# Causal Inference Course: Homework 2

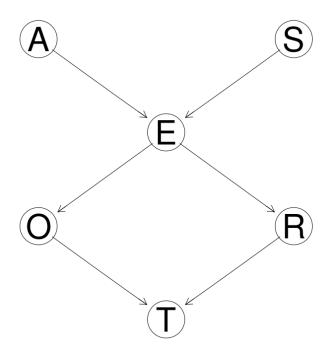
Dan Saattrup Nielsen, August 2020

This homework concerns building generative models, both Bayesian networks using bnlearn in R, and probabilistic programming using pyro in Python.

Our data is the survey data, containing the following categorical variables:

- **Age** (**A**): The age of the individual, which is *young* (**young**) if they'reless than 30 years old, *adult* (**adult**) if they're between 30 and 60 years old, and *old* (**old**) otherwise
- Sex (S): The biological sex of the individual, which here is assumed to be binary: male (M) or female (F)
- Education (E): The highest level of education completed by the individual, which can be *high school* (high) or *university degree* (uni)
- Occupation (O): Whether the individual is an *employee* (emp) or is *self* employed (self)
- **Residence** (**R**): The size of the city the individual lives in, which can be either *small* (**small**) or *big* (**big**)
- **Travel (T)**: The means of transport favoured by the individual, recorded as *car* (**car**), *train* (**train**) or *other* (**other**)

Here travel is the target of the survey. We're using the following DAG as our model of the generative process of the data:



We start by defining this DAG in bnlearn:

```
net <- bnlearn::model2network('[A][S][E|A:S][O|E][R|E][T|O:R]')</pre>
```

Next, we will collect every possible d-separation statement in our graph in the variable arg\_sets:

```
vars <- nodes(net)
pairs <- combn(x = vars, 2, list)
arg_sets <- list()
for(pair in pairs){
  others <- setdiff(vars, pair)
  conditioning_sets <- unlist(lapply(0:4, function(.x) combn(others, .x, list)), recursive =
  for(set in conditioning_sets){
    args <- list(x = pair[1], y = pair[2], z = set)
    arg_sets <- c(arg_sets, list(args))
  }
}</pre>
```

## **Question 1: Markov Property**

A distribution P satisfies the **Markov property** with respect to a DAG G if for disjoint node sets A, B, C it holds that

$$A \perp_G B | C \Rightarrow A \perp_P B | C.$$

#### 1.1

To evaluate which of the potential d-separations are *actual* d-separations, we use bnlearn's dseparation function. Here we store all the true d-separations in dseps:

```
d_sep <- bnlearn::dseparation
dseps <- list()
for(args in arg_sets){
   if (d_sep(bn = net, x = args$x, y = args$y, z = args$z) == TRUE){
     dseps <- c(dseps, list(args))
   }
}</pre>
```

We can then check how many true d-separations there are:

```
> length(dseps)
61
```

## 1.2

We say that a d-separation statement  $X \perp_G Y | Z$  is **non-redundant** if Z is minimal. As an example, for the nodes A and T in the DAG,  $A \top T | E$  would

be non-redundant (since X and Y aren't unconditionally independent of each other), but  $A \perp_G T | O, R, S$  is redundant, as  $A \perp_G T | O, R$  holds.

## 1.3

To list all the non-redundant d-separation statements, we do a simple check for each pair of nodes, to see if it's possible to remove a node from the conditioning set Z and maintain conditional independence:

```
dseps.nonredundant <- list()
for(args in dseps){
  nonredundant <- TRUE
  for(z in args$z){
    z.removed <- args$z[args$z != z]
    if(d_sep(bn = net, x = args$x, y = args$y, z = z.removed) == TRUE){
      nonredundant <- FALSE
      break
    }
}
if(nonredundant == TRUE){
    dseps.nonredundant <- c(dseps.nonredundant, list(args))
}</pre>
```

