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# Kalman Filter Theory and Applications Equation Drilldown

[https://github.com/musicarroll/kalman\\_course](https://github.com/musicarroll/kalman_course)

Michael L. Carroll

June 17, 2023

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# Part I

## The Five Basic Kalman Equations Topics

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### Topics

- Understanding the Equations: Heuristic Introduction

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- **Equation Drilldown: Taking the Equations Apart**

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- **Examples: Resistor Revisited**

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- The Five Kalman Filter Equations
- **Examples: Resistor Revisited**
- Exercises

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  - The Five Kalman Filter Equations
  - **Examples: Resistor Revisited**
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# Scalar Example: Resistor Revisited

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- The Kalman gain equation

$$K(k) = P^{-}(k) H(k)^{\top} [H(k) P^{-}(k) H(k)^{\top} + R(k)]^{-1}$$

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$\hat{x}^+(k) = \hat{x}^-(k) + K(k) [z(k) - H(k)\hat{x}^-(k)]$  becomes

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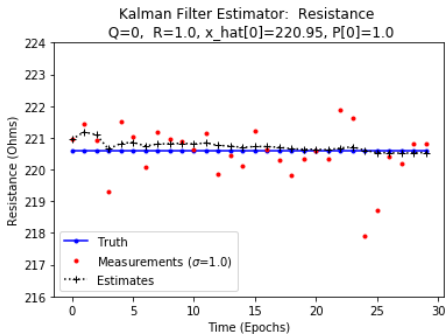
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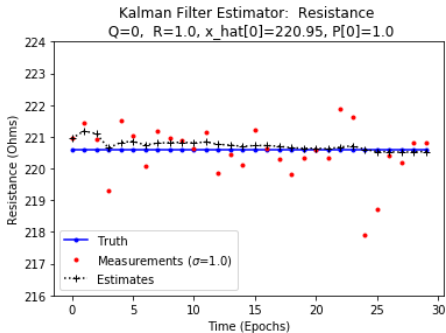
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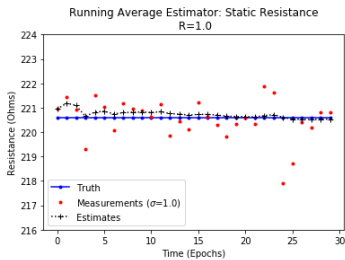


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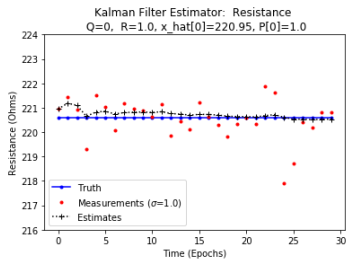


# Static, Scalar Example: Resistor Revisited: Comparing KF and Running Average

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(a) Simple Running Average Estimator

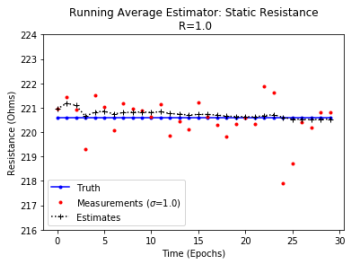


(b) Kalman Estimator

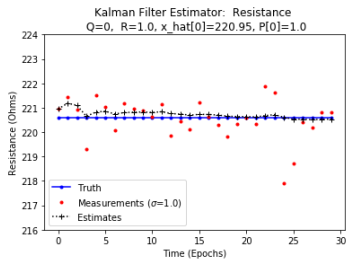
Figure: Comparing Running Average and Kalman Estimators



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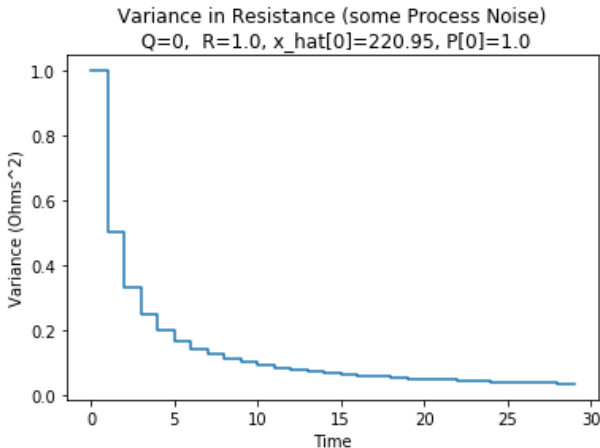
Figure: Comparing Running Average and Kalman Estimators

# Kalman Sawtooth Plots

With constant dynamics ( $\Phi = I$ ) and no process noise ( $Q = 0$ )  $\rightarrow$  no upticks:

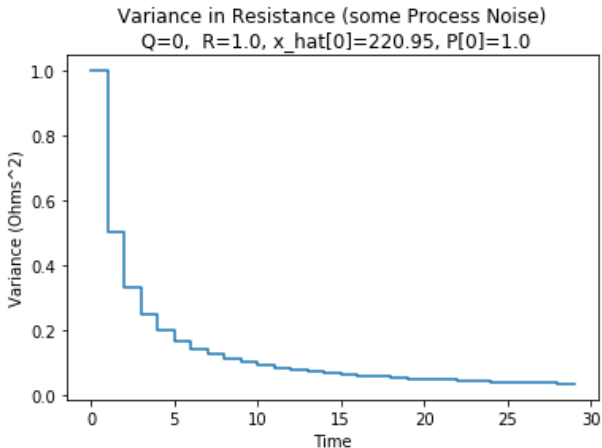
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