



Murtaza Khuzema Basuwala

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Experience

10.2020-Present

OBO Bettermann GmbH

Industrial Engineer

- Implementation of Industry 4.0 techniques for smart factory.
- Data visualization and exploration
- Designing machine learning models for predictive maintenance.

10.2019-09.2020

Research assistant at the Fachhochschule Südwestfalen Soest, Germany

- Designing and testing reinforcement learning and deep learning algorithms.
 - Data exploration and visualization using Pandas, Matplotlib, etc.
 - Worked with the company Bültmann GmbH, where the task was to analyse their production dataset using pandas and use machine learning algorithms to find ways to improve the production efficiency.
- **Software used: ROS/Gazebo, Python | Deep Learning Framework: Pytorch**

07.2017-08.2017

Internship – Ashok Leyland Ltd (Research & Development Centre), Chennai, Indian

- A frame assembly with CATIA was designed for a four-wheeled heavy vehicle to withstand the weight of the engine, radiator, transmission, and exhaust system.
- Run the vibration analysis of the assembly with ENOVIA to analyze the frequency of vibration based on real world simulation.

Education

04.2018 – 09.2020

Fachhochschule Südwestfalen, Soest, Germany

M.Sc. Systems Engineering & Engineering Management

Focus Area: Advanced Control Technology, Systems Engineering (Machine Learning and Reinforcement Learning), Advanced Production Engineering, International Project Management.

2013 – 2017

Sri Sairam Engineering College, Chennai Tamilnadu, India

Bachelor's in Mechanical Engineering (CGPA - 1.8)

Master Thesis:

Jul 2019-Sept 2020

Fachhochschule Südwestfalen, Soest, Deutschland

Coordination of two Universal Robots (UR5) in ROS/Gazebo with reinforcement learning (artificial intelligence) algorithms like Proximal Policy Optimization (PPO)

- **Task 1:** Training a UR5 robot with Robotiq 85 gripper to reach random targets using reinforcement learning, and then testing it additionally to reach new targets.
- **Task 2:** Coordination of two UR5 robots with Robotiq 85 grippers to reach a common target position using reinforcement learning, so that one robot can transfer an object to another.
- Once the robots are trained properly, they can easily be generalized to similar tasks.

	<ul style="list-style-type: none"> • State-of-the-art Proximal Policy Optimization (PPO) is used as the RL agent for the robot environment. • Software used: ROS/Gazebo, Python Deep Learning Framework: Pytorch <p>Grade – 1.0</p>
Projects:	
10.2020-11.2020	<p><i>Identifying Pneumothorax Disease UNet</i></p> <ul style="list-style-type: none"> • A UNet was developed using Convolution Neural Networks to learn the chest X-ray images provided by the Society for Imaging and Informatics in Medicine (SIIM). • The X-ray images were pre-processed using image augmentation libraries and then given as input to the model. • Software used: Python Frameworks: Pytorch, Albumentations
02.2019-03.2019	<p><i>Controlling a mobile robot (Turtlebot3) in ROS to reach random target positions using Reinforcement Learning (AI)</i></p> <ul style="list-style-type: none"> • The mobile robot learns to reach a random target position using various Reinforcement Learning algorithms such as Q-Learning, Actor-Critic, and Proximal Policy Optimization (PPO). If the mobile robot is trained to sufficiently random targets, it generalizes to reach new targets on which it is never trained to reach on. • Software used: ROS/Gazebo, Python Deep Learning Framework: Pytorch
11.2018-02.2019	<p><i>Motion control of the Peristaltic Sorting Machine (PSM) using Reinforcement Learning (AI)</i></p> <ul style="list-style-type: none"> • To develop a Reinforcement Learning agent for the actuator of the PSM machine to reach random parcel positions in the most efficient way. • Advantage Actor-Critic (A2C) was used as the RL agent for the PSM Environment • Software used: Python Deep Learning Framework: Pytorch, Keras
10.2019-03.2020	<p><i>Design a robot station using AutoCAD Inventor to assemble a UR5 robot</i></p> <ul style="list-style-type: none"> • Design of a robot station for my laboratory in the Fachhochschule Südwestfalen for the assembly of a UR5 robot for research purposes.
04.2018-08.2018	<p><i>Project plan for the construction of a Power Plant (international project management)</i></p> <ul style="list-style-type: none"> • To develop a project plan for the construction of a power plant (international project management) • Software used: MS Project
04.2018-08.2018	<p><i>Non-linear controller for a Bioreactor System (Advanced Control Technology)</i></p> <ul style="list-style-type: none"> • To develop and design a linear and non-linear controller that can control the non-linearity of a bioreactor system. • Software used: Matlab/Simulink
04.2018-08.2018	<p><i>Modelling and Simulation of Mechanical Systems</i></p> <ul style="list-style-type: none"> • Estimation and calculation of pressure loads, thermal loads and other factors for a thin concrete fin with a variable rectangular cross-section. • Software used: Matlab/Simulink
07.2016-04.2017	<p><i>Bachelor Thesis - Prosthetic-Attachment in Four Wheelers for People with Disabled Legs</i></p> <ul style="list-style-type: none"> • Design and manufacture of a prosthetic attachment in a four-wheeler that can help people with disabled legs to ride a four-wheeler. • Software used: SolidWorks, ANSYS, CATIA

Accomplishments:

<i>Jun 2020</i>	<ul style="list-style-type: none">• Improving Deep Neural Networks: Hyperparameter tuning, Regularization and Optimization (Coursera)
<i>Jun 2020</i>	<ul style="list-style-type: none">• Structuring Machine Learning Projects (Coursera)
<i>May 2020</i>	<ul style="list-style-type: none">• Deep Neural Networks with Pytorch from IBM (Coursera)
<i>Feb-May 2020</i>	<ul style="list-style-type: none">• Reinforcement Learning Specialization from University of Alberta and Alberta Machine Learning Intelligence Institute (Coursera)
<i>Apr-May 2020</i>	<ul style="list-style-type: none">• Neural Networks and Deep Learning offered by deeplearning.ai (Coursera)
<i>Feb-March 2020</i>	<ul style="list-style-type: none">• Python Programmer (DataCamp)
<i>Feb-March 2020</i>	<ul style="list-style-type: none">• Python Bootcamp: Python3(Udemy)
<i>Dec 2019</i>	<ul style="list-style-type: none">• Using OpenAI with ROS (The Construct)
<i>Dec 2019</i>	<ul style="list-style-type: none">• TF ROS 101 (The Construct)
<i>Dec 2019</i>	<ul style="list-style-type: none">• ROS Control 101(The Construct)
<i>Jan 2017</i>	<ul style="list-style-type: none">• Professional in Product Design – CADD Centre Chennai

Skills:

<i>Technical</i>	<ul style="list-style-type: none">• ROS (Robotic Operating System) (Good)• Python (Good)• Spyder (Good)• Jupyter Notebook (Good)• MATLAB/Simulink (Good)• AutoCad Inventor (Good)• CATIA (Good)• MS Project (Good)• MS Office (Good)
<i>Organisational</i>	<ul style="list-style-type: none">• Loyal• Optimistic• Creative
<i>Languages</i>	<ul style="list-style-type: none">• English (C1)• German (Goethe, B1)• Hindi, Gujrathi, Urdu, Tamil (Native)