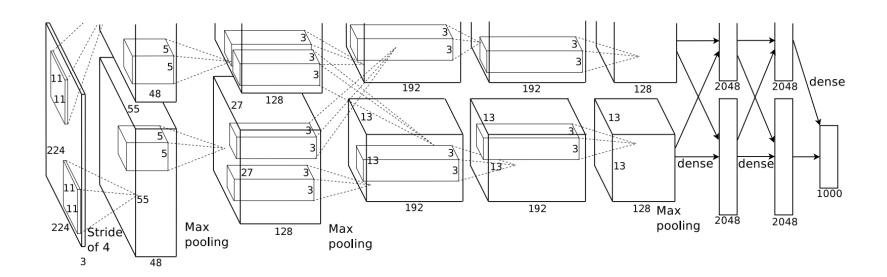


CONVOLUTIONAL NEURAL NET ARCHITECTURES

ALEXNET

- Created in 2012 for the ImageNet Large Scale Visual Recognition Challenge (ILSVRC)
- Task: predict the correct label from among 1000 classes
- Dataset: around 1.2 million images
- Considered the "flash point" for modern deep learning
- Demolished the competition
- Top 5 error rate of 15.4%
- Next best: 26.2%

ALEXNET—MODEL DIAGRAM



ALEXNET—DETAILS

- They performed data augmentation for training
- Includes cropping, horizontal flipping, and other manipulations

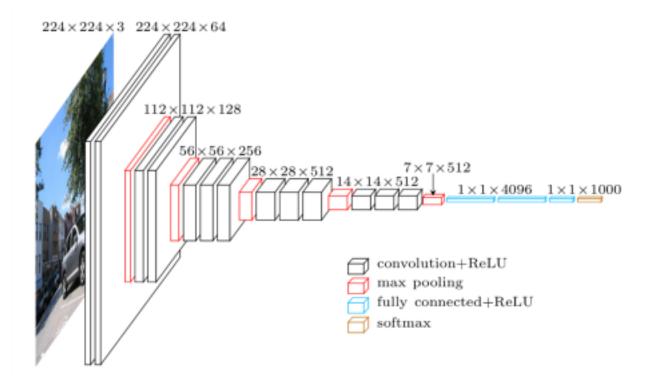
ALEXNET—DETAILS

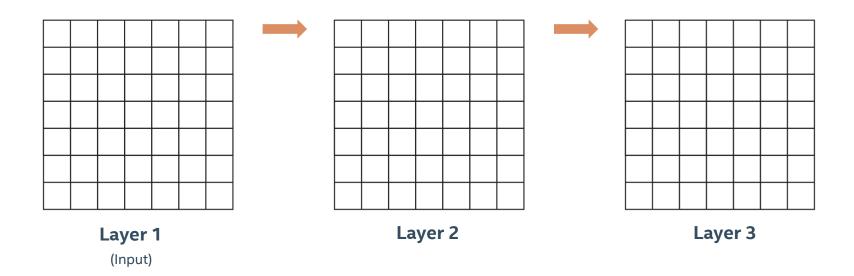
- They performed data augmentation for training
 - Cropping, horizontal flipping, and other manipulations
- Basic Template:
 - Convolutions with ReLUs
 - Sometimes add maxpool after convolutional layer
 - Fully connected layers at the end before a softmax classifier

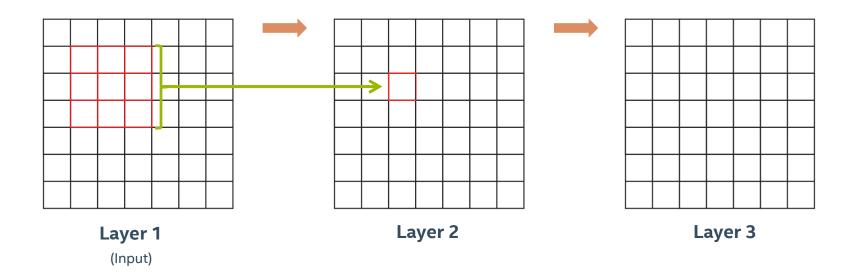
- Simplify Network Structure
- Avoid Manual Choices of Convolution Size
- Very Deep Network with 3x3 Convolutions
- These "effectively" give rise to larger convolutions

