-1})^k = XD^kX^{-1}$ for all $0 \leq k \leq n$)

6. (a) For any $u, v \in \mathbb{R}^n$, show that $|u \cdot v| \leq \|u\| \|v\|$ (Cauchy Schwartz inequality).
 (b) For any $u, v \in \mathbb{R}^n$, show that $\|u + v\| \leq \|u\| + \|v\|$ (Triangle inequality).

Solution:

- (a) Note that, if \mathbf{u}, \mathbf{v} are scalar multiple of each other, i.e. $\mathbf{v} = \lambda \mathbf{u}$ (or vice versa), then

$$LHS = |\mathbf{u} \cdot \lambda \mathbf{u}| = |\lambda| \|\mathbf{u}\|^2 = \|\mathbf{u}\| \|\mathbf{v}\| = RHS, \quad (1)$$

and we are done.

Suppose \mathbf{u} and \mathbf{v} are linearly independent. Let $t \in \mathbb{R}$. Consider

$$\begin{aligned} 0 < \langle t\mathbf{u} + \mathbf{v}, t\mathbf{u} + \mathbf{v} \rangle &= t^2 \langle \mathbf{u}, \mathbf{u} \rangle + 2t \langle \mathbf{u}, \mathbf{v} \rangle + \langle \mathbf{v}, \mathbf{v} \rangle \\ &= t^2 \|\mathbf{u}\|^2 + 2t \langle \mathbf{u}, \mathbf{v} \rangle + \|\mathbf{v}\|^2 \end{aligned}$$

Since \mathbf{u}, \mathbf{v} are linearly independent, the quadratic equation in t given by

$$t^2 \|\mathbf{u}\|^2 + 2t \langle \mathbf{u}, \mathbf{v} \rangle + \|\mathbf{v}\|^2 = 0$$

cannot have a real root, which implies

$$4 \langle \mathbf{u}, \mathbf{v} \rangle^2 - 4 \|\mathbf{u}\|^2 \|\mathbf{v}\|^2 < 0 \implies |\mathbf{u} \cdot \mathbf{v}| < \|\mathbf{u}\| \|\mathbf{v}\|. \quad (2)$$

From (1) and (2) the result follows.

- (b) We will use Cauchy Schwartz inequality to prove this part.

$$\begin{aligned} (\|u\| + \|v\|)^2 &= \|u\|^2 + \|v\|^2 + 2\|u\| \|v\| \\ &\geq \|u\|^2 + \|v\|^2 + 2|u \cdot v| \quad (\text{Cauchy Schwartz inequality}) \\ &\geq \|u\|^2 + \|v\|^2 + 2(u \cdot v) \\ &= \|u + v\|^2 \\ \implies \|u\| + \|v\| &\geq \|u + v\|. \quad (\because \text{both quantities are non-negative}) \end{aligned}$$

7. Let A be a real symmetric matrix.

- (a) Show that all the eigenvalues of A are real.
 (b) Show that any two eigenvectors corresponding to distinct eigenvalues are orthogonal.

Solution: A is real & symmetric $\Rightarrow A^* = \overline{A}^T = A$.

- (a) Let $\lambda \in \mathbb{C}$ be an eigenvalue of $A \in \mathbb{R}^{n \times n}$. A is real and symmetric i.e. $A^* = A$. Therefore,

$$\begin{aligned} Au = \lambda u &\Rightarrow (Au)^* = \lambda^* u^* \\ &\Rightarrow u^* A^* = \lambda^* u^* \Rightarrow u^* A = \lambda^* u^* \\ &\Rightarrow (u^* A)u = (\lambda^* u^*)u \Rightarrow u^*(\lambda u) = \lambda^* \|u\|^2 \quad (\text{since } Au = \lambda u) \\ &\Rightarrow \lambda \|u\| = \lambda^* \|u\| \\ &\Rightarrow \lambda = \lambda^* \quad (\text{since } u \text{ is non-zero}) \\ &\Rightarrow \lambda \in \mathbb{R}. \end{aligned}$$

