

## Piecewise $n$ -th order spline approximation

- let  $x_0, \dots, x_N$  be a sequence of  $N + 1$  data points with (numerical) derivatives  $x_0^{(k)}, \dots, x_N^{(k)}$  up to the  $k$ -th order; assumption is that these data points are results of an underlying function  $f(t)$  at instants  $t_0, \dots, t_N$  equidistantly distributed with  $h = \Delta t$
- sought are  $N$  piecewise spline representations  $p_0(t), \dots, p_{N-1}(t)$  of  $f(t)$
- let  $p_s(t)$  be the sought  $n$ -th order spline representation of the segment  $[t_s, t_{s+1}]$

$$p_s(t) = \sum_{i=0}^n a_{s,i} T_s^i(t), \quad T_s(t) = \frac{t - t_s}{h} \Rightarrow p_s^{(k)}(t) = \frac{1}{h^k} \sum_{i=k}^n \frac{i!}{(i-k)!} a_{s,i} T_s^{i-k}(t) \quad (1)$$

- in particular, the derivatives at joint knots read

$$p_s^{(k)}(t_s) = \frac{k!}{h^k} a_{s,k}, \quad p_s^{(k)}(t_{s+1}) = \frac{1}{h^k} \sum_{i=k}^n \frac{i!}{(i-k)!} a_{s,i} \quad (2)$$

## Data approximation constraints

- interpolation of given data points up to the  $m$ -th order derivative yields  $2(m + 1)$  constraints

$$p_s^{(0)}(t_s) = x_s^{(0)}, \quad p_s^{(0)}(t_{s+1}) = x_{s+1}^{(0)}, \quad \dots, \quad p_s^{(m)}(t_s) = x_s^{(m)}, \quad p_s^{(m)}(t_{s+1}) = x_{s+1}^{(m)} \quad (3)$$

- expressed in matrix notation

$$\begin{pmatrix} x_s^{(0)} \\ \vdots \\ x_s^{(m)} \\ x_{s+1}^{(0)} \\ \vdots \\ x_{s+1}^{(m)} \end{pmatrix} = \begin{pmatrix} \frac{0!}{h^0} & 0 & 0 & \dots & 0 \\ & \ddots & \vdots & & \vdots \\ 0 & \frac{m!}{h^m} & 0 & \dots & 0 \\ \frac{0!}{0!h^0} & \dots & \frac{m!}{m!h^0} & \frac{(m+1)!}{(m+1)!h^0} & \dots & \frac{n!}{n!h^0} \\ & \ddots & \vdots & \vdots & & \vdots \\ 0 & \frac{m!}{0!h^m} & \frac{(m+1)!}{1!h^m} & \dots & \frac{n!}{(n-m)!h^m} \end{pmatrix} \begin{pmatrix} a_{s,0} \\ \vdots \\ a_{s,n} \end{pmatrix} \quad (4)$$

## Spline continuity constraints

- continuity up to the  $k$ -th order derivative gives  $k$  constraints ( $k = 0$  is trivially fulfilled)

$$p_s^{(1)}(t_s) = p_{s-1}^{(1)}(t_s), \quad \dots, \quad p_s^{(k)}(t_s) = p_{s-1}^{(k)}(t_s) \quad (5)$$

- expressed in matrix notation

$$\begin{pmatrix} \frac{1}{h^1} \sum_{i=1}^n \frac{i!}{(i-1)!} a_{s-1,i} \\ \vdots \\ \frac{1}{h^k} \sum_{i=k}^n \frac{i!}{(i-k)!} a_{s-1,i} \end{pmatrix} = \begin{pmatrix} \frac{1!}{h^1} & 0 & 0 & \dots & 0 \\ & \ddots & \vdots & & \vdots \\ 0 & \frac{k!}{h^k} & 0 & \dots & 0 \end{pmatrix} \begin{pmatrix} a_{s,0} \\ \vdots \\ a_{s,n} \end{pmatrix} \quad (6)$$