

**PRECAT**

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## Introduction:

- What is data structure & its classification?
- What is an algorithm?

## Array:

- **Searching Algorithms:** Linear Search & Binary Search
- **Sorting Algorithms:**
  - Selection Sort, Bubble Sort & Insertion Sort: Algorithms & Implementation
  - Merge Sort & Quick Sort: Only Algorithms.
- Limitations of an Array data structure



## Linked List:

- Concept & Definition
- Implementation of Singly Linear Linked List Operations: Addition & Deletion.
- Concepts:
  - Singly Circular Linked List
  - Doubly Linear Linked List
  - Doubly Circular Linked List.
- Difference between Array and Linked List



## **Stack:**

- Concept & Definition
- Implementation of Stack by using an array

## **+ Stack Application Algorithms:**

- Conversion of infix expression into its equivalent postfix expression.
- Conversion of infix expression into its equivalent prefix expression.
- Conversion of prefix expression into its equivalent postfix expression.
- Evaluation of postfix expression



## # Queue:

- Concept & Definition
- Types of Queue
- Implementation of Linear Queue & Circular Queue

**Tree terminologies**

**Graph terminologies**



## Q. What is Data Structure?

Data Structure is a way to store data elements into the memory (i.e. into the main memory) in an organized manner so that operations like addition, deletion, traversal, searching, sorting etc... can be performed on it efficiently.



# Data Structures: Introduction

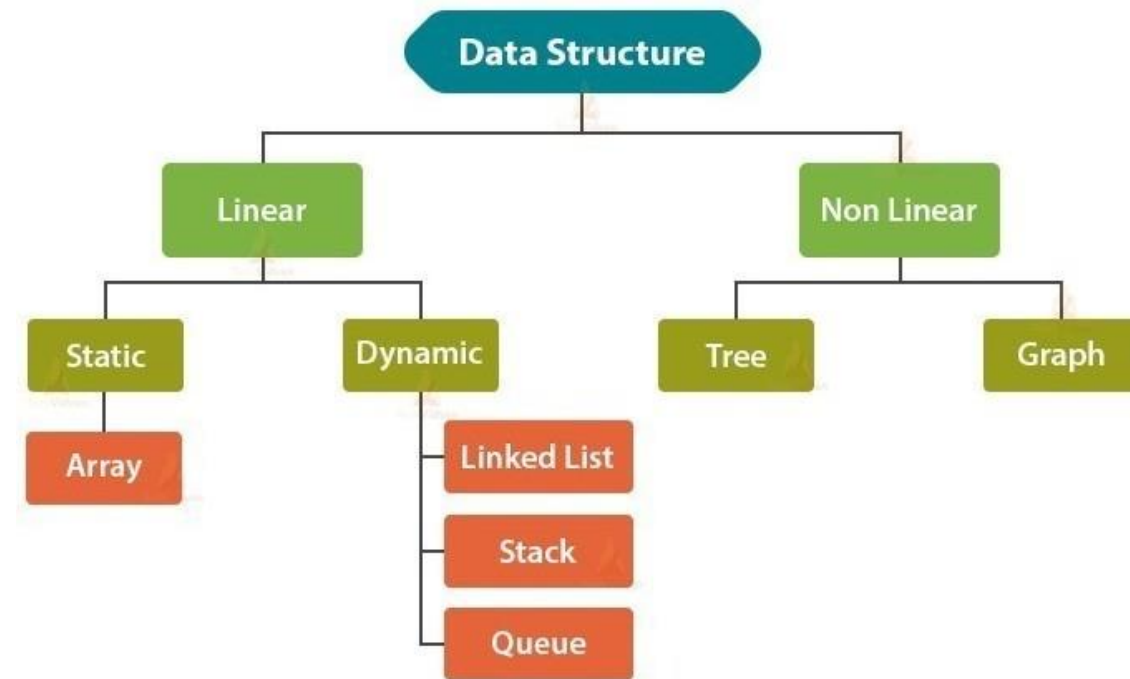
Two types of **Data Structures** are there:

