# FA3 KHAFAJI

March 10, 2025

[1]: from sympy import \*

```
import numpy as np
     import polars as pl
    0.0.1 1.
[2]: x = symbols('x')
    h = 0.1
     x_{list} = [2.9, 3, 3.1, 3.2]
     fx_list = [-4.827866, -4.240058, -3.496909, -2.596792]
[3]: def three_point(x_vals, fx_vals, h):
         f_prime_vals = []
         for idx, fval in enumerate(fx_vals):
             if idx == 0:
                 x plus h idx = x vals.index(x vals[idx] + h)
                 x_plus_2h_idx = x_vals.index(x_vals[idx] + 2*h)
                 fx_plus_h = fx_vals[x_plus_h_idx]
                 fx_plus_2h = fx_vals[x_plus_2h_idx]
                 f_{prime} = (1/(2*h))*(-3*fval +4*fx_plus_h-fx_plus_2h) # left approx
                 f_prime_vals.append(f_prime)
             elif idx == len(fx_vals)-1:
                 x_minus_h_idx = x_vals.index(x_vals[idx] - h)
                 x_{minus_2h_idx} = x_{vals.index}(x_{vals_idx} - 2*h)
                 fx_minus_h = fx_vals[x_minus_h_idx]
                 fx_minus_2h = fx_vals[x_minus_2h_idx]
                 f_prime = (1/(2*h))*(3*fval -4*fx_minus_h +fx_minus_2h) # right_{\square}
      \hookrightarrow approx
                 f_prime_vals.append(f_prime)
             else:
                 x_plus_h_idx = x_vals.index(x_vals[idx] + h)
                 x_minus_h_idx = x_vals.index(x_vals[idx] - h)
                 fx_plus_h = fx_vals[x_plus_h_idx]
```

```
fx_minus_h = fx_vals[x_minus_h_idx]
                 f_{prime} = (1/(2*h))*(-fx_{minus_h+fx_plus_h}) #midpoint
                 f_prime_vals.append(f_prime)
         return f_prime_vals
[4]: fprime_x_list = three_point(x_list, fx_list,h)
     data = {
         "x":x list,
         "fx":fx_list,
         "fprime_x":fprime_x_list
     }
[5]: df = pl.DataFrame(data)
     df
[5]: shape: (4, 3)
            fx
                       fprime_x
      х
      ---
            ---
                        ___
      f64 f64
                        f64
      2.9 -4.827866 5.101375
      3.0 -4.240058 6.654785
      3.1 -3.496909 8.21633
      3.2 -2.596792 9.78601
    0.0.2 2.
[6]: x = symbols('x')
     fx_2 = tan(x)
     h = 0.1
     nodes = [2+0.1*n \text{ for } n \text{ in } range(1,6)]
     print(nodes)
    [2.1, 2.2, 2.3, 2.4, 2.5]
[7]: fx_2-5prime = simplify(diff(fx_2, x, 4))
     max_in_interval = maximum(fx_2_5prime, x, Interval(2.1,2.5))
     error = (max_in_interval)*(h**4)/30
     print(f"the absolute maximum error is {abs(error)}")
```

the absolute maximum error is 0.000114034352711179

#### 0.0.3 3.

```
[8]: x_list_3 = [1.28, 1.29, 1.3, 1.31, 1.4]
y_list_3 = [11.59006, 13.78176, 14.04276, 14.30741, 16.86187]
h=0.01

approx_3 = (y_list_3[1]-2*y_list_3[2]+y_list_3[3])/(h**2)

print(f"The approximate derivative of f(1.3) is {round(approx_3,10)}")
```

The approximate derivative of f(1.3) is 36.5

#### 0.0.4 4.

getting  $N_3(h)$ , an approximation to  $f'(x_0)$  for  $f(x) = x + e^x$ , with h=0.4

```
[9]: x = symbols('x')
x_list_4 = [-0.4, 0, 0.4]
f_3 = x + E**(x)
h= 0.4

n1_h = (1/(2*h))*(-f_3.subs(x,-0.4)+f_3.subs(x,0.4)) #midpoint

n1_hdiv2 = (1/(2*(h/2)))*(-f_3.subs(x,-0.2)+f_3.subs(x,0.2))

n1_hdiv4 = (1/(2*(h/4)))*(-f_3.subs(x,-0.1)+f_3.subs(x,0.1))

n2_h = (1/3)*(4*n1_hdiv2 - n1_h)

n2_hdiv2 = (1/3)*(4*n1_hdiv4 - n1_hdiv2)

n3_h = (1/15)*(16*n2_hdiv2-n2_h)

print(f"The approximation to the derivative of the given function at x_0 = 0 is_u ⋅ {n3_h}")
```

