

# Surface Integrals

## Stokes' Theorem, Divergence Theorem

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## Parametric surface

**Definition:** A continuous function  $\Phi : D \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3$  is called a **parametric surface** in  $\mathbb{R}^3$ . The image  $S := \Phi(D)$  is called a **geometric surface** surface in  $\mathbb{R}^3$ .

- Let  $f : D \rightarrow \mathbb{R}$  be continuous. Then  $\text{Graph}(f) \subset \mathbb{R}^3$  is a surface parametrized by  $\Phi : D \rightarrow \mathbb{R}^3$  given by

$$\Phi(u, v) := (u, v, f(u, v)).$$

- The sphere  $S : x^2 + y^2 + z^2 = r^2$  is parametrized by  $\Phi : [0, \pi] \times [0, 2\pi] \rightarrow \mathbb{R}^3$  given by

$$\Phi(u, v) := (r \sin u \cos v, r \sin u \sin v, r \cos u).$$

## Smooth parametric surface

Let  $\Phi : D \subset \mathbb{R}^2 \rightarrow \mathbb{R}^3$  be a parametric surface and let  $\Phi(u, v) = (x(u, v), y(u, v), z(u, v))$ . Then the partial derivatives of  $\Phi$ , when exist, are given by

$$\Phi_u = (x_u, y_u, z_u) \text{ and } \Phi_v = (x_v, y_v, z_v).$$

The parametric surface  $S = \Phi(D)$  is said to be smooth if  $\Phi$  is  $C^1$  and  $\Phi_u \times \Phi_v \neq 0$  for  $(u, v) \in D$ .

Assumptions:

- $D$  is connected
- $\Phi$  is injective except possibly on the boundary  $\partial D$
- $\Phi$  is  $C^1$  and  $\Phi_u \times \Phi_v \neq 0$  for  $(u, v) \in D$ .

# Surface area and surface area differential

The **surface area differential** is given by

$$dS = \|\Phi_u \times \Phi_v\| du dv.$$

Set  $E := \|\Phi_u\|^2$ ,  $G := \|\Phi_v\|^2$  and  $F := \Phi_u \bullet \Phi_v$ . Then the **surface area** of  $S$  is given by

$$\begin{aligned} \text{Area}(S) &= \text{Area}(\Phi(D)) = \iint_D \|\Phi_u \times \Phi_v\| du dv \\ &= \iint_D \sqrt{EG - F^2} du dv. \end{aligned}$$

$$\bullet \text{Area}(S) = \iint_D \sqrt{\left(\frac{\partial(x,y)}{\partial(u,v)}\right)^2 + \left(\frac{\partial(y,z)}{\partial(u,v)}\right)^2 + \left(\frac{\partial(z,x)}{\partial(u,v)}\right)^2} du dv$$

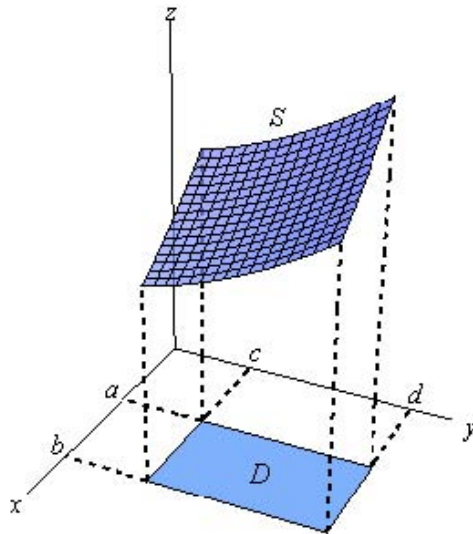


Figure: Surface element

## Examples

- Consider the **cylinder**  $S$  parametrized by

$$\Phi(u, v) := (r \cos u, r \sin u, v), (u, v) \in [0, 2\pi] \times [0, h].$$

$$\text{Area}(S) = \int_0^h \int_0^{2\pi} \|\Phi_u \times \Phi_v\| du dv = \int_0^h \int_0^{2\pi} r du dv = 2\pi rh.$$