**1. Linear/Basic:** data elements gets stored into the memory in a linear manner and hence can be accessed linearly.

- Array
- Structure & Union
- Class
- Linked List
- Stack
- Queue

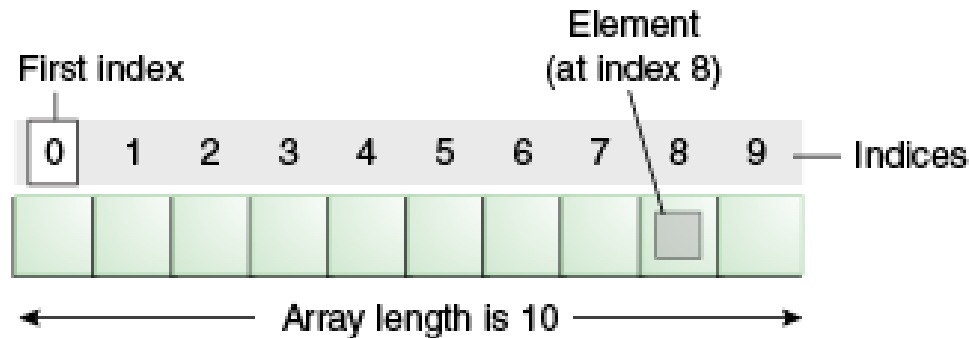
**2.Non-linear/Advanced:** data elements gets stored into the memory in a non-linear manner and hence can be accessed non-linearly.

- Tree (Hierarchical)
- Graph



# Data Structures: Introduction

**Array:** It is a collection of logically related similar type of elements in which data elements gets stored into the memory at contiguous locations.



**Structure:** It is a collection of logically related similar and dissimilar type of elements gets stored into the memory collectively (as a single entity/record).

Size of structure is sum of size of all its members.

**Union:** Union is same like structure, except, memory allocation i.e. size of union is the size of max size member defined in it and that memory gets shared among all its members for effective memory utilization (can be used in a special case only).





# Data Structures: Introduction

## Q. What is a Program?

- A program is a set of instructions written in any programming language (like C, C++, Java, Python, Assembly etc...) given to the machine to do specific task.
- **An algorithm is a template whereas a program is an implementation of an algorithm.**

## Q. What is an Algorithm?

- An algorithm is a finite set of instructions written in human understandable language (like english), if followed, accomplishes a given task.
- An algorithm is a finite set of instructions written in human understandable language (like english) **with some programming constraints**, if followed, accomplishes a given task, such an algorithm also called as **pseudocode**.



# Data Structures: Introduction

**Example: An algorithm to do sum of all array elements**

**Algorithm ArraySum(A, n)//whereas A is an array of size n**

```
{  
    sum=0;//initially sum is 0  
    for( index = 1 ; index <= size ; index++ ) {  
        sum += A[ index ];//add each array element into the sum  
    }  
    return sum;  
}
```

- In this algorithm, **traversal/scanning** operation is applied on an array. Initially sum is 0, each array element gets added into to the sum by traversing array sequentially from the first element till last element and final result is returned as an output.



# Data Structures: Introduction

- **Analysis of an algorithm** is a work of determining how much **time** i.e. computer time and **space** i.e. computer memory it needs to run to completion.

- There are two measures of an analysis of an algorithms:

**1.Time Complexity:** It is the amount of time i.e. computer time required for an algorithm to run to completion.

**2.Space Complexity:** It is the amount of space i.e. computer memory required for an algorithm to run to completion.

**Asymptotic Analysis:** It is a **mathematical** way to calculate time complexity and space complexity of an algorithm **without implementing it in any programming language**.

- In this type of analysis, analysis can be done on the basis of **basic operation** in that algorithm.  
e.g. in searching & sorting algorithms comparison is the basic operation and hence analysis gets done on the basis of no. of comparisons, in addition of matrices algorithms addition is the basic operation and hence on the basis of addition operation.



# Data Structures: Introduction

**"Best case time complexity"**: if an algo takes min amount of time to complete its execution then it is referred as best case time complexity.

**"Worst case time complexity"**: if an algo takes max amount of time to complete its execution then it is referred as worst case time complexity.

**"Average case time complexity"**: if an algo takes neither min nor max amount of time to complete its execution then it is referred as an average case time complexity.

**"Asympotic Notations"**:

**1.Big Omega ( $\Omega$ )**:this notation is used to denote best case time complexity

**2. Big Oh ( $O$ )**: this notation is used to denote worst case time complexity

**3.Big Theta ( $\theta$ )**:this notation is used to denote an average case time complexity



# Data Structures: Searching Algorithms

## 1. Linear Search/Sequential Search:

- In this algorithm, key element gets compared sequentially with each array element by traversing it from first element till either match is found or maximum till the last element.

### Algorithm LinearSearch(A, size, key)

```
{  
    for( index = 1 ; index <= size ; index++ ){ if(  
        key == A[ index ] )  
        return true;  
    }  
    return false;  
}
```

arr	10	20	30	40	50	60	70	80
	0	1	2	3	4	5	6	7



# Data Structures: Searching Algorithms

**Best Case:** If key is found at very first position in only 1 no. of comparison then it is considered as a best case and running time of an algorithm in this case is  $O(1) = \Omega(1)$

**Worst Case:** If either key is found at last position or key does not exist, maximum  $n$  no. of comparisons takes place, it is considered as a worst case and running time of an algorithm in this case is  $O(n) = \Omega(n)$

**Average Case:** If key is found at any in between position it is considered as an average case and running time of an algorithm in this case is  $O(n/2) = \Theta(n)$



# Data Structures: Searching Algorithms

## 2. Binary Search/Logarithmic Search:

- This algorithm follows **divide-and-conquer** approach.
- To apply binary search on an array prerequisite is that array elements must be in a sorted manner.
- In this algorithm, in first iteration, by means of calculating mid position big size array gets divided into two subarray's, **left subarray** and **right subarray**, key element gets compared with element which is at mid position, if key is found at mid position in very first iteration in only 1 no. of comparison, then it is considered as a best case and in this case an algorithm takes  $O(1)$  time.
- If key is not found in the first iteration then either it will get searched into left subarray or into the right subarray by applying same logic repeatedly till either key is not found or till max the size of any subarray is valid i.e. size of subarray is greater or equal to 1.



# Data Structures: Searching Algorithms

```
Algorithm BinarySearch(A, n, key) //A is an array of size "n", and key to be search
{
    left = 1;
    right = n;

    while( left <= right )
    {
        //calculate mid position
        mid = (left+right)/2;
        //compare key with an ele which is at mid position
        if( key == A[ mid ] )//if found return true
            return true;

        //if key is less than mid position element
        if( key < A[ mid ] )
        {
            right = mid-1; //search key only in a left subarray
        }
        else //if key is greater than mid position element
        {
            left = mid+1; //search key only in a right subarray
        }
    } //repeat the above steps either key is not found or max any subarray is valid
    return false;
}
```





# Data Structures: Searching Algorithms

**Best Case:** if the key is found in very first iteration at mid position in only 1 no. of comparison it is considered as a best case and running time of an algorithm in this case is  $O(1) = \Omega(1)$ .

**Worst Case:** if either key is not found or key is found at leaf position it is considered as a worst case and running time of an algorithm in this case is  $O(\log n) = O(\log n)$ .

**Average Case:** if key is not found in the first iteration and it is found at non-leaf position it is considered as an average case and running time of an algorithm in this case is  $O(\log n) = \Theta(\log n)$ .



# Data Structures: Sorting Algorithms

## 1. Selection Sort:

-In this algorithm, in first iteration, first position gets selected and element which is at selected position gets compared with all its next position elements, if selected position element found greater than any other position element then swapping takes place and in first iteration smallest element gets settled at first position.

-In the second iteration, second position gets selected and element which is at selected position gets compared with all its next position elements, if selected position element found greater than any other position element then swapping takes place and in second iteration second smallest element gets settled at second position, and so on in maximum **(n-1)** no. of iterations all array elements gets arranged in a sorted manner.



# Data Structures: Sorting Algorithms

Iteration-1	Iteration-2	Iteration-3	Iteration-4	Iteration-5
<div><div>302060501040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>103060502040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102060503040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102030605040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102030406050</div><div>012345</div><div>sel_pospos</div></div>
<div><div>203060501040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>103060502040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102050603040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102030506040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102030405060</div><div>012345</div><div></div></div>
<div><div>203060501040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>103060502040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102030605040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102030406050</div><div>012345</div><div></div></div>	
<div><div>203060501040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102060503040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102030605040</div><div>012345</div><div></div></div>		
<div><div>103060502040</div><div>012345</div><div>sel_pospos</div></div>	<div><div>102060503040</div><div>012345</div><div></div></div>			
<div><div>103060502040</div><div>012345</div><div></div></div>				



# Data Structures: Sorting Algorithms

**Best Case** :  $\Omega(n^2)$   
**Worst Case** :  $O(n^2)$   
**Average Case** :  $\Theta(n^2)$

## 2. Bubble Sort:

- In this algorithm, in every iteration elements which are at two consecutive positions gets compared, if they are already in order then no need of swapping between them, but if they are not in order i.e. if prev position element is greater than its next position element then swapping takes place, and by this logic in first iteration largest element gets settled at last position, in second iteration second largest element gets settled at second last position and so on, in max **(n-1)** no. of iterations all elements gets arranged in a sorted manner.





# Data Structures: Sorting Algorithms

Iteration-1	Iteration-2	Iteration-3	Iteration-4	Iteration-5
<div><div>302060501040</div><div>012345</div><div>pospos+1</div></div>	<div><div>203050104060</div><div>012345</div><div>pospos+1</div></div>	<div><div>203010405060</div><div>012345</div><div>pospos+1</div></div>	<div><div>201030405060</div><div>012345</div><div>pospos+1</div></div>	<div><div>102030405060</div><div>012345</div><div>pospos+1</div></div>
<div><div>203060501040</div><div>012345</div><div>pospos+1</div></div>	<div><div>203050104060</div><div>012345</div><div>pospos+1</div></div>	<div><div>203010405060</div><div>012345</div><div>pospos+1</div></div>	<div><div>102030405060</div><div>012345</div><div>pospos+1</div></div>	<div><div>102030405060</div><div>012345</div><div></div></div>
<div><div>203060501040</div><div>012345</div><div>pospos+1</div></div>	<div><div>203050104060</div><div>012345</div><div>pospos+1</div></div>	<div><div>201030405060</div><div>012345</div><div>pospos+1</div></div>	<div><div>102030405060</div><div>012345</div><div></div></div>	
<div><div>203050601040</div><div>012345</div><div>pospos+1</div></div>	<div><div>203010504060</div><div>012345</div><div>pospos+1</div></div>	<div><div>201030405060</div><div>012345</div><div></div></div>		
<div><div>203050106040</div><div>012345</div><div>pospos+1</div></div>	<div><div>203010405060</div><div>012345</div><div></div></div>			
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<div><div>203050104060</div><div>012345</div><div></div></div>				



# Data Structures: Sorting Algorithms

**Best Case** :  $\Omega(n)$  – if array elements are already arranged in a sorted manner.

**Worst Case** :  $O(n^2)$

**Average Case** :  $\theta(n^2)$

## 3. Insertion Sort:

-In this algorithm, in every iteration one element gets selected as a **key element** and key element gets inserted into an array at its appropriate position towards its left hand side elements in a such a way that elements which are at left side are arranged in a sorted manner, and so on, in max **(n-1)** no. of iterations all array elements gets arranged in a sorted manner.

- This algorithm works efficiently for already sorted input sequence by design and hence running time of an algorithm is  $O(n)$  and it is considered as a best case.



