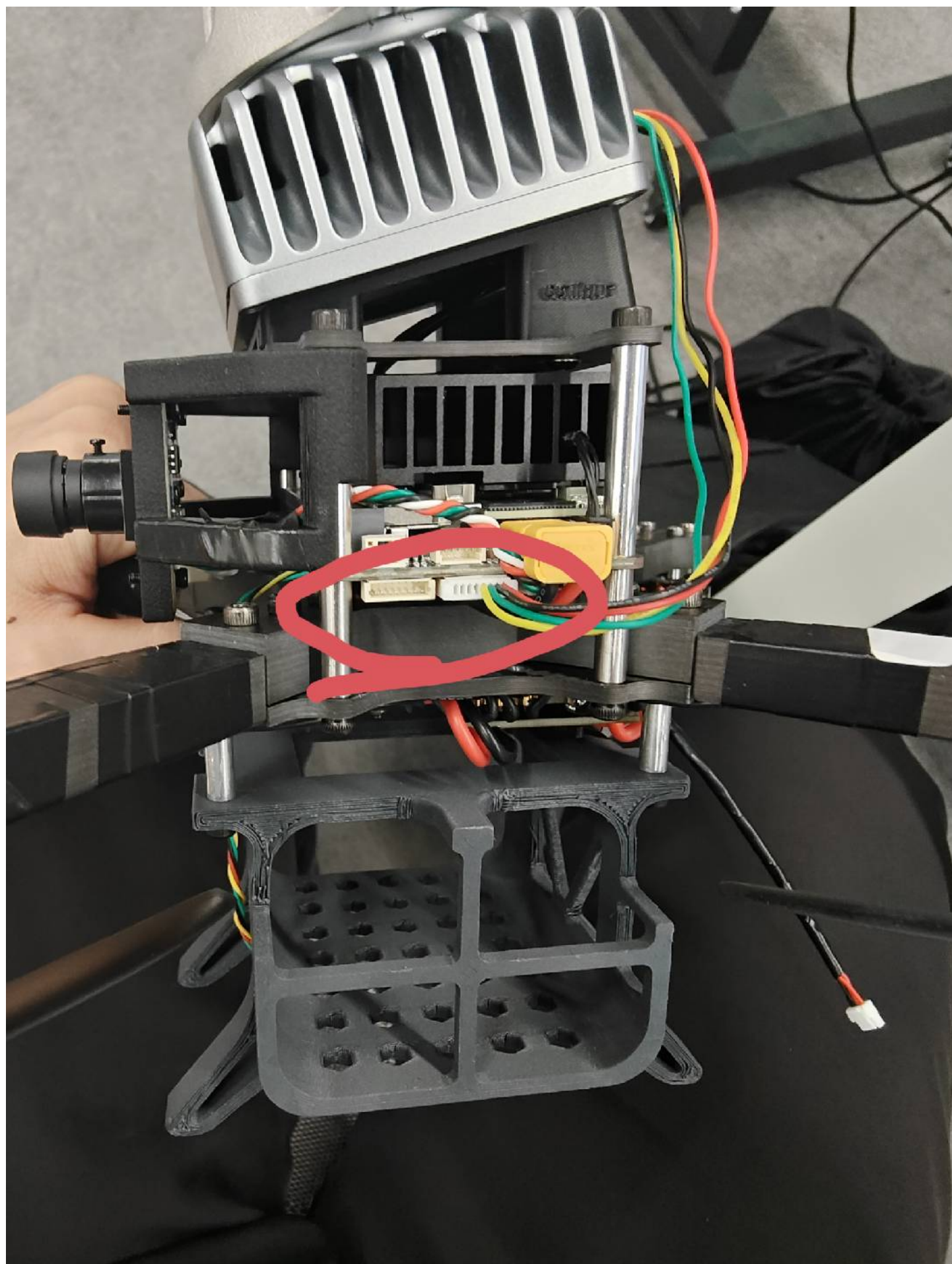


618飞机载板双网口设置

| | | |
|---|---|---|
|  | <div>orin-board.zip</div> <div>115.99MB</div> |  |
|  | <div>V2版本资料.zip</div> <div>14.90MB</div> |  |
|  | <div>r8125-9.015.00.tar.bz2</div> <div>109.66KB</div> |  |

安装驱动即可。需要先同步一下时间，然后运行文件夹中的脚本即可。最后验证一下网口能否使用。



Home

nv@ubuntu: ~/618test



DRONE_ID=0

DRONE_NUM=6

nv@ubuntu:~/618test\$ sudo date -s "2025-6-16 15:46:00"

[sudo] password for nv:

2025年 06月 16日 星期一 15:46:00 CST

nv@ubuntu:~/618test\$

DRONE_ID=0

DRONE_NUM=6

nv@ubuntu:~/618test\$ cd ..

nv@ubuntu:~\$ cd r8125-9.015.00/

nv@ubuntu:~/r8125-9.015.00\$ sudo ./autorun.sh

[sudo] password for nv:

Check old driver and unload it.

Build the module and install

At main.c:167:

- SSL error:02001002:system library:fopen:No such file or directory: ../crypto/bio/bss_file.c:69

- SSL error:2006D080:BIIO routines:BIIO_new_file:no such file: ../crypto/bio/bss_file.c:76

sign-file: certs/signing_key.pem: No such file or directory

Warning: modules_install: missing 'System.map' file. Skipping depmod.

DEPMOD 5.10.192-tegra

load module r8125

Updating initramfs. Please wait.

update-initramfs: Generating /boot/initrd.img-5.10.192-tegra

W: Couldn't identify type of root file system for fsck hook

Completed.

nv@ubuntu:~/r8125-9.015.00\$

6月16 15:58

lin 25W

display_point_cloud_ROS1.rviz - RViz

2D Pose Estimate 2D Nav Goal Publish Point

- Ethernet (eth1) Connected
- DiffRobot
- On
- Settings
- Lock
- Power Off / Log Out