The approximation to the derivative of the given function at  $x_0 = 0$  is 2.0000001273551

# 0.0.5 5.

approximate

$$\int_{0}^{\frac{\pi}{4}} x \sin(x) \, dx$$

using the Trapezoidal rule

[10]: 
$$x = symbols('x')$$

$$f_5 = x*sin(x)$$

The approximation of the integral using the trapezoidal rule is: sqrt(2)\*pi\*\*2/64, which is approximately 0.2180895062

[10]:  $\frac{\sqrt{2}\pi^2}{64}$ 

### 0.0.6 6.

approximate

$$\int_0^{\frac{\pi}{4}} x sin(x) \, dx$$

using the Simpson's rule

# 0.0.7 7.

abs(error\_simp\_7)

```
Give the errors for 5 and 6
     for 5. the error is given by \frac{h^3}{12}f''(\xi)
     for 6. the error is given by \frac{h^5}{90}f^{(4)}(\xi)
[12]: # solving for error for number 5
      f_2ndprime_7 = diff(f_5, x, 2)
      print(f"The 2nd derivative of the given function is: {f_2ndprime_7}")
      print("Since x is small in the domain, and the range of both sinx and cosx in \Box
       the domain are from 0 to 0.785, the function will yield the highest value in,
       ⇔the interval at f''(0)")
      error_trap_7 = ((h_5**3)/12) * f_2ndprime_7.subs(x, 0)
      error_trap_7 = simplify(error_trap_7)
      print(f"The absolute maximum error for number 5 is {abs(error_trap_7)}")
      abs(error_trap_7)
     The 2nd derivative of the given function is: -x*sin(x) + 2*cos(x)
     Since x is small in the domain, and the range of both sinx and cosx in the
     domain are from 0 to 0.785, the function will yield the highest value in the
     interval at f''(0)
     The absolute maximum error for number 5 is pi**3/384
[12]: \pi^3
     384
[13]: # solving for error in number 6
      f_4thprime_7 = diff(f_6, x, 4)
      print(f"The 4th derivative of the given function is: {f_2ndprime_7}")
      print("Since x is small in the domain, and the range of both sinx and cosx in \sqcup
       \hookrightarrowthe domain are from 0 to 0.785, the function will yield the highest value in_{\sqcup}
       ⇔the interval at f''(0)")
      error_simp_7 = ((h_6**5)/90) * f_4thprime_7.subs(x, 0)
      error_simp_7 = simplify(error_simp_7)
      print(f"The absolute maximum error for number 5 is {abs(error_simp_7)}")
```

The 4th derivative of the given function is: -x\*sin(x) + 2\*cos(x)Since x is small in the domain, and the range of both sinx and cosx in the domain are from 0 to 0.785, the function will yield the highest value in the interval at f''(0)

The absolute maximum error for number 5 is pi\*\*5/737280

[13]:  $\pi^5$   $\overline{737280}$ 

#### 0.0.8 8.

approximate  $\int_1^1 0 \frac{1}{x} dx$  using Closed and Open Newton-Cotes formula for n=3, Are the accuracies consistent with the error formulas?

```
[14]: # closed newton cotes
      x = symbols('x')
      f 8 = 1/x
      n=3
      a_8 = 1
      b_8 = 10
      h_8 = (10-1)/n
      x1_8_closed = a_8 + h_8
      x2_8_closed = a_8 + 2*h_8
      approx_closed_8 = ((3*h_8)/8)*(
          f_8.subs(x, a_8)
          + 3*f_8.subs(x, x1_8_closed)
          + 3 *f_8.subs(x, x2_8\_closed)
          + f_8.subs(x, b_8)
      approx_closed_8 = simplify(approx_closed_8)
      print(f"The approximated integral using the Closed Newton-Cotes formula is⊔
       →{approx_closed_8}")
```

The approximated integral using the Closed Newton-Cotes formula is 2.56339285714286

The approximated integral using the Open Newton-Cotes formula is 2.11637855533253

The indefinite integral is log(x), which is the natural logarithm The evaluated integral results to: log(10), which is approximately equal to 2.302585093

the 4th prime of our function is 24/x\*\*5. From the interval of [1,10], x=1

provides the maximum value, giving us f(x) = 24

The absolute maximum error for the Closed Newton-Cotes formula is 218.7, while it is 299.1816 for the Open Newton-Cotes formula

The error values we obtained are very big, which can be blamed on our huge intervals (3 for closed, 1.8 for open). Although our approximations are well within the error range, it is still worrying whether or not our approximations are approximations or wild guesses.

[17]: