



# **COL215 DIGITAL LOGIC AND SYSTEM DESIGN**

Logic and FSM Minimization –  
Algorithmic Approach  
03 November 2017

# Algorithmic approach – tabular method

## Quine McCluskey method

Two phases :

- Generation of all prime implicants
- Finding a minimum cover

# Iterative steps for PI generation

In  $i^{\text{th}}$  iteration, implicants with  $2^i$  minterms are generated by combining two implicants with  $2^{i-1}$  minterms. Let the number of variables be denoted by  $n$ .

What is the maximum number of iterations that may be required?

# Grouping of implicants

In each iteration, the implicants are grouped according to the number of 1's in the implicants.

What is the maximum number of groups that may be formed in  $i^{\text{th}}$  iteration?

# Groups from which implicants combine

In  $i^{\text{th}}$  iteration, implicants from  $j^{\text{th}}$  group and  $k^{\text{th}}$  group can combine.

How are  $j$  and  $k$  related?

# Finding minimum cover

- What are essential prime implicants?
- What role is played by essential prime implicants?
- Which rows are removed – dominating or dominated?
- Which columns are removed – dominating or dominated?
- What is branching and when is it used?

# Algorithmic approach – cubical technique

Starting point need not be the minterm set

Two operations over cubes:

- star (\*) operation
  - used to generate new cubes
- sharp (#) operation
  - used to check coverage



# Star (\*) operation

Possible results of operation

$C = A * B$  on cubes A and B

- if A and B are far apart, no new cube is generated
- if A, B overlap, the result is intersection of A and B
- if A, B differ in exactly one literal, new cube generated is union of a part of A and a part of B

$A_i \backslash B_i$	0	1	x
0	0	$\emptyset$	0
1	$\emptyset$	1	1
x	0	1	x

If  $A_i * B_i = \emptyset$  for more than one i, then  $C = \emptyset$

Otherwise, if  $A_i * B_i \neq \emptyset$  then

$$C_i = A_i * B_i$$

else

$$C_i = x$$



# Sharp (#) operation

Possible results of operation

$C = A \# B$  on cubes  $A$  and  $B$

- if  $A$  and  $B$  are disjoint, the result is  $A$
- if  $A$  is contained in  $B$ , the result is empty
- if  $B$  partly overlaps with  $A$ , the result is non-overlapping part of  $A$

$A_i \setminus B_i$	0	1	x
0	$\varepsilon$	$\emptyset$	$\varepsilon$
1	$\emptyset$	$\varepsilon$	$\varepsilon$
x	1	0	$\varepsilon$

If  $A_i \# B_i = \emptyset$  for some  $i$ ,  
then  $C = A$

If  $A_i \# B_i = \varepsilon$  for all  $i$ ,  
then  $C = \emptyset$

# Finite State Machine Model

Quintuple  $(X, Y, S, \delta, \lambda)$

$X$  = set of primary input patterns

$Y$  = set of primary output patterns

$S$  = set of states {includes an initial state}

$\delta$  = state transition function  $S \times X \rightarrow S$

$\lambda$  = output function

$S \times X \rightarrow Y$  for Mealy model or

$S \rightarrow Y$  for Moore model

# Assumptions

- Synchronous circuits
- Single clock
- Single phase
- Edge triggered D type flip-flops/registers

# State minimization

- Deriving an FSM with similar behavior and minimum number of states
- State minimization may lead to reduction in the register bits and logic gates (because of reduced no. of transitions)

# Completely specified FSMs

Definition of state equivalence:

$\text{equiv}(s_i, s_j)$  iff

$\text{output\_seq}(s_i, \text{input\_seq}) =$   
 $\text{output\_seq}(s_j, \text{input\_seq})$

for all  $\text{input\_seq}$

# Completely specified FSMs

Easier way to check:

$\text{equiv}(s_i, s_j)$  iff

$(s_i = s_j)$

or

$\lambda(s_i, x) = \lambda(s_j, x)$  and

$\text{equiv}(\delta(s_i, x), \delta(s_j, x))$ ,

for all  $x$  in  $X$

$s_i, s_j$  are identical

produce same output  
for  $x$

their  $x$ -successor are  
equivalent

# Computing equiv relation

Iterative definition:

$s_i, s_j$  are *k-equivalent*

iff they can't be distinguished by input sequences  
of length upto  $k$

=>

$s_i, s_j$  are  $(k+1)$ -equivalent

iff they are  $k$ -equivalent and

their  $x$ -successors are  $k$ -equivalent, for all  $x$



# Computing equiv relation

Another iterative definition:

$s_i, s_j$  are *k-distinguishable*

iff they can be distinguished by input sequences of length upto  $k$

=>

$s_i, s_j$  are  $(k+1)$ -distinguishable

iff they are  $k$ -distinguishable or

their  $x$ -successors is  $k$ -distinguishable, for some  $x$

# Partitioning states into sets of equivalent states

- Required partition is obtained as a series  $\pi_1, \pi_2, \pi_3, \dots, \pi_n$ . Max value of  $n = |S|$
- In  $\pi_k$ ,  $s_i$  and  $s_j$  are in the same block iff they are  $k$ -equivalent
- $\pi_{k+1}$  is obtained from  $\pi_k$  by checking if successors of state pairs in same block are  $k$ -equivalent or not
- The process terminates when  $\pi_{k+1}$  is found to be same as  $\pi_k$



**QUESTIONS?**