- (b) Let λ_1, λ_2 ($\lambda_1 \neq \lambda_2$) are two eigenvalues of A and the corresponding eigenvectors are u_1, u_2 respectively. Then

$$Au_1 = \lambda_1 u_1 \quad Au_2 = \lambda_2 u_2.$$

Now,

$$\begin{aligned} \lambda_1 u_2^T u_1 &= u_2^T (Au_1) = (u_2^T A) u_1 \\ &= (A^T u_2)^T u_1 = (Au_2)^T u_1 \quad (\text{since } A^T = A) \\ &= \lambda_2 u_2^T u_1 \\ \Rightarrow \lambda_1 u_2^T u_1 &= \lambda_2 u_2^T u_1 \\ \Rightarrow (\lambda_1 - \lambda_2) u_2^T u_1 &= 0 \Rightarrow u_2^T u_1 = 0. \end{aligned}$$

This completes the proof. □

8. If A and B are $n \times n$ matrices with n distinct eigenvalues. Then show that $AB = BA$ if and only if A and B have the same eigenvectors.

Solution: Suppose, A has distinct eigenvalues $\lambda_1, \dots, \lambda_n$ and the corresponding eigenvectors v_1, \dots, v_n respectively. Also let B has distinct eigenvalues μ_1, \dots, μ_n and the corresponding eigenvectors u_1, \dots, u_n respectively. Also suppose $AB = BA$. Then we have

$$\begin{aligned} ABu_i &= A(\mu_i u_i) \\ \Rightarrow BAu_i &= \mu_i (Au_i) \quad (\because AB = BA) \end{aligned}$$

This implies that, if $Au_i \neq 0$ then Au_i is an eigenvector of B corresponding to the eigenvalue μ_i . Otherwise if $Au_i = 0$ then, u_i is an eigenvector of A corresponding to the eigenvalue 0. But since all the μ_i 's are distinct, so dimension of each eigenspace is 1 and therefore

$$Au_i = cu_i \quad \text{for some } c \in \{\lambda_1, \dots, \lambda_n\}.$$

Hence u_i is an eigenvector of A .

Conversely, suppose A and B both have same set of eigenvectors v_1, \dots, v_n i.e.

$$Av_i = \lambda_i v_i \quad Bv_i = \mu_i v_i \quad \text{for } i = 1, \dots, n$$

where all λ_i 's are distinct and also all μ_i 's are distinct. Then we have

$$(AB)v_i = A(\mu_i v_i) = \mu_i (Av_i) = \mu_i \lambda_i v_i = \lambda_i (\mu_i v_i) = \lambda_i Bv_i = B(\lambda_i v_i) = (BA)v_i,$$

for all $i = 1, \dots, n$.

This implies $AB = BA$.

9. Find an orthogonal basis for \mathbb{R}^4 containing the vectors: $\mathbf{v}_1 = [1 \ -1 \ 1 \ -1]^T$ and $\mathbf{v}_2 = [1 \ 1 \ 1 \ 1]^T$.

Remark 1. A set of orthogonal vectors can be extended to a basis.

Solution: Let us first extend this set to a basis of \mathbb{R}^4 . Then by Gram-Schmidt process, we can find a orthogonal basis.

Clearly, $\mathbf{v}_3 = [1 \ 0 \ 0 \ 0]^T$ and $\mathbf{v}_4 = [0 \ 1 \ 0 \ 0]^T$ extend the given set of vectors to a basis of

\mathbb{R}^4 .