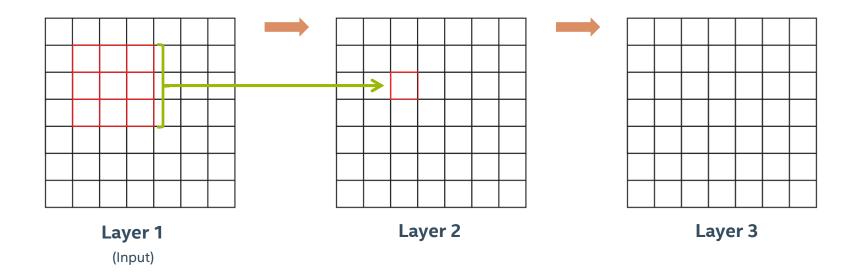
Reference: Very Deep Convolutional Networks for Large-Scale Image Recognition Karen Simonyan and Andrew Zisserman, 2014

VGG16 DIAGRAM

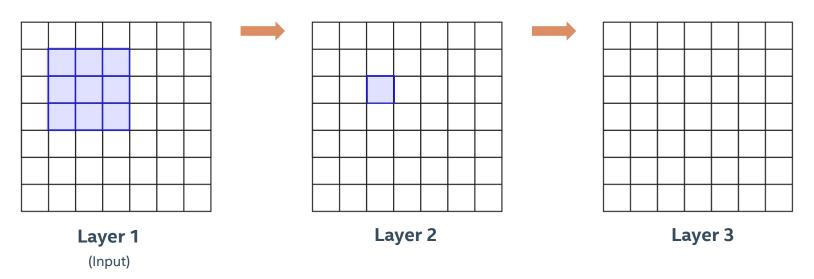




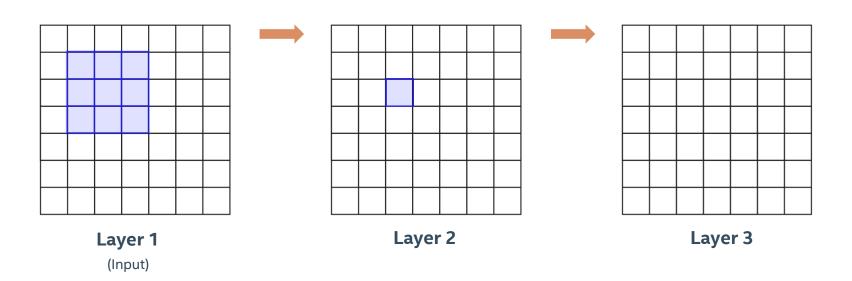




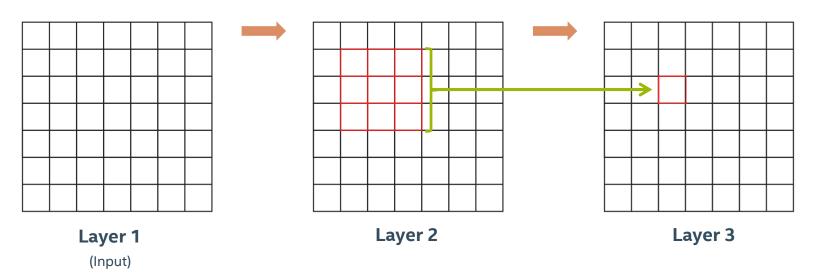
We can say that the "receptive field" of layer 2 is 3x3. Each output has been influenced by a 3x3 patch of inputs.

