

Analog Inputs of ATMEGA328P

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Learning Objectives

LO-3: Use microcontrollers to implement basic functions of typical embedded systems in Assembly and C languages.

Using analog inputs with ATMEGA 328P

At the end of this activity, you will be able to implement analog to digital converter on ATMEGA 328P microcontroller

You need to have **the data sheet for** ATMEGA 328P microcontroller in order to complete this exercise

Instructions to Complete the Workshop Activity

Workshops are group activities with three members for each group.

Every member of the group should have a copy of the activity and should be able to demonstrate the results to the instructor.

Evaluation deadlines will be given after each workshop session. Every student/group has to demonstrate their work and submit the required documents/simulation files to the LMS depending on the instructions give during the workshop.

It is your responsibility to get your work demonstrations evaluated by the instructor within one week from the date of workshop delivery.

A/D converter in Atmega 328P

• Features a 10-bit successive approximation ADC.

• Connected to an 8-channel analog multiplexer which allows eight single-ended voltage inputs constructed from the pins of Port A.

The minimum value represents GND.

 The maximum value can be customised to the voltage on the AREF/AVcc or internal 1.1V depending on the settings.

6 analog input pins in PORTA

Figure 1

Number of output bits, D, corresponds to the number of quantization levels, N. $N = 2^{D}$ and the number of quantization intervals is Q = N - 1.

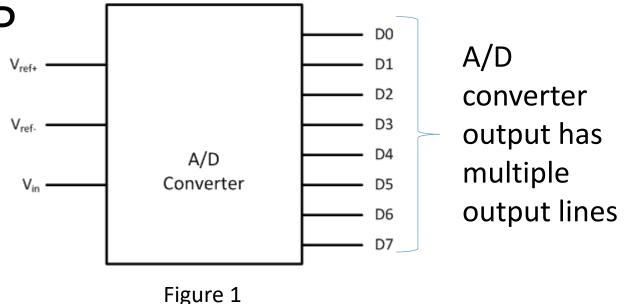
ADC output = Q * (Vin - Vref-)/(Vref+ - Vref-)

In some cases Vref- may not be present. They consider the Vref- to be the ground voltage.

A/D converter in Atmega 328P

ADC output = Q * Vin / Vref+

ground voltage.



In some cases Vref- may not be present. They consider the Vref- to be the

3. Settings Required for A/D Converter

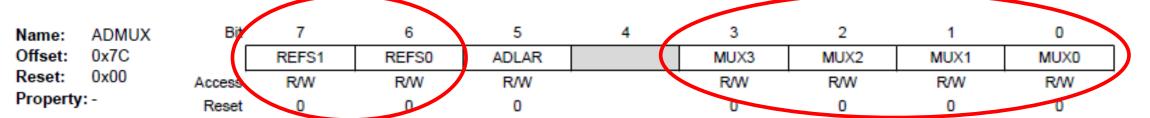


Figure 3.1

REFS[1:0]	Voltage Reference Selection
00	AREF, Internal V _{ref} turned off
01	AV _{CC} with external capacitor at AREF pin
10	Reserved
11	Internal 1.1V Voltage Reference with external capacitor at AREF pin

Set 00 at REFS1 : REFS0 in order to enable AREF external reference voltage

ADLAR bit is to be set if you are to left align the result

MUX[3:0]	Single Ended Input
0000	ADC0
0001	ADC1
0010	ADC2
0011	ADC3
0100	ADC4
0101	ADC5

Select channel 0 by dressing MUX3:MUX0 to 0000

Settings Required for A/D Converter

Name: ADCSRA

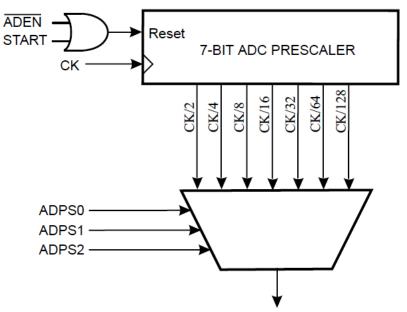
Offset: 0x7A Reset: 0x00

Property: -

Bit	7	6	5	4	3	2	1	0
	ADEN	ADSC	ADATE	ADIF	ADIE	ADPS2	ADPS1	ADPS0
cess	R/W	R/W	R/W	RW	R/W	R/W	RW	R/W
Reset	0	0	0	0	0	0	0	0

Prescaling and Conversion Timing

Figure 28-3. ADC Prescaler



Prescalar	Frequency
2	8 Mhz
4	4 Mhz
8	2 Mhz
16	1 Mhz
32	500 khz
64	250 khz
128	125 khz

111	128
125 khz i	s between
50 and 20	00 khz.

