# **Ahmed Muni**

Waterloo, ON



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(519) 591-2138



Portfolio Website



muniahmed



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#### **SUMMARY**

A systems engineer with co-op experience in robotics and automation. An excellent team member, self-starter, quick learner, and Tony Stark enthusiast.

# **LANGUAGES**

Python, C, C++, JavaScript Flutter/Dart, HTML, CSS

#### FRAMEWORKS & LIBRARIES

OpenCV, ROS2, React.js, Node.js, Express.js, MongoDB, jQuery, Bootstrap

## **TOOLS & SOFTWARE**

SOLIDWORKS, Fusion 360, Linux, VSCode, MATLAB, KiCad

#### **EDUCATION**

BSc in Engineering Systems and Computing University of Guelph - 2021

## **RELEVANT COURSES**

Data Structures & Algorithms, Object Oriented Programming, Large Scale Software Architecture, Complex Systems, Signal Processing, Robotic Systems, Linear Algebra, Systems and Control Theory

# **WORK EXPERIENCE**

# **Robotics Engineer**

May 2019 - Aug 2019

s2e Technologies | Waterloo, ON

Tech stack: Python, OpenCV, Autonomous Vehicles

- Acquired \$1M in partner funding through autonomous vehicle project proposal for EVE Park project
- Lead development of POC for offboard autonomous vehicle guidance system that resulted in a assessment success rate of 97.4%
- Designed guidance system using OpenCV and Python which tracked positions of vehicle and environmental hazards to safely guide the vehicle
- Constructed assessment site for autonomous vehicle prototype testing

# **PROJECTS**

## **Capstone Project - Autonomous Vaccine Preparation Device**

- Designed a device that autonomously fills syringes directly from vial to increase vaccination speed, with an interdisciplinary engineering team
- Utilized KiCad to design electrical schematics of device
- Developed CAD model of device using SOLIDWORKS

#### Six-Axis Robotic Arms Labs

Tech stack: Python, OpenCV

- Developed software in Python and OpenCV to manipulate Fanuc, Kuka, and Baxter robotic arms to complete several unique tasks
- Designed and implemented control algorithms on robot to find and pick up objects, accurately stack them or place them into a container, and write text with a marker onto a sheet of paper
- Utilized Kuka smartPAD to control and program Kuka robotic arm

## **BUSINESSES**

## **Anvil - Phone Repair Business**

- Started and operated a phone repair business
- Conducted over 60+ repairs and business transactions
- Provided problem solving and troubleshooting to deduce issues with damaged phones
- Presented and effectively explained repair requirements to clients