- For the **sphere**  $S$  given by

$$\Phi(u, v) := (r \sin u \cos v, r \sin u \sin v, r \cos u)$$

$$\begin{aligned} \text{Area}(S) &= \int_0^\pi \int_0^{2\pi} \|\Phi_u \times \Phi_v\| du dv \\ &= \int_0^\pi \int_0^{2\pi} r^2 \sin u du dv = 4\pi r^2. \end{aligned}$$

## Surface integrals of scalar fields

Let  $S$  be a surface parametrized by  $\Phi : D \rightarrow \mathbb{R}^3$  and let  $f : S \rightarrow \mathbb{R}$  be continuous. Then the **surface integral** of  $f$  over  $S$  is given by

$$\begin{aligned} \iint_S f(x, y, z) dS &:= \iint_D f(\Phi(u, v)) \|\Phi_u \times \Phi_v\| \, du dv \\ &= \lim_{\mu(P) \rightarrow 0} \sum_{i,j} f(c_{ij}) \Delta S_{ij}. \end{aligned}$$

Also

$$\iint_S f dS = \iint_D f(\phi(u, v)) \sqrt{EG - F^2} \, du dv.$$

## Example

Evaluate  $\iint_S x^2 dS$  over the sphere  $S : x^2 + y^2 + z^2 = 1$ .

We have  $\|\Phi_u \times \Phi_v\| = \sin u$  and

$$\begin{aligned} \iint_S x^2 dS &= \int_0^{2\pi} \int_0^\pi \sin^3 u \cos^2 v \, du dv \\ &= \int_0^\pi \sin^3 u \, du \int_0^{2\pi} \cos^2 v \, dv = 4\pi/3. \end{aligned}$$



## Oriented surface

**Informal:** A surface  $S \subset \mathbb{R}^3$  is **orientable** if it has two sides.

**Formal:** A surface  $S \subset \mathbb{R}^3$  is orientable if there exists a continuous vector field  $\mathbf{n} : S \rightarrow \mathbb{R}^3$  such that  $\mathbf{n}(x, y, z)$  is a unit normal to  $S$  at  $(x, y, z)$ .

A surface  $S \subset \mathbb{R}^3$  together with a continuous normal vector field  $\mathbf{n}$  on it is called an **oriented surface**, that is, the pair  $(S, \mathbf{n})$  is called an **oriented surface**.

Let  $\Phi : D \rightarrow \mathbb{R}^3$  be a parametrization of an oriented surface  $(S, \mathbf{n})$ . Then  $\Phi$  is called a **consistent** parametrization if

$$\mathbf{n}(x, y, z) = \frac{\Phi_u \times \Phi_v}{\|\Phi_u \times \Phi_v\|}.$$

## Positively oriented surface

A closed oriented surface  $(S, \mathbf{n})$  is called **positively oriented** if the unit normal vector field  $\mathbf{n}$  on  $S$  points **outward**.

For the unit sphere  $\Phi(u, v) = (\sin u \cos v, \sin u \sin v, \cos u)$ ,

$$\mathbf{n} = \frac{\Phi_u \times \Phi_v}{\|\Phi_u \times \Phi_v\|} = \Phi(u, v)$$

which points outward. Thus  $(S, \mathbf{n})$  is positively oriented.

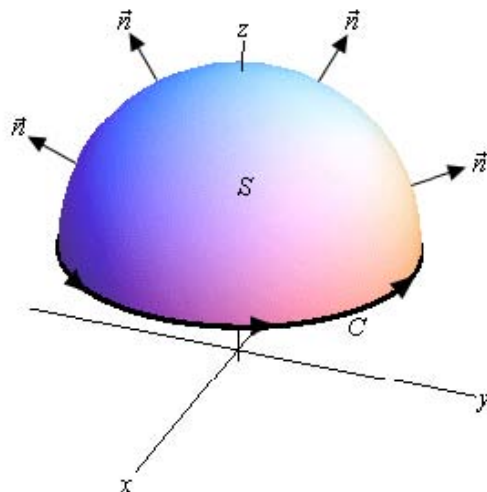
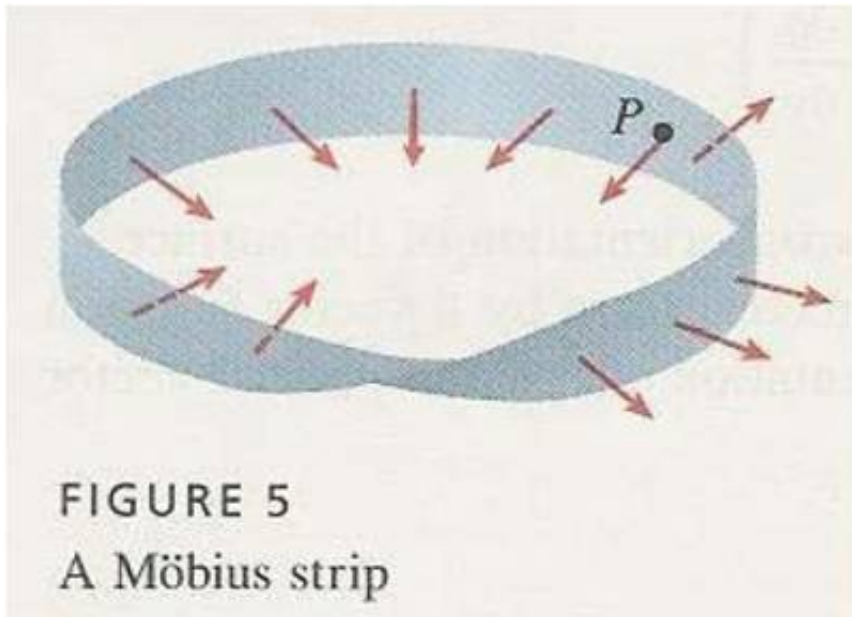


Figure: Oriented surface



## Surface integrals of vector fields

Let  $(S, \mathbf{n})$  be an oriented surface in  $\mathbb{R}^3$  and let  $F : S \rightarrow \mathbb{R}^3$  be a continuous vector field. Then  $F \bullet \mathbf{n}$  is the **normal component** of  $F$ .

**Interpretation:** Flux of  $F$  through the oriented surface  $S$  per unit surface area  $= F \bullet \mathbf{n}$ .

The **surface integral** of  $F$  over the **oriented surface**  $(S, \mathbf{n})$  is defined by

$$\iint_S F \bullet d\mathbf{S} := \iint_S (F \bullet \mathbf{n}) dS.$$

- $\iint_S F \bullet d\mathbf{S}$  is the **flux** of  $F$  through the oriented surface  $S$ .

## Surface integrals of vector fields

Let  $\Phi : D \rightarrow \mathbb{R}^3$  be a consistent parametrization of the oriented surface  $(S, \mathbf{n})$ . Then

$$\iint_S F \bullet d\mathbf{S} := \iint_S F \bullet \mathbf{n} dS = \iint_D F \bullet (\Phi_u \times \Phi_v) du dv.$$

## Example

Let  $F(x, y, z) := (z, y, x)$ . Evaluate  $\iint_S F \bullet d\mathbf{S}$  over the unit sphere  $S : x^2 + y^2 + z^2 = 1$ .

