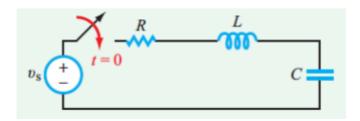
Lecture 6 Second-Order Circuits

What if we have both L and C in the circuit

Series RLC Circuits

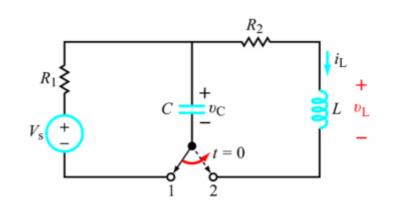


when $i_L(0_-) = 0, v_c(0_-) = 0$ find $V_c(t)$

$$egin{cases} i_L(t) = crac{dv_c(t)}{dt} \ V_s - R \cdot i_L(t) - Lrac{di_l(t)}{dt} - v_c(t) = 0 \end{cases} \Rightarrow RCrac{dv_c(t)}{dt} + LCrac{d^2v_c(t)}{dt^2} + v_c(t) = v_s \ rac{d^2v_c(t)}{dt^2} + rac{R}{L}rac{dv_c(t)}{dt} + rac{1}{LC}v_c(t) = rac{v_s}{LC} \ \end{cases}$$

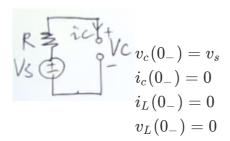
这是一个二阶方程,所以也是二阶电路。second order circuit

Initial and Final condition

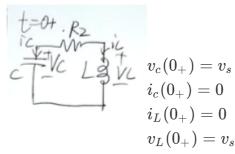


$$egin{aligned} ext{Find} \ v_c(0_-), i_c(0_-), i_L(0_-), v_L(0_-), \ v_c(0_+), i_c(0_+), i_L(0_+), v_L(0_+), \ v_c(\infty), i_c(\infty), i_L(\infty), v_L(\infty) \end{aligned}$$

1. $t=0_-$ steady state capacitor likes open circuit inductor like short circuit



2. t = 0+ 电容电压不突变, 电感电流不突变



3.
$$t = \infty$$

$$v_c(\infty)=0$$

$$i_c(\infty)=0$$

$$i_L(\infty)=0$$

$$v_L(\infty)=0$$

Example

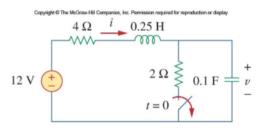
The switch has been closed for a long time. It is open at

t = 0. Find

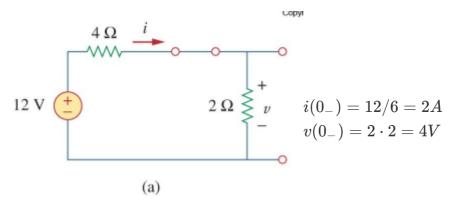
•
$$i(0^+), v(0^+)$$

•
$$di(0^+)/dt$$
, $dv(0^+)/dt$

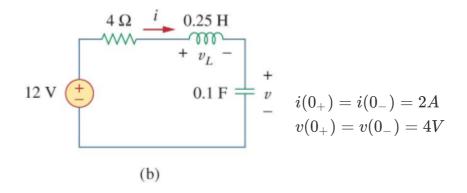
•
$$i(\infty)$$
, $v(\infty)$



1.
$$t = 0_{-}$$

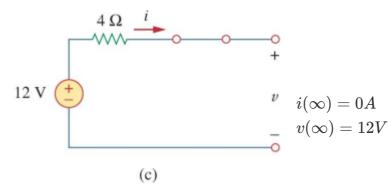


2.
$$t = 0_+$$



$$rac{di(0_+)}{dt} = rac{1}{L}V_L(0_+) = 12 - 2*4 - 4 = 0A/s$$
 $rac{dv(0_+)}{dt} = rac{1}{c}i_C(0_+) = 2/0.1 = 20V/s$

