

P2_Rajasekharan_Pillai_Murali_Krishnan_autoencoders

October 3, 2019

#Student Name: Murali Krishnan Rajasekharan Pillai #ECE 595 Machine Learning II #Project
2: Autoencoders - Student Code

```
[1]: !nvidia-smi
```

Thu Oct 3 23:29:30 2019

```
+-----+
| NVIDIA-SMI 430.40      Driver Version: 418.67      CUDA Version: 10.1      |
+-----+-----+-----+-----+
| GPU   Name           Persistence-M| Bus-Id        Disp.A | Volatile Uncorr. ECC |
| Fan  Temp  Perf  Pwr:Usage/Cap|      Memory-Usage | GPU-Util  Compute M. |
+-----+-----+-----+-----+
|    0   Tesla K80          Off      | 00000000:00:04:0 Off |             0         |
| N/A   35C    P8      29W / 149W |      0MiB / 11441MiB |      0%      Default  |
+-----+-----+-----+-----+

+-----+-----+-----+-----+
| Processes:                                                       GPU Memory |
|  GPU       PID    Type    Process name                     Usage      |
+-----+-----+-----+-----+
| No running processes found                                     |
+-----+-----+-----+-----+
```

```
[46]: from google.colab import drive
drive.mount('/content/gdrive', force_remount=True)
MODEL_LOCATION = "gdrive/My Drive/ece595_ml2/models/"
```

Mounted at /content/gdrive

```
[3]: #Import necessary packages
import numpy as np
from keras.datasets import mnist
from keras.layers import Dense, Conv2D, MaxPooling2D, UpSampling2D
from keras.models import Sequential, model_from_json
import matplotlib.pyplot as plt
from keras import backend as K
from tensorflow.keras.callbacks import Callback
```

```
import pickle
```

Using TensorFlow backend.

#Part 0: Importing and Normalizing Data

```
[4]: #Load MNIST data and normalize to [0,1]
(data_train, _), (data_test, _) = mnist.load_data()
data_train = data_train/255.0
data_test = data_test/255.0
```

Downloading data from <https://s3.amazonaws.com/img-datasets/mnist.npz>
11493376/11490434 [=====] - 1s 0us/step

```
[0]: #Reshape training and testing data into 784-dimensional vectors
data_train = data_train.reshape(-1, 784)
data_test = data_test.reshape(-1, 784)
```

1 Part 1 : Fully Connected Autoencoder

```
[0]: class model_methods(object):
    def __init__(self, loss_fn, optim, ndim):
        """
        Try to develop a class which contains common functionality of
        NN models. Like saving a model & it's weights.
        """
        self.loss_fn = loss_fn
        self.optim = optim
        self.ndim = ndim

    def save_model_weights(self, h5_file_name):
        """
        Save weights of the model
        Parameters:
            :h5_file_name: Identifier of the model weights h5 file
        """
        self.model.save_weights(h5_file_name)

    def save_model(self, json_file_name):
        """
        Save the model
        Parameters:
            :json_file_name: Identifier of the model in json file
        """
        ae_model_json = self.model.to_json()
        with open(json_file_name, 'w') as json_file:
            json_file.write(ae_model_json)
```

```

def load_model(self, json_file_name, h5_file_name):
    json_file = open(MODEL_LOCATION + json_file_name, 'r')
    loaded_from_json = json_file.read()
    json_file.close()
    ae_model = model_from_json(loaded_from_json)
    ae_model.load_weights(MODEL_LOCATION + h5_file_name)
    return ae_model

def save_model_history(self, model_history, file_name):
    """
    Save model history as a pickle file
    """
    with open(file_name, 'wb') as f:
        pickle.dump(model_history, f)

def load_model_history(self, pkl_file_name):
    """
    Load model history pickle file
    """
    with open(MODEL_LOCATION + pkl_file_name, 'rb') as f:
        ae_history = pickle.load(f)
    return ae_history

```

```

[0]: class deep_autoencoder(model_methods):
    def __init__(self, loss_fn, optim, ndim):
        super().__init__(loss_fn, optim, ndim)
        self.model = self._build_model(self.ndim)

    def _build_model(self, ndim):
        """
        Defines and compiles the architecture
        Parameters:
            :loss_fn: The loss function used in the model
            :optim: The optimizer used for model
        Returns:
            :model: The compiled model
        """
        model = Sequential()
        # First Hidden Layer
        model.add(Dense(400,
                        activation='relu',
                        kernel_initializer='uniform',
                        input_dim=self.ndim))
        # Second Hidden Layer
        model.add(Dense(196,

```

```

        activation='relu',
        kernel_initializer='uniform'))
# third Hidden Layer (BottleNeck)
model.add(Dense(100,
        activation='relu',
        kernel_initializer='uniform'))
# Fourth Hidden Layer
model.add(Dense(196,
        activation='relu',
        kernel_initializer='uniform'))
# Fifth Hidden Layer
model.add(Dense(400,
        activation='relu',
        kernel_initializer='uniform'))
# Output Layer
→ model.add(Dense(self.ndim,
        activation='sigmoid',
        kernel_initializer='uniform'))
model.compile(loss=self.loss_fn,
        optimizer=self.optim)
return model

def fit(self, d_train, d_test,
        n_epochs=100,
        batch_size=50,
        display=25):
    """
    Fit the model

    Parameters:
        :d_train:    Tuple of (training data, training labels)
        :d_test:     Tuple of (testing data, testing labels)
        :n_epochs:   Number of epochs for fit
        :batch_size: Number of samples per gradient update
    Returns:
        :model_history: History object containing all model history info

    """
    data_train, labels_train = d_train
    #out_batch = NBatchLogger(display)
    model_history = self.model.fit(data_train, labels_train,
        validation_data=d_test,
        epochs=n_epochs,
        batch_size=batch_size,
        shuffle=True,
        )

```

```
return model_history
```

```
[0]: ae = deep_autoencoder("mse", "adam", 784)
```

```
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:66: The name tf.get_default_graph is deprecated. Please use tf.compat.v1.get_default_graph instead.
```

```
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:541: The name tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.
```

```
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4432: The name tf.random_uniform is deprecated. Please use tf.random.uniform instead.
```

```
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:793: The name tf.train.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.
```

```
[0]: ae_history = ae.fit((data_train, data_train),  
                        (data_test, data_test),  
                        n_epochs=150,  
                        batch_size=1024)
```

```
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:1033: The name tf.assign_add is deprecated. Please use tf.compat.v1.assign_add instead.
```

```
WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:1020: The name tf.assign is deprecated. Please use tf.compat.v1.assign instead.
```

Train on 60000 samples, validate on 10000 samples

Epoch 1/150

60000/60000 [=====] - 2s 37us/step - loss: 0.1067 - val_loss: 0.0730

Epoch 2/150

60000/60000 [=====] - 1s 21us/step - loss: 0.0695 - val_loss: 0.0654

Epoch 3/150

60000/60000 [=====] - 1s 21us/step - loss: 0.0619 - val_loss: 0.0573

Epoch 4/150

60000/60000 [=====] - 1s 22us/step - loss: 0.0547 - val_loss: 0.0507

Epoch 5/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0475 -
val_loss: 0.0423
Epoch 6/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0374 -
val_loss: 0.0337
Epoch 7/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0321 -
val_loss: 0.0299
Epoch 8/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0289 -
val_loss: 0.0269
Epoch 9/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0264 -
val_loss: 0.0251
Epoch 10/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0247 -
val_loss: 0.0236
Epoch 11/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0232 -
val_loss: 0.0223
Epoch 12/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0221 -
val_loss: 0.0212
Epoch 13/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0210 -
val_loss: 0.0201
Epoch 14/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0200 -
val_loss: 0.0193
Epoch 15/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0191 -
val_loss: 0.0184
Epoch 16/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0182 -
val_loss: 0.0175
Epoch 17/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0175 -
val_loss: 0.0173
Epoch 18/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0169 -
val_loss: 0.0165
Epoch 19/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0165 -
val_loss: 0.0162
Epoch 20/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0161 -
val_loss: 0.0157

Epoch 21/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0157 -
val_loss: 0.0154
Epoch 22/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0152 -
val_loss: 0.0150
Epoch 23/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0148 -
val_loss: 0.0145
Epoch 24/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0143 -
val_loss: 0.0141
Epoch 25/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0140 -
val_loss: 0.0137
Epoch 26/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0136 -
val_loss: 0.0135
Epoch 27/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0133 -
val_loss: 0.0133
Epoch 28/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0130 -
val_loss: 0.0128
Epoch 29/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0126 -
val_loss: 0.0125
Epoch 30/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0124 -
val_loss: 0.0123
Epoch 31/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0121 -
val_loss: 0.0120
Epoch 32/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0119 -
val_loss: 0.0118
Epoch 33/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0117 -
val_loss: 0.0115
Epoch 34/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0114 -
val_loss: 0.0112
Epoch 35/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0112 -
val_loss: 0.0111
Epoch 36/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0110 -
val_loss: 0.0108