# Data Structures: Sorting Algorithms

**Best Case** :  $\Omega(n)$  – if array elements are already arranged in a sorted manner.

**Worst Case** :  $O(n^2)$

**Average Case:**  $\Theta(n^2)$

- Insertion sort algorithm is an efficient algorithm for smaller input size array.

## 4. Merge Sort:

- This algorithm follows **divide-and-conquer** approach.

- In this algorithm, big size array is divided logically into smallest size (i.e. having size 1) subarrays, as if size of subarray is 1 it is sorted, after dividing array into sorted smallest size subarray's, subarrays gets merged into one array step by step in a sorted manner and finally all array elements gets arranged in a sorted manner.

- This algorithm works fine for **even** as well **odd** input size array.

- This algorithm takes extra space to sort array elements, and hence its space complexity is more.

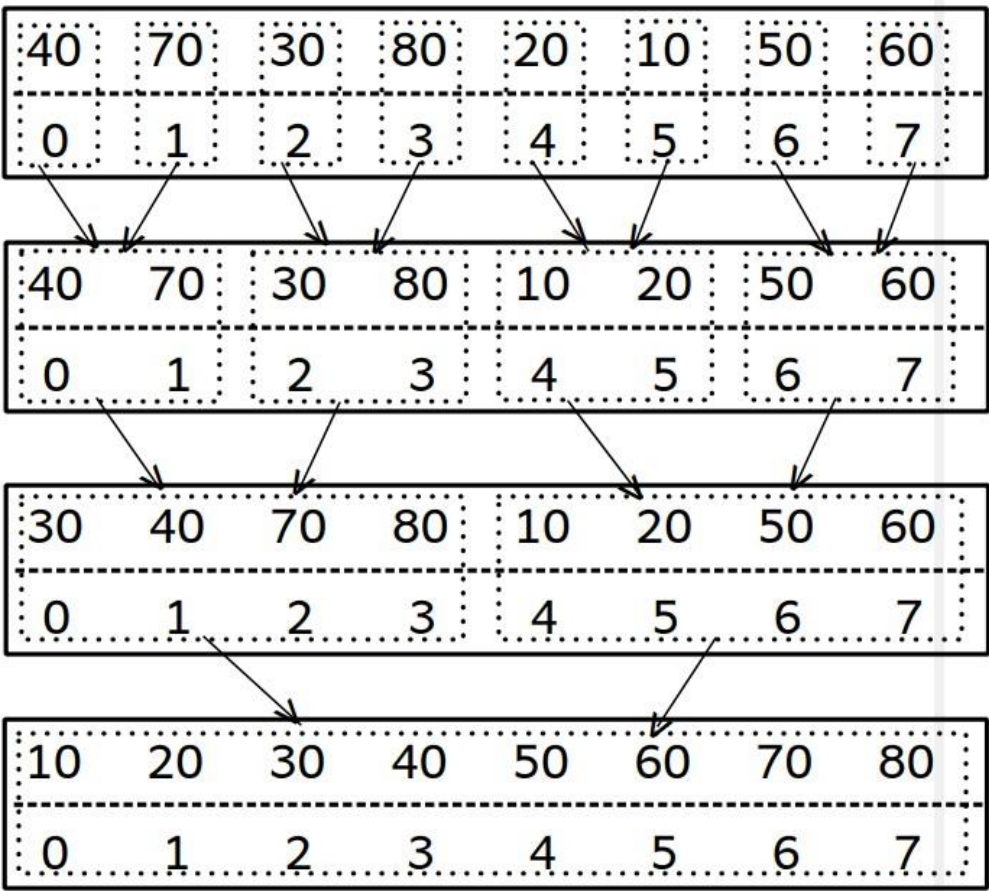
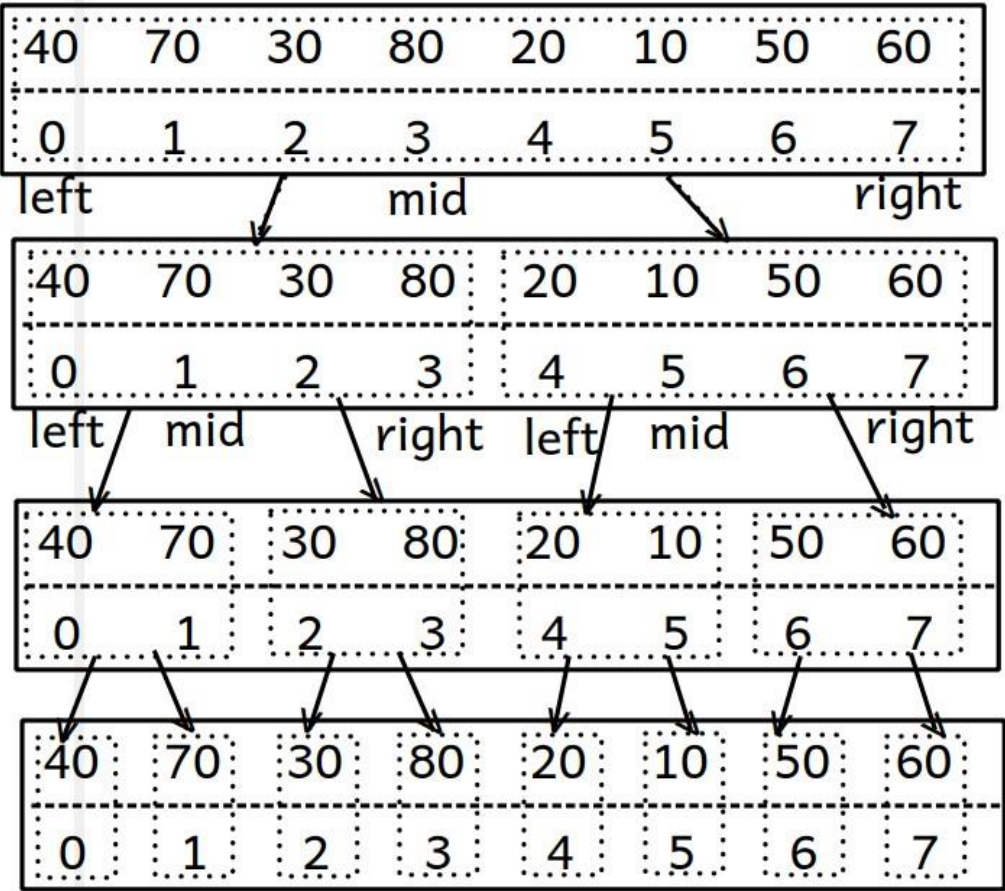