We have

$$\Phi(u, v) = (\sin u \cos v, \sin u \sin v, \cos u), (u, v) \in [0, \pi] \times [0, 2\pi],$$

$$\Phi_u \times \Phi_v = (\sin^2 u \cos v, \sin^2 u \sin v, \sin u \cos u).$$

Thus

$$\begin{aligned} \iint_S F \bullet d\mathbf{S} &= \int_0^{2\pi} \int_0^\pi (2 \sin^2 u \cos u \cos v + \sin^3 u \sin^2 v) du dv \\ &= \frac{4\pi}{3}. \end{aligned}$$

# Stokes' Theorem

**Stokes' Theorem:** Let  $(S, \mathbf{n})$  be a (piecewise) smooth oriented surface with (piecewise) smooth positively oriented boundary  $\partial S$ . Let  $F : S \rightarrow \mathbb{R}^3$  be  $C^1$  vector field. Then

$$\iint_S \text{curl}(F) \bullet \mathbf{n} dS = \int_{\partial S} F \bullet T ds = \int_{\partial S} F \bullet d\mathbf{r},$$

where  $T$  is the tangent field on  $\partial S$ .

**Divergence Theorem:** Let  $V \subset \mathbb{R}^3$  be a solid region with positively oriented boundary surface  $(S, \mathbf{n})$ . Let  $F : V \rightarrow \mathbb{R}^3$  be  $C^1$ . Then

$$\iint_S F \bullet \mathbf{n} dS = \iiint_V \text{div}(F) dV.$$



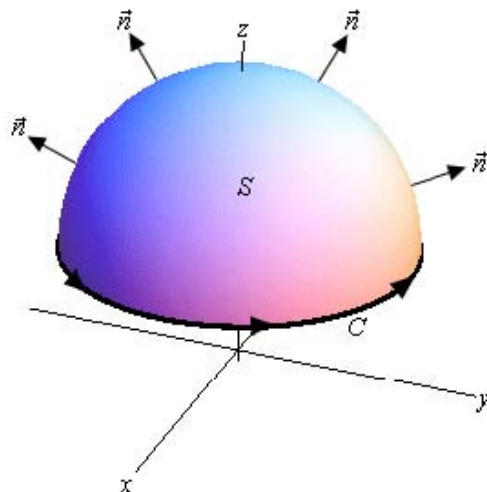


Figure: Oriented surface

## Green's theorem in vector form

Let  $D \subset \mathbb{R}^2$  be a **simply connected** (no holes) region with **positively oriented** boundary  $\partial D$ . Let  $F = (P, Q)$  be  $C^1$  vector field on  $D$ . Identifying  $F = (P, Q)$  with  $F = (P, Q, 0)$  we have

$$\begin{aligned}\iint_D \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dA &= \iint_D \operatorname{curl}(F) \bullet \mathbf{k} dA \\ &= \oint_{\partial D} F \bullet d\mathbf{r}.\end{aligned}$$

## Examples:

- Let  $F = (ye^z, xe^z, xye^z)$ . Then for any oriented surface  $S$  with positively oriented boundary  $\partial S$

$$\int_{\partial S} F \bullet d\mathbf{r} = \iint_S \text{curl}(F) \bullet d\mathbf{S} = 0$$

because  $\text{curl}(F) = 0$ .

- If  $F : \mathbb{R}^3 \rightarrow \mathbb{R}^3$  is such that  $\text{curl}F = 0$  then  $F$  is a gradient vector field. Indeed, by Stoke's theorem

$$\oint_{\partial S} F \bullet d\mathbf{r} = \iint_S \text{curl}(F) \bullet d\mathbf{S} = 0.$$

Thus the line integral is path independent and hence  $F$  is conservative.

## Example:

Let  $F = (2x, y^2, z^2)$  and  $S : x^2 + y^2 + z^2 = 1$ . Evaluate the surface integral

$$\iint_S F \bullet d\mathbf{S}.$$

By Divergence theorem

$$\begin{aligned}\iint_S F \bullet d\mathbf{S} &= \iiint_V \operatorname{div}(F) dV \\ &= 2 \iiint_V (1 + y + z) dV \\ &= 2 \iiint_V dV = \frac{8\pi}{3}.\end{aligned}$$

\*\*\* End \*\*\*