

MURALI KARTEEK

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Education

UNIVERSITY OF ILLINOIS

URBANA-CHAMPAIGN

MENG IN AUTONOMY AND ROBOTICS

August 2025 Illinois, USA

INDIAN INSTITUTE OF TECHNOLOGY

KHARAGPUR

B.TECH IN ELECTRICAL ENGINEERING

April 2021 Kharagpur, India

Coursework

Deep Learning Foundations And Applications• Machine learning• Embedded Systems• Control Systems Engineering• Probability And Stochastic Process• Computer Architecture And Operating Systems• Programming And Data Structures

Skills

PROGRAMMING/AI FRAMEWORKS

Python • C • Verilog• Keras• TensorFlow• Pytorch

SOFTWARE & TOOLS

ROS• GitHub• Docker• Anaconda• Linux• Arduino IDE• SolidWorks• OpenCV• GYM AI

LANGUAGES

English• Japanese• Hindi• Telugu

Scholarships

SCHOLARSHIP FOR HIGHER EDUCATION (SHE)

Certifications

QUBIT BY QUBIT

INTRODUCTION TO QUANTUM COMPUTING

ONLINE COURSE SPONSORED BY IBM

QUANTUM

Oct 2020 - May 2021 California, USA

DEEP LEARNING SPECIALIZATION.

DEEP LEARNING, ONLINE COURSES IN

COURSERA OFFERED BY DEEPLARNING.AI

Publication

ROBOCUP SYMPOSIUM

Research contribution in "KgpKubs 2019 Team Description Paper" which includes software, hardware and mechanical developments made by krssg from 2019 to 2020

April 2020 Kharagpur, India

Competitions

ROBOCUP SSL 2019

QUALIFIED FOR ROBOCUP SOCCER SMALL SCALE LEAGUE 2019

June 2019 Sydney, AUS

Experience

ROBOTICS ENGINEER

KONICA MINOLTA

Oct 2021 – July 2024

Tokyo, Japan

- Specialized in industrial automation, particularly bulk bin pick-and-place robots.
- Applied classical and AI-based computer vision for precise 6-DoF item detection and prediction.
- Developed an algorithm using NANOSAM and Blip to automate training annotations for deep learning models, removing human effort and speeding up model training.
- Filled 2 patents in computer vision and Robotic grasping.

MACHINE LEARNING INTERN

PHILIPS INNOVATION CAMPUS

April 2020 - June 2020

Bangalore, India

- Expertly analyzed CT scans and medical images from Luna 16 dataset, utilizing advanced image pre-processing techniques.
- Created and deployed a 3D volumetric UNet model to effectively segment lung nodules.
- Advanced early-stage lung cancer diagnosis research through innovative image analysis and deep learning.

Projects

MULTITASK LEARNING WITH LANGUAGE USING AIRL

KONICA MINOLTA & GEORGIA TECH

Nov 2021 - Aug 2022

Tokyo, Japan

- Collaborated with Professor Matthew Gomblay and research scholars from Georgia Tech to pioneer a language-driven approach for multi-task learning in manipulation domains.
- Achieved a remarkable 72% accuracy milestone, demonstrating up to a 200% enhancement in zero-shot task success rates and accelerated skill transfer to novel tasks, showcasing the power of language-based goal specification in robotics.

PORTRS : PAYLOAD ORGANIZATION AND TRANSPORTATION ROBOTIC SYSTEM

KONICA MINOLTA & JAPAN AEROSPACE EXPLORATION AGENCY

Feb 2023 - July 2024

Tokyo, Japan

- Collaborated with JAXA Japan Aerospace Exploration Agency to create a novel solution for visually assisting multi-limbed robot.
- Designed and optimized an AI model for grasping the existing in-ship interface and manipulating various objects inside International Space Station.

KHARAGPUR ROBOSOCER STUDENTS' GROUP

INDIAN INSTITUTE OF TECHNOLOGY KHARAGPUR

Feb 2018 - April 2021

Kharagpur, India

- Key in FPGA control code design for motors and sensors in the Embedded Systems team, boosting soccer robot performance.
- Chosen for RoboCup, Sydney 2019 and Montreal 2018, showcasing tech skills and cross-team collaboration.
- Led assembly of 8 operational RoboCup robots, highlighting dedication and teamwork across university years.