ADPS[2:0]

000

001

010

100

101

110

Division Factor

16

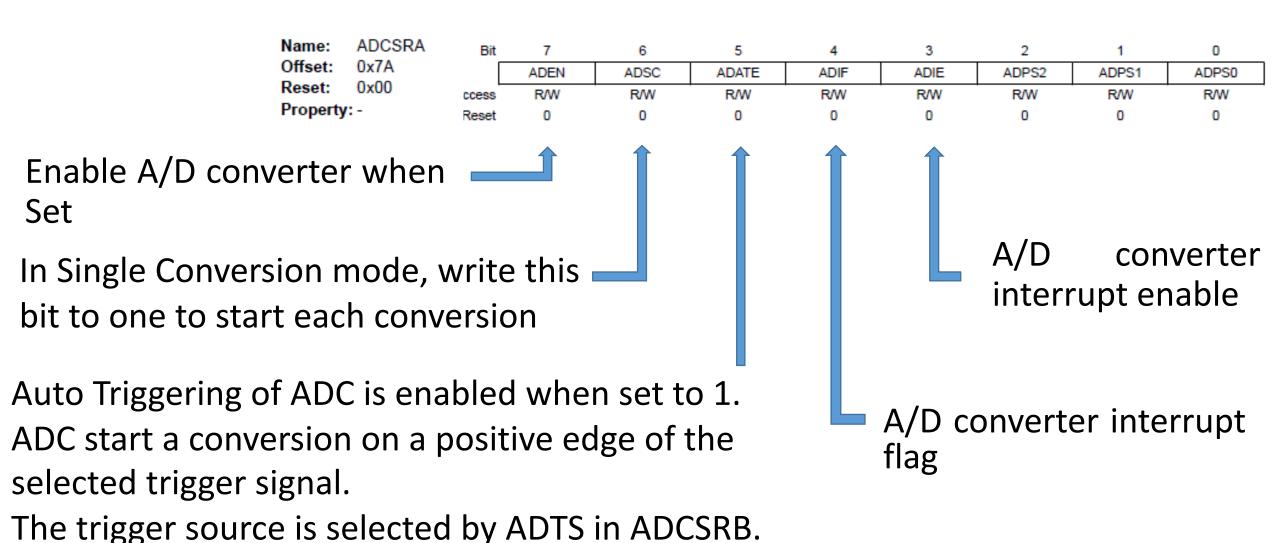
32 64

Pre-scalar should be 128

By default, the successive approximation circuitry requires an input clock frequency between 50kHz and 200kHz to get maximum resolution. If a lower resolution than 10 bits is needed, the input clock frequency to the ADC can be higher than 200kHz to get a higher sample rate.