We can now inspect dseps.nonredundant to see what the non-redundant dseparation statements in the graph are:

```
> dseps.nonredundant
[[1]]
[[1]]$x
[1] "A"

[[1]]$y
[1] "O"

[[1]]$z
[1] "E"

[[2]]
[[2]]$x
[1] "A"

[[2]]$y
[1] "R"

[[2]]$z
```

- [1] "E"
- [[3]]
- [[3]]\$x
- [1] "A"
- [[3]]\$y [1] "S"
- [[3]]\$z
- character(0)
- [[4]]
- [[4]]\$x
- [1] "A"
- [[4]]\$y
- [1] "T"
- [[4]]\$z
- [1] "E"
- [[5]]
- [[5]]\$x
- [1] "A"
- [[5]]\$y
- [1] "T"
- [[5]]\$z
- [1] "O" "R"
- [[6]]
- [[6]]\$x
- [1] "E"
- [[6]]\$y
- [1] "T"
- [[6]]\$z
- [1] "O" "R"

[[7]]

[[7]]\$x

[1] "0"

[[7]]\$y

[1] "R"

[[7]]\$z

[1] "E"

[[8]]

[[8]]\$x

[1] "0"

[[8]]\$y

[1] "S"

[[8]]\$z

[1] "E"

[[9]]

[[9]]\$x

[1] "R"

[[9]]\$y

[1] "S"

[[9]]\$z

[1] "E"

[[10]]

[[10]]\$x

[1] "S"

[[10]]\$y

[1] "T"

[[10]]\$z

[1] "E"

[[11]]

```
[[11]]$x
[1] "S"

[[11]]$y
[1] "T"

[[11]]$z
[1] "O" "R"
```

Every one of the 11 d-separations should thus be read as  $x \perp_G y | z$ , so the last one for instance states that  $S \perp_G T | O, R$ , which can be seen by inspection to be non-redundant.

#### 1.4

To make the search for d-separations more efficient, we can, for every pair of nodes, do a breadth-first search for the conditioning variables: first condition on one variable at a time, then pairs, and so on. As soon as we reach a conditional independence we know that the d-separation is non-redundant, and every set of conditioning variables containing that non-redundant set will also satisfy the d-separation statement, so there's no need to test them (via the d\_sep function).

### 1.5

We now check how many of the true d-separations also satisfy conditional independence in our dataset. For every d-separation, we use bnlearn's ci.test function to check this:

```
dseps.ci <- list()
for(args in dseps){
  indep <- ci.test(x = args$x, y = args$y, z = args$z, data = df)
  if(indep$p.value > 0.05){
    dseps.ci <- c(dseps.ci, list(args))
  }
}</pre>
```

We can now check how large the proportion of true d-separations witness true conditional independence relations in the data:

```
> length(setdiff(dseps, dseps.ci)) / length(dseps)
[1] 0.9180328
```

### 1.6

We can also check how large the proportion of true *non-redundant* d-separations witness true conditional independence relations in the data:

```
dseps.nonredundant.ci <- list()
for(args in dseps.nonredundant){</pre>
```

```
indep <- ci.test(x = args$x, y = args$y, z = args$z, data = df)
if(indep$p.value > 0.05){
   dseps.nonredundant.ci <- c(dseps.nonredundant.ci, list(args))
}
}
length(dseps.nonredundant.ci) / length(dseps.nonredundant)
[1] 1</pre>
```

Based on the results in 1.5 and 1.6, the Markov property holds for this DAG and dataset.