Epoch 37/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0108 -
val_loss: 0.0107
Epoch 38/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0106 -
val_loss: 0.0106
Epoch 39/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0105 -
val_loss: 0.0105
Epoch 40/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0104 -
val_loss: 0.0102
Epoch 41/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0101 -
val_loss: 0.0102
Epoch 42/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0100 -
val_loss: 0.0100
Epoch 43/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0099 -
val_loss: 0.0098
Epoch 44/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0098 -
val_loss: 0.0097
Epoch 45/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0096 -
val_loss: 0.0096
Epoch 46/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0095 -
val_loss: 0.0096
Epoch 47/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0094 -
val_loss: 0.0096
Epoch 48/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0093 -
val_loss: 0.0093
Epoch 49/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0091 -
val_loss: 0.0093
Epoch 50/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0090 -
val_loss: 0.0090
Epoch 51/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0089 -
val_loss: 0.0089
Epoch 52/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0088 -
val_loss: 0.0088

Epoch 53/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0087 -
val_loss: 0.0088
Epoch 54/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0086 -
val_loss: 0.0088
Epoch 55/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0085 -
val_loss: 0.0086
Epoch 56/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0084 -
val_loss: 0.0085
Epoch 57/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0082 -
val_loss: 0.0083
Epoch 58/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0082 -
val_loss: 0.0083
Epoch 59/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0081 -
val_loss: 0.0081
Epoch 60/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0079 -
val_loss: 0.0081
Epoch 61/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0079 -
val_loss: 0.0083
Epoch 62/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0078 -
val_loss: 0.0080
Epoch 63/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0077 -
val_loss: 0.0078
Epoch 64/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0076 -
val_loss: 0.0078
Epoch 65/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0075 -
val_loss: 0.0076
Epoch 66/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0075 -
val_loss: 0.0076
Epoch 67/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0074 -
val_loss: 0.0075
Epoch 68/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0073 -
val_loss: 0.0074

Epoch 69/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0073 -
val_loss: 0.0074
Epoch 70/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0072 -
val_loss: 0.0074
Epoch 71/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0071 -
val_loss: 0.0074
Epoch 72/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0071 -
val_loss: 0.0073
Epoch 73/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0070 -
val_loss: 0.0074
Epoch 74/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0069 -
val_loss: 0.0071
Epoch 75/150
60000/60000 [=====] - 1s 23us/step - loss: 0.0069 -
val_loss: 0.0071
Epoch 76/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0069 -
val_loss: 0.0071
Epoch 77/150
60000/60000 [=====] - 1s 23us/step - loss: 0.0068 -
val_loss: 0.0070
Epoch 78/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0067 -
val_loss: 0.0069
Epoch 79/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0067 -
val_loss: 0.0068
Epoch 80/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0066 -
val_loss: 0.0068
Epoch 81/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0066 -
val_loss: 0.0067
Epoch 82/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0065 -
val_loss: 0.0069
Epoch 83/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0065 -
val_loss: 0.0066
Epoch 84/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0064 -
val_loss: 0.0066

Epoch 85/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0064 -
val_loss: 0.0067
Epoch 86/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0064 -
val_loss: 0.0066
Epoch 87/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0063 -
val_loss: 0.0067
Epoch 88/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0063 -
val_loss: 0.0065
Epoch 89/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0062 -
val_loss: 0.0065
Epoch 90/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0062 -
val_loss: 0.0065
Epoch 91/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0062 -
val_loss: 0.0065
Epoch 92/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0061 -
val_loss: 0.0064
Epoch 93/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0061 -
val_loss: 0.0064
Epoch 94/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0061 -
val_loss: 0.0063
Epoch 95/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0060 -
val_loss: 0.0063
Epoch 96/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0060 -
val_loss: 0.0063
Epoch 97/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0059 -
val_loss: 0.0062
Epoch 98/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0059 -
val_loss: 0.0061
Epoch 99/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0059 -
val_loss: 0.0062
Epoch 100/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0058 -
val_loss: 0.0060

Epoch 101/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0058 -
val_loss: 0.0061
Epoch 102/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0058 -
val_loss: 0.0060
Epoch 103/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0057 -
val_loss: 0.0060
Epoch 104/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0057 -
val_loss: 0.0059
Epoch 105/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0057 -
val_loss: 0.0060
Epoch 106/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0057 -
val_loss: 0.0061
Epoch 107/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0056 -
val_loss: 0.0060
Epoch 108/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0056 -
val_loss: 0.0059
Epoch 109/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0056 -
val_loss: 0.0059
Epoch 110/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0056 -
val_loss: 0.0058
Epoch 111/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0055 -
val_loss: 0.0058
Epoch 112/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0055 -
val_loss: 0.0058
Epoch 113/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0055 -
val_loss: 0.0058
Epoch 114/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0055 -
val_loss: 0.0057
Epoch 115/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0054 -
val_loss: 0.0057
Epoch 116/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0054 -
val_loss: 0.0057

Epoch 117/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0054 -
val_loss: 0.0057
Epoch 118/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0054 -
val_loss: 0.0056
Epoch 119/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0053 -
val_loss: 0.0056
Epoch 120/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0053 -
val_loss: 0.0057
Epoch 121/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0053 -
val_loss: 0.0055
Epoch 122/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0052 -
val_loss: 0.0057
Epoch 123/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0052 -
val_loss: 0.0055
Epoch 124/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0052 -
val_loss: 0.0055
Epoch 125/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0052 -
val_loss: 0.0056
Epoch 126/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0051 -
val_loss: 0.0054
Epoch 127/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0051 -
val_loss: 0.0054
Epoch 128/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0051 -
val_loss: 0.0054
Epoch 129/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0051 -
val_loss: 0.0054
Epoch 130/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0051 -
val_loss: 0.0054
Epoch 131/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0051 -
val_loss: 0.0054
Epoch 132/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0050 -
val_loss: 0.0053

Epoch 133/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0050 -
val_loss: 0.0053
Epoch 134/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0050 -
val_loss: 0.0054
Epoch 135/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0050 -
val_loss: 0.0053
Epoch 136/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0050 -
val_loss: 0.0053
Epoch 137/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0049 -
val_loss: 0.0053
Epoch 138/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0049 -
val_loss: 0.0053
Epoch 139/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0049 -
val_loss: 0.0053
Epoch 140/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0049 -
val_loss: 0.0053
Epoch 141/150
60000/60000 [=====] - 1s 22us/step - loss: 0.0049 -
val_loss: 0.0052
Epoch 142/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0048 -
val_loss: 0.0052
Epoch 143/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0048 -
val_loss: 0.0052
Epoch 144/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0048 -
val_loss: 0.0051
Epoch 145/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0048 -
val_loss: 0.0051
Epoch 146/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0047 -
val_loss: 0.0051
Epoch 147/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0047 -
val_loss: 0.0051
Epoch 148/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0047 -
val_loss: 0.0051

```
Epoch 149/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0047 -
val_loss: 0.0051
Epoch 150/150
60000/60000 [=====] - 1s 21us/step - loss: 0.0047 -
val_loss: 0.0050
```

```
[0]: ae.save_model_weights("ae_model_weights.h5")
      ae.save_model("ae_model.json")
      ae.save_model_history(ae_history, "ae_model_history.pkl")

[0]: ! cp -r ae_model.json ae_model_weights.h5 ae_model_history.pkl ./gdrive/My\
      ↳Drive/ece595_ml2/models/

[0]: ae_model = ae.load_model("ae_model.json", "ae_model_weights.h5")

[0]: reconstructions = ae_model.predict(data_test)

[0]: print(len(ae_model.layers))
      print(ae_model.summary())
```

6

Model: "sequential_1"

| Layer (type) | Output Shape | Param # |
|-----------------|--------------|---------|
| dense_1 (Dense) | (None, 400) | 314000 |
| dense_2 (Dense) | (None, 196) | 78596 |
| dense_3 (Dense) | (None, 100) | 19700 |
| dense_4 (Dense) | (None, 196) | 19796 |
| dense_5 (Dense) | (None, 400) | 78800 |
| dense_6 (Dense) | (None, 784) | 314384 |

Total params: 825,276
 Trainable params: 825,276
 Non-trainable params: 0

None

```
[0]: def get_hidden_layers_representation(model, data_test):
      """
      Find the hidden layers representation for a model
      Parameters:
          :model: The model object whose hidden layers to extract
```

```

:test data:      The test data whose representations we seek
Returns:
:hl:            The weights of the hidden layers
"""

n_layers = len(model.layers)
hl_weights = {}
for i in range(1, n_layers+1, 1):
    hl_function = K.function([model.layers[0].input], [model.layers[i-1].output])
    hl_weights[i] = []
    hl_weights[i].append(hl_function([data_test])[0])
return hl_weights