$$3. t = \infty$$



Natural Response自然响应,零输入响应

series RLC circuit

$$V_c = V_c + V_c + V_c = V_c$$

$$egin{aligned} egin{aligned} i_L(t) &= crac{dv_c(t)}{dt} \ -R \cdot i_L(t) - Lrac{di_l(t)}{dt} - v_c(t) &= 0 \end{aligned} \Rightarrow RCrac{dv_c(t)}{dt} + LCrac{d^2v_c(t)}{dt^2} + v_c(t) &= 0 \ rac{d^2v_c(t)}{dt^2} + prac{dv_c(t)}{dt} + qv_c(t) &= 0, ext{ where } p = rac{R}{L}, q = rac{1}{LC} \end{aligned}$$

解上述二阶常系数微分方程($\mathbf{2}^{nd}$ order ordinary differential equation/ODE)就可以解除这个电路。

Let $V_C(t)=Ae^{st}$, then $Ae^{st}(s^2+ps+q)=0$. Solve equation $s^2+ps+q=0$ about s

$$s = rac{-p \pm \sqrt{p^2 - 4q}}{2} = rac{R}{2L} \pm \sqrt{(rac{R}{2L})^2 - rac{1}{LC}}$$

So we have 3 cases here:

1. overdamped 过阻尼 s have two different real solution

where $(\frac{R}{2L})^2 - \frac{1}{LC} > 0$, let $\alpha = \frac{R}{2L}$, $\omega_0 = \frac{1}{\sqrt{LC}}$ so the equation about the circuit can be interpret into $s^2 + 2\alpha s + \omega_0^2 = 0$, so that

$$s_{1,2} = -lpha \pm \sqrt{lpha^2 - \omega_0^2}.$$

Therefore $V_C(t)=A_1e^{s_1t}+A_2e^{s_2t}$,where A_1,A_2 can be found using two initial conditions.

2. **critically damped** 临界阻尼 s have only one real solution

where
$$(\frac{R}{2L})^2 - \frac{1}{LC} = 0$$
, let $\alpha = \frac{R}{2L}$, $\omega_0 = \frac{1}{\sqrt{LC}}$, $\alpha = \omega_0 \ s = s_1 = s_2 = -\alpha$

Therefore $V_C(t)=(A_1t+A_2)e^{st}$, where A_1,A_2 can be found using two initial conditions.

3. **underdamped** 欠阻尼 s_1, s_2 are complex

where $(\frac{R}{2L})^2 - \frac{1}{LC} < 0$, let $\alpha = \frac{R}{2L}$, $\omega_0 = \frac{1}{\sqrt{LC}}$ so the equation about the circuit can be interpret into $s^2 + 2\alpha s + \omega_0^2 = 0$, so that

$$s_{1,2} = -lpha \pm \sqrt{\omega_0^2 - lpha^2} i$$
, seeing that $V_C(t) \in \mathbb{R}$

$$c_1 e^{s_1 t} + c_2 e^{s_2 t} = c_1 e^{-(\alpha + j\omega_d i)t} + c_2 e^{-(\alpha - j\omega_d i)t} \ (c_1 e^{s_1 t} + c_2 e^{s_2 t})^* = c_1^* e^{-(\alpha - j\omega_d i)t} + c_2^* e^{-(\alpha + j\omega_d i)t}$$

so that $c_1=c_2^*$, then

$$v_c(t) = e^{-lpha t} [A_1 cos\omega_d t + A_2 sin\omega_d t]$$

Summary series RLC network

Case
$$\alpha = \frac{R}{2L}, \omega_0 = \sqrt{\frac{1}{LC}}$$

$$1 \quad \text{overdamped} \quad \alpha > \omega \Leftrightarrow R > 2\sqrt{\frac{L}{C}} \quad V_C(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$$

