Murtaza Khuzema Basuwala

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Experience

10.2020 - Present OBO Bettermann Group

Industrial Engineer

- **Objectives:** Industry 4.0, Predictive Maintenance, Data Visualization and Exploration, Machine Learning, Deep Learning, AI.
- Tools: ViewSystems, Python, Schaefler Smart Utility, OPC-UA Interface.

10.2019 - 09.2020 Student Research Assistant at Fachhochschule Südwestfalen Soest, Germany

- Objectives:
 - Design and test reinforcement learning, deep learning, and machine learning algorithms.
 - Worked with the company Bültmann GmbH, to analyse their data and improve their production using machine learning.
- Tools and Libraries: Python, Pandas, Pytorch, Numpy, Matplotlib, Seaborn, Scikit-Learn, etc.

07.2017 - 08.2017 Intern at Ashok Leyland Ltd (R&D Centre), Chennai, India

- Objectives:
 - A four-wheeler assembly was designed for a heavy vehicle to withstand the weight of the engine, radiator, transmission, and exhaust system.
 - Run the vibration analysis of the assembly to analyse the frequency of vibration based on real world simulation.
- Tools and Libraries: CATIA, Enovia

Education

04.2018 - 09.2020 Master of Science in Systems Engineering and Engineering Management

(CGPA-1,6)

Fachhochschule Südwestfalen, Soest, Germany

Focus areas: Machine Learning, Deep Learning, Reinforcement Learning, Advanced Production Engineering, Modelling and Simulation of Mechanical Systems.

Other areas: International Project Management, Integrated Management and Business & Engineering.

08.2013 - 05.2017 Bachelor's in Mechanical Engineering (CGPA - 1,8)

Sri Sairam Engineering College, India

Focus areas: Machine design, Production Engineering, Kinematics and Dynamics of Machines, Operations Research.

Master Thesis

12.2019 - 09.2020

Coordination of two Universal Robot (UR5) in ROS/Gazebo with Reinforcement Learning algorithm - Proximal Policy Optimization (PPO) - Grade - (CGPA - 1,0)

Fachhochschule Südwestfalen, Soest, Germany

- Objectives:

Coordination of two UR5 robots with Robotiq 85 grippers to reach a common target position using reinforcement learning, so that one robot can transfer an object to another.

- Developing robot environment for training the RL agent.
- Training a UR5 robot with Robotiq 85 gripper to reach random targets using reinforcement learning, and then testing it additionally to reach new targets.
- Coordination of two UR5 robots with Robotiq 85 grippers to reach a common target position using reinforcement learning, so that one robot can transfer an object to another.
- Tools and libraries: Python, PyTorch, ROS/Gazebo

Projects

10.2020 - 11.2020

Identifying Pneumothorax Disease using UNet - CNN (Deep Learning)

- A UNet was developed using Convolution Neural Networks to learn the chest X-ray images provided by the Society for Imaging and Informatics in Medicine (SIIM).
- The X-ray images were pre-processed using image augmentation libraries and then given as input to the model.
- Tools and libraries: Python, Pandas, PyTorch, Scikit-Learn, Matplotlib, Numpy, Seaborn, Albumentations

09.2015 – 03.2018 Controlling a mobile robot (Turtlebot3) in ROS to reach random target position using Reinforcement Learning

- The mobile robot learns to reach a random target position using various reinforcement learning algorithms such as Q-Learning, Actor-Critic, and Proximal Policy Optimization (PPO).
- If the mobile robot is trained on sufficiently random targets, it generalizes to reach new targets on which it has never been trained on.
- Tools and libraries: Python, PyTorch, ROS/Gazebo, Matplotlib, Numpy

09.2015 - 03.2018 Motion Control of a Peristaltic Sorting Machine (PSM) using Reinforcement Learning

- To develop a reinforcement learning agent for the actuator of the PSM machine to reach random parcel position in the most efficient way.
- Advantage Actor.Critic (A2C) was used as the RL agent for the PSM environment.
- Tools and libraries: Python, PyTorch, Numpy, Matplotlib

09.2015 - 03.2018 Non-liner controller for a Bioreactor System (Advanced Control Technology)

- To develop and design a linear and a non-linear controller to control the non-linearity of the bioreactor system.
- Tools and libraries: Matlab/Simulink

Certifications

- 1. Deep Learning Specialization, deeplerning.ai, Coursera Focus Area: Improving Deep Neural Networks: Hyperparameter tuning, Regularization and Optimization, Neural Networks and Deep Learning, Structuring Machine Learning Projects, Sequence Models, Convolution Neural Networks.
- 2. Reinforcement Learning Specialization, *Alberta Machine Intelligence Institute, Coursera*
 - **Focus Area:** Sample-based Learning Methods, Prediction and Control with Function Approximation.
- 3. Deep Neural Networks with Pytorch, IBM Coursera
- 4. Python Programmer, Datacamp
- 5. Python Bootcamp: Python 3, *Udemy*
- 6. Using OpenAI with ROS, The Construct
- 7. TF Ros 101, The Construct
- 8. ROS Control 101, The Construct

Skills

- **Skillset:** Machine Learning, Deep Learning, Deep Reinforcement Learning, Robotic Programming, Advanced Production Engineering.
- **Programming Languages:** Python, MATLAB & Simulink, basics of SQL and R.
- **Python Libraries**: PyTorch, TensorFlow, Keras, Gym, Scikit-Learn, XGBoost, Numpy, Pandas, Plotly, Seaborn, Matplotlib, Flask, Streamlit, Rospy.
- Tools and Technologies: ROS, Microsoft VS Code, Spyder, PyCharm, Sublime Text, Jupyter Notebook, GitHub, AutoCAD, Catia V5, MS Office, MS Project, MS Publisher.
- Operating Systems: Windows, MacOS, Linux (Ubuntu).
- Interpersonal Skills: Public speaking, Team player, Adaptability.
- Languages: English, German (B1), Hindi, Tamil, Guajarati, Urdu, Arabic (writing & reading).

Hobbies

Painting, Cricket, Reading, Running.