k214577-lab8

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[4]: #TASK NUMBER 1
     from itertools import product
     # Define the sample space for four children, each can be a boy (B) or a girl (G)
     sample_space = list(product("BG", repeat=4))
     # Count outcomes with exactly two boys
     count_2_boys = sum(1 for outcome in sample_space if outcome.count('B') == 2)
     # Calculate probability of having exactly two boys
     probability_2_boys = count_2_boys / len(sample_space)
     print(sample_space)
     print("Total number of outcomes:", len(sample_space))
     print("Number of outcomes with 2 boys:", count_2_boys)
     print("Probability of having exactly two boys:", probability_2_boys)
    [('B', 'B', 'B', 'B'), ('B', 'B', 'B', 'G'), ('B', 'B', 'G', 'B'), ('B', 'B',
    'G', 'G'), ('B', 'G', 'B', 'B'), ('B', 'G', 'B', 'G'), ('B', 'G', 'G', 'B'),
    ('B', 'G', 'G', 'G'), ('G', 'B', 'B', 'B'), ('G', 'B', 'B', 'G'), ('G', 'B',
    'G', 'B'), ('G', 'B', 'G', 'G'), ('G', 'G', 'B', 'B'), ('G', 'G', 'B', 'G'),
    ('G', 'G', 'G', 'B'), ('G', 'G', 'G', 'G')]
    Total number of outcomes: 16
    Number of outcomes with 2 boys: 6
    Probability of having exactly two boys: 0.375
[5]: #TASK NUMBER 2
     # Define the sample space for a six-sided die
     sample_space = [1, 2, 3, 4, 5, 6]
     # Define the event E: getting a number less than 4
     event_E = [1, 2, 3]
     # Calculate probability of event E
     prob_E = len([outcome for outcome in sample_space if outcome in event_E]) / __
      →len(sample_space)
     print("Probability of rolling a number less than 4:", prob_E)
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Probability of rolling a number less than 4: 0.5

Probability of drawing a red marble given that it is blue: 0.5

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[9]: #TASK NUMBER 4
     import numpy as np
     # Define states and observations
     states = ['healthy', 'sick']
     observations = ['cough', 'no cough']
     # Define transition and emission probabilities
     transition_probabilities = np.array([[0.7, 0.3], [0.4, 0.6]])
     emission_probabilities = np.array([[0.1, 0.9], [0.8, 0.2]])
     initial_state_probabilities = np.array([0.5, 0.5])
     def viterbi(obs, states, start_p, trans_p, emit_p):
         V = [\{\}]
         path = \{\}
         \# Initialize the path and probability for each state based on the first \sqcup
      \hookrightarrowobservation
         for state in states:
             V[0][state] = start_p[states.index(state)] * emit_p[states.
      →index(state)][observations.index(obs[0])]
             path[state] = [state]
         # Build the Viterbi graph
         for t in range(1, len(obs)):
             V.append({})
             newpath = {}
             for cur state in states:
                 max_prob, max_state = max((V[t-1][prev_state] * trans_p[states.
      →index(prev_state)][states.index(cur_state)] * emit_p[states.
      dindex(cur_state)][observations.index(obs[t])], prev_state) for prev_state in_
      ⇔states)
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V[t][cur_state] = max_prob
    newpath[cur_state] = path[max_state] + [cur_state]

path = newpath

# Find the most likely final state and path
    max_prob, max_state = max((V[len(obs) - 1][state], state) for state in_u
states)
    return max_prob, path[max_state]

# Define observation sequence and perform Viterbi algorithm
observation_sequence = ['cough', 'no cough', 'cough']
probability, most_likely_states = viterbi(observation_sequence, states,_u
initial_state_probabilities, transition_probabilities,_u
emission_probabilities)

print("Most likely sequence of states:", most_likely_states)
print("Probability of the sequence:", probability)
```

Most likely sequence of states: ['sick', 'healthy', 'sick'] Probability of the sequence: 0.0345600000000001

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[11]: #TASK NUMBER 5
      # Define the probabilities of selecting each plan
      prob_P1 = 0.30
      prob_P2 = 0.20
      prob_P3 = 0.50
      # Define the probabilities of a defect given each plan
      prob_defect_given_P1 = 0.01
      prob_defect_given_P2 = 0.03
      prob_defect_given_P3 = 0.02
      # Calculate the total probability of a defect occurring
      prob_defect = (prob_P1 * prob_defect_given_P1 +
                     prob_P2 * prob_defect_given_P2 +
                     prob_P3 * prob_defect_given_P3)
      # Calculate the posterior probabilities of each plan given a defect
      posterior_P1 = (prob_P1 * prob_defect_given_P1) / prob_defect
      posterior_P2 = (prob_P2 * prob_defect_given_P2) / prob_defect
      posterior_P3 = (prob_P3 * prob_defect_given_P3) / prob_defect
      # Determine the most likely plan responsible for a defective product
      plans = [(posterior_P1, "Plan 1"), (posterior_P2, "Plan 2"), (posterior_P3, ___

¬"Plan 3")]
     most_likely_plan = max(plans, key=lambda x: x[0]) # Use a lambda for clarity
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# Output the result
print("Most likely plan responsible for the defective product:",
omost_likely_plan[1])
```

Most likely plan responsible for the defective product: Plan 3

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[10]: #TASK NUMBER 6
      # Define the three boxes and their content
      box1 = {'gold': 2, 'silver': 0}
      box2 = {'gold': 0, 'silver': 2}
      box3 = {'gold': 1, 'silver': 1}
      # Define the probabilities of picking each box
      p_box = [1/3, 1/3, 1/3] # Uniform distribution for box selection
      # Calculate the probability of picking a gold coin
      p_gold = sum(box['gold'] / sum(box.values()) * p for box, p in zip([box1, box2,__
       →box3], p_box))
      # Calculate the conditional probabilities for the other coin being gold
      p_other_gold_given_box = [1 if 'gold' in box and box['gold'] == 2 else 0 for__
       \rightarrowbox in [box1, box2, box3]]
      print("Probability of picking a gold coin:", p_gold)
      print("Probabilities that the other coin is gold given the box selection:",_{\sqcup}
       →p_other_gold_given_box)
```

Probability of picking a gold coin: 0.5 Probabilities that the other coin is gold given the box selection: [1, 0, 0]