
Kalman Filter Theory and Applications Equation Drilldown

https://github.com/musicarroll/kalman_course

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Part I

The Five Basic Kalman Equations Topics

Part I

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Topics

- Understanding the Equations: Heuristic Introduction

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- Understanding the Equations: Heuristic Introduction
- **Equation Drilldown: Taking the Equations Apart**

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- State Space Concepts

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- Exercises

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Constant Velocity Motion

Non-accelerated, kinematic motion in 1 dimension

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- Thus, $\Phi = \begin{bmatrix} 1 & \Delta t \\ 0 & 1 \end{bmatrix}$, $\Delta t = t_k - t_{k-1}$ (assumed constant),
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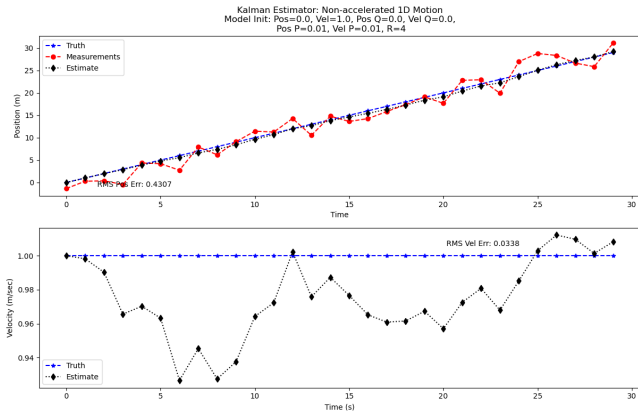
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Constant Velocity Motion

Filter Performance (without Process Noise)

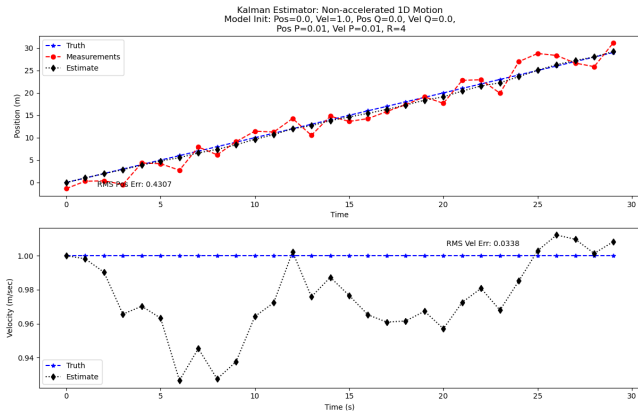
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Filter Sawtooth Plot

Note uptick in uncertainty even without process noise, due to $\Phi \neq I$ in covariance extrapolation; causes increase in uncertainty:

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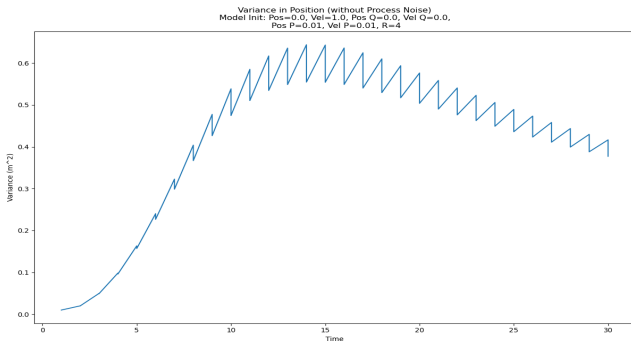
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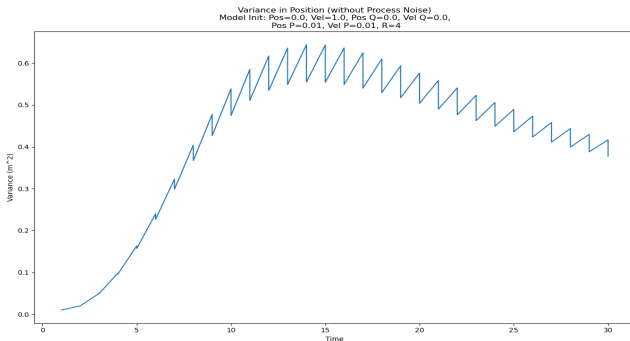


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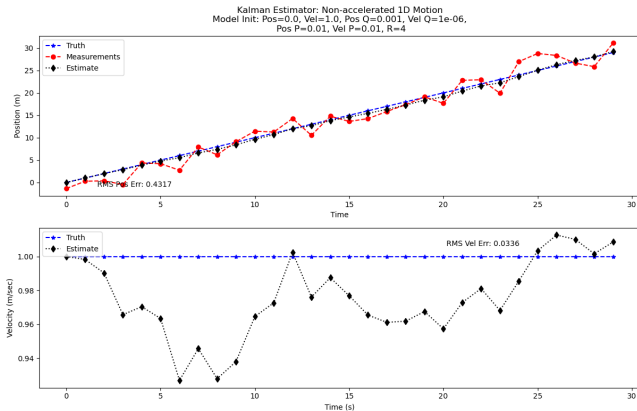