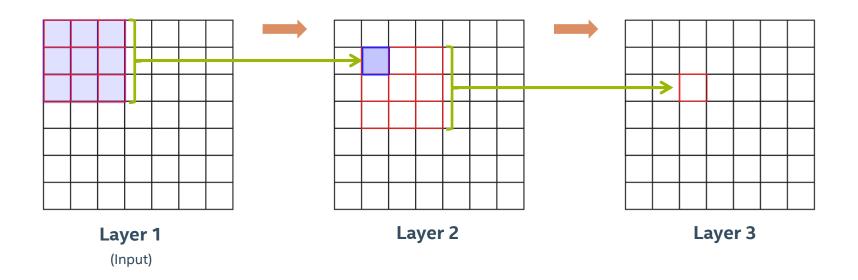


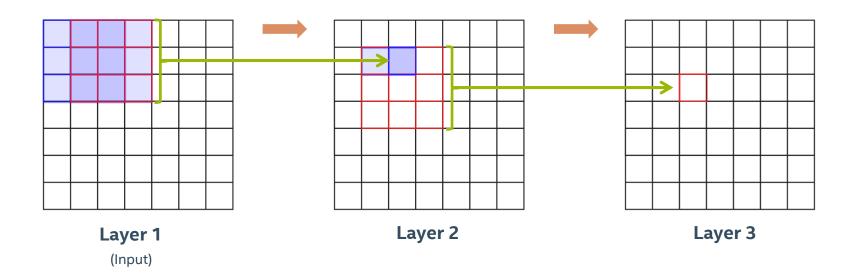
What about on layer 3?

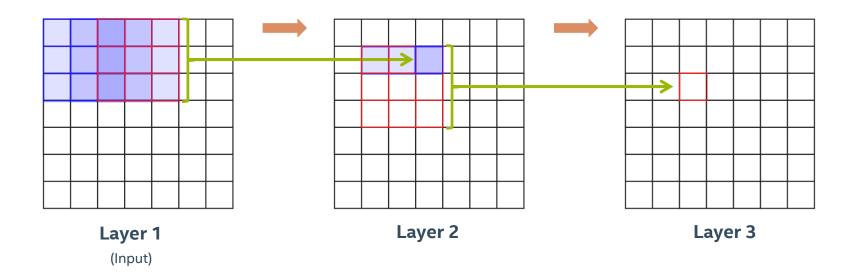


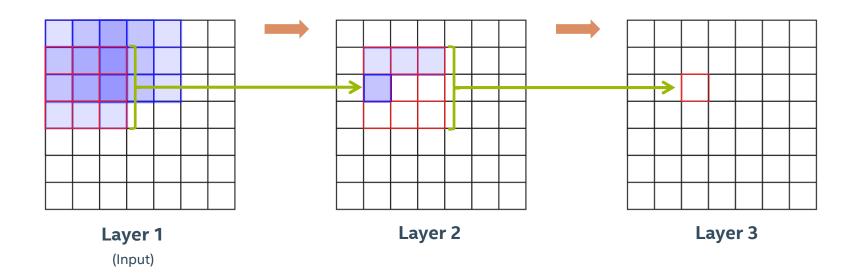
This output on Layer 3 uses a 3x3 patch from layer 2. How much from layer 1 does it use?