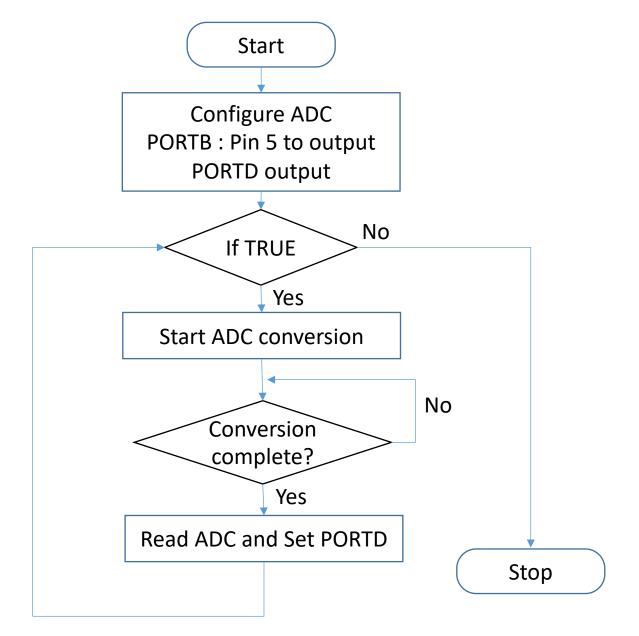
ADC CLOCK SOURCE

Settings Required for A/D Converter

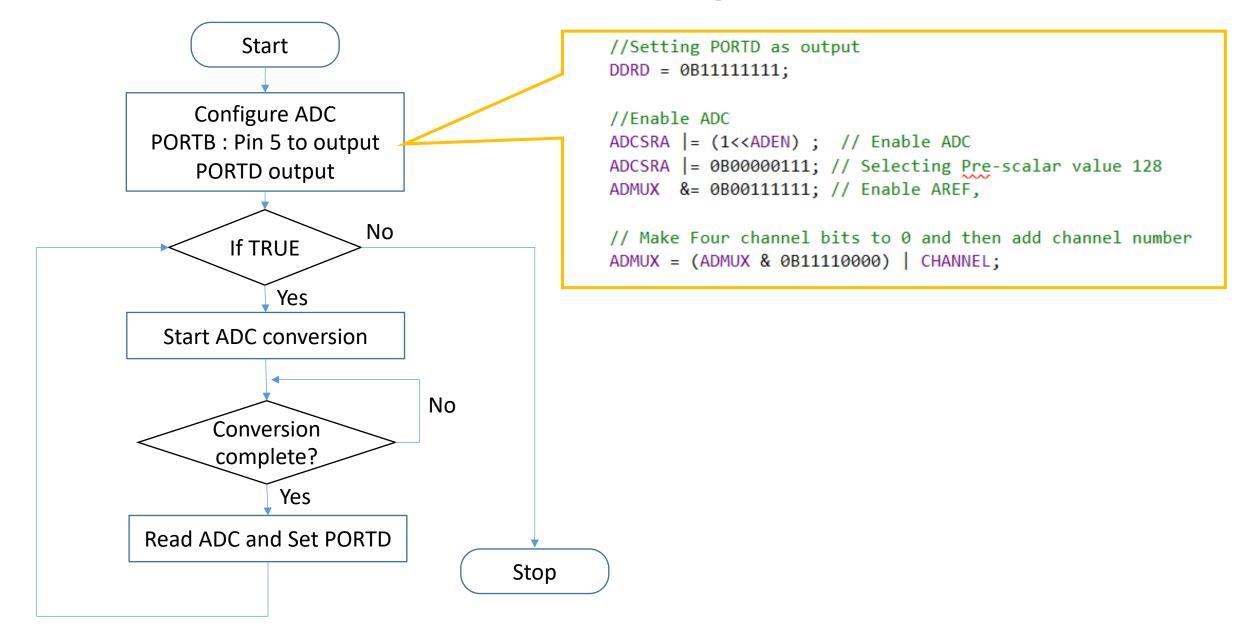


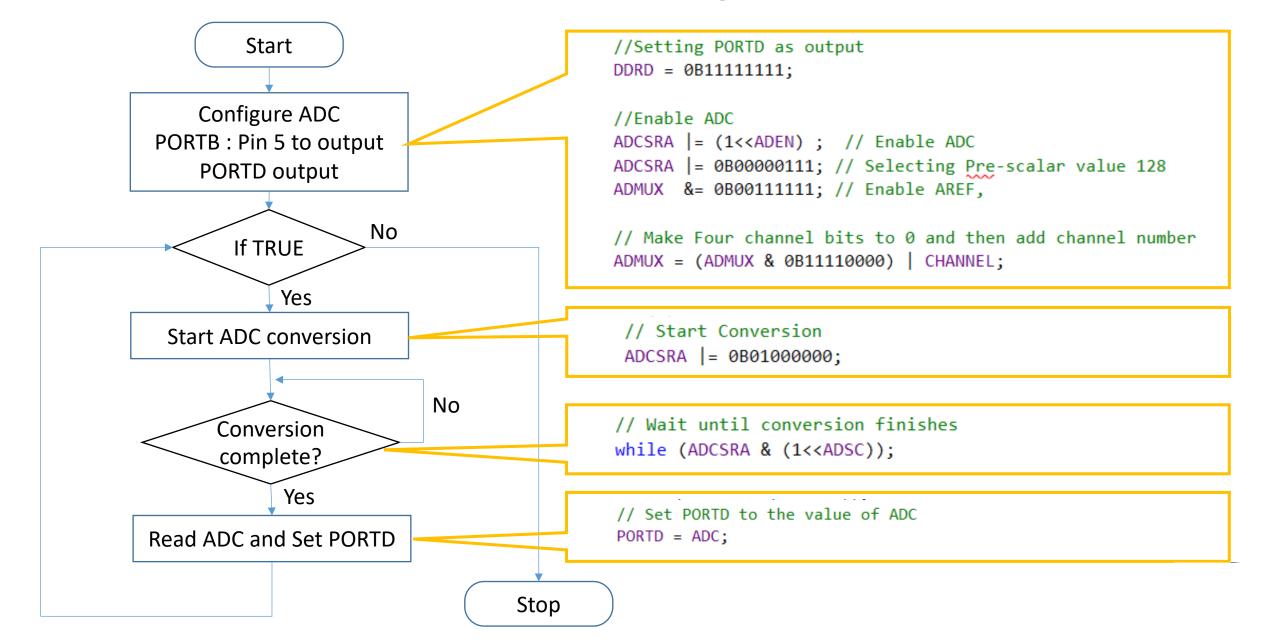
Look at the data sheet for ADCSRB

Figure 3.2



Single Conversion Mode

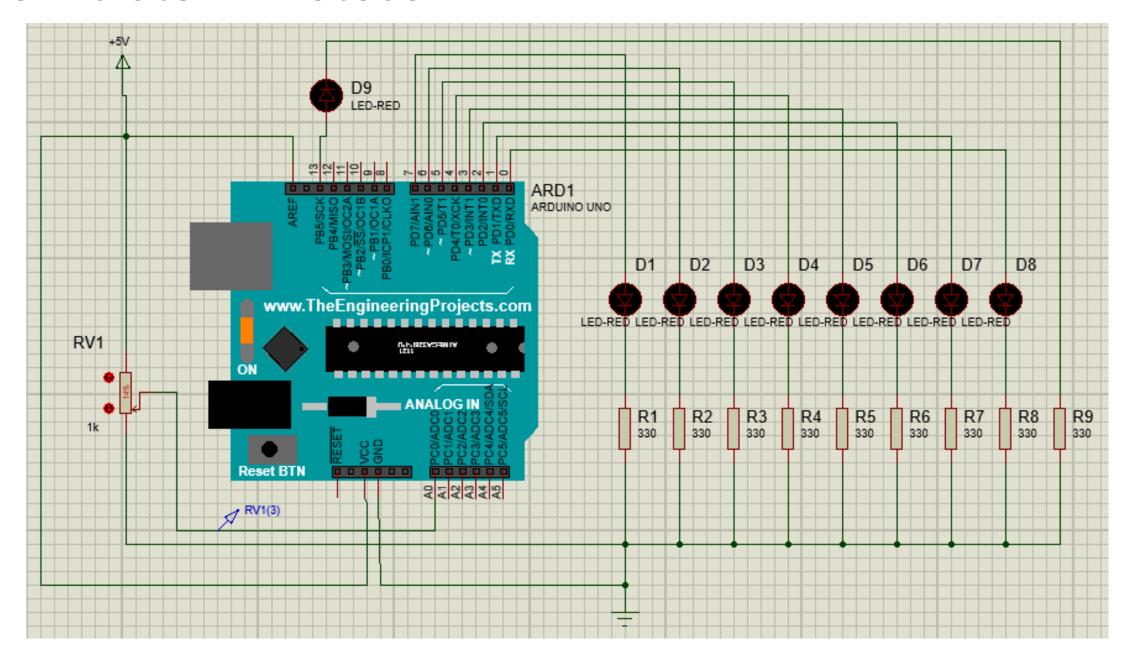


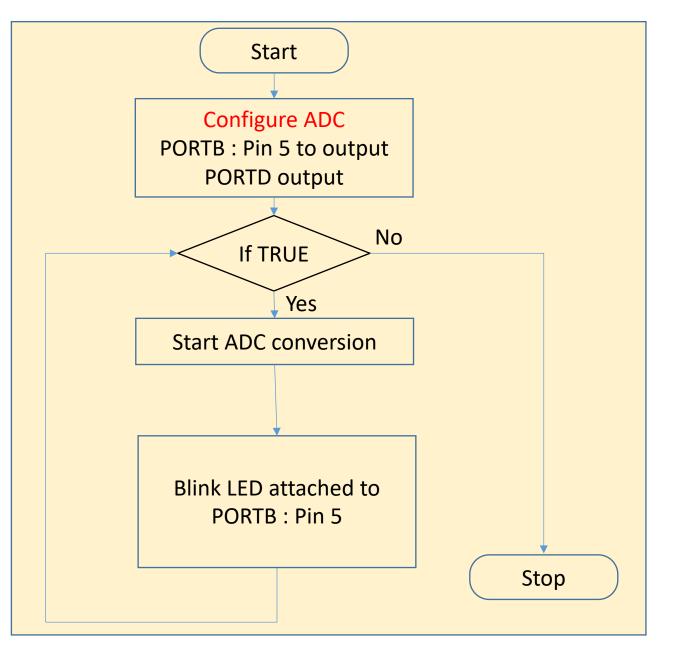


```
#define F_CPU 16000000UL
#include <avr/io.h>
#include <util/delay.h>
#define CHANNEL 0B00000000
```

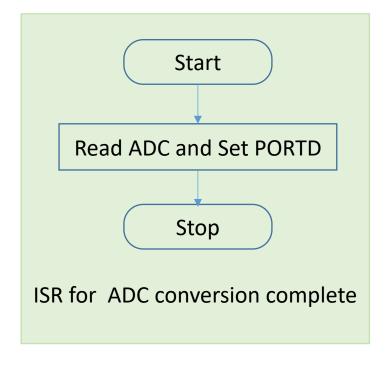
```
]int main(void)
    //Setting PORTD as output
    DDRD = 0B111111111;
    //Enable ADC
    ADCSRA = (1<<ADEN); // Enable ADC
    ADCSRA |= 0B00000111; // Selecting Pre-scalar value 128
    ADMUX &= 0B00111111; // Enable AREF,
    // Make Four channel bits to 0 and then add channel number
    ADMUX = (ADMUX & 0B11110000) | CHANNEL;
    while (1)
       // Start Conversion
        ADCSRA = 0B01000000;
        // Wait until conversion finishes
        while (ADCSRA & (1<<ADSC));</pre>
        // Set PORTD to the value of ADC
        PORTD = ADC;
        delay ms(500);
```