$$s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$$

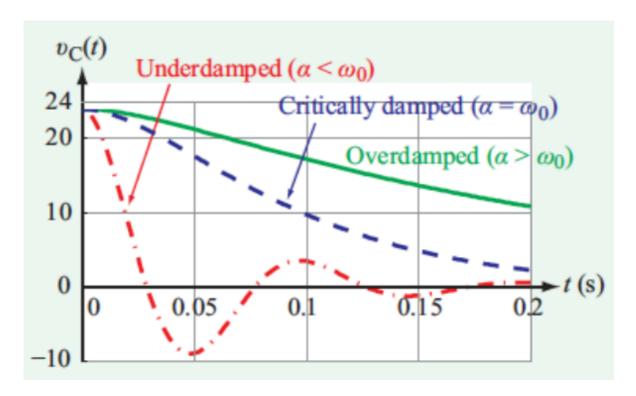
$$2 \quad \text{critically damped} \quad \alpha = \omega \Leftrightarrow R = 2\sqrt{\frac{L}{C}} \quad V_C(t) = (A_1 t + A_2) e^{st}$$

$$s = -\alpha$$

$$3 \quad \text{underdamped} \quad \alpha < \omega \Leftrightarrow R < 2\sqrt{\frac{L}{C}} \quad V_C(t) = e^{-\alpha t} [A_1 cos\omega_d t + A_2 sin\omega_d t]$$

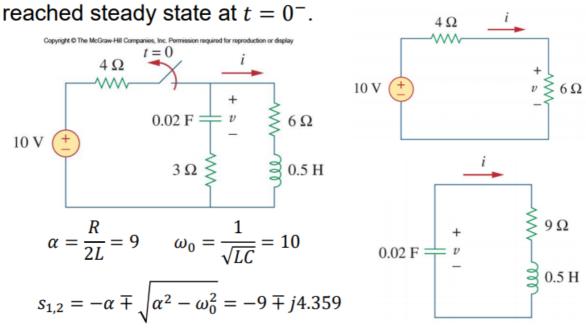
$$\omega_0 = \sqrt{\omega_0^2 - \alpha^2}$$

Image



Example

Find v(t) &i(t) in the circuit below. Assume the circuit has



$$V(t) = e^{-\alpha t} \left[A_1 \cos w dt + A_2 \sin w dt \right]$$

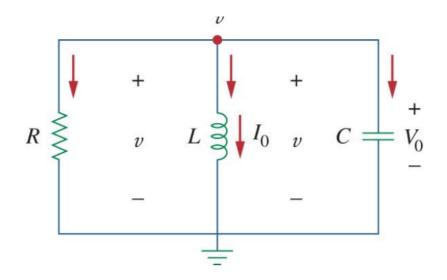
$$= e^{-9t} \left[A_1 \cos 4.389t + A_2 \sin 4.359t \right]$$

From
$$i(0+) = iA$$

 $\Rightarrow -c \frac{dV(0+)}{dt} = iA \Rightarrow \frac{dV(0+)}{dt} = -toV/s$.
 $\Rightarrow \int \frac{dV(0+)}{dt} = -9A_1 + 4.359A_2 = -50$ $\Rightarrow \int A_2 = 0.918$.
 $V(0+) = A_1 = 6$
 $\Rightarrow V(t) = e^{-9t} \left(6\cos 4.359t + 0.918 \sin 4.359t \right) V$

More Notes

parallel RLC circuit



$$egin{cases} V_c(t) = Lrac{di_L(t)}{dt} \ rac{V_c}{R} + i_L + crac{dV_c}{dt} = 0 \end{cases} \Rightarrow rac{L}{R}rac{di_L(t)}{dt} + LCrac{d^2i_L(t)}{dt^2} + i_L(t) = 0 \ \Rightarrow rac{d^2i_L}{dt^2} + rac{1}{RC}rac{di_L}{dt} + rac{i_L}{LC} = 0 \end{cases}$$

1. **overdamped** 过阻尼 s have two different real solution

where $(\frac{1}{2RC})^2 - \frac{1}{LC} > 0$, let $\alpha = \frac{1}{2RC}$, $\omega_0 = \frac{1}{\sqrt{LC}}$ so the equation about the circuit can be interpret into $s^2+2\alpha s+\omega_0^2=0$, so that

$$s_{1,2} = -lpha \pm \sqrt{lpha^2 - \omega_0^2}.$$

Therefore $i_L(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$,where A_1, A_2 can be found using two initial conditions.