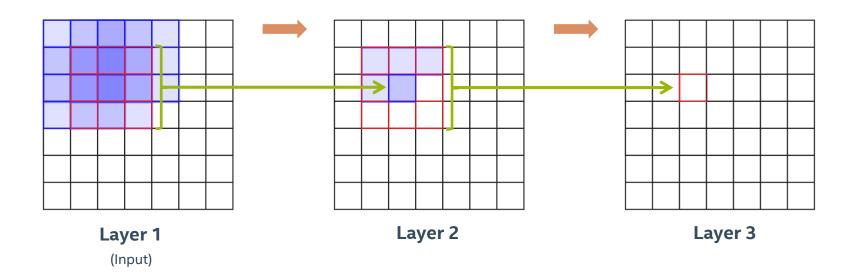


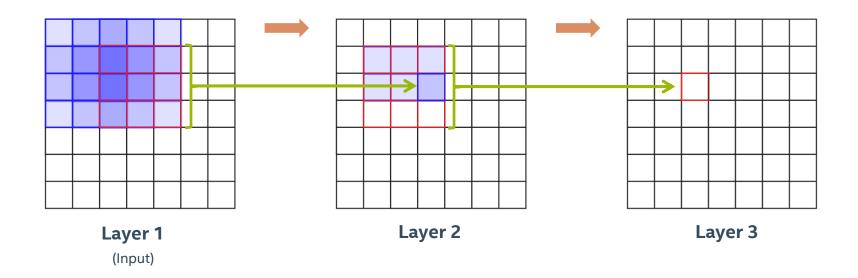


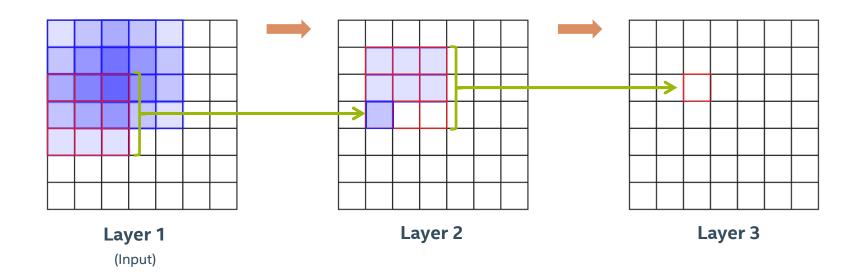


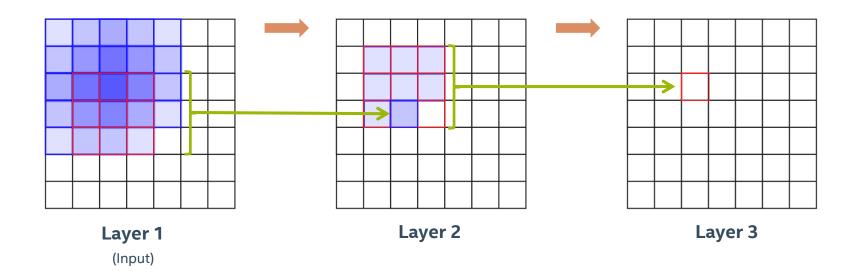


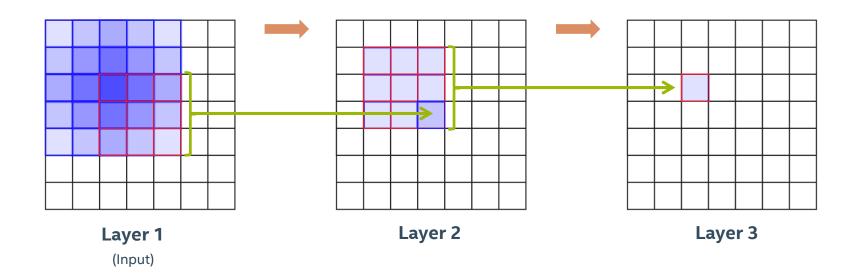


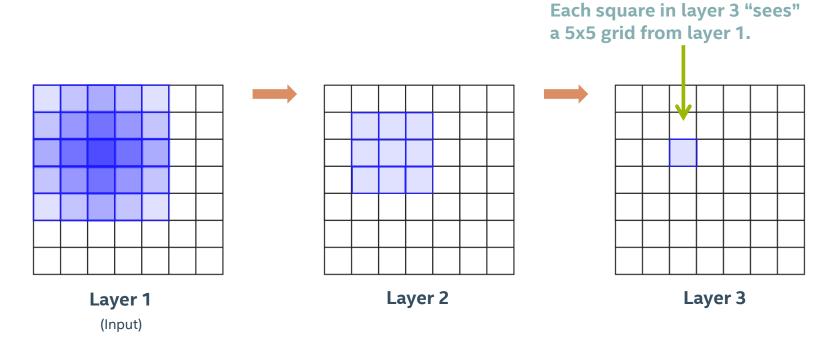












Two 3x3, stride 1 convolutions in a row \rightarrow one 5x5.

Three 3x3 convolutions \rightarrow one 7x7 convolution.

Benefit: fewer parameters.