Simulate In Proteus

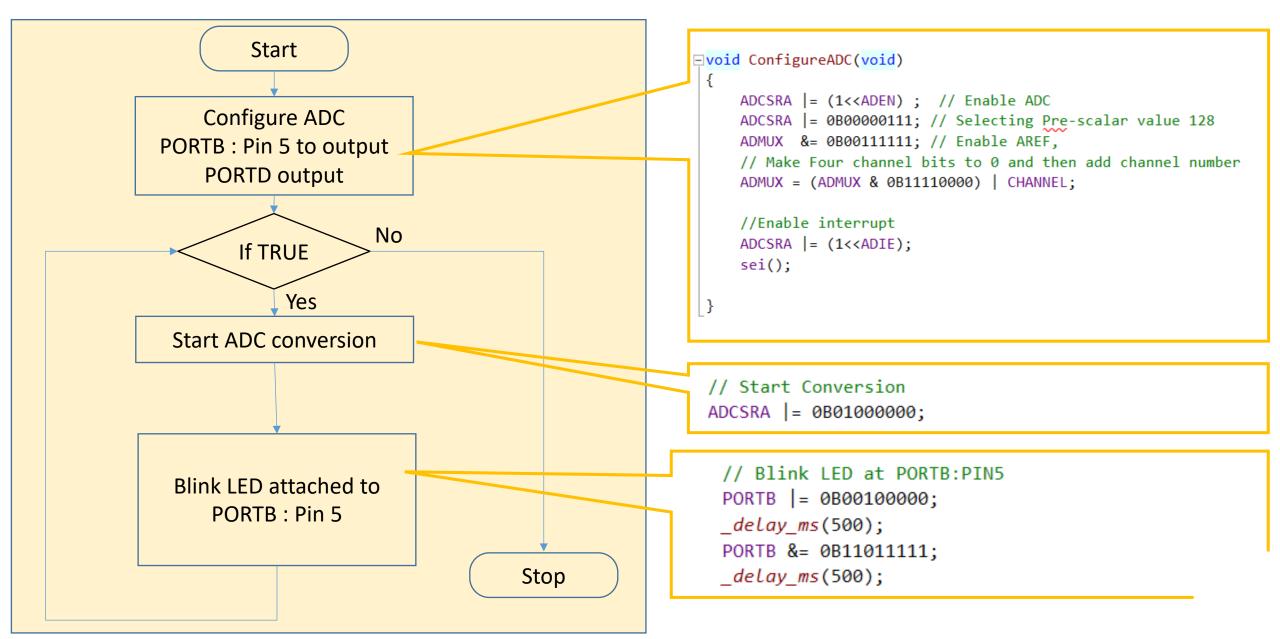




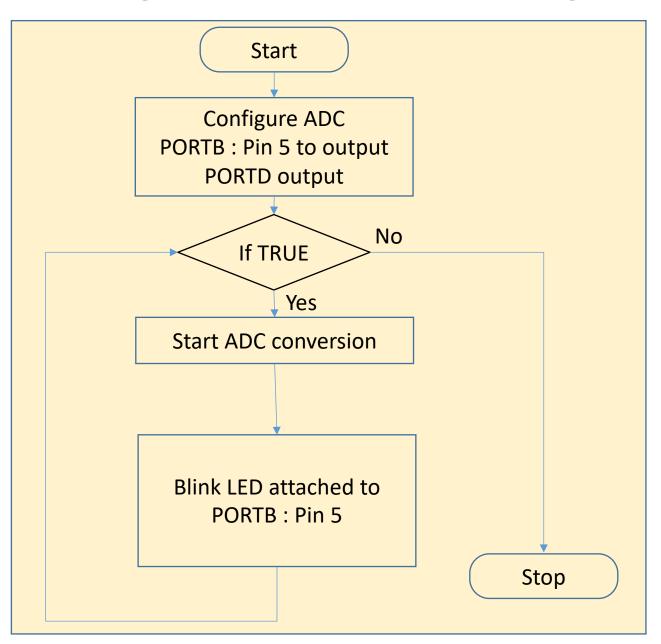
Single Conversion Mode with Interrupt

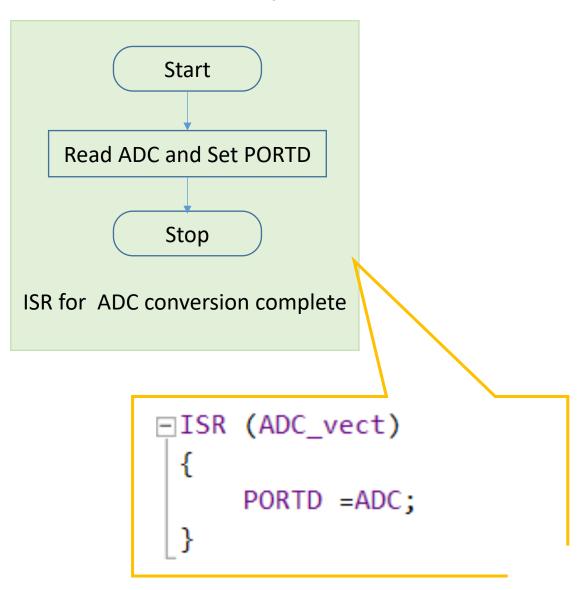


Coding A/D Converter Program With Interrupt



Coding A/D Converter Program With Interrupt





Code for A/D Converter Program With Interrupt

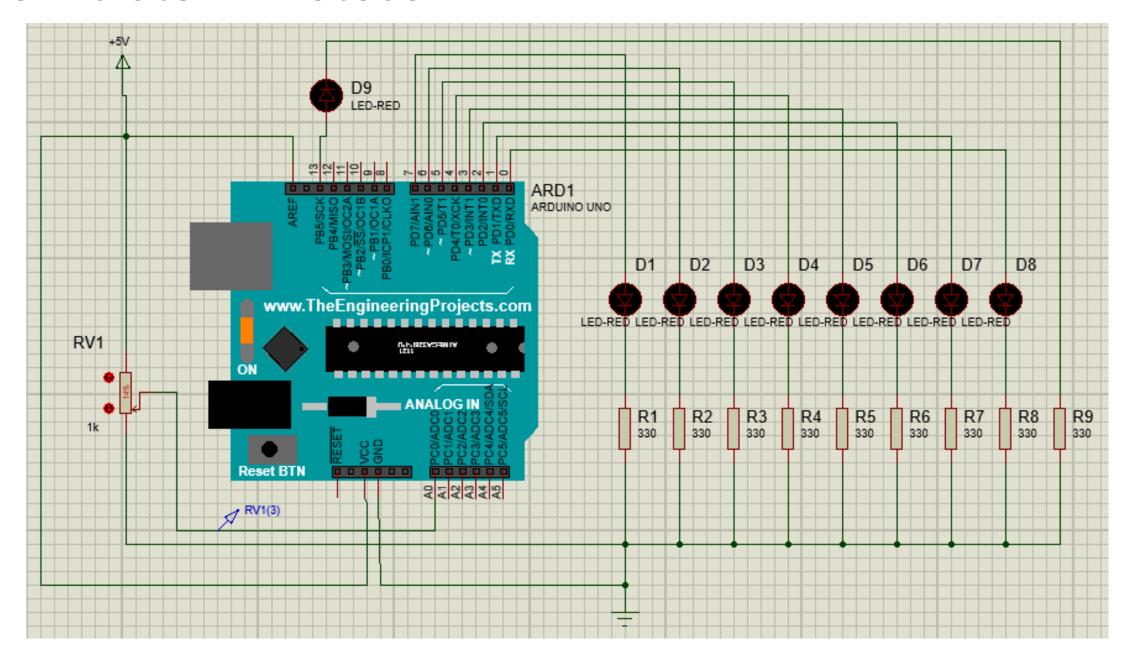
```
#define F CPU 16000000UL
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>
#define CHANNEL 0B00000000
void ConfigureADC(void);
int main(void)
   //Setting PORTD as output
    DDRD = 0B111111111;
    DDRB = 0B00100000;
    ConfigureADC();
    while (1)
        // Start conversion
        ADCSRA = 0B01000000; // Start Conversion
        // Blink LED at PORTB:PIN5
        PORTB |= 0B00100000;
        _delay_ms(500);
        PORTB &= 0B11011111;
        delay ms(500);
```