2. **critically damped** 临界阻尼 s have only one real solution

where
$$(\frac{1}{2RC})^2-\frac{1}{LC}=0$$
, let $lpha=\frac{1}{2RC}, \omega_0=\frac{1}{\sqrt{LC}}, lpha=\omega_0 \ s=s_1=s_2=-lpha$

Therefore $i_L(t)=(A_1t+A_2)e^{st}$,where A_1,A_2 can be found using two initial conditions.

3. **underdamped** 欠阻尼 s_1, s_2 are complex

where $(\frac{1}{2RC})^2 - \frac{1}{LC} < 0$, let $\alpha = \frac{1}{2RC}$, $\omega_0 = \frac{1}{\sqrt{LC}}$ so the equation about the circuit can be interpret into $s^2+2lpha s+\omega_0^2=0$, so that

$$s_{1,2} = -lpha \pm \sqrt{\omega_0^2 - lpha^2} i$$
, seeing that $V_C(t) \in \mathbb{R}$

$$c_1 e^{s_1 t} + c_2 e^{s_2 t} = c_1 e^{-(\alpha + j\omega_d i)t} + c_2 e^{-(\alpha - j\omega_d i)t}$$

$$(c_1e^{s_1t}+c_2e^{s_2t})^*=c_1^*e^{-(\alpha-j\omega_di)t}+c_2^*e^{-(\alpha+j\omega_di)t}$$

so that $c_1 = c_2^*$, then

$$i_L(t) = e^{-lpha t} [A_1 cos \omega_d t + A_2 sin \omega_d t]$$

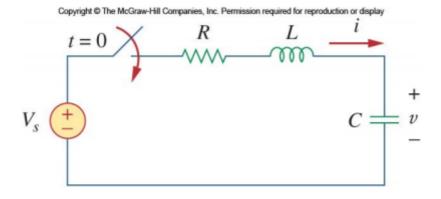
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overdamped
$$\alpha > \omega \Leftrightarrow \frac{1}{R} > 2\sqrt{\frac{L}{C}}$$
 $V_C(t) = A_1e^{s_1t} + A_2e^{s_2t}$ $s_{1,2} = -\alpha \pm \sqrt{\alpha^2 - \omega_0^2}$ $\left\{\begin{array}{l} s_1A_1 + s_2A_2 = \frac{i(0_+)}{c} \\ A_1 + A_2 = v(0_+) \end{array}\right\}$ 2 critically damped $\alpha = \omega \Leftrightarrow \frac{1}{R} = 2\sqrt{\frac{L}{C}}$ $V_C(t) = (A_1t + A_2)e^{st}$ $s = -\alpha$ $\left\{\begin{array}{l} A_1 + sA_2 = \frac{i(0_+)}{c} \\ A_2 = v(0_+) \end{array}\right\}$ 3 underdamped $\alpha < \omega \Leftrightarrow \frac{1}{R} < 2\sqrt{\frac{L}{C}}$ $V_C(t) = e^{-\alpha t}[A_1cos\omega_d t + A_2sin\omega_d t]$ $\omega_0 = \sqrt{\omega_0^2 - \alpha^2}$ $\left\{\begin{array}{l} \omega_0 A_2 - \alpha A_1 = \frac{i(0_+)}{c} \\ A_1 = v(0_+) \end{array}\right\}$

Step response 阶跃响应

series RLC circuit



$$\frac{d^2V}{dt^2} + \frac{R}{L}\frac{dV}{dt} + \frac{V}{LC} = \frac{V_s}{LC}$$
 Solution: $V(t) = \underbrace{V_t(t)}_{\text{transient response}} + \underbrace{V_{ss}(t)}_{\text{steady state response}}$ (*)

