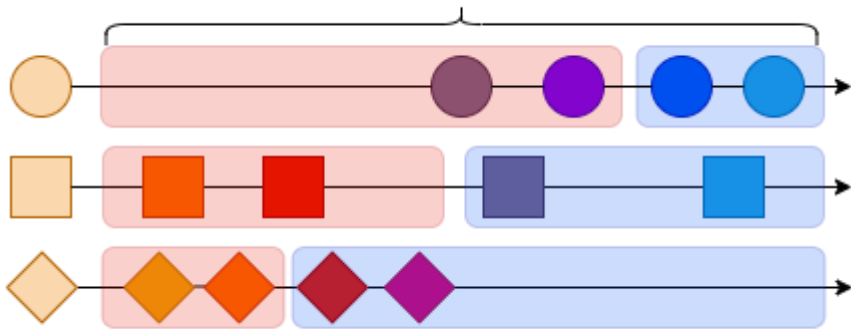


Anchor

Neighbours



Observation Sequences