

# Práctica 8 - Cámaras

## Ejercicio 1

```
R1 = rotateZ(90) * rotateY(90)
```

```
R1 = 3x3
    0.0000  -1.0000  0.0000
    0.0000   0.0000  1.0000
   -1.0000    0      0.0000
```

```
R2 = rotateZ(90) * rotateX(90)
```

```
R2 = 3x3
    0.0000  -0.0000  1.0000
    1.0000   0.0000 -0.0000
     0      1.0000  0.0000
```

```
R3 = rotateZ(30) * rotateY(90) * rotateX(45)
```

```
R3 = 3x3
    0.0000  0.2588  0.9659
    0.0000  0.9659 -0.2588
   -1.0000  0.0000  0.0000
```

Notar que aplicamos las rotaciones en el orden especificado (ZYX). Cuando no es necesario rotar en algún eje, se multiplica por la matriz identidad.

## Ejercicio 2

```
X = [3 4 -3]
```

```
X = 1x3
    3    4   -3
```

```
C = [5 3 5]
```

```
C = 1x3
    5    3    5
```

```
R = rotateY(90)
```

```
R = 3x3
    0.0000    0  1.0000
     0      1.0000    0
   -1.0000    0  0.0000
```

```
X_cam = R * (X-C)'
```

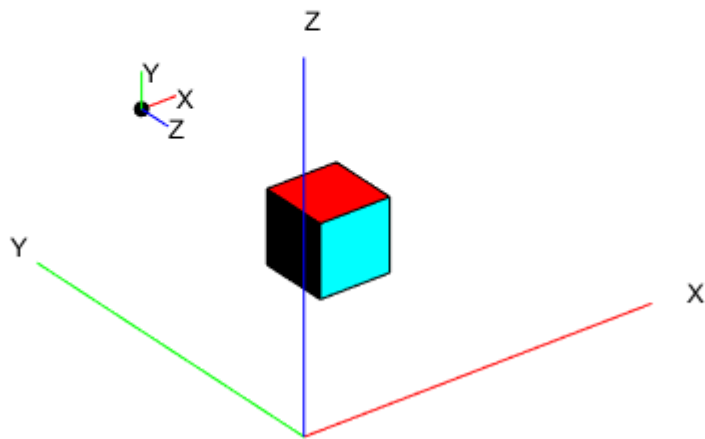
```
X_cam = 3x1
   -8.0000
```

1.0000  
2.0000

### Ejercicio 3

```
f = 0.1;  
s = 0;  
px = 0.5; py = 0.5;  
theta_x = pi/2; %-3*pi/4;  
theta_y = 0;  
theta_z = 0; %pi/4;%0;  
C = [3 10 3]'; % enfrentado  
  
generar_camara(f, s, px, py, theta_x, theta_y, theta_z, C)
```