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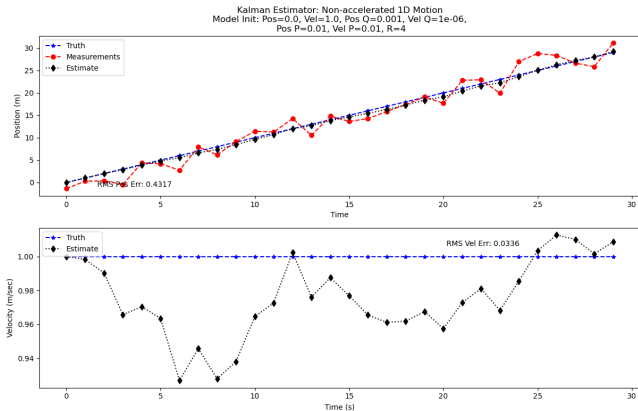
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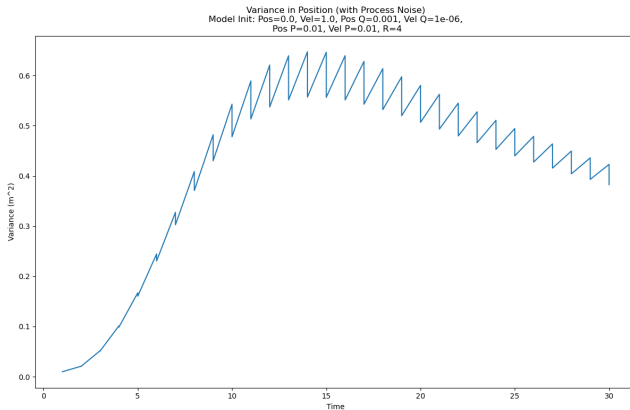


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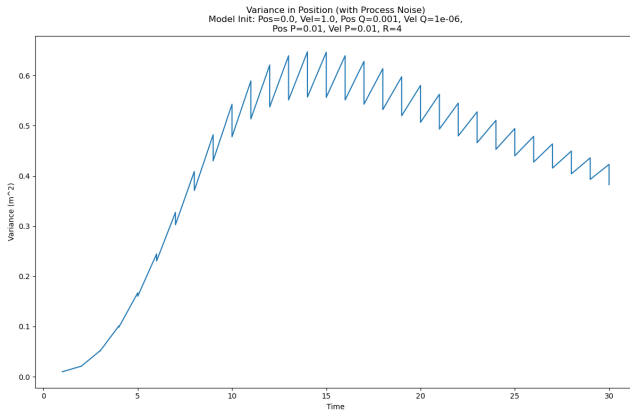
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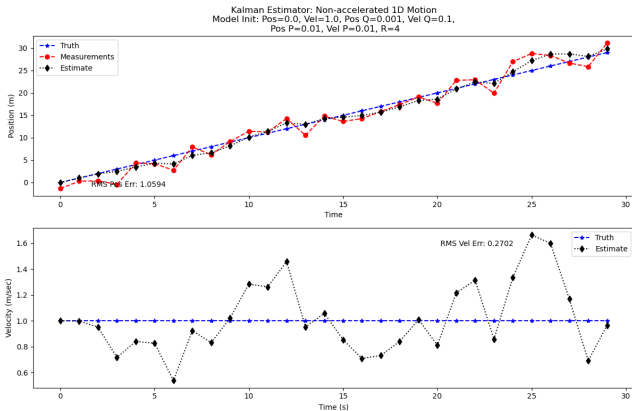


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Filter Performance (30 samples; large Process Noise)

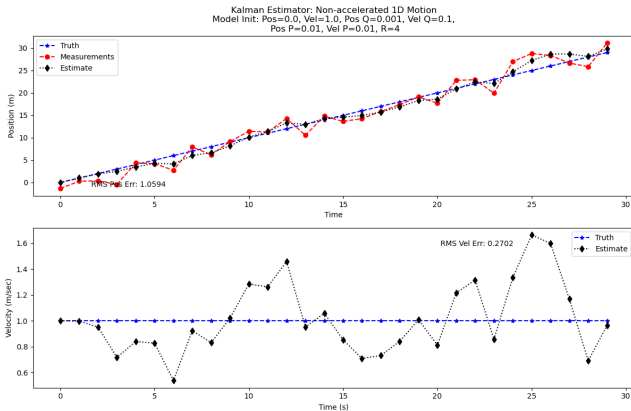
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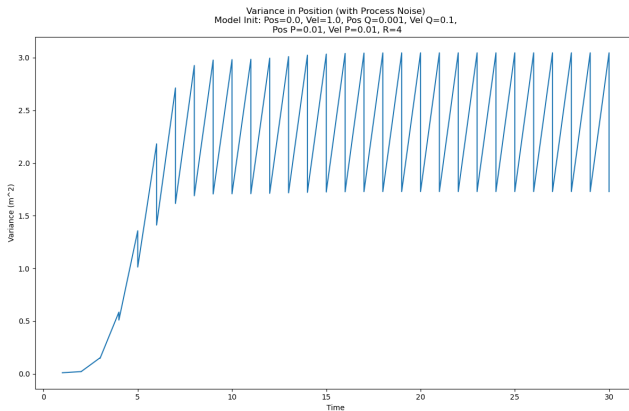