It is a bit strange that there are d-separations which are true conditional independencies but which stop reflecting true conditional independencies after we condition on further variables (and maintain the d-separation, so no collider bias is happening). These are the five culprits:

```
> setdiff(dseps, dseps.ci)
[[1]]
[[1]]$x
[1] "A"
[[1]]$y
[1] "0"
[[1]]$z
[1] "E" "S"
[[2]]
[[2]]$x
[1] "A"
[[2]]$y
[1] "R"
[[2]]$z
[1] "E" "O"
[[3]]
[[3]]$x
[1] "0"
[[3]]$y
```

```
[1] "S"
[[3]]$z
[1] "A" "E"
[[4]]
[[4]]$x
[1] "0"
[[4]]$y
[1] "S"
[[4]]$z
[1] "E" "T"
[[5]]
[[5]]$x
[1] "S"
[[5]]$y
[1] "T"
[[5]]$z
[1] "E" "O"
```

## Question 2: Faithfulness

A distribution P is **faithful** with respect to a DAG G if for disjoint node sets A, B, C it holds that

$$A \perp_P B | C \Rightarrow A \perp_G B | C.$$

In other words, it's the dual version of the Markov property.

### 2.1

Analogous to what we did in Question 1, we now make a list cis containing all the true conditional independence relations in our dataset:

```
cis <- list()
for(args in dseps){
  indep <- ci.test(x = args$x, y = args$y, z = args$z, data = df)
  if(indep$p.value > 0.05){
    cis <- c(cis, list(args))</pre>
```

```
}
}
```

As before, we can count how many conditional independence relations there are:

```
> length(cis)
[1] 56
```

#### 2.2

We now check how many true conditional independence relations reflect true d-separations in the DAG, as before. We start by storing them in cis.dsep:

```
cis.dsep <- list()
for(args in cis){
  if(d_sep(bn = net, x = args$x, y = args$y, z = args$z) == TRUE){
    cis.dsep <- c(cis.dsep, list(args))
  }
}
Next, we compute the proportion:
> length(cis.dsep) / length(cis)
```

## 2.3

[1] 1

If we were to check whether the true conditional independence relations were not only true d-separations, but *non-redundant* d-separations, we see that, non-surprisingly, the proportion is a lot smaller:

```
> length(intersect(cis.dsep, dseps.nonredundant)) / length(cis.dsep)
[1] 0.1964286
```

### 2.4

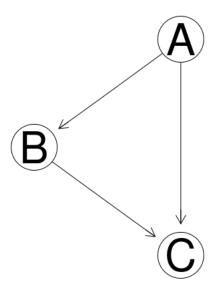
From the result in 2.2, I would conclude that the faithfulness assumption holds for this DAG and dataset. There's no reason to believe that every conditional independence relation corresponds to a non-redundant d-separation, as there are plenty of redundant conditional independence relations as well.

## Question 3: Intervention as Graph Mutilation

We now build a new DAG that we will be working with:

```
net <- model2network('[A][B|A][C|B:A]')
alias <- c('off', 'on')
cptA <- matrix(c(0.5, 0.5), ncol=2)
dimnames(cptA) <- list(NULL, alias)
cptB <- matrix(c(.8, .2, .1, .9), ncol=2)</pre>
```

```
\begin{array}{lll} \mbox{dimnames(cptB)} &<-\mbox{ list(B = alias, A = alias)} \\ \mbox{cptC} &<-\mbox{ matrix(c(.9, .1, .99, .01, .1, .9, .4, .6))} \\ \mbox{dim(cptC)} &<-\mbox{ c(2, 2, 2)} \\ \mbox{dimnames(cptC)} &<-\mbox{ list(C = alias, A = alias, B = alias)} \\ \mbox{model} &<-\mbox{ custom.fit(net, list(A = cptA, B = cptB, C = cptC))} \\ \mbox{graphviz.plot(model)} \end{array}
```



We now calculate the following conditional probability, using (the conditional version of) Bayes' Rule:

$$\begin{split} &P(A = \text{on}|B = \text{on}, C = \text{on}) \\ &= \frac{P(C = \text{on}|B = \text{on}, A = \text{on})P(A = \text{on}|B = \text{on})}{P(C = \text{on}|B = \text{on})} \\ &= \frac{P(C = \text{on}|B = \text{on}, A = \text{on})P(A = \text{on}|B = \text{on})}{P(C = \text{on}|B = \text{on}, A = \text{on})P(A = \text{on}|B = \text{on}) + P(C = \text{on}|B = \text{on}, A = \text{off})P(A = \text{off}|B = \text{on})} \end{aligned} \tag{3}$$