**Mundo (X=rojo,Y=verde,Z=azul)**

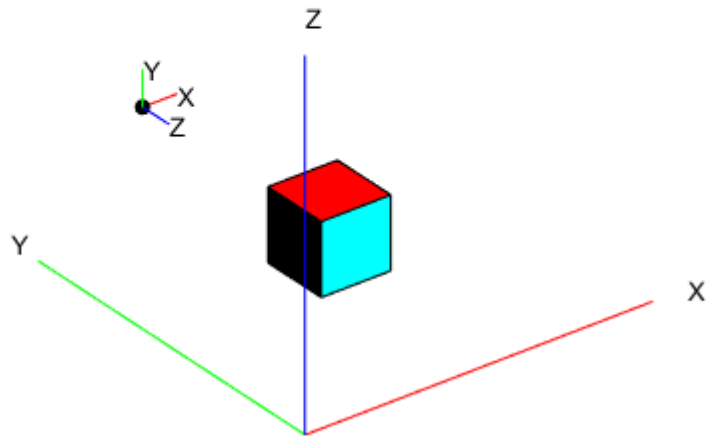




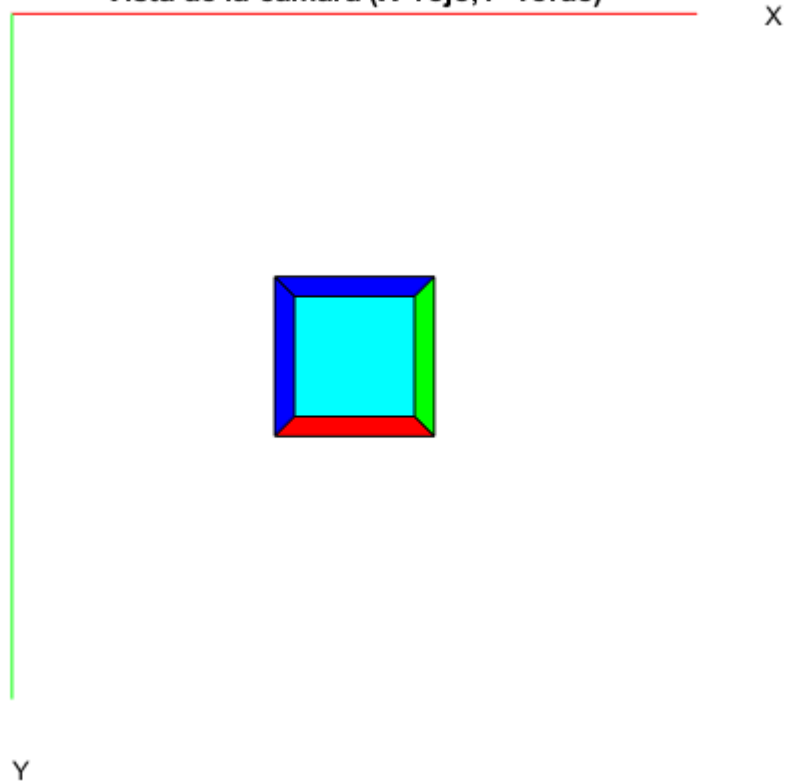
```
f = 0.7;
s = 0;
px = 0.5; py = 0.5;
theta_x = pi/2; % -3*pi/4;
theta_y = 0;
theta_z = 0; % pi/4; % 0;
C = [3 10 3]'; % enfrentado

generar_camara(f, s, px, py, theta_x, theta_y, theta_z, C)
```

Mundo (X=rojo,Y=verde,Z=azul)



Vista de la camara (X=rojo,Y=verde)

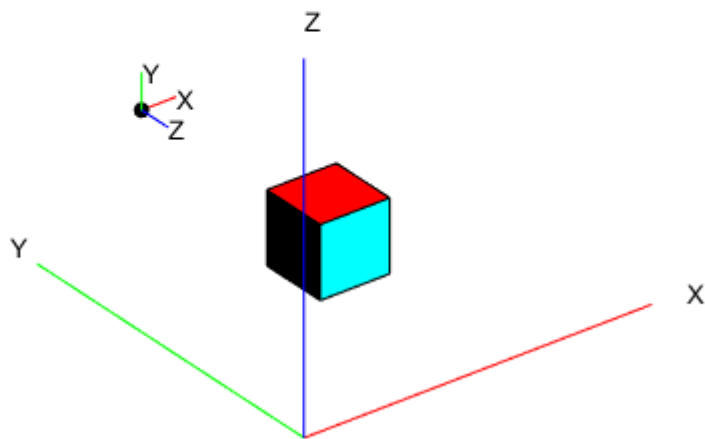


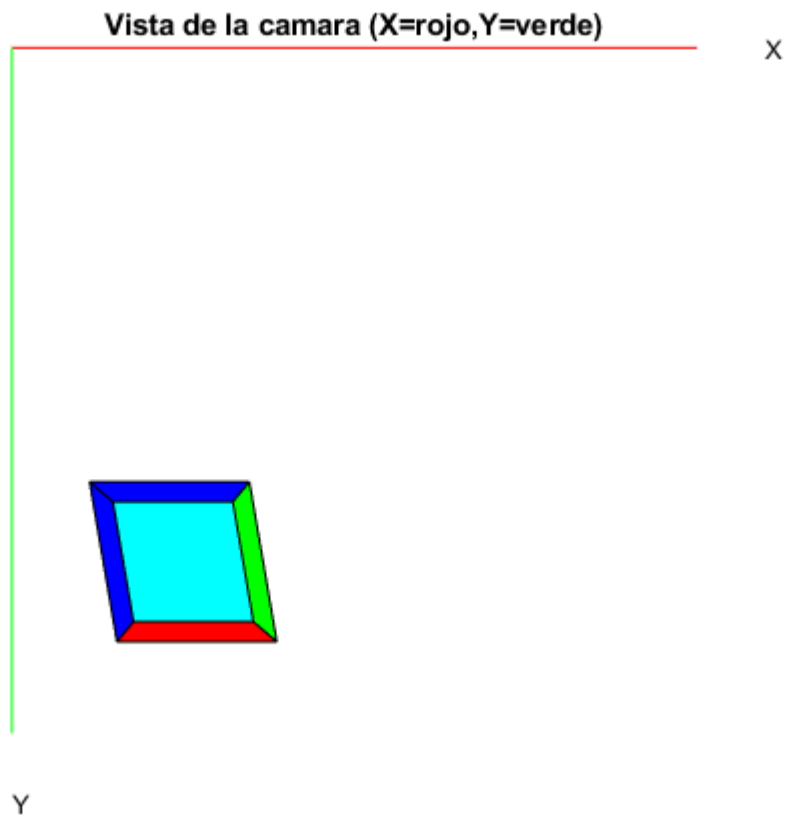
```
f = 0.7;  
s = 0.12;  
px = 0.25; py = 0.75;
```

```
theta_x = pi/2; % -3*pi/4;  
theta_y = 0;  
theta_z = 0; % pi/4; % 0;  
C = [3 10 3]'; % enfrentado
```

```
generar_camara(f, s, px, py, theta_x, theta_y, theta_z, C)
```