# Data Structures: Sorting Algorithms

## ## Merge Sort ##

Dividing big size array into smallest size subarrays

Merge already sorted arrays





# Data Structures: Sorting Algorithms

Best Case	: <del><math>\Omega(n \log n)</math></del>
Worst Case	: $O(n \log n)$
Average Case	: <del><math>\Theta(n \log n)</math></del>

## 5. Quick Sort:

- This algorithm follows **divide-and-conquer** approach.
- In this algorithm the basic logic is a **partitioning**.
- **Partitioning:** in partitioning, pivot element gets selected first (it may be either leftmost or rightmost or middle most element in an array), after selection of pivot element all the elements which are smaller than pivot gets arranged towards as its left as possible and elements which are greater than pivot gets arranged as its right as possible, and big size array is divided into two subarray's, so after first pass pivot element gets settled at its appropriate position, elements which are at left of pivot is referred as **left partition** and elements which are at its right referred as a **right partition**.



# Data Structures: Sorting Algorithms

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**Best Case** :  ~~$\Omega(n \log n)$~~   
**Worst Case** :  $O(n^2)$  – worst case rarely occurs  
**Average Case** :  ~~$\theta(n \log n)$~~

- Quick sort algorithm is an efficient sorting algorithm for larger input size array.



# Data Structures: Linked List

## - Limitations of an array data structure:

- 1.Array is static**, i.e. size of an array is fixed, its size cannot be either grow or shrink during runtime.
- 2.Addition and deletion operations on an array are not efficient as it takes  $O(n)$  time**, and hence to overcome these two limitations of an Array **Linked List** data structure has been designed.