By Gram-Schmidt process, we get

$$\begin{aligned}
\mathbf{u}_1 &= \mathbf{v}_1 \\
\mathbf{u}_2 &= \mathbf{v}_2 - \frac{\langle \mathbf{u}_1, \mathbf{v}_2 \rangle}{\|\mathbf{u}_1\|^2} \mathbf{u}_1 = \mathbf{v}_2 \quad (\because \langle \mathbf{u}_1, \mathbf{v}_2 \rangle = 0) \\
\mathbf{u}_3 &= \mathbf{v}_3 - \frac{\langle \mathbf{u}_1, \mathbf{v}_3 \rangle}{\|\mathbf{u}_1\|^2} \mathbf{u}_1 - \frac{\langle \mathbf{u}_2, \mathbf{v}_3 \rangle}{\|\mathbf{u}_2\|^2} \mathbf{u}_2 \\
&= \mathbf{v}_3 - \frac{1}{4} \mathbf{u}_1 - \frac{1}{4} \mathbf{u}_2 = \begin{bmatrix} \frac{1}{2} & 0 & -\frac{1}{2} & 0 \end{bmatrix}^T \\
\mathbf{u}_4 &= \mathbf{v}_4 - \frac{\langle \mathbf{u}_1, \mathbf{v}_4 \rangle}{\|\mathbf{u}_1\|^2} \mathbf{u}_1 - \frac{\langle \mathbf{u}_2, \mathbf{v}_4 \rangle}{\|\mathbf{u}_2\|^2} \mathbf{u}_2 - \frac{\langle \mathbf{u}_3, \mathbf{v}_4 \rangle}{\|\mathbf{u}_3\|^2} \mathbf{u}_3 \\
&= \mathbf{v}_4 + \frac{1}{4} \mathbf{u}_1 - \frac{1}{4} \mathbf{u}_2 - 0 \mathbf{u}_3 = \begin{bmatrix} 0 & \frac{1}{2} & 0 & -\frac{1}{2} \end{bmatrix}^T
\end{aligned}$$

Then $\{\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3, \mathbf{u}_4\}$ is a required basis.

10. Let W be the row space of the matrix

$$\begin{bmatrix} 2 & 1 & 2 & 1 & 2 \\ 1 & 2 & 1 & 2 & 1 \\ 3 & 1 & 3 & 1 & 3 \\ 1 & 3 & 1 & 3 & 1 \\ 1 & 4 & 1 & 4 & 1 \end{bmatrix}.$$

Compute W^\perp and the orthogonal decomposition of the vector $\mathbf{v} = [1 \ 2 \ 3 \ 4 \ 5]$ with respect to W .

Solution: Since $W = \text{row}(A)$, so $W^\perp = \text{null}(A)$. Therefore

$$\begin{aligned}
&\begin{bmatrix} 2 & 1 & 2 & 1 & 2 \\ 1 & 2 & 1 & 2 & 1 \\ 3 & 1 & 3 & 1 & 3 \\ 1 & 3 & 1 & 3 & 1 \\ 1 & 4 & 1 & 4 & 1 \end{bmatrix} \begin{matrix} R_3 \leftarrow R_3 - R_1 \\ R_4 \leftarrow R_4 - R_2 \\ R_5 \leftarrow R_5 - R_2 \end{matrix} \begin{bmatrix} 2 & 1 & 2 & 1 & 2 \\ 1 & 2 & 1 & 2 & 1 \\ 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 2 & 0 & 2 & 0 \end{bmatrix} \begin{matrix} R_1 \leftarrow R_1 - 2R_3 \\ R_2 \leftarrow R_2 - R_3 \\ R_5 \leftarrow R_5 - 2R_4 \end{matrix} \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 0 & 2 & 0 & 2 & 0 \\ 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \\
&\begin{matrix} R_2 \leftarrow R_2 - 2R_1 \\ R_4 \leftarrow R_4 - R_1 \end{matrix} \begin{bmatrix} 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix} \begin{matrix} R_2 \leftrightarrow R_1 \\ R_1 \leftrightarrow R_3 \end{matrix} \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}.
\end{aligned}$$

Therefore x_3, x_4, x_5 are free variables. Let

$$x_3 = s, \quad x_4 = t, \quad x_5 = r.$$

Therefore $x_1 = -x_3 - x_5 = -s - r$, and $x_2 = -x_4 = -t$.

Hence we have

$$W^\perp = \left\{ \begin{bmatrix} -s-r \\ -t \\ s \\ t \\ r \end{bmatrix} = s \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} + r \begin{bmatrix} -1 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} = su_1 + tu_2 + ru_3 : s, t, r \in \mathbb{R} \right\}$$

Here $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3$ forms a basis of W^\perp . We need to have an orthogonal basis. First two are already orthogonal. By Gram-Schmidt process, we get

$$\mathbf{u}_3' = \mathbf{u}_3 - \frac{\langle \mathbf{u}_1, \mathbf{u}_3 \rangle}{\|\mathbf{u}_1\|^2} \mathbf{u}_1 - \frac{\langle \mathbf{u}_2, \mathbf{u}_3 \rangle}{\|\mathbf{u}_2\|^2} \mathbf{u}_2 = \begin{bmatrix} -\frac{1}{2} & 0 & -\frac{1}{2} & 0 & 1 \end{bmatrix}^T$$

By the orthogonal decomposition theorem, we can write

$$\mathbf{v} = \text{proj}_{W^\perp}(\mathbf{v}) + \text{perp}_{W^\perp}(\mathbf{v}).$$

Since an orthogonal basis of W^\perp is given by $\mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3'$, hence

$$\begin{aligned} \text{proj}_{W^\perp}(\mathbf{v}) &= \text{proj}_{\mathbf{u}_1}(\mathbf{v}) + \text{proj}_{\mathbf{u}_2}(\mathbf{v}) + \text{proj}_{\mathbf{u}_3'}(\mathbf{v}) \\ &= \frac{\langle \mathbf{u}_1, \mathbf{v} \rangle}{\|\mathbf{u}_1\|^2} \mathbf{u}_1 + \frac{\langle \mathbf{u}_2, \mathbf{v} \rangle}{\|\mathbf{u}_2\|^2} \mathbf{u}_2 + \frac{\langle \mathbf{u}_3', \mathbf{v} \rangle}{\|\mathbf{u}_3'\|^2} \mathbf{u}_3' \\ &= (1)\mathbf{u}_1 + (1)\mathbf{u}_2 + (2)\mathbf{u}_3' \\ &= [-2 \quad -1 \quad 0 \quad 1 \quad 2]^T \\ \Rightarrow \text{perp}_W(\mathbf{v}) &= \mathbf{v} - \text{proj}_{W^\perp}(\mathbf{v}) \\ &= [3 \quad 3 \quad 3 \quad 3 \quad 3]^T. \end{aligned}$$

11. Let $S = \{\mathbf{v}_1, \dots, \mathbf{v}_k\}$ be an orthonormal set in \mathbb{R}^n . Let $\mathbf{x} \in \mathbb{R}^n$ be a vector. Then show that

$$\|\mathbf{x}\|^2 \geq |\mathbf{x} \cdot \mathbf{v}_1|^2 + |\mathbf{x} \cdot \mathbf{v}_2|^2 + \dots + |\mathbf{x} \cdot \mathbf{v}_k|^2.$$

Also show that the above becomes an equality if and only if $x \in \text{Span}(S)$.

Solution: Since every orthonormal set in \mathbb{R}^n can be extended to a basis of \mathbb{R}^n , therefore let $\{\mathbf{v}_1, \dots, \mathbf{v}_k, \mathbf{u}_{k+1}, \dots, \mathbf{u}_n\}$ be a orthogonal basis of \mathbb{R}^n . (This is possible by Gram-Schmidt process)

Then for any $\mathbf{x} \in \mathbb{R}^n$ we can write

$$\begin{aligned} \mathbf{x} &= \text{proj}_{\mathbf{v}_1}(\mathbf{x}) + \dots + \text{proj}_{\mathbf{v}_k}(\mathbf{x}) + \text{proj}_{\mathbf{u}_{k+1}}(\mathbf{x}) + \dots + \text{proj}_{\mathbf{u}_n}(\mathbf{x}) \\ &= \frac{\langle \mathbf{v}_1, \mathbf{x} \rangle}{\|\mathbf{v}_1\|^2} \mathbf{v}_1 + \dots + \frac{\langle \mathbf{v}_k, \mathbf{x} \rangle}{\|\mathbf{v}_k\|^2} \mathbf{v}_k + \frac{\langle \mathbf{u}_{k+1}, \mathbf{x} \rangle}{\|\mathbf{u}_{k+1}\|^2} \mathbf{u}_{k+1} + \dots + \frac{\langle \mathbf{u}_n, \mathbf{x} \rangle}{\|\mathbf{u}_n\|^2} \mathbf{u}_n \\ &= \langle \mathbf{v}_1, \mathbf{x} \rangle \mathbf{v}_1 + \dots + \langle \mathbf{v}_k, \mathbf{x} \rangle \mathbf{v}_k + \frac{\langle \mathbf{u}_{k+1}, \mathbf{x} \rangle}{\|\mathbf{u}_{k+1}\|^2} \mathbf{u}_{k+1} + \dots + \frac{\langle \mathbf{u}_n, \mathbf{x} \rangle}{\|\mathbf{u}_n\|^2} \mathbf{u}_n \\ &\quad (\text{since } S \text{ is an orthonormal set, so } \|\mathbf{v}_i\| = 1 \text{ for all } 1 \leq i \leq n) \\ \Rightarrow \|\mathbf{x}\|^2 &= |\mathbf{x} \cdot \mathbf{v}_1|^2 + |\mathbf{x} \cdot \mathbf{v}_2|^2 + \dots + |\mathbf{x} \cdot \mathbf{v}_k|^2 + \underbrace{|\mathbf{x} \cdot \mathbf{u}_{k+1}|^2 + \dots + |\mathbf{x} \cdot \mathbf{u}_n|^2}_{(\geq 0)} \\ &\geq |\mathbf{x} \cdot \mathbf{v}_1|^2 + |\mathbf{x} \cdot \mathbf{v}_2|^2 + \dots + |\mathbf{x} \cdot \mathbf{v}_k|^2. \end{aligned}$$

This completes the proof.

12. Let A be a 2×2 orthogonal matrix. Show that there exists a real number θ such that

$$A = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix} \quad \text{or} \quad A = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix}.$$

In the first case, A rotates the vectors of \mathbb{R}^2 by the angle θ counter-clockwise, and in the second case, A reflects the vectors of \mathbb{R}^2 about a line; in this case find the line.

Solution: Let $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$. Since A is orthogonal, therefore

$$AA^T = I_2 \Rightarrow \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} a & c \\ b & d \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \Rightarrow a^2 + b^2 = 1 = c^2 + d^2, ac + bd = 0.$$

Take $a = \cos \theta, b = \sin \theta$ and $c = \cos \phi, d = \sin \phi$.

From this $ac + bd = 0 \Rightarrow \cos \theta \cos \phi + \sin \theta \sin \phi = 0 \Rightarrow \cos(\theta - \phi) = 0 \Rightarrow \theta - \phi = \frac{\pi}{2}, -\frac{\pi}{2}$.

Case 1: $\theta - \phi = -\frac{\pi}{2} \Rightarrow \phi = (\frac{\pi}{2} + \theta)$. In this case,

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ \cos \phi & \sin \phi \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix},$$

which rotates the vectors of \mathbb{R}^2 by the angle θ counter-clockwise.

Case 2: $\theta - \phi = \frac{\pi}{2} \Rightarrow \phi = -(\frac{\pi}{2} - \theta)$. In this case,

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ \cos \phi & \sin \phi \end{bmatrix} = \begin{bmatrix} \cos \theta & \sin \theta \\ \sin \theta & -\cos \theta \end{bmatrix},$$

which reflects the vectors of \mathbb{R}^2 about a line L .

Let us determine equation the line L . Note that any point $(x, y) \in L$ if and only if $A \begin{bmatrix} x & y \end{bmatrix}^T = \begin{bmatrix} x & y \end{bmatrix}^T$. Therefore L is precisely the null space of

$$A - I = \begin{bmatrix} \cos \theta - 1 & \sin \theta \\ \sin \theta & -\cos \theta - 1 \end{bmatrix}.$$

$$[A - I | 0] \xrightarrow{REF} \left[\begin{array}{cc|c} \cos \theta - 1 & \sin \theta & 0 \\ 0 & 0 & 0 \end{array} \right]$$

Therefore $\text{null}(A - I) = \text{span}([\cot \frac{\theta}{2}, 1]^T)$, which gives the equation of the line

$$L : y = \tan \frac{\theta}{2} x.$$