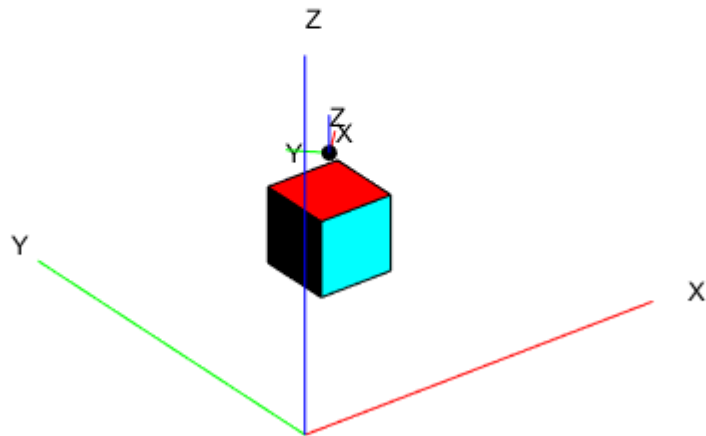
**Mundo (X=rojo,Y=verde,Z=azul)**



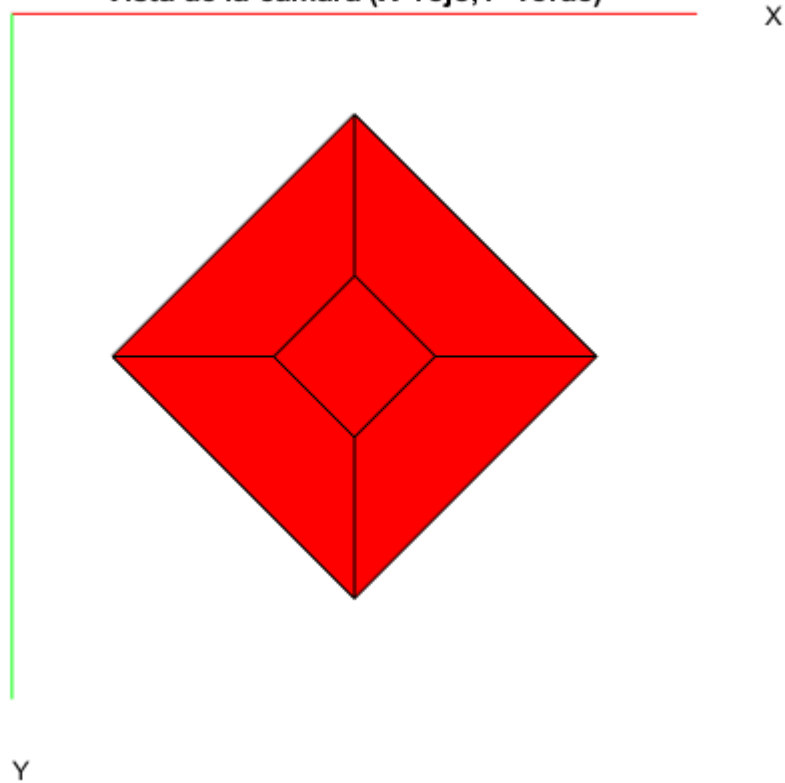


```
f = 0.25;  
s = 0;  
px = 0.5; py = 0.5;  
theta_x = 0;  
theta_y = 0;  
theta_z = pi/4;  
C = [3 3 5]'; % desde arriba, centrado en el cubo  
  
generar_camara(f, s, px, py, theta_x, theta_y, theta_z, C)
```

Mundo (X=rojo,Y=verde,Z=azul)



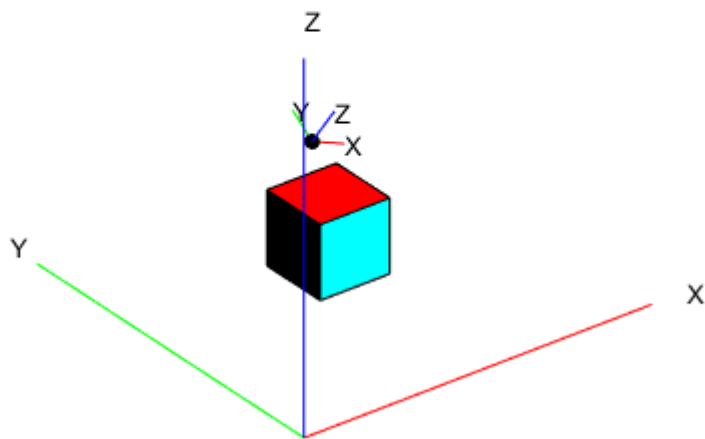
Vista de la camara (X=rojo,Y=verde)



```
f = 0.1;  
s = 0;  
px = 0.5; py = 0.5;
```

```
theta_x = pi/8;  
theta_y = pi/8;  
theta_z = 0;  
C = [1 1 7]';  
  
generar_camara(f, s, px, py, theta_x, theta_y, theta_z, C)
```

**Mundo (X=rojo,Y=verde,Z=azul)**





Vista de la camara (X=rojo,Y=verde)

X

Y

