

## EGE UNIVERSITY ELECTRICAL AND ELECTRONICS ENGINEERING

## CONTROL SYSTEMS 1 LAB-10

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16.06.2021	

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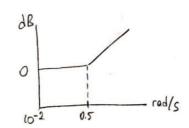
(5)

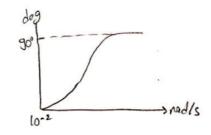
(50)

$$1- G(s) = \frac{2000(s+0.5)}{s(s+10)(s+50)}$$

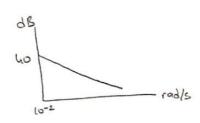
$$= \frac{2000.0.5}{10.50} \cdot \frac{(\frac{s}{0.5}+1)}{s(\frac{s}{10}+1)(\frac{s}{50}+1)} = 2 \cdot \frac{(\frac{s}{0.5}+1)}{s(\frac{s}{10}+1)(\frac{s}{50}+1)}$$

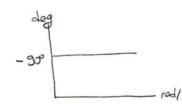
$$G(jw) = 2 \frac{\left(\frac{jw}{60.5} + 1\right)}{jw\left(\frac{jw}{60} + 1\right)\left(\frac{jw}{50} + 1\right)}$$





## 20 log L , ton-1 ( w ) -> 1 ju rain



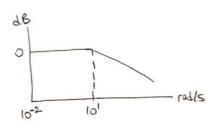


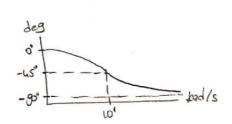
$$20\log 10^2 = 40dB$$
  
 $-4ar^{-1}(\frac{10^{-2}}{0}) = -90^\circ$ 

ee

ø

$$-ton^{-1}(\frac{\omega}{10}) = 0^{\circ}$$
  $\rightarrow$  Lüwik degerler icin  
 $-ton^{-1}(\frac{\omega}{10}) = -90^{\circ}$   $\rightarrow$  böyök degerler icin





## **MATLAB KODU**

```
clc;clear;close all;
%1.SORU
G1=tf(2,1);
bode (G1)
hold on
G2=tf([1/0.5 1],1);
bode (G2)
hold on
G3=tf(1,[1 0]);
bode (G3)
hold on
G4=tf(1,[1/10 1]);
bode (G4)
hold on
G5=tf(1,[1/50 1]);
bode (G5)
hold on
G=G1*G2*G3*G4*G5;
bode (G)
legend('G1','G2','G3','G4','G5','G')
%2.SORU
%K=0.1
%K=1
%K=2
K = 10
num=1;
den=conv(conv([1 1],[1 1]),[1 0]);
GG=tf(num, den);
figure(1)
rlocus(GG)
figure(2)
bode (K*GG)
grid on
```

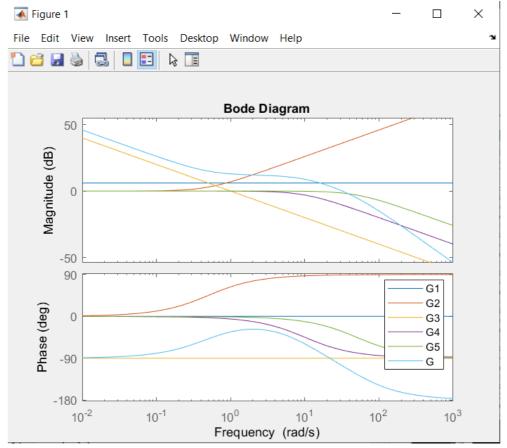


Figure 1 G1, G2, G3, G4, G5 ve G transfer fonksiyonları için bode grafiği

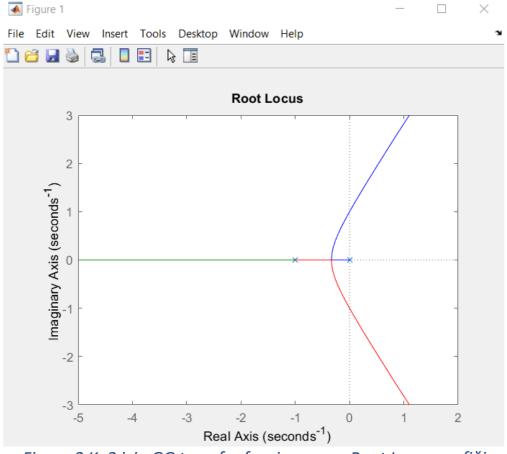


Figure 2 K=2 için GG transfer fonsiyonunun Root Locus grafiği

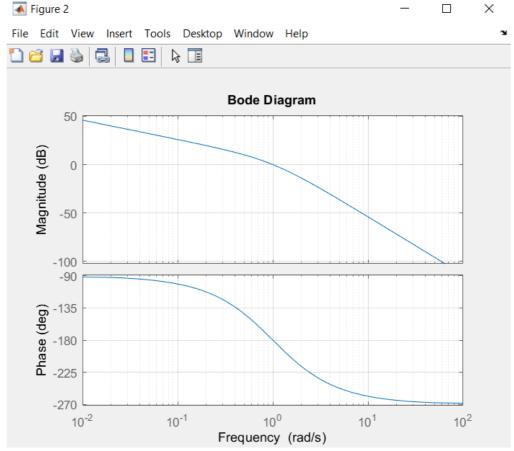


Figure 3 K=2 için GG transfer fonsiyonunun bode grafiği

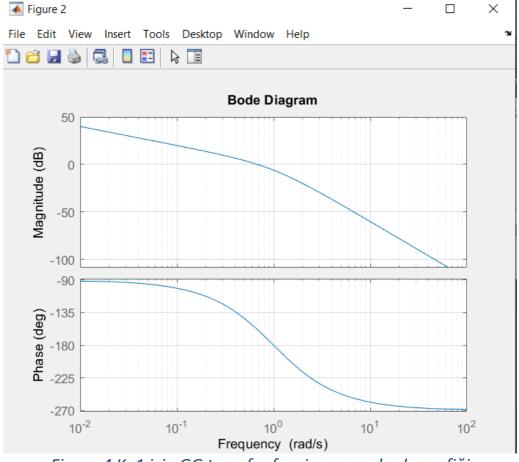


Figure 4 K=1 için GG transfer fonsiyonunun bode grafiği

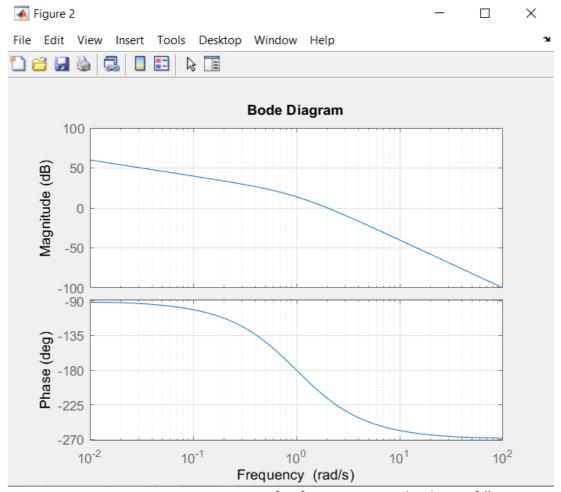


Figure 5 K=10 için GG transfer fonsiyonunun bode grafiği