Statement: specifically, for step response, $V_t(t)$ is the same format as in natural response, $V_{ss} = V_s$, v(t) is the solution to equation(*)

$$lpha=rac{R}{2L}, \omega_0=\sqrt{rac{1}{LC}}$$

Case

overdamped
$$lpha>\omega\Leftrightarrow R>2\sqrt{rac{L}{C}}$$
 $V_C(t)=A_1e^{s_1t}+A_2e^{s_2t}+V_s$ $s_{1,2}=-lpha\pm\sqrt{lpha^2-\omega_0^2}$

2 critically damped
$$lpha=\omega\Leftrightarrow R=2\sqrt{rac{L}{C}} \quad egin{array}{c} V_C(t)=(A_1t+A_2)e^{st}+V_s \ s=-lpha \end{array}$$

$$lpha<\omega\Leftrightarrow R<2\sqrt{rac{L}{C}} \hspace{0.5cm} V_C(t)=e^{-lpha t}[A_1cos\omega_dt+A_2sin\omega_dt]+V_s \ \omega_0=\sqrt{\omega_0^2-lpha^2}$$

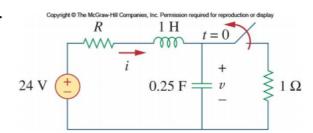
example

Find v(t) and i(t) for t > 0.
 Consider three cases:

$$R = 5\Omega$$

$$R = 4\Omega$$

$$R = 1\Omega$$



When $R = 5\Omega$,

• For t < 0, switch closed, capacitor open, inductor shorted.

$$i(0) = 4A = C \frac{dv(0)}{dt}, \ v(0) = 4V, \ \frac{dv(0)}{dt} = 16$$

■ For t > 0, switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 2.5$$
, $\omega_0 = \frac{1}{\sqrt{LC}} = 2$, $s_{1,2} = -1, -4$ Overdamped.
$$v(t) = v_{ss} + (A_1 e^{-t} + A_2 e^{-4t})$$

$$\frac{1}{2 \times 1 H} = 25 \text{ rad/s}, \quad w_0 = \frac{1}{1 \times 025} \text{ rad/s} = 2 \text{ rad/s}. \quad d>w_0.$$

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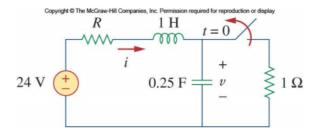
$$\frac{1}{2 \times 1 H} = 25 \text{ rad/s}. \quad d>w_0.$$

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$$\frac{1}{2 \times 1 H} = 25 \text{$$



When $R = 4\Omega$,

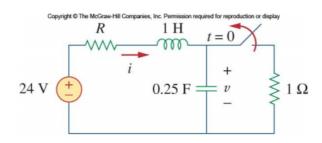
• For t < 0, switch closed, capacitor open, inductor shorted.

$$i(0) = 4.8A = C \frac{dv(0)}{dt}, \ v(0) = 4.8V, \ \frac{dv(0)}{dt} = 19.2$$

• For t > 0, switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 2$$
, $\omega_0 = \frac{1}{\sqrt{LC}} = 2$, $s_{1,2} = -2$ Critically damped $v(t) = v_{ss} + (A_1 + A_2 t)e^{-2t}$

(b)
$$R=4\pi$$
, $V(0+)=4.8V$, $\tilde{V}(0+)=4.8A$. Critically $Q = 4\pi = 2rad/s$, $W_0 = \sqrt{1\times0.25} = 2rad/s$. $Q = W_0$. darped $\Rightarrow S_1 = S_2 = S = -Q = -2$. $\Rightarrow V(t) = (-19.2t - 19.2)e^{-2t}$ $\Rightarrow V(t) = (AittA_L)e^{-2t} + 24V$. $\Rightarrow V(0+) = A_2 + 24 = 4.8 \Rightarrow A_2 = -19.2$ $\Rightarrow A_1 = -19.2$ $\Rightarrow A_2 = -19.2$ $\Rightarrow A_2 = -19.2$ $\Rightarrow A_3 = -19.2$ $\Rightarrow A_4 = -19.2$ $\Rightarrow A_4 = -19.2$ $\Rightarrow A_4 = -19.2$



When $R = 1\Omega$,

• For t < 0, switch closed, capacitor open, inductor shorted.