We start by calculating P(A = on|B = on), using Bayes' Rule again:

$$P(A = \text{on}|B = \text{on}) \tag{4}$$

$$= \frac{P(B = \text{on}|A = \text{on})P(A = \text{on})}{P(B = \text{on})}$$
(5)

$$= \frac{P(B = \text{on})}{P(B = \text{on}|A = \text{on})P(A = \text{on})}$$

$$= \frac{P(B = \text{on}|A = \text{on})P(A = \text{on})}{P(B = \text{on}|A = \text{on})P(A = \text{on})} + P(B = \text{on}|A = \text{off})P(A = \text{off})}$$
(6)

$$=\frac{0.9\cdot0.5}{0.9\cdot0.5+0.2\cdot0.5}\tag{7}$$

$$\approx 0.82$$
 (8)

From this we calculate the desired conditional probability:

$$P(A = \text{on}|B = \text{on}, C = \text{on})$$

$$= \frac{P(C = \text{on}|B = \text{on}, A = \text{on})P(A = \text{on}|B = \text{on})}{P(C = \text{on}|B = \text{on}, A = \text{on})P(A = \text{on}|B = \text{on}) + P(C = \text{on}|B = \text{on}, A = \text{off})P(A = \text{off}|B = \text{on})}$$

$$\approx \frac{0.6 \cdot 0.82}{0.6 \cdot 0.82 + 0.9 \cdot (1 - 0.82)}$$

$$\approx 0.75$$
(12)

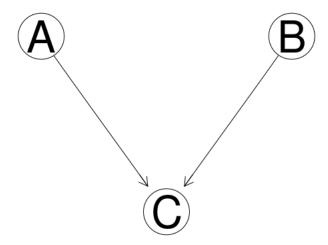
### 3.2

We can estimate the above conditional probability by sampling the model, using the rbn function in bnlearn:

## 3.3

Rather than working with conditional probabilities, we now turn to interventions. We can use bnlearn's mutilated function to perform the intervention do(B = on):

```
net.mutilated <- bnlearn::mutilated(net, list(B='on'))
graphviz.plot(net.mutilated)</pre>
```



We now calculate the following intervention, analogous to its conditional probability statement from 3.1. We start by applying the conditional Bayes' Rule as before:

$$P(A = \operatorname{on}|\operatorname{do}(B = \operatorname{on}), C = \operatorname{on})$$

$$P(C = \operatorname{on}|\operatorname{do}(B = \operatorname{on}), A = \operatorname{on}) P(A = \operatorname{on}|\operatorname{do}(B = \operatorname{on}))$$

$$(13)$$

$$= \frac{P(C = \text{on}|\text{do}(B = \text{on}), A = \text{on})P(A = \text{on}|\text{do}(B = \text{on}))}{P(C = \text{on}|\text{do}(B = \text{on}))}$$

$$(14)$$

$$= \frac{P(C = \text{on}|\text{do}(B = \text{on}), A = \text{on})P(A = \text{on}|\text{do}(B = \text{on}))}{P(C = \text{on}|\text{do}(B = \text{on}))}$$
(14)  
$$= \frac{P(C = \text{on}|\text{do}(B = \text{on}), A = \text{on})P(A = \text{on}|\text{do}(B = \text{on}))}{P(C = \text{on}|\text{do}(B = \text{on}), A = \text{on})P(A = \text{on}) + P(C = \text{on}|\text{do}(B = \text{on}), A = \text{off})P(A = \text{off})}$$
(15)

We now need to change the expression into one without any do-statements.