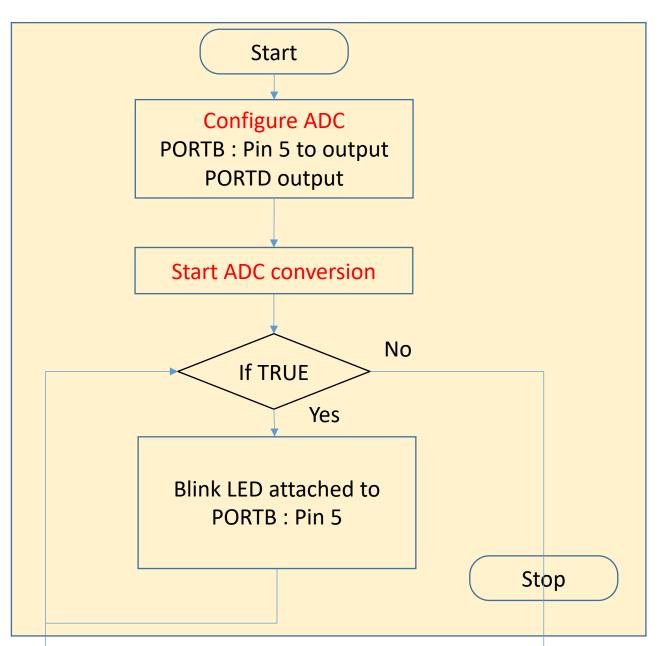
```
□void ConfigureADC(void)
     ADCSRA = (1<<ADEN); // Enable ADC
     ADCSRA |= 0B00000111; // Selecting Pre-scalar value 128
     ADMUX &= 0B00111111; // Enable AREF,
     // Make Four channel bits to 0 and then add channel number
     ADMUX = (ADMUX & 0B11110000) | CHANNEL;
     //Enable interrupt
     ADCSRA |= (1<<ADIE);
     sei();

☐ISR (ADC vect)

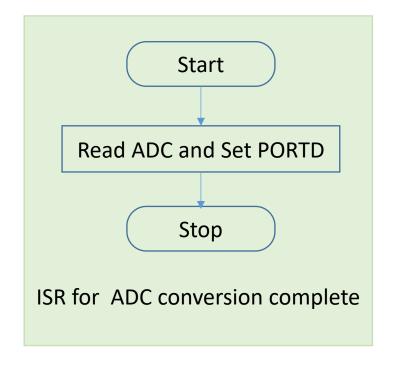
     PORTD =ADC:
```

Simulate In Proteus





Free Running Mode with Interrupt



Coding A/D Converter Program With Interrupt

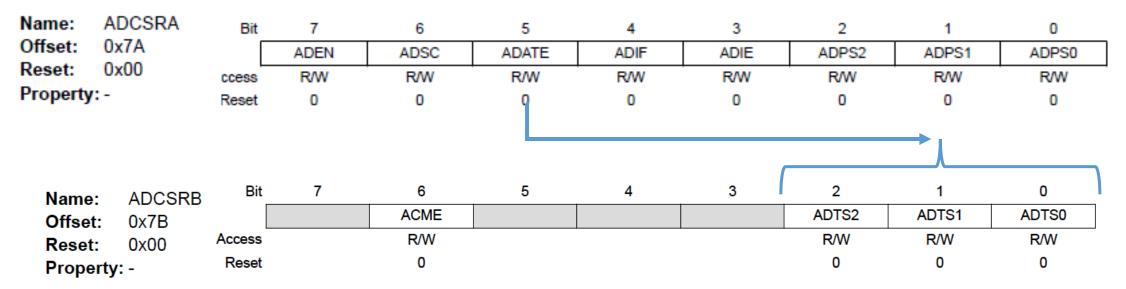
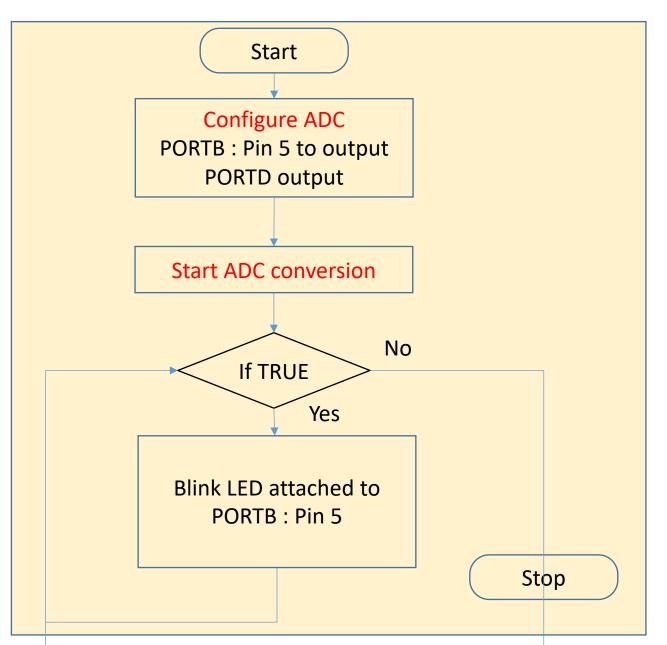
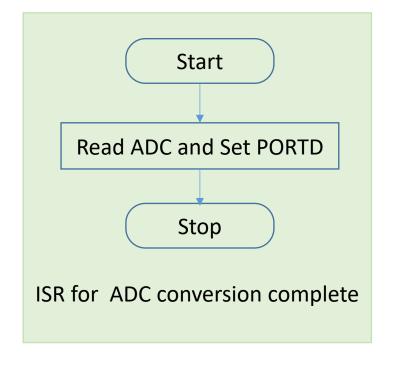