$$i(0) = 12A = C \frac{dv(0)}{dt}, \ v(0) = 12V, \ \frac{dv(0)}{dt} = 48$$

• For t > 0, switch open, a series RLC network

$$\alpha = \frac{R}{2L} = 0.5$$
, $\omega_0 = \frac{1}{\sqrt{LC}} = 2$, $s_{1,2} = -0.5 \mp j1.936$ Underdamped $v(t) = v_{ss} + (A_1 \cos 1.936t + A_2 \sin 1.936t)e^{-0.5t}$

(C)
$$R=10$$
, $V(0+)=12V$, $i(0+)=12A$.

 $Q = \frac{10}{2\times 1H} = 0.5 \text{ rad/s}$. $W_0 = \frac{1}{1\times 0.25} = 2 \text{ rad/s}$. $Q < W_0$.

 $W_0 = \frac{1}{1\times 0.25} = -0.5 \text{ tig/936}$. $W_0 = \frac{1}{1\times 0.25} = -0.5 \text{ tig/936}$.

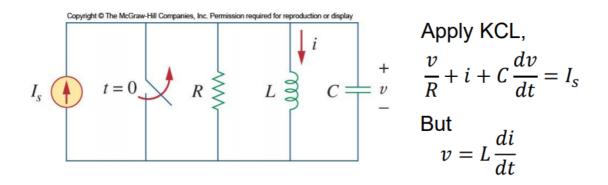
 $V(t) = e^{-0.5t} (B_1 \cos 1.936t + B_2 \sin 1.936t) + 24V$.

From instruction:

 $V(0+) = B_1 + 24 = 12 \Rightarrow B_1 = -12$.

 $i(0+) = c \frac{dV(t)}{dt}|_{t=0+} = \frac{1}{4}(-0.5B_1 + 1.936B_2) = 12$
 $\int B_1 = -12$, $B_2 = 21.694$. $\Rightarrow V(t) = e^{-0.5t} (-12\cos 1.936t + 21.6945\cos 1.936t) + 24V$.

parallel RLC Circuit



So we get

$$\frac{d^2i}{d^2t} + \frac{1}{RC}\frac{di}{dt} + \frac{i}{LC} = \frac{I_s}{LC}$$

$$\frac{d^2I}{dt^2} + \frac{1}{RC}\frac{dI}{dt} + \frac{I}{LC} = \frac{I_s}{LC}$$
Solution: $I(t) = \underbrace{I_t(t)}_{\text{transient response}} + \underbrace{I_{ss}(t)}_{\text{steady state response}}$ (*)

Statement: specifically, for step response, $I_t(t)$ is the same format as in natural response, $I_{ss} = I_s$, v(t) is the solution to equation(*)

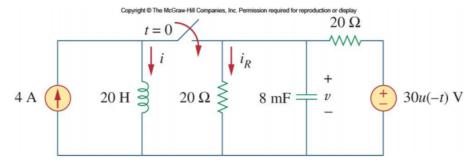
$$lpha=rac{R}{2L}, \omega_0=\sqrt{rac{1}{LC}}$$

Case

Case		$lpha=rac{R}{2L}, \omega_0=\sqrt{rac{1}{LC}}$	
1	overdamped	$lpha > \omega \Leftrightarrow R > 2\sqrt{rac{L}{C}}$	$egin{split} I_L(t) &= A_1 e^{s_1 t} + A_2 e^{s_2 t} + I_s \ s_{1,2} &= -lpha \pm \sqrt{lpha^2 - \omega_0^2} \end{split}$
2	critically damped	$lpha = \omega \Leftrightarrow R = 2\sqrt{rac{L}{C}}$	$I_L(t) = (A_1t + A_2)e^{st} + I_s \ s = -lpha$
3	underdamped	$lpha < \omega \Leftrightarrow R < 2\sqrt{rac{L}{C}}$	$I_L(t) = e^{-lpha t} [A_1 cos \omega_d t + A_2 sin \omega_d t] + I_s \ \omega_0 = \sqrt{\omega_0^2 - lpha^2}$

example

• Find i(t) and $i_R(t)$ for t > 0.