- The third rule of do-calculus (deletion of actions) allows us to conclude that P(A = on|do(B = on)) is equal to P(A = on), which is applicable since A is d-separated by B in the mutilated graph in which all ingoing edges to B have been removed.
- The second rule of do-calculus (action/observation exchange) gives us that we can exchange the do-expression in P(C = on|do(B = on), A = on) with its conditional counterpart; the same thing is the case where A = off.

These two lemmata then gives us the following:

$$P(A = \text{on}|\text{do}(B = \text{on}), C = \text{on})$$

$$= \frac{P(C = \text{on}|B = \text{on}, A = \text{on})P(A = \text{on})}{P(C = \text{on}|B = \text{on}, A = \text{on})P(A = \text{on}) + P(C = \text{on}|B = \text{on}, A = \text{off})P(A = \text{off})}$$

$$= \frac{0.6 \cdot 0.5}{0.6 \cdot 0.5 + 0.9 \cdot 0.5}$$

$$= 0.4$$
(16)
$$(17)$$

$$= \frac{0.6 \cdot 0.5}{0.6 \cdot 0.5 + 0.9 \cdot 0.5}$$

$$= 0.4$$
(19)

As in 3.2, we can also estimate the probability from 3.4 by sampling the model:

We see that this is in agreement with the analytical result from 3.4.

## Question 4: Implement Intervention in Pyro

## 4.1

We can implement the model from Question 3 in Pyro as follows:

def intervention():

```
[
            [
                .60, \# P(C = 'on' | A = 'on', B = 'on')
                .40 # P(C = 'off' | A = 'on', B = 'on')
            ],
                .01, \# P(C = 'on' | A = 'on', B = 'off')
                .99 # P(C = 'off' | A = 'on', B = 'off')
            ]
        ],
        .90, # P(C = 'on' | A = 'off', B = 'on')
                .10 # P(C = 'off' | A = 'off', B = 'on')
            ],
                .10, \# P(C = 'on' \mid A = 'off', B = 'off')
                .90 # P(C = 'off' | A = 'off', B = 'off')
            ]
        ]
    ])
    A = pyro.sample('A', dist.Categorical(probs = prob_A))
    B = pyro.sample('B', dist.Categorical(probs = prob_B[A]))
    C = pyro.sample('C', dist.Categorical(probs = prob_C[A][B]))
    return C
4.2
We now compute the conditional probability P(A = \text{on}|B = \text{on}, C = \text{on}) from
3.1 and 3.2, using Pyro:
# Create the conditional distribution
conditioned = pyro.condition(
    intervention,
    {'B': torch.tensor(0), 'C': torch.tensor(0)}
)
# Estimate the joint distribution with the Importance Sampling algorithm
posterior = pyro.infer.Importance(conditioned, num_samples = 10000).run()
# Get the marginal distribution from A
marginal = pyro.infer.EmpiricalMarginal(posterior, 'A')
# Generate samples from the marginal distribution and record how many
```

```
# of them are 'on'
samples = [marginal() for _ in range(10000)]
ons = [sample for sample in samples if sample == torch.tensor(0)]
From samples and ons we can then find the conditional probability:
>>> len(ons) / len(samples)
0.742
4.3
Lastly, we use Pyro to also compute the interventional distribution P(A =
\operatorname{on}|\operatorname{do}(B=\operatorname{on}), C=\operatorname{on}):
# Intervene on B
intervened = pyro.do(
    intervention,
    {'B': torch.tensor(0)}
)
# Condition on C
conditioned = pyro.condition(
    intervened,
    {'C': torch.tensor(0)}
)
# Estimate the joint distribution with the Importance Sampling algorithm
posterior = pyro.infer.Importance(conditioned, num_samples = 10000).run()
# Get the marginal distribution from A
marginal = pyro.infer.EmpiricalMarginal(posterior, 'A')
# Generate samples from the marginal distribution and record how many
# of them are 'on'
samples = [marginal() for _ in range(10000)]
ons = [sample for sample in samples if sample == torch.tensor(0)]
From samples and ons we can then find the conditional probability:
>>> len(ons) / len(samples)
0.4051
```