```

```
[0]: w_hl = get_hidden_layers_representation(ae_model, data_test)
```

1.1 Layer Representations

```

[0]: n = 10
n_layers = len(ae_model.layers)
layers = [' Input ',
          ' HL 1 ',
          ' HL 2 ',
          ' Bottleneck ',
          ' HL 4 ',
          ' HL 5 ',
          ' Output ']
cols = ['{}'.format(col) for col in layers]
#rows = ['Row {}'.format(row) for row in ['A', 'B', 'C', 'D']]
fig, axes = plt.subplots(nrows=n, ncols=n_layers+1, figsize=(10, 10))
for i in range(n):
    axes[i, 0].imshow(data_test[i].reshape(28, 28),
                      cmap=plt.cm.gray)
    axes[i, 1].imshow(w_hl[1][0][i,:].reshape(20, 20),
                      cmap=plt.cm.gray)
    axes[i, 2].imshow(w_hl[2][0][i,:].reshape(14, 14),
                      cmap=plt.cm.gray)
    axes[i, 3].imshow(w_hl[3][0][i,:].reshape(10, 10),
                      cmap=plt.cm.gray)
    axes[i, 4].imshow(w_hl[4][0][i,:].reshape(14, 14),
                      cmap=plt.cm.gray)
    axes[i, 5].imshow(w_hl[5][0][i,:].reshape(20, 20),
                      cmap=plt.cm.gray)
    axes[i, 6].imshow(w_hl[6][0][i,:].reshape(28, 28),
                      cmap=plt.cm.gray)
    for ax, col in zip(axes[0], cols):
        ax.set_title(col)
    for j in range(n_layers+1):

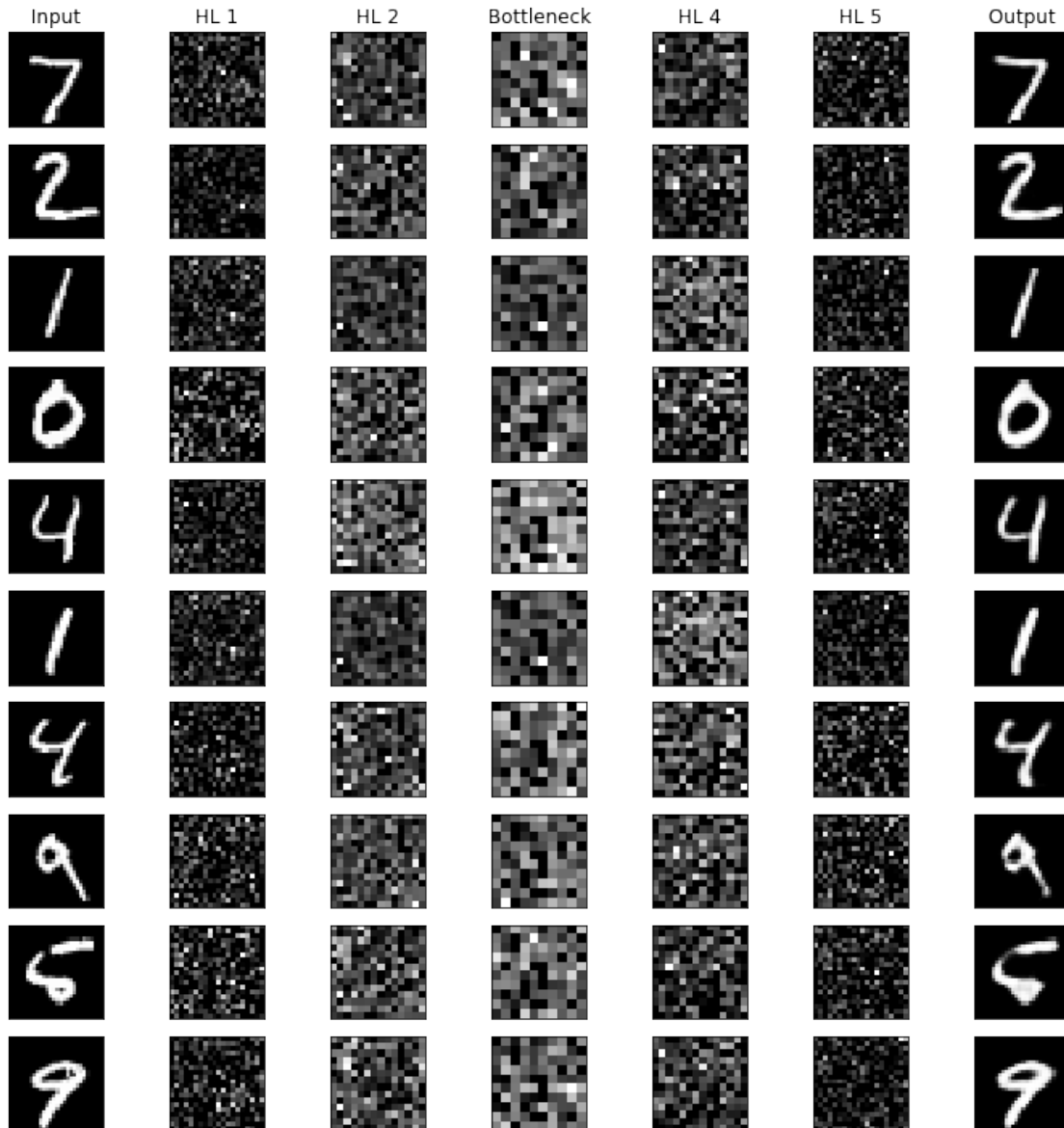
```



```

axes[i, j].get_xaxis().set_visible(False)
axes[i, j].get_yaxis().set_visible(False)
fig.tight_layout()
plt.show()

```

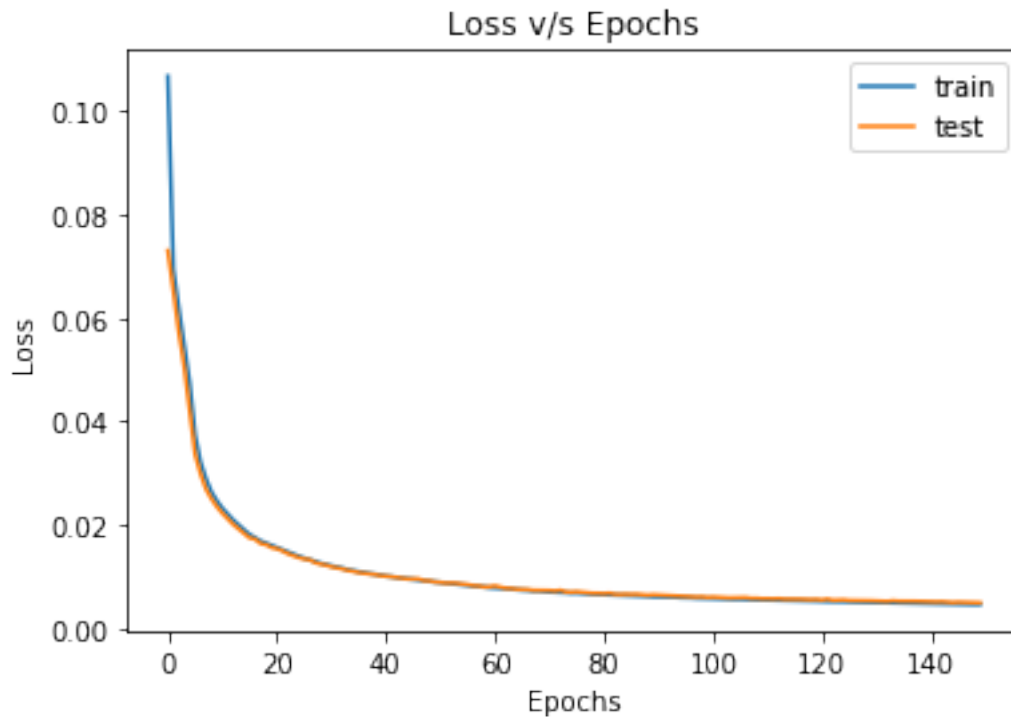


1.2 Loss Curves

```
[0]: ae_history = ae.load_model_history("ae_model_history.pkl")
```

```
[0]: plt.plot(ae_history.history['loss'])
plt.plot(ae_history.history['val_loss'])
```

```
plt.xlabel("Epochs")
plt.ylabel("Loss")
plt.title("Loss v/s Epochs")
plt.legend(['train', 'test'], loc='upper right')
plt.show()
```