Constant Velocity Motion

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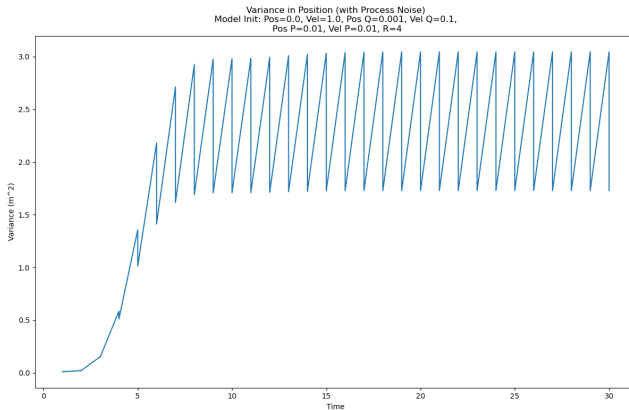
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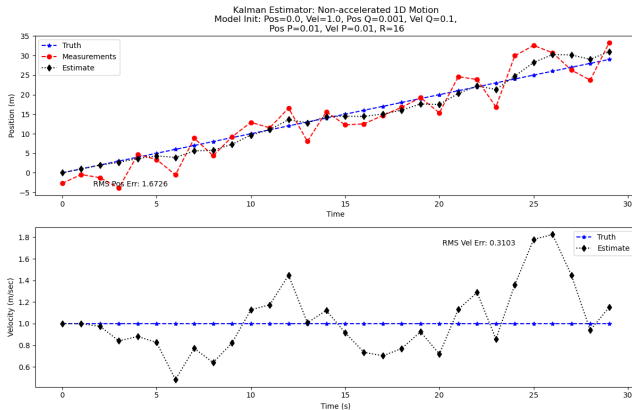
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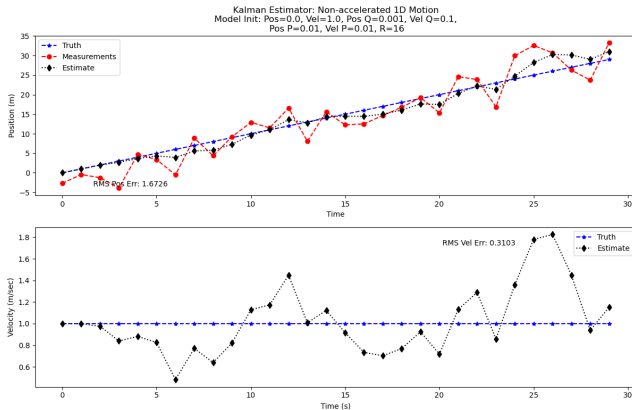
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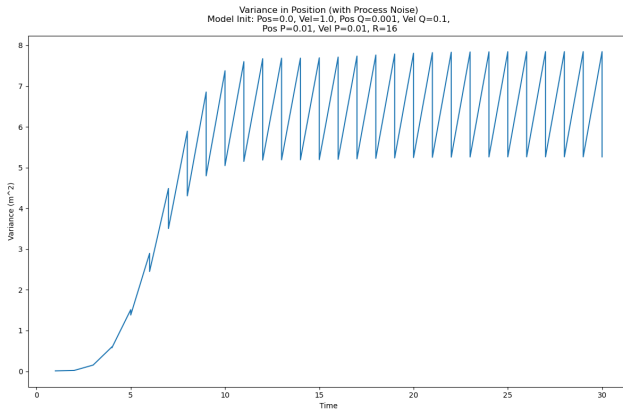
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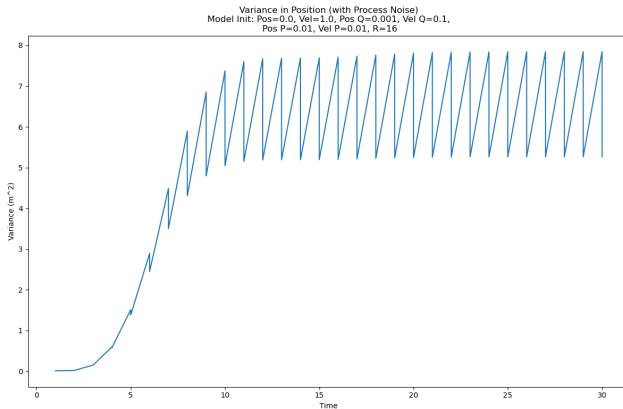
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