# James Mullen

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Research Interests Human-robot interaction, Virtual and augmented reality, Embodied AI, operationalized AI, image/video synthesis.

**Education** UNIVERSITY OF MARYLAND

2021-2026 (Expected)

Ph.D. in Computer Science Advised by Dinesh Manocha and Ming Lin in GAMMA Lab

VIRGINIA TECH 2017-2021

B.S in Mechanical Engineering, Computer Science Minor 3.91 GPA

Experience

### UNIVERSITY OF MARYLAND

2021-Present

### **NSF Fellow and Graduate Research Assistant**

**Human Animation Placement** 

- · Designed PAAK, a method to *place 3D human animations into an arbitrary scene* such that interactions with the scene are maintained using an autoencoder, scene geometry, and active learning techniques
- · For example, if the animation involves sitting or touching an object, PAAK places the human into the scene such that it is sitting in a chair or touching an object
- · Conducted a user study to test the perceived realism of the scene placements
- · Research resulted in a first author publication at IEEE/CVF WACV
- $\cdot$  Follow up work tailors the animations to the geometry of the scene, resulting in even more natural-looking scene placements work under review

Virtual Reality for Characterizing Driver Behavior

· Developed a system for collecting human driving data in pre-crash scenarios to model human behavior

**Embodied AI** 

· Conducting research tackling the robot instruction-following problem in a generalized zero-shot setting

**RAYTHEON** 2018-2021

AI Research Intern & Principal Investigator

Advisor: Dr. Philip Sallee

## Computer Vision Research Projects

- · Initiated a research proposal, then ran and completed a research project exploring connections between imagery annotation types and neural network performance
- · Research resulted in granted U.S. Patent No. 11,068,747 [5], and a publication at the IEEE Conference on Computer Vision and Pattern Recognition [2]
- · Pitched and secured funding as Principal Investigator to develop novel probabilistic pseudo-annotations for achieving state-of-the-art detection results on cheaply annotated data, **Patent Application #16/586480 [5]** filed
- · Designed and implemented a new, clustering-based method of hardening neural networks against out of distribution data, data drift, and adversarial attacks in a focus to operationalize AI, **Patent Application #17/081612 [3]** filed Innovation Center Research Project
- · Developed a grant proposal and pitched to a panel of 7 research and business executives, selected for funding from over 100 applicants
- · Directed execution including tracking funds, managing the team, developing business interest, and filing **Patent Application** #16/745885 [4]
- · Postulated a unique approach to course of action planning using 'costmaps' and AI

#### **VIRGINIA TECH**

### **Undergraduate Research**

Advisor: Dr. Brain Lattimer, Dr. Dylan Losey Communicating Robot Learning (Dr. Losey)

2020-2021

- $\cdot$  Designing methods to gather information from a robot as it learns, and present said information to a human intuitively through haptic and AR feedback devices
- · Designed and conducted a user study to evaluate our multi-modality method against single-modality baselines
- · Resulted in a publication at IEEE Robotics and Automation Letters [1]
- Wrote VT ME Grant application and was awarded funding for the project
  Satellite Imagery Super-Resolution (Dr. Lattimer)
- · Explored a super-resolution of GOES Imagery to VIIRS-I Imagery to produce high resolution, frequent imagery for use in wildland fire burn map creation
- · Wrote VSGC Fellowship application and was awarded funding for the project

Refereed Conference Proceedings and Journal Articles

- 1. **James F. Mullen Jr.**, Divya Kothandaraman, Aniket Bera, and Dinesh Manocha, "Placing Human Animations into 3D Scenes by Learning Interaction- and Geometry-Driven Keyframes," *IEEE/CVF Winter Conference on the Applications of Computer Vision (WACV)*, 2023
- 2. **J. F. Mullen**, J. Mosier, S. Chakrabarti, A. Chen, T. White and D. P. Losey, "Communicating Inferred Goals With Passive Augmented Reality and Active

- Haptic Feedback," in IEEE Robotics and Automation Letters, vol. 6, no. 4, pp. 8522-8529, Oct. 2021, doi: 10.1109/LRA.2021.3111055.
- 3. **James F. Mullen Jr.,** Franklin R. Tanner, and Philip A. Sallee, "Comparing the Effects of Annotation Type on Machine Learning Detection Performance," *IEEE Conference on Computer Vision and Pattern Recognition Workshops (CVPR)*, 2019.

#### **Patents**

- 4. Philip A. Sallee, **James F. Mullen Jr.**, "Hardening Deep Neural Networks," *US Patent Application* 17/081612, 2020.
- 5. **James F. Mullen Jr.** and Rupal Nigam, "Systems and Methods for Multi-Factor Pathfinding," *US Patent Application* 16/745885, 2020.
- 6. **James F. Mullen Jr.**, Jon Goldstein, Philip A. Sallee, and Franklin R. Tanner, "A Training Schema for Extended Object Detection with Point-Wise Labels," *US Patent Application* 16/586480, 2019.
- 7. Philip A. Sallee, **James F. Mullen Jr.**, and Franklin R. Tanner, "Machine Learning Using Informed Pseudolabels" (U.S. Patent No. 11,068,747). U.S. Patent and Trademark Office. (2021)

Honors & Awards	National Science Foundation Graduate Research Fellowship	2022
	Raytheon AI/ML Scholars Award	2020
	Virginia Tech Mechanical Engineering Grant	2020
	Virginia Space Grant Consortium (VSGC) Fellowship	2020
	Raytheon Innovation Grant (x2)	2018 & 2019
	Raytheon Achievement Award (x2)	2018 & 2019
	Edward H. Cahill Memorial Scholarship	2019
	Pratt Engineering Scholarship	2018
Outreach	Montgomery County Animal Shelter Volunteer	2019 to Present
	Eagle Scout	2015