618飞机检查是否有光流数据
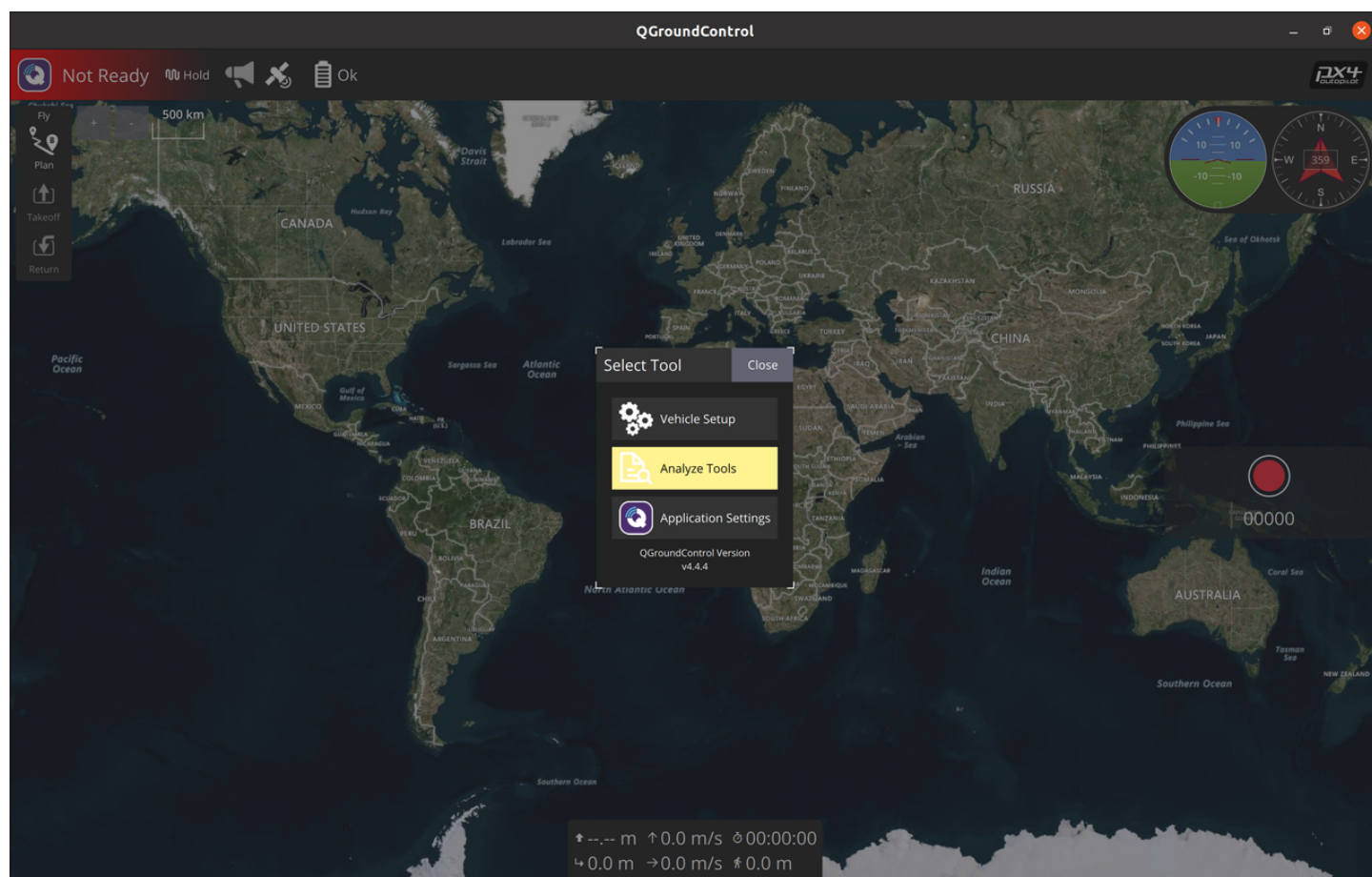
连接上qgc并给飞机上电，点击analyze tools中的mavlink inspector，找到optical_flow_rad，若有则说明有光流数据此时可以上下移动无人机观察其distance是否有变化

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GeoTag Images

MAVLink Console

MAVLink Inspector

Vibration

Inspect real time MAVLink messages.

1	ALTITUDE	10.0Hz
1	ATTITUDE	50.0Hz
1	ATTITUDE_QUATERNION	50.0Hz
1	ATTITUDE_TARGET	8.0Hz
1	BATTERY_STATUS	0.8Hz
1	CURRENT_EVENT_SEQUENCE	0.8Hz
1	DISTANCE_SENSOR	10.0Hz
1	ESTIMATOR_STATUS	5.0Hz
1	EVENT	1.3Hz
1	EXTENDED_SYS_STATE	2.0Hz
1	HEARTBEAT	1.0Hz
1	HIGHRES_IMU	50.0Hz
1	LINK_NODE_STATUS	1.0Hz
1	LOCAL_POSITION_NED	30.0Hz
1	MISSION_CURRENT	1.0Hz
1	ODOMETRY	30.0Hz
1	OPEN_DRONE_ID_LOCATION	1.0Hz
1	OPTICAL_FLOW_RAD	10.0Hz
1	PING	1.0Hz
1	SCALED_IMU	25.0Hz

Message: OPTICAL_FLOW_RAD (106) 10.0Hz
Component: 1
Count: 556

Name	Value	Type	Plot 1	Plot 2
time_usec	161017899	uint64_t	☐	☐
sensor_id	0	uint8_t	☐	☐
integration_time_us	20000	uint32_t	☐	☐
integrated_x	0	float	☐	☐
integrated_y	0	float	☐	☐
integrated_xgyro	5.75811e-05	float	☐	☐
integrated_ygyro	1.61909e-05	float	☐	☐
integrated_zgyro	9.87489e-06	float	☐	☐
temperature	0	int16_t	☐	☐
quality	0	uint8_t	☐	☐
time_delta_distance_us	0	uint32_t	☐	☐
distance	-1	float	☐	☐