#Part 2: Deep Convolutional AutoEncoder

```
[0]: #Reshape training and testing data into 784-dimensional vectors
data_train = data_train.reshape(-1, 28, 28, 1)
data_test = data_test.reshape(-1, 28, 28, 1)
```

```
[0]: class convolutional_autoencoder(model_methods):
    def __init__(self, loss_fn, optim, ndim):
        super().__init__(loss_fn, optim, ndim)
        self.model = self._build_model(self.ndim)

    def _build_model(self, ndim):
        """
        Defines and compiles the architecture
        Parameters:
            :loss_fn: The loss function used in the model
            :optim: The optimizer used for model
        Returns:
```

```

:model: The compiled model
"""
model = Sequential()

# First Hidden Layer
model.add(Conv2D(16,
                 kernel_size=3,
                 activation='relu',
                 kernel_initializer='uniform',
                 padding='same',
                 input_shape=(self.ndim, self.ndim, 1)))

# Second Hidden Layer
model.add(MaxPooling2D(pool_size=(2, 2),
                      padding='same'))

# Third Hidden Layer
model.add(Conv2D(8,
                 kernel_size=3,
                 activation='relu',
                 padding='same',
                 kernel_initializer='uniform'))

# Fourth Hidden Layer (Bottleneck)
model.add(MaxPooling2D(pool_size=(2, 2),
                      padding='same'))

#Fifth Hidden Layer
model.add(Conv2D(8,
                 kernel_size=3,
                 padding='same',
                 activation='relu',
                 kernel_initializer='uniform'))

# Sixth Hidden Layer
model.add(UpSampling2D(size=(2, 2)))

#Seventh Hidden Layer
model.add(Conv2D(16,
                 kernel_size=3,
                 activation='relu',
                 padding='same',
                 kernel_initializer='uniform'))

# Eighth hidden layer
model.add(UpSampling2D(size=(2, 2)))

# Output layer
model.add(Conv2D(1,
                 kernel_size=3,
                 kernel_initializer='uniform',
                 padding='same',
                 activation='sigmoid'))

```

```

model.compile(loss=self.loss_fn,
              optimizer=self.optim)
return model

def fit(self, d_train, d_test,
        n_epochs=100,
        batch_size=50,
        display=25):
    """
    Fit the model

    Parameters:
        :d_train:    Tuple of (training data, training labels)
        :d_test:     Tuple of (testing data, testing labels)
        :n_epochs:   Number of epochs for fit
        :batch_size: Number of samples per gradient update
    Returns:
        :model_history: History object containing all model history info

    """
    data_train, labels_train = d_train
    #out_batch = NBatchLogger(display)
    model_history = self.model.fit(data_train, labels_train,
                                   validation_data=d_test,
                                   epochs=n_epochs,
                                   batch_size=batch_size,
                                   shuffle=True,
                                   )
    return model_history

```

```
[8]: cae = convolutional_autoencoder('binary_crossentropy', 'adam', 28)
```

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:66: The name tf.get_default_graph is deprecated. Please use tf.compat.v1.get_default_graph instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:541: The name tf.placeholder is deprecated. Please use tf.compat.v1.placeholder instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4432: The name tf.random_uniform is deprecated. Please use tf.random.uniform instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:4267: The name tf.nn.max_pool is deprecated. Please use tf.nn.max_pool2d instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:2239: The name tf.image.resize_nearest_neighbor is deprecated. Please use tf.compat.v1.image.resize_nearest_neighbor instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/optimizers.py:793: The name tf.train.Optimizer is deprecated. Please use tf.compat.v1.train.Optimizer instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/keras/backend/tensorflow_backend.py:3657: The name tf.log is deprecated. Please use tf.math.log instead.

WARNING:tensorflow:From /usr/local/lib/python3.6/dist-packages/tensorflow/python/ops/nn_impl.py:180: add_dispatch_support.<locals>.wrapper (from tensorflow.python.ops.array_ops) is deprecated and will be removed in a future version.
Instructions for updating:
Use tf.where in 2.0, which has the same broadcast rule as np.where

```
[0]: cae_history = cae.fit((data_train, data_train),  
                          (data_test, data_test),  
                          n_epochs=150,  
                          batch_size=1024)
```

Train on 60000 samples, validate on 10000 samples

Epoch 1/150

60000/60000 [=====] - 6s 107us/step - loss: 0.5798 -
val_loss: 0.4495

Epoch 2/150

60000/60000 [=====] - 3s 47us/step - loss: 0.3640 -
val_loss: 0.2452

Epoch 3/150

60000/60000 [=====] - 3s 47us/step - loss: 0.1978 -
val_loss: 0.1640

Epoch 4/150

60000/60000 [=====] - 3s 46us/step - loss: 0.1455 -
val_loss: 0.1287

Epoch 5/150

60000/60000 [=====] - 3s 47us/step - loss: 0.1219 -
val_loss: 0.1145

Epoch 6/150

60000/60000 [=====] - 3s 47us/step - loss: 0.1117 -
val_loss: 0.1066

Epoch 7/150

60000/60000 [=====] - 3s 47us/step - loss: 0.1045 -

```

val_loss: 0.1001
Epoch 8/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0990 -
val_loss: 0.0957
Epoch 9/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0953 -
val_loss: 0.0930
Epoch 10/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0928 -
val_loss: 0.0906
Epoch 11/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0909 -
val_loss: 0.0890
Epoch 12/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0894 -
val_loss: 0.0876
Epoch 13/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0881 -
val_loss: 0.0865
Epoch 14/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0870 -
val_loss: 0.0854
Epoch 15/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0860 -
val_loss: 0.0845
Epoch 16/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0851 -
val_loss: 0.0837
Epoch 17/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0843 -
val_loss: 0.0829
Epoch 18/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0835 -
val_loss: 0.0822
Epoch 19/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0829 -
val_loss: 0.0817
Epoch 20/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0824 -
val_loss: 0.0812
Epoch 21/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0819 -
val_loss: 0.0807
Epoch 22/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0815 -
val_loss: 0.0803
Epoch 23/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0811 -

```

```
val_loss: 0.0801
Epoch 24/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0807 -
val_loss: 0.0796
Epoch 25/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0804 -
val_loss: 0.0794
Epoch 26/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0801 -
val_loss: 0.0790
Epoch 27/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0797 -
val_loss: 0.0786
Epoch 28/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0794 -
val_loss: 0.0784
Epoch 29/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0791 -
val_loss: 0.0781
Epoch 30/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0788 -
val_loss: 0.0779
Epoch 31/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0786 -
val_loss: 0.0777
Epoch 32/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0784 -
val_loss: 0.0775
Epoch 33/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0782 -
val_loss: 0.0773
Epoch 34/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0781 -
val_loss: 0.0771
Epoch 35/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0779 -
val_loss: 0.0770
Epoch 36/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0777 -
val_loss: 0.0768
Epoch 37/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0776 -
val_loss: 0.0767
Epoch 38/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0774 -
val_loss: 0.0765
Epoch 39/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0773 -
```

```

val_loss: 0.0764
Epoch 40/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0772 -
val_loss: 0.0763
Epoch 41/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0770 -
val_loss: 0.0762
Epoch 42/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0769 -
val_loss: 0.0762
Epoch 43/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0769 -
val_loss: 0.0759
Epoch 44/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0767 -
val_loss: 0.0758
Epoch 45/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0765 -
val_loss: 0.0757
Epoch 46/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0764 -
val_loss: 0.0757
Epoch 47/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0763 -
val_loss: 0.0756
Epoch 48/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0763 -
val_loss: 0.0754
Epoch 49/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0762 -
val_loss: 0.0754
Epoch 50/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0761 -
val_loss: 0.0753
Epoch 51/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0760 -
val_loss: 0.0752
Epoch 52/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0759 -
val_loss: 0.0751
Epoch 53/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0758 -
val_loss: 0.0750
Epoch 54/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0758 -
val_loss: 0.0749
Epoch 55/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0757 -