One 3x3 layer $3 \times 3 \times C \times C = 9C^2$

One 7x7 layer
$$7 \times 7 \times C \times C = 49C^2$$

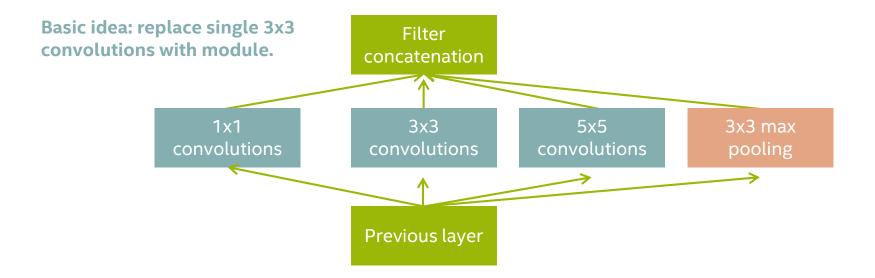
Three 3x3 layers

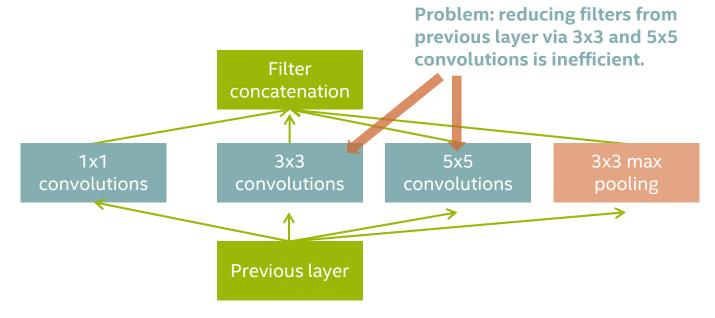
$$3 \times (9C^2) = 27C^2$$

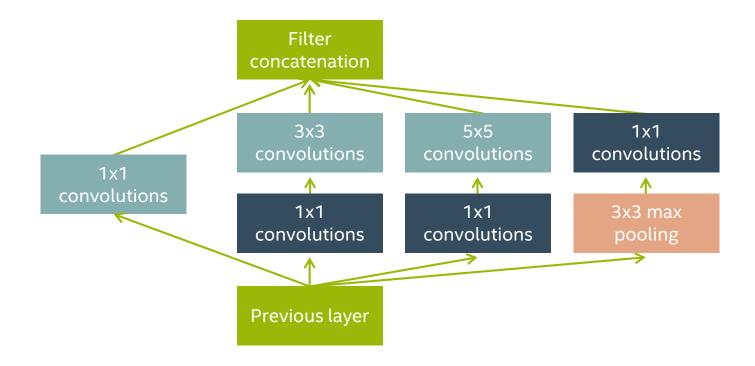
 $49C^2 \rightarrow 27C^2 \rightarrow \approx 45\%$ reduction!

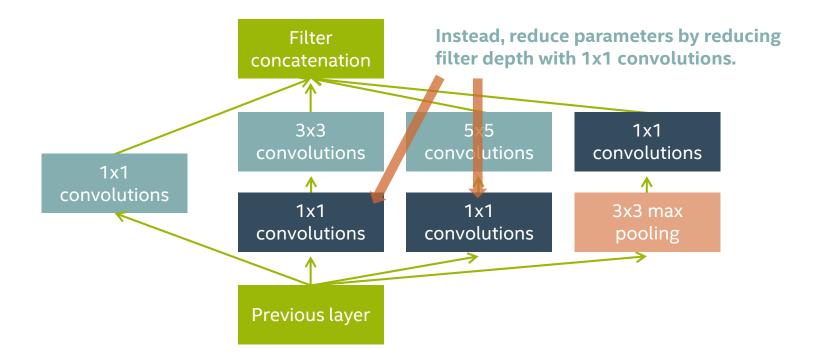
- One of the first architectures to experiment with many layers (More is better!)
- Can use multiple 3x3 convolutions to simulate larger kernels with fewer parameters
- Served as "base model" for future works

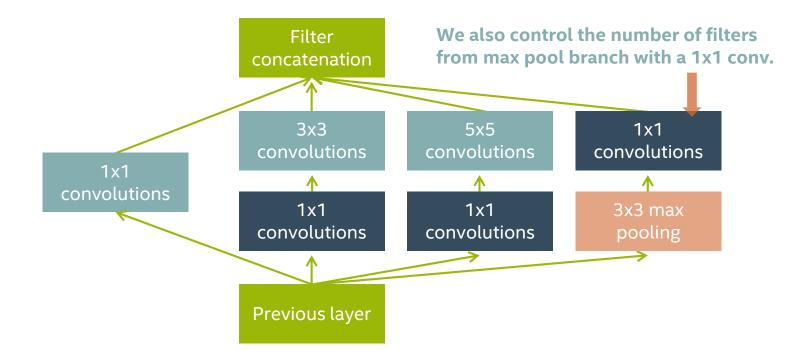
- Szegedy et al 2014
- Idea: network would want to use different receptive fields
- Want computational efficiency
- Also want to have sparse activations of groups of neurons
- Hebbian principle: "Fire together, wire together"
- Solution: Turn each layer into branches of convolutions
- Each branch handles smaller portion of workload
- Concatenate different branches at the end

