# ASL\_Project

May 11, 2022

# 1 Computer Vision for reading American Sign Language (ASL)

```
[]: from google.colab import drive drive.mount('/content/drive')
```

# 1.1 Importing libraries

```
[]: import matplotlib.pyplot as plt
     import seaborn as sns
     import numpy as np
     import torch
     from tqdm import tqdm
     import torch.nn as nn
     from torch import optim
     import torch.nn.functional as F
     import torchvision.datasets as datasets
     from torchvision.io import read_image
     from torchvision import transforms
     from torchvision import models
     from torch.utils.data import Dataset, DataLoader, u
     ⇒SubsetRandomSampler,random_split
     import glob
     from mpl_toolkits.axes_grid1 import ImageGrid
     from skimage.transform import resize
```

```
[]: train_path='/content/drive/MyDrive/ASL_Project/dataset/asl_alphabet_train/

→asl_alphabet_train'

test_path='/content/drive/MyDrive/ASL_Project/dataset/ASL_TEST/

→asl_alphabet_test'

my_test_path='/content/drive/MyDrive/ASL_Project/My_Test_ASL'
```

# 1.1.1 Viewing the images from the training set

### 1.1.2 Viewing the images from self-generated test data

## 1.2 Transformations

### Transformations on the Train dataset

```
[]: train_transforms = transforms.Compose([transforms.Resize((96,96)), transforms.RandomHorizontalFlip(p=0.3), transforms.ToTensor()])
```

### Transformations on the Test dataset

```
[]: test_transforms = transforms.Compose([transforms.Resize((96,96)), transforms.ToTensor()])
```

```
[]: # performing resize and horizontal flip transformations on the train data set
data= datasets.ImageFolder(train_path, transform=train_transforms)