```



```
val_loss: 0.0749
Epoch 56/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0756 -
val_loss: 0.0748
Epoch 57/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0756 -
val_loss: 0.0747
Epoch 58/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0755 -
val_loss: 0.0747
Epoch 59/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0754 -
val_loss: 0.0746
Epoch 60/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0754 -
val_loss: 0.0745
Epoch 61/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0753 -
val_loss: 0.0745
Epoch 62/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0753 -
val_loss: 0.0745
Epoch 63/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0752 -
val_loss: 0.0744
Epoch 64/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0751 -
val_loss: 0.0743
Epoch 65/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0750 -
val_loss: 0.0743
Epoch 66/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0750 -
val_loss: 0.0742
Epoch 67/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0749 -
val_loss: 0.0742
Epoch 68/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0749 -
val_loss: 0.0741
Epoch 69/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0749 -
val_loss: 0.0741
Epoch 70/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0748 -
val_loss: 0.0740
Epoch 71/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0748 -
```

```

val_loss: 0.0740
Epoch 72/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0747 -
val_loss: 0.0739
Epoch 73/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0746 -
val_loss: 0.0739
Epoch 74/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0746 -
val_loss: 0.0739
Epoch 75/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0746 -
val_loss: 0.0738
Epoch 76/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0745 -
val_loss: 0.0738
Epoch 77/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0745 -
val_loss: 0.0737
Epoch 78/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0744 -
val_loss: 0.0737
Epoch 79/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0745 -
val_loss: 0.0736
Epoch 80/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0743 -
val_loss: 0.0736
Epoch 81/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0743 -
val_loss: 0.0736
Epoch 82/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0743 -
val_loss: 0.0735
Epoch 83/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0742 -
val_loss: 0.0735
Epoch 84/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0742 -
val_loss: 0.0735
Epoch 85/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0742 -
val_loss: 0.0734
Epoch 86/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0742 -
val_loss: 0.0735
Epoch 87/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0741 -

```

```
val_loss: 0.0733
Epoch 88/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0741 -
val_loss: 0.0733
Epoch 89/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0740 -
val_loss: 0.0733
Epoch 90/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0740 -
val_loss: 0.0733
Epoch 91/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0740 -
val_loss: 0.0733
Epoch 92/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0739 -
val_loss: 0.0732
Epoch 93/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0739 -
val_loss: 0.0732
Epoch 94/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0739 -
val_loss: 0.0732
Epoch 95/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0739 -
val_loss: 0.0731
Epoch 96/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0738 -
val_loss: 0.0731
Epoch 97/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0738 -
val_loss: 0.0731
Epoch 98/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0738 -
val_loss: 0.0730
Epoch 99/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0738 -
val_loss: 0.0730
Epoch 100/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0737 -
val_loss: 0.0730
Epoch 101/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0737 -
val_loss: 0.0730
Epoch 102/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0737 -
val_loss: 0.0729
Epoch 103/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0736 -
```

```
val_loss: 0.0729
Epoch 104/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0737 -
val_loss: 0.0729
Epoch 105/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0736 -
val_loss: 0.0729
Epoch 106/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0736 -
val_loss: 0.0729
Epoch 107/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0735 -
val_loss: 0.0728
Epoch 108/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0735 -
val_loss: 0.0728
Epoch 109/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0735 -
val_loss: 0.0728
Epoch 110/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0735 -
val_loss: 0.0728
Epoch 111/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0735 -
val_loss: 0.0728
Epoch 112/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0734 -
val_loss: 0.0728
Epoch 113/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0734 -
val_loss: 0.0727
Epoch 114/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0734 -
val_loss: 0.0727
Epoch 115/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0734 -
val_loss: 0.0728
Epoch 116/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0734 -
val_loss: 0.0727
Epoch 117/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0733 -
val_loss: 0.0726
Epoch 118/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0734 -
val_loss: 0.0726
Epoch 119/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0733 -
```

```
val_loss: 0.0726
Epoch 120/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0733 -
val_loss: 0.0728
Epoch 121/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0733 -
val_loss: 0.0726
Epoch 122/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0733 -
val_loss: 0.0726
Epoch 123/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0732 -
val_loss: 0.0726
Epoch 124/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0732 -
val_loss: 0.0726
Epoch 125/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0732 -
val_loss: 0.0725
Epoch 126/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0732 -
val_loss: 0.0725
Epoch 127/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0732 -
val_loss: 0.0725
Epoch 128/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0732 -
val_loss: 0.0725
Epoch 129/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0731 -
val_loss: 0.0725
Epoch 130/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0731 -
val_loss: 0.0724
Epoch 131/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0731 -
val_loss: 0.0724
Epoch 132/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0731 -
val_loss: 0.0724
Epoch 133/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0731 -
val_loss: 0.0725
Epoch 134/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0731 -
val_loss: 0.0724
Epoch 135/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0730 -
```

```

val_loss: 0.0723
Epoch 136/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0731 -
val_loss: 0.0723
Epoch 137/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0730 -
val_loss: 0.0723
Epoch 138/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0730 -
val_loss: 0.0723
Epoch 139/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0730 -
val_loss: 0.0723
Epoch 140/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0730 -
val_loss: 0.0723
Epoch 141/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0730 -
val_loss: 0.0723
Epoch 142/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0729 -
val_loss: 0.0722
Epoch 143/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0729 -
val_loss: 0.0722
Epoch 144/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0729 -
val_loss: 0.0722
Epoch 145/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0729 -
val_loss: 0.0724
Epoch 146/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0729 -
val_loss: 0.0722
Epoch 147/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0729 -
val_loss: 0.0722
Epoch 148/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0729 -
val_loss: 0.0722
Epoch 149/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0729 -
val_loss: 0.0723
Epoch 150/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0728 -
val_loss: 0.0721

```

```

[0]: cae.save_model_weights("cae_model_weights.h5")
      cae.save_model("cae_model.json")
      cae.save_model_history(cae_history, "cae_model_history.pkl")

[0]: ! cp -r cae_model.json cae_model_weights.h5 cae_model_history.pkl ./gdrive/My\
      ↪Drive/ece595_ml2/models/

[0]: cae_model = cae.load_model("cae_model.json", "cae_model_weights.h5")

[0]: cae_reconstructions = cae_model.predict(data_test)

[14]: print(len(cae_model.layers))
      print(cae_model.summary())

```

9

Model: "sequential_2"

| Layer (type) | Output Shape | Param # |
|-------------------------------|--------------------|---------|
| conv2d_1 (Conv2D) | (None, 28, 28, 16) | 160 |
| max_pooling2d_1 (MaxPooling2) | (None, 14, 14, 16) | 0 |
| conv2d_2 (Conv2D) | (None, 14, 14, 8) | 1160 |
| max_pooling2d_2 (MaxPooling2) | (None, 7, 7, 8) | 0 |
| conv2d_3 (Conv2D) | (None, 7, 7, 8) | 584 |
| up_sampling2d_1 (UpSampling2) | (None, 14, 14, 8) | 0 |
| conv2d_4 (Conv2D) | (None, 14, 14, 16) | 1168 |
| up_sampling2d_2 (UpSampling2) | (None, 28, 28, 16) | 0 |
| conv2d_5 (Conv2D) | (None, 28, 28, 1) | 145 |

Total params: 3,217
 Trainable params: 3,217
 Non-trainable params: 0

```

[0]: cae_w_hl = get_hidden_layers_representation(cae_model, data_test)

