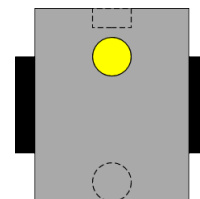
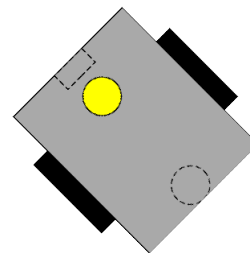


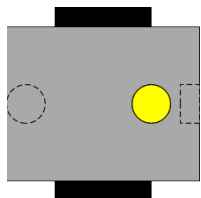
angle = 0



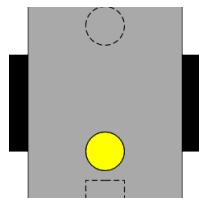
angle = 45



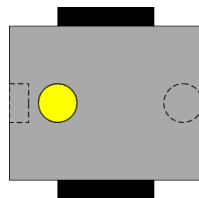
angle = 270



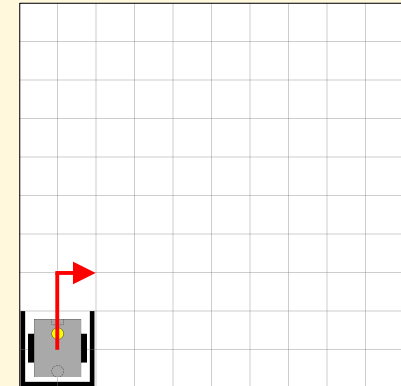
angle = 180



angle = 90



### Example



```
selectMap("map1");
robotStartPosition(100, 100, 0);
robotConnect();
```

```
forward();
forward();
right();
forward();
```

```
robotDisconnect();
```

### Hint

Go forward twice. Then turn right. Then forward once.