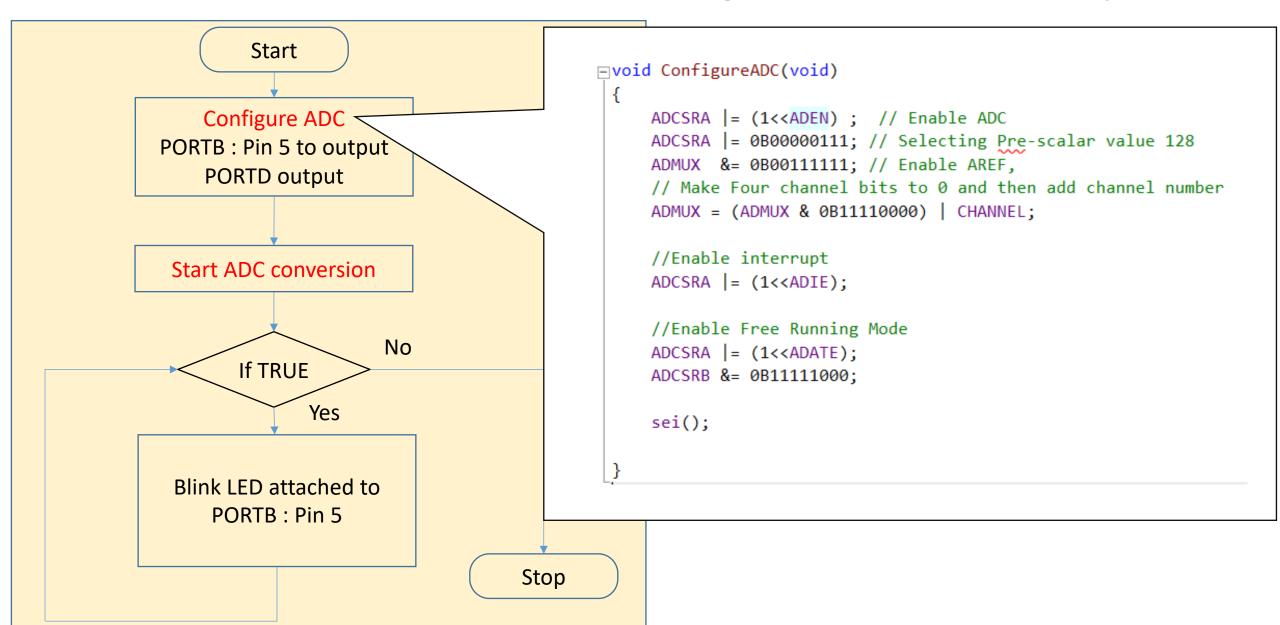
Table 28-6. ADC Auto Trigger Source Selection

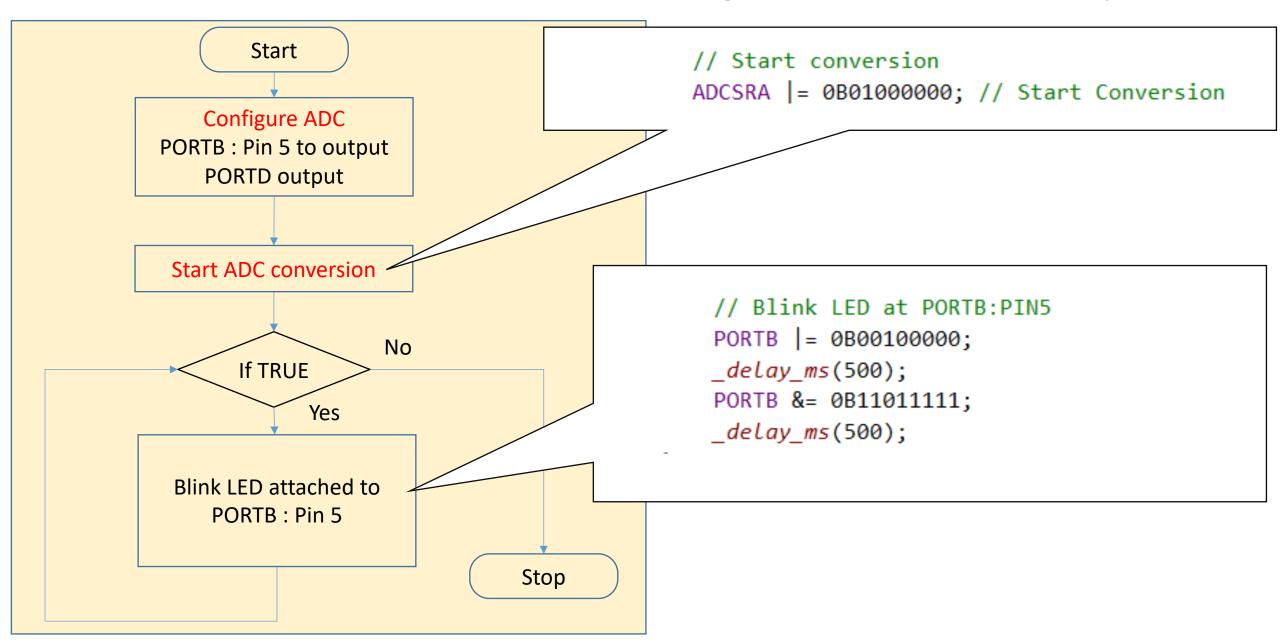
ADTS[2:0]	Trigger Source
000	Free Running mode
001	Analog Comparator
010	External Interrupt Request 0
011	Timer/Counter0 Compare Match A
100	Timer/Counter0 Overflow
101	Timer/Counter1 Compare Match B
110	Timer/Counter1 Overflow
111	Timer/Counter1 Capture Event