```

1.3 Layer Representation

```
[0]: n_samples = 10
n_layers = len(cae_model.layers)
layers = [' Input ',
          ' Conv2d 1 ',
          ' MP 1 ',
          ' Conv2d 2 ',
          ' MP 2 ',
          ' Bottleneck ',
          ' US 1 ',
          ' Conv2d 3 ',
          ' US 2 ',
          ' Output ']
cols = ['{}'.format(col) for col in layers]

[0]: n_kernels = [cae_w_hl[i][0][0].shape[2] for i in range(1, n_layers)]

[0]: def hidden_layer_weights(mat):
    """
    hidden weights
    """
    f = mat.shape[0]
    m = max(mat.shape[2] // 4, 1)
    n = max(mat.shape[2] // m, 1)
    temp = np.zeros((f*m, f*n))
    for j in range(m):
        for k in range(n):
            temp[f*j:f*(j+1), f*k:f*(k+1)] = mat[:, :, j*m+k]
    return temp

[44]: fig, axes = plt.subplots(nrows=n_samples, ncols=n_layers+1, figsize=(12, 12))
for i in range(n_samples):
    axes[i, 0].imshow(data_test[i].reshape(28, 28),
                      cmap=plt.cm.gray)

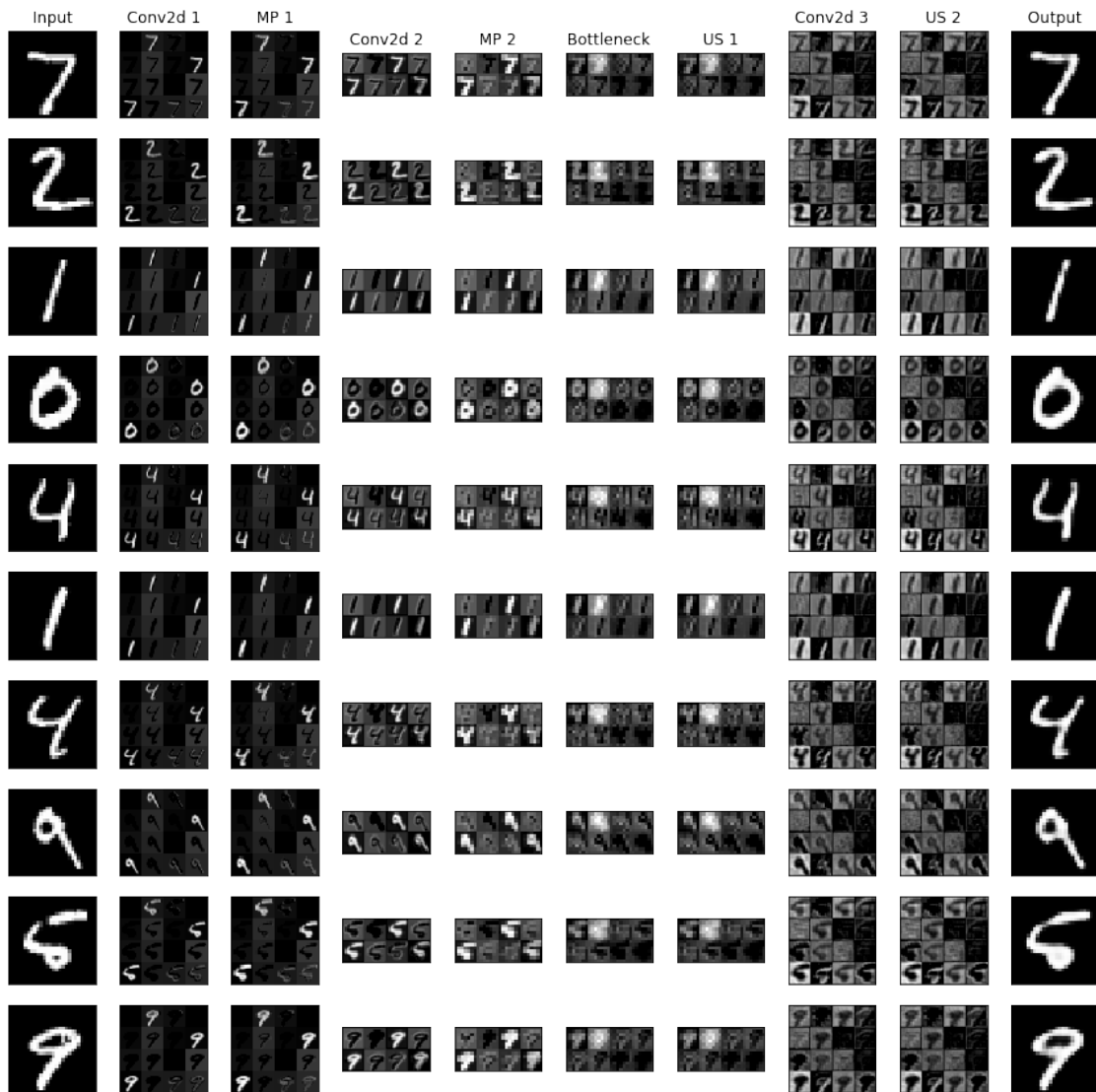
    temp1 = hidden_layer_weights(cae_w_hl[1][0][i])
    axes[i, 1].imshow(temp1, cmap=plt.cm.gray)
    temp2 = hidden_layer_weights(cae_w_hl[2][0][i])
    axes[i, 2].imshow(temp2, cmap=plt.cm.gray)
    temp3 = hidden_layer_weights(cae_w_hl[3][0][i])
    axes[i, 3].imshow(temp3, cmap=plt.cm.gray)
    temp4 = hidden_layer_weights(cae_w_hl[4][0][i])
    axes[i, 4].imshow(temp4, cmap=plt.cm.gray)
    temp5 = hidden_layer_weights(cae_w_hl[5][0][i])
    axes[i, 5].imshow(temp5, cmap=plt.cm.gray)
    temp6 = hidden_layer_weights(cae_w_hl[6][0][i])
    axes[i, 6].imshow(temp6, cmap=plt.cm.gray)
    temp7 = hidden_layer_weights(cae_w_hl[7][0][i])
```



```

axes[i, 7].imshow(temp7, cmap=plt.cm.gray)
temp8 = hidden_layer_weights(cae_w_hl[8][0][i])
axes[i, 8].imshow(temp8, cmap=plt.cm.gray)
temp9 = hidden_layer_weights(cae_w_hl[9][0][i])
axes[i, 9].imshow(temp9, cmap=plt.cm.gray)
for ax, col in zip(axes[0], cols):
    ax.set_title(col)
for j in range(n_layers+1):
    axes[i, j].get_xaxis().set_visible(False)
    axes[i, j].get_yaxis().set_visible(False)
fig.tight_layout()
plt.show()

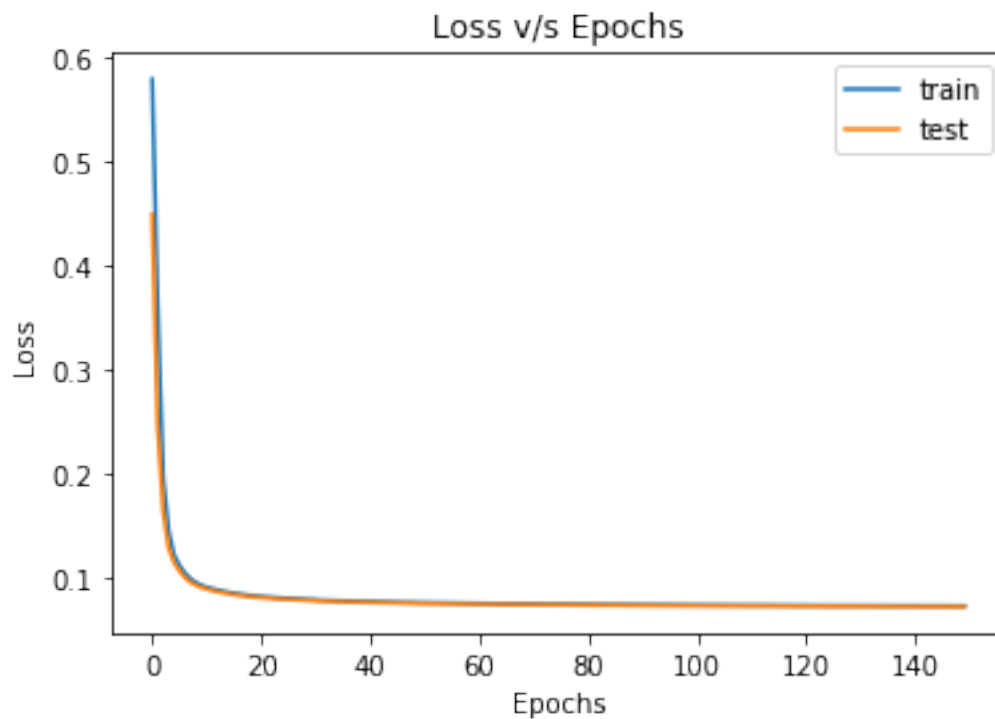
```



1.4 Loss Curves

```
[0]: cae_history = cae.load_model_history("cae_model_history.pkl")
```

```
[48]: plt.plot(cae_history.history['loss'])  
plt.plot(cae_history.history['val_loss'])  
plt.xlabel("Epochs")  
plt.ylabel("Loss")  
plt.title("Loss v/s Epochs")  
plt.legend(['train', 'test'], loc='upper right')  
plt.show()
```



#Part 3: Denoising AutoEncoder

```
[0]: #Inject noise into testing data  
noise_factor = 0.25  
data_train_noisy = data_train + noise_factor * np.random.normal(loc=0.0, scale=1.  
    ↪0, size=data_train.shape)  
data_test_noisy = data_test + noise_factor * np.random.normal(loc=0.0, scale=1.  
    ↪0, size=data_test.shape)  
  
#Clip to stay within valid (normalized) pixel range  
data_train_noisy = np.clip(data_train_noisy, 0., 1.)  
data_test_noisy = np.clip(data_test_noisy, 0., 1.)
```

```
#Reshape data to comply with input of denoising autoencoder
data_train_noisy = data_train_noisy.reshape(-1, 28, 28, 1)
data_test_noisy = data_test_noisy.reshape(-1, 28, 28, 1)
```

1.5 Original Samples of Training Data

```
[0]: n_samples = 10
     layers = [' Input ',
               ' Noisy Input ']
     cols = ['{}'.format(col) for col in layers]

[55]: fig, axes = plt.subplots(nrows=n_samples, ncols=2, figsize=(12, 12))
     for i in range(n_samples):
         axes[i, 0].imshow(data_train[i].reshape(28, 28),
                           cmap=plt.cm.gray)
         axes[i, 1].imshow(data_train_noisy[i].reshape(28, 28),
                           cmap=plt.cm.gray)
         for ax, col in zip(axes[0], cols):
             ax.set_title(col)
         for j in range(2):
             axes[i, j].get_xaxis().set_visible(False)
             axes[i, j].get_yaxis().set_visible(False)
     fig.tight_layout()
     plt.show()
```

