

# Eigen

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g++ name-of-file.cpp -I/usr/include/eigen3 -std=c++11; ./a.out
using namespace Eigen; (Do this after #include)
#include <Eigen/Eigen/Dense> or <Eigen/Dense>
```

## Eigen

## What it does

Vector2d x

MatrixXd A(2,3)

v.size()

A(0,1) = 3;

x = A.lu().solve(b);

A.transpose();

MatrixXd A(MatrixXd::Identity(5,5))

c = min(a,b)

A.rows()

A.cols()

A.col(3) = x

A.colwise() = meanFace

cout << A

x[i]

MatrixXd A

VectorXd c = VectorXd::Ones(n); c = (1,1,1,1)

std::pow(v(3),2) v[3]<sup>2</sup>

Vector (a,b)

$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$

eg. b of v. (1,2,3)  $\Rightarrow$  3

$\begin{pmatrix} a & b \\ c & d \end{pmatrix}$

solve for x in  $Ax=b$

$A^T$

Identity Matrix 5x5

Minimum of a and b is stored in c

#rows of A

#columns of A

$A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$

subtract meanFace from every column in A.

Prints out A

Access ith element of a Vector that is type CONST

LLT<MatrixXd> LLT(A); Computes Cholesky  $A=LL^T$  for A. *name*

MatrixXd L = LLT.matrixL(); Gets factor L of Cholesky *name*

$X = L.triangularView<Lower>().solve(B);$  Solve for X in  $L \cdot X = B$  where L is lower-triangular and X can be a Matrix.

HouseholderQR<MatrixXd> qr(A); Computes Householder QR of A.

Q = qr.householderQ(); Get Q

R = qr.matrixQR().triangularView<Upper>(); Get R

Rhin = MatrixXd::Identity(min(m,n), m) \* R; Get min Q if  $m > n$  then you can replace  $\min(m,n)$  with n

Qrhin = Q \* MatrixXd::Identity(m, min(m,n)); Get min R

JacobiSVD<MatrixXd> svd(A);

v = svd.singularValues();

U = svd.matrixU();

V = svd.matrixV();

v.norm() // Take the  $\|v\|_2$  norm of v

vector.segment(i,j) // returns a reference to the segment of vector starting from i with length j.

Matrix.diagonal() // returns a vector reference to the diagonal of the matrix.

Matrix.diagonal(1) (or -1) // returns a vector reference to the diagonal of the matrix moved by 1 (bzw. -1).

vector.head(i) // returns a reference to the first i elements of vector.

vector.tail(i) // returns a reference to the last i elements of vector (order remains unchanged)

MatrixORvector.cwiseQuotient(MatrixORvector2) // self explanatory.

Don't know what happens if not same size