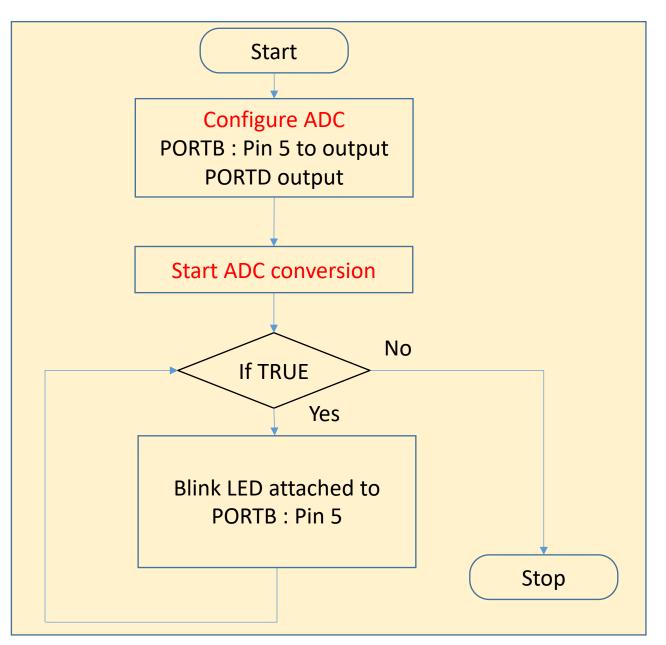


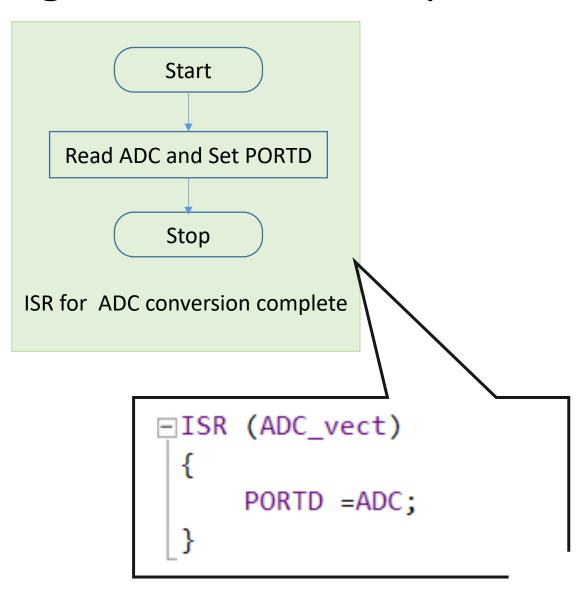
Free Running Mode with Interrupt











Code for A/D Converter Program With Interrupt

```
#define F CPU 16000000UL
#include <avr/io.h>
#include <util/delay.h>
#include <avr/interrupt.h>
#define CHANNEL 0B00000000
void ConfigureADC(void);
int main(void)
   //Setting PORTD as output
    DDRD = 0B111111111;
    DDRB = 0800100000;
    ConfigureADC();
    // Start conversion
    ADCSRA = 0B01000000; // Start Conversion
    while (1)
        // Blink LED at PORTB:PIN5
        PORTB |= 0B00100000;
       _delay_ms(500);
        PORTB &= 0B11011111;
       delay ms(500);
```

```
□void ConfigureADC(void)
     ADCSRA = (1<<ADEN); // Enable ADC
     ADCSRA |= 0B00000111; // Selecting Pre-scalar value 128
     ADMUX &= 0B00111111; // Enable AREF,
     // Make Four channel bits to 0 and then add channel number
     ADMUX = (ADMUX & 0B11110000) | CHANNEL;
     //Enable interrupt
     ADCSRA = (1 << ADIE);
     //Enable Free Running Mode
     ADCSRA = (1 << ADATE);
     ADCSRB &= 0B11111000;
     sei();
□ISR (ADC vect)
     PORTD =ADC;
```

Simulate In Proteus