**Linked List: It is a collection/list of logically related similar type of elements in which,**

**-an address of first element in a collection/list is stored into a pointer variable referred as a head pointer.**

**-each element contains data and an address of its next (as well as its previous element).**

**- An element in a Linked List is also called as a Node.**

**-Four types of linked lists are there: Singly Linear Linked List, Singly Circular Linked List, Doubly Linear Linked List and Doubly Circular Linked List.**



# Data Structures: Linked List

- Basically we can perform **addition, deletion, traversal** etc... operations on linked list data structure.
- We can add and delete node by three ways: we can add node into the linked list at last position, at first position and at any specific position, similarly we can delete node from linked list which is at first position, last position and at any specific position.

## 1. **Singly Linear Linked List:** It is a linked list in which

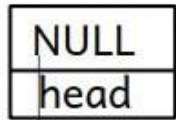
- head always contains an address of first element, if list is not empty.
- each node has two parts:
  - i. data part:** contains data of any primitive/non-primitive type.
  - ii. pointer part(next):** contains an address of its next element/node.
- last node points to NULL, i.e. next part of last node contains NULL.



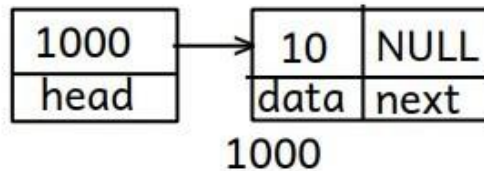
# Data Structures: Linked List

## SINGLY LINEAR LINKED LIST ##

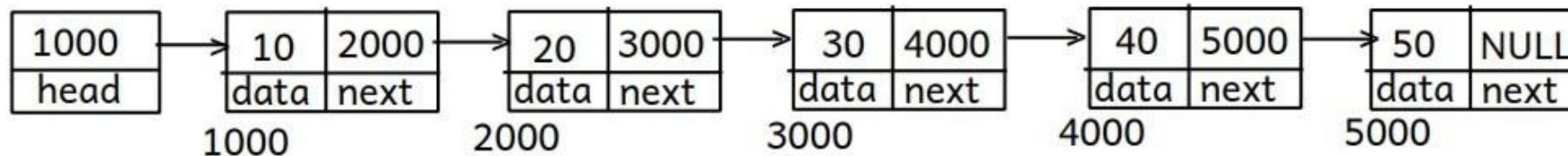
1) singly linear linked list --> list is empty



2) singly linear linked list --> list contains only one node



3) singly linear linked list --> list contains more than one nodes



# Data Structures: Linked List

## Limitations of Singly Linear Linked List:

- Add node at last position & delete node at last position operations are not efficient as it takes  $O(n)$  time.
- We can start traversal only from first node and can traverse the SLL only in a forward direction.
- Previous node of any node cannot be accessed from it.
- **Any node cannot be revisited** – to overcome this limitation Singly Circular Linked List has been designed.

## 2. Singly Circular Linked List: It is a linked list in which

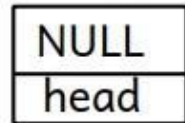
- head always contains an address of first element, if list is not empty.
- each node has two parts:
  - i. data part: contains data of any primitive/non-primitive type.
  - ii. pointer part(next): contains an address of its next element/node.
- last node points to first node, i.e. next part of last node contains an address of first node.



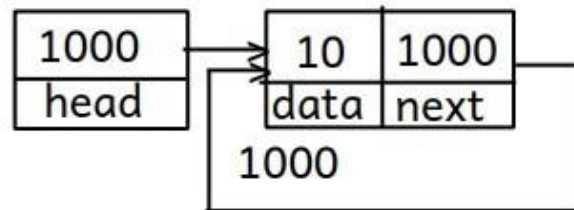
# Data Structures: Linked List

## SINGLY CIRCULAR LINKED LIST ##

1) singly circular linked list --> list is empty



2) singly circular linked list --> list contains only one node



3) singly circular linked list --> list contains more than one nodes