Initial values (
$$t < 0$$
): $i(0) = 4A$, $v(0) = \frac{20}{20 + 20} \times 30V = 15V = L\frac{di(0)}{dt}$
For $t > 0$, $\alpha = \frac{1}{2RC} = \frac{1}{2 \times 10 \times 8 \times 10^{-3}} = 6.25$, $\omega_0 = \frac{1}{\sqrt{LC}} = \frac{1}{\sqrt{20 \times 8 \times 10^{-3}}} = 2.5$
$$s_{1,2} = -6.25 \mp 5.7282$$

$$i(t) = I_S + A_1 e^{S_1 t} + A_2 e^{S_2 t}$$

General RLC Circuit

example

General RLC Circuits

- Find the complete response v for t > 0 in the circuit.
- 2Ω

1. Initial conditions

$$v(0^+) = v(0^-) = 12V, i(0^+) = i(0^-) = 0$$

$$\frac{dv(0^+)}{dt} = \frac{i_C(0^+)}{C} = \frac{-12/2}{0.5} = -12 \, V/s$$

2. Transient response

KCL at node a:
$$i = \frac{v}{2} + 0.5 \frac{dv}{dt}$$

KVL on left mesh: $4i + 1\frac{di}{dt} + v = 0$

$$\Rightarrow \frac{d^2v}{dt^2} + 5\frac{dv}{dt} + 6v = 0 \Rightarrow v_t(t) = A_1e^{-2t} + A_2e^{-3t} = 12e^{-2t} - 4e^{-3t}$$

3. Steady-state response $v_{ss}(t) = 4V_{\text{Lecture 6}}$

$$v_{ss}(t) = 4V$$
Lecture 6

4. Put together

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Summary

1. without excitation(Natural Response)自然响应

Case		$rac{d^2y(t)}{dt}+2lpharac{dy(t)}{dt}+\omega_0^2y(t)=0$	
1	overdamped	$\alpha > \omega$	$y(t) = A_1 e^{s_1 t} + A_2 e^{s_2 t}$
			$s_{1,2}=-lpha\pm\sqrt{lpha^2-\omega_0^2}$
2	critically damped	$lpha=\omega$	$y(t) = (A_1t + A_2)e^{st} \ s = -lpha$
3	underdamped	$\alpha < \omega$	$y(t) = e^{-lpha t} [A_1 cos \omega_d t + A_2 sin \omega_d t] \ \omega_0 = \sqrt{\omega_0^2 - lpha^2}$

2. with any excitation

$$rac{d^2y(t)}{dt}+2lpharac{dy(t)}{dt}+\omega_0^2y(t)=f(t) \ y(t)=y_b+y_p$$

 y_h is the general solution to the corresponding homogeneous equation y_p is a particular solution \$

how to find y_p

$$f(t)=e^{rt}P_m(t),P_m(t)$$
是关于t的m次多项式, $r\in\mathbb{R}$
$$\begin{cases} r
eq s_{1,2}, & y_p=Qm(t)e^{rt} \ r=s_1 ext{ or } s_2(s_1
eq s_2), & y_p=tQ_m(t)e^{rt} \ r=s_1=s_2, & y_p=t^2Q_m(t)e^{rt} \end{cases}$$

2.

$$f(t) = e^{rt}(Mcos\omega t + Nsin\omega t), r, M, N, \omega \in \mathbb{R}, \omega
eq 0 \ \left\{egin{aligned} r \pm j\omega
eq s_{1,2}, & y_p = e^{rt}(B_1cos\omega t + B_2sin\omega t) \ r \pm j\omega = s_{1,2}, & y_p = te^{rt}(B_1cos\omega t + B_2sin\omega t) \end{aligned}
ight.$$

3.

\$\$

$$f(t) = f_1(t) + f_2(t) y_p = y_{p_1} + y_{p_2}$$

\$\$

$$f(t) = f_1(t) + f_2(t) y_p = y_{p_1} + y_{p_2} \\$$