Input



Noisy Input



1.6 Denoising Autoencoder

```
[0]: dae = convolutional_autoencoder('binary_crossentropy', 'adam', 28)
[58]: dae_history = dae.fit((data_train_noisy, data_train),
                           (data_test_noisy, data_test),
                           n_epochs=150,
                           batch_size=1024)
```

Train on 60000 samples, validate on 10000 samples

```
Epoch 1/150
60000/60000 [=====] - 4s 67us/step - loss: 0.5769 -
val_loss: 0.4620
Epoch 2/150
60000/60000 [=====] - 3s 47us/step - loss: 0.3768 -
val_loss: 0.2586
Epoch 3/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1919 -
val_loss: 0.1667
Epoch 4/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1545 -
val_loss: 0.1379
Epoch 5/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1262 -
val_loss: 0.1160
Epoch 6/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1135 -
val_loss: 0.1090
Epoch 7/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1084 -
val_loss: 0.1053
Epoch 8/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1053 -
val_loss: 0.1028
Epoch 9/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1032 -
val_loss: 0.1011
Epoch 10/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1016 -
val_loss: 0.0998
Epoch 11/150
60000/60000 [=====] - 3s 47us/step - loss: 0.1004 -
val_loss: 0.0986
Epoch 12/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0994 -
```

```

val_loss: 0.0977
Epoch 13/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0985 -
val_loss: 0.0969
Epoch 14/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0978 -
val_loss: 0.0962
Epoch 15/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0972 -
val_loss: 0.0958
Epoch 16/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0967 -
val_loss: 0.0951
Epoch 17/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0961 -
val_loss: 0.0948
Epoch 18/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0957 -
val_loss: 0.0945
Epoch 19/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0953 -
val_loss: 0.0938
Epoch 20/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0948 -
val_loss: 0.0934
Epoch 21/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0944 -
val_loss: 0.0930
Epoch 22/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0941 -
val_loss: 0.0926
Epoch 23/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0937 -
val_loss: 0.0925
Epoch 24/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0933 -
val_loss: 0.0920
Epoch 25/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0930 -
val_loss: 0.0918
Epoch 26/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0926 -
val_loss: 0.0913
Epoch 27/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0923 -
val_loss: 0.0911
Epoch 28/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0921 -

```

```

val_loss: 0.0908
Epoch 29/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0918 -
val_loss: 0.0906
Epoch 30/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0916 -
val_loss: 0.0903
Epoch 31/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0913 -
val_loss: 0.0901
Epoch 32/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0910 -
val_loss: 0.0899
Epoch 33/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0908 -
val_loss: 0.0896
Epoch 34/150
60000/60000 [=====] - 3s 46us/step - loss: 0.0906 -
val_loss: 0.0894
Epoch 35/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0904 -
val_loss: 0.0895
Epoch 36/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0902 -
val_loss: 0.0890
Epoch 37/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0899 -
val_loss: 0.0887
Epoch 38/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0897 -
val_loss: 0.0887
Epoch 39/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0896 -
val_loss: 0.0884
Epoch 40/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0894 -
val_loss: 0.0882
Epoch 41/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0891 -
val_loss: 0.0881
Epoch 42/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0890 -
val_loss: 0.0878
Epoch 43/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0888 -
val_loss: 0.0877
Epoch 44/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0886 -

```

```

val_loss: 0.0875
Epoch 45/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0885 -
val_loss: 0.0875
Epoch 46/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0882 -
val_loss: 0.0872
Epoch 47/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0881 -
val_loss: 0.0870
Epoch 48/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0879 -
val_loss: 0.0868
Epoch 49/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0878 -
val_loss: 0.0866
Epoch 50/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0876 -
val_loss: 0.0865
Epoch 51/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0874 -
val_loss: 0.0863
Epoch 52/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0873 -
val_loss: 0.0862
Epoch 53/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0871 -
val_loss: 0.0861
Epoch 54/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0870 -
val_loss: 0.0859
Epoch 55/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0868 -
val_loss: 0.0859
Epoch 56/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0868 -
val_loss: 0.0858
Epoch 57/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0866 -
val_loss: 0.0855
Epoch 58/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0865 -
val_loss: 0.0855
Epoch 59/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0864 -
val_loss: 0.0854
Epoch 60/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0862 -

```



```
val_loss: 0.0852
Epoch 61/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0861 -
val_loss: 0.0851
Epoch 62/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0861 -
val_loss: 0.0850
Epoch 63/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0859 -
val_loss: 0.0849
Epoch 64/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0858 -
val_loss: 0.0851
Epoch 65/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0857 -
val_loss: 0.0847
Epoch 66/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0857 -
val_loss: 0.0846
Epoch 67/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0855 -
val_loss: 0.0846
Epoch 68/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0855 -
val_loss: 0.0845
Epoch 69/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0854 -
val_loss: 0.0844
Epoch 70/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0853 -
val_loss: 0.0844
Epoch 71/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0853 -
val_loss: 0.0843
Epoch 72/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0851 -
val_loss: 0.0843
Epoch 73/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0851 -
val_loss: 0.0842
Epoch 74/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0850 -
val_loss: 0.0840
Epoch 75/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0850 -
val_loss: 0.0840
Epoch 76/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0848 -
```

```
val_loss: 0.0840
Epoch 77/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0848 -
val_loss: 0.0839
Epoch 78/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0848 -
val_loss: 0.0838
Epoch 79/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0847 -
val_loss: 0.0838
Epoch 80/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0846 -
val_loss: 0.0837
Epoch 81/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0845 -
val_loss: 0.0837
Epoch 82/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0845 -
val_loss: 0.0838
Epoch 83/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0845 -
val_loss: 0.0835
Epoch 84/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0844 -
val_loss: 0.0835
Epoch 85/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0844 -
val_loss: 0.0835
Epoch 86/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0843 -
val_loss: 0.0834
Epoch 87/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0842 -
val_loss: 0.0833
Epoch 88/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0842 -
val_loss: 0.0833
Epoch 89/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0841 -
val_loss: 0.0833
Epoch 90/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0841 -
val_loss: 0.0832
Epoch 91/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0840 -
val_loss: 0.0831
Epoch 92/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0841 -
```

```

val_loss: 0.0831
Epoch 93/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0839 -
val_loss: 0.0831
Epoch 94/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0839 -
val_loss: 0.0831
Epoch 95/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0839 -
val_loss: 0.0830
Epoch 96/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0838 -
val_loss: 0.0829
Epoch 97/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0838 -
val_loss: 0.0829
Epoch 98/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0838 -
val_loss: 0.0829
Epoch 99/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0837 -
val_loss: 0.0829
Epoch 100/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0836 -
val_loss: 0.0828
Epoch 101/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0836 -
val_loss: 0.0827
Epoch 102/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0836 -
val_loss: 0.0827
Epoch 103/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0836 -
val_loss: 0.0828
Epoch 104/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0835 -
val_loss: 0.0826
Epoch 105/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0835 -
val_loss: 0.0826
Epoch 106/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0834 -
val_loss: 0.0827
Epoch 107/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0834 -
val_loss: 0.0825
Epoch 108/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0833 -

```

```
val_loss: 0.0825
Epoch 109/150
60000/60000 [=====] - 3s 49us/step - loss: 0.0833 -
val_loss: 0.0825
Epoch 110/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0833 -
val_loss: 0.0824
Epoch 111/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0832 -
val_loss: 0.0824
Epoch 112/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0833 -
val_loss: 0.0825
Epoch 113/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0832 -
val_loss: 0.0823
Epoch 114/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0831 -
val_loss: 0.0823
Epoch 115/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0831 -
val_loss: 0.0823
Epoch 116/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0831 -
val_loss: 0.0822
Epoch 117/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0831 -
val_loss: 0.0822
Epoch 118/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0830 -
val_loss: 0.0822
Epoch 119/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0830 -
val_loss: 0.0822
Epoch 120/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0829 -
val_loss: 0.0821
Epoch 121/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0829 -
val_loss: 0.0821
Epoch 122/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0829 -
val_loss: 0.0822
Epoch 123/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0829 -
val_loss: 0.0820
Epoch 124/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0829 -
```

```

val_loss: 0.0823
Epoch 125/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0829 -
val_loss: 0.0821
Epoch 126/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0828 -
val_loss: 0.0819
Epoch 127/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0828 -
val_loss: 0.0820
Epoch 128/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0827 -
val_loss: 0.0819
Epoch 129/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0828 -
val_loss: 0.0820
Epoch 130/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0828 -
val_loss: 0.0818
Epoch 131/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0827 -
val_loss: 0.0818
Epoch 132/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0827 -
val_loss: 0.0818
Epoch 133/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0826 -
val_loss: 0.0818
Epoch 134/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0826 -
val_loss: 0.0818
Epoch 135/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0826 -
val_loss: 0.0817
Epoch 136/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0826 -
val_loss: 0.0817
Epoch 137/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0826 -
val_loss: 0.0820
Epoch 138/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0826 -
val_loss: 0.0817
Epoch 139/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0825 -
val_loss: 0.0817
Epoch 140/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0825 -