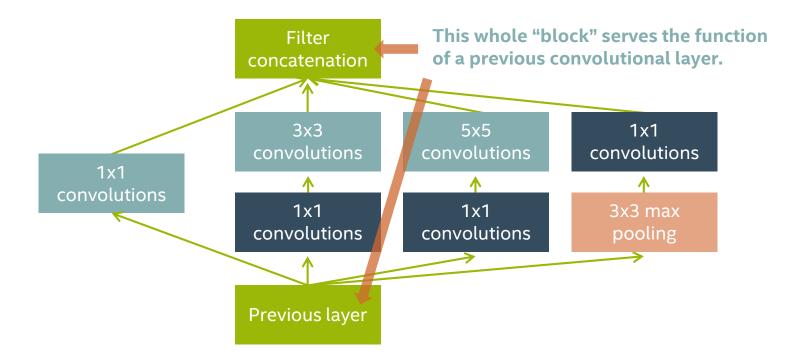




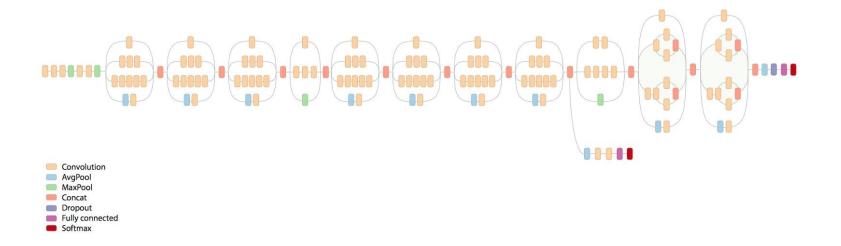






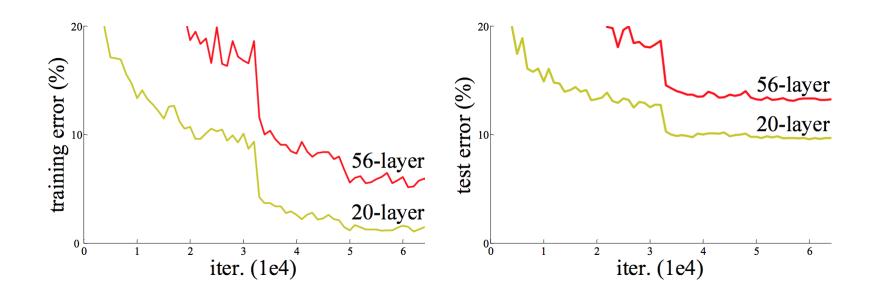


INCEPTION V3 SCHEMATIC



RESNET-MOTIVATION

Issue: Deeper Networks performing worse on training data! (as well as test data)

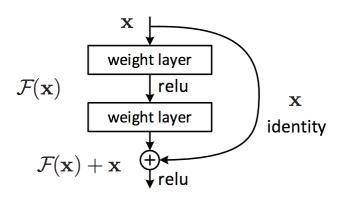


RESNET

- Surprising because deeper networks should overfit more
- So what's happening?
- Early layers of Deep Networks are very slow to adjust
- Analogous to "Vanishing Gradient" issue
- In theory, should be able to just have an "identity" transformation that makes the deeper network behave like a shallower one

RESNET

- Assumption: best transformation over multiple layers is close to $\mathcal{F}(x)+x$
- $x \rightarrow$ input to series of layers
- $\mathcal{F}(x) \rightarrow$ function represented by several layers (such as convs)
- Enforce this by adding "shortcut connections"
- Add the inputs from an earlier layer to the output of current layer



RESNET

- Add previous layer back in to current layer!
- Similar idea to "boosting"

