Indian Institute of Technology Guwahati, PH102: Physics-II

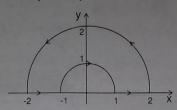
Mid Sem Exam

Time allotted: 2 hours

Date: 22 Feb, 2013

Important instruction: Please keep the answers to all parts of a question in one place.

1. Let $\vec{A} = r \sin \phi \hat{r} + r^2 \hat{\phi}$. (a) Evaluate $\oint \vec{A} \cdot d\vec{l}$ along the closed path shown below. (b) Verify the above result using the Stoke's theorem. [3+3=6]

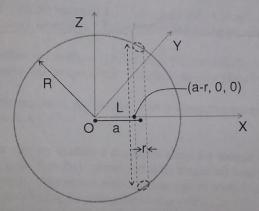


2. A spherical conducting shell of radius 'a', centred at the origin has a potential

$$V(r) = \begin{cases} \bigvee_{0} & \text{if } r \leq a \\ \frac{V_0 a}{r} & \text{if } r > a \end{cases}$$

with the reference point at infinity. (a) Obtain the expression of stored energy for a volume enclosing all space. (b) What is the net charge Q on the spherical shell?

3. A cylindrical slot of radius 'r' is removed from a charged sphere of radius 'R' having uniform volume charge density '\rho'. The axis of the cylindrical slot of mean length 'L', is parallel to the Z axis and is intersecting the X axis at a distance 'a' from the origin, O, as shown in the figure below. Assuming L≫r, find (a) the electric field, and (b) the potential, at the point (a-r,0,0) located on the surface of the cylindrical slot. [3+3=6]Take the origin O as the reference to describe the potential. 4 L>>a



- 4. Consider two long concentric circular cylinders of radius r=1 mm and r=20 mm. For the inner cylinder potential, V = 0 while for the outer cylinder V = 150 V and there is no charge in the region in between. Use Laplace's equation to find (a) the potential, V(r), and (b) the electric field, for the region between the two cylinders (i.e. 1 mm<r< 20 mm). [4+2=6]
- 5/Two infinite grounded conducting planes are held a distance 'a' apart. A point charge 'q' is placed between them at a distance x from one plane. (a) What is the number of image charges? (b) Obtain the expression of force on q. (c) Show that as $a \to \infty$, the force on 'q' is same as due to a single grounded conducting [1+3+2=6]plane at a distance x.

Useful information: In the case of a curvilinear co-ordinate system

- 1. $\vec{\nabla}T = \frac{1}{h_1} \frac{\partial T}{\partial u_1} \hat{u}_1 + \frac{1}{h_2} \frac{\partial T}{\partial u_2} \hat{u}_2 + \frac{1}{h_3} \frac{\partial T}{\partial u_3} \hat{u}_3$
- 2. $\vec{\nabla} \times \vec{A} = \frac{1}{h_2 h_3} \{ \frac{\partial}{\partial u_2} (h_3 A_{u_3}) \frac{\partial}{\partial u_3} (h_2 A_{u_2}) \} \hat{u_1} + \frac{1}{h_3 h_1} \{ \frac{\partial}{\partial u_3} (h_1 A_{u_1}) \frac{\partial}{\partial u_1} (h_3 A_{u_3}) \} \hat{u_2} + \frac{1}{h_1 h_2} \{ \frac{\partial}{\partial u_1} (h_2 A_{u_2}) \frac{\partial}{\partial u_2} (h_1 A_{u_1}) \} \hat{u_3}$
- 3. $\nabla^2 T = \frac{1}{h_1 h_2 h_3} \left[\frac{\partial}{\partial u_1} \left(\frac{h_2 h_3}{h_1} \frac{\partial T}{\partial u_1} \right) + \frac{\partial}{\partial u_2} \left(\frac{h_3 h_1}{h_2} \frac{\partial T}{\partial u_2} \right) + \frac{\partial}{\partial u_3} \left(\frac{h_1 h_2}{h_3} \frac{\partial T}{\partial u_3} \right) \right]$