```

```

val_loss: 0.0817
Epoch 141/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0825 -
val_loss: 0.0817
Epoch 142/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0825 -
val_loss: 0.0817
Epoch 143/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0824 -
val_loss: 0.0816
Epoch 144/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0824 -
val_loss: 0.0816
Epoch 145/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0824 -
val_loss: 0.0816
Epoch 146/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0824 -
val_loss: 0.0816
Epoch 147/150
60000/60000 [=====] - 3s 49us/step - loss: 0.0824 -
val_loss: 0.0815
Epoch 148/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0824 -
val_loss: 0.0815
Epoch 149/150
60000/60000 [=====] - 3s 48us/step - loss: 0.0823 -
val_loss: 0.0815
Epoch 150/150
60000/60000 [=====] - 3s 47us/step - loss: 0.0823 -
val_loss: 0.0815

```

```

[0]: dae.save_model_weights("dae_model_weights.h5")
     dae.save_model("dae_model.json")
     dae.save_model_history(dae_history, "dae_model_history.pkl")

[0]: ! cp -r dae_model.json dae_model_weights.h5 dae_model_history.pkl ./gdrive/My\
     ↳ Drive/ece595_ml2/models/

[0]: dae_model = dae.load_model("dae_model.json", "dae_model_weights.h5")

[0]: dae_reconstructions = dae_model.predict(data_test_noisy)

[63]: print(len(dae_model.layers))
      print(dae_model.summary())

```

```

9
Model: "sequential_2"
-----

```

| Layer (type) | Output Shape | Param # |
|-------------------------------|--------------------|---------|
| conv2d_6 (Conv2D) | (None, 28, 28, 16) | 160 |
| max_pooling2d_3 (MaxPooling2) | (None, 14, 14, 16) | 0 |
| conv2d_7 (Conv2D) | (None, 14, 14, 8) | 1160 |
| max_pooling2d_4 (MaxPooling2) | (None, 7, 7, 8) | 0 |
| conv2d_8 (Conv2D) | (None, 7, 7, 8) | 584 |
| up_sampling2d_3 (UpSampling2) | (None, 14, 14, 8) | 0 |
| conv2d_9 (Conv2D) | (None, 14, 14, 16) | 1168 |
| up_sampling2d_4 (UpSampling2) | (None, 28, 28, 16) | 0 |
| conv2d_10 (Conv2D) | (None, 28, 28, 1) | 145 |
| Total params: 3,217 | | |
| Trainable params: 3,217 | | |
| Non-trainable params: 0 | | |
| None | | |

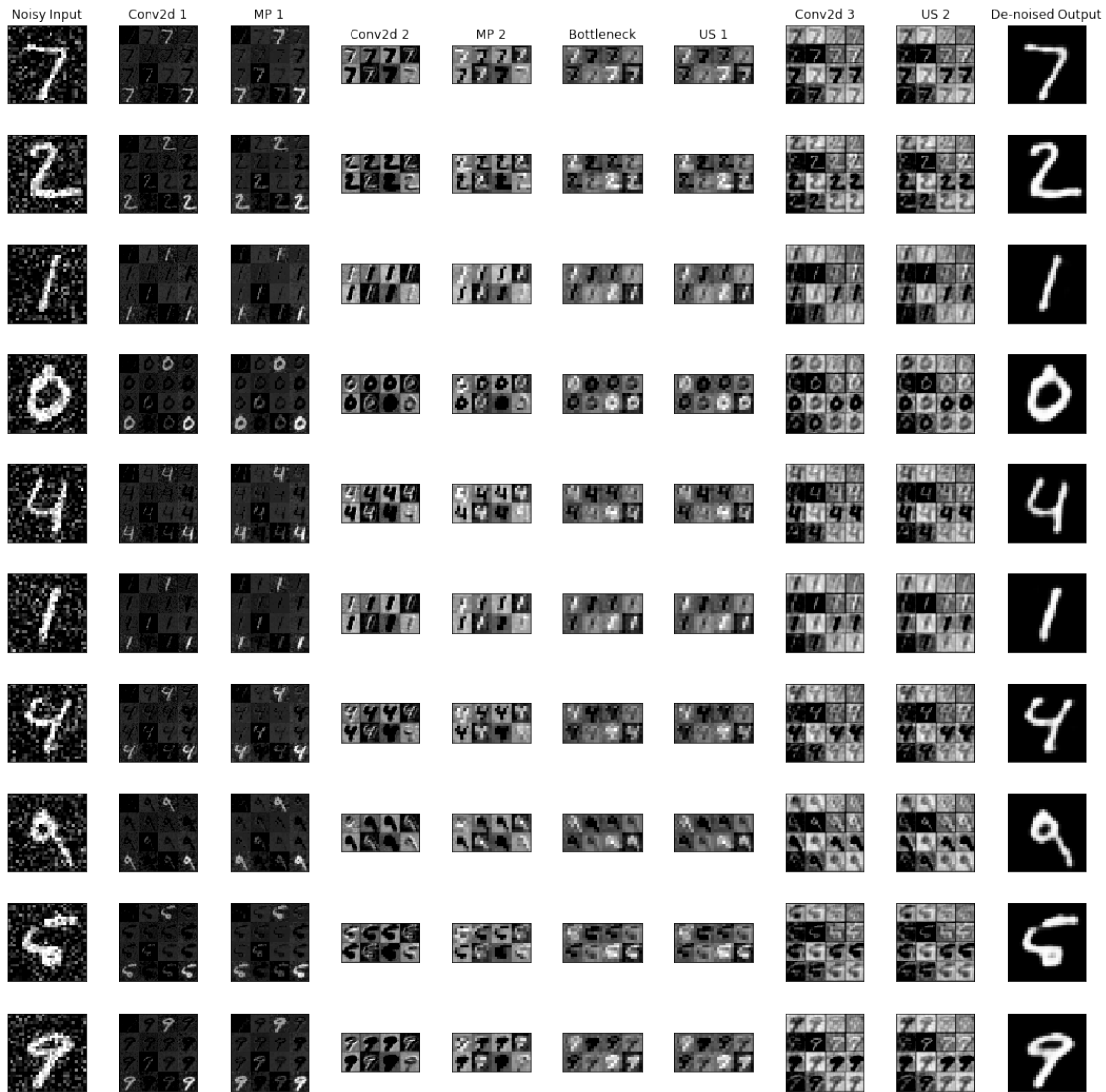
```
[0]: dae_w_hl = get_hidden_layers_representation(dae_model, data_test_noisy)
```

1.7 Layer Representation

```
[0]: n_samples = 10
n_layers = len(dae_model.layers)
layers = [' Noisy Input ',
          ' Conv2d 1 ',
          ' MP 1 ',
          ' Conv2d 2 ',
          ' MP 2 ',
          ' Bottleneck ',
          ' US 1 ',
          ' Conv2d 3 ',
          ' US 2 ',
          ' De-noised Output ']
cols = ['{}'.format(col) for col in layers]
```

```
[0]: n_kernels = [dae_w_hl[i][0][0].shape[2] for i in range(1, n_layers)]
```

```
[71]: fig, axes = plt.subplots(nrows=n_samples, ncols=n_layers+1, figsize=(15, 15))
for i in range(n_samples):
    axes[i, 0].imshow(data_test_noisy[i].reshape(28, 28),
                      cmap=plt.cm.gray)
    for j in range(1, n_layers + 1, 1):
        temp1 = hidden_layer_weights(dae_w_hl[j][0][i])
        axes[i, j].imshow(temp1, cmap=plt.cm.gray)
    for ax, col in zip(axes[0], cols):
        ax.set_title(col)
    for j in range(n_layers+1):
        axes[i, j].get_xaxis().set_visible(False)
        axes[i, j].get_yaxis().set_visible(False)
fig.tight_layout()
plt.show()
```



1.8 Loss Curves

```
[72]: plt.plot(dae_history.history['loss'])  
plt.plot(dae_history.history['val_loss'])  
plt.xlabel("Epochs")  
plt.ylabel("Loss")  
plt.title("Loss v/s Epochs")  
plt.legend(['train', 'test'], loc='upper right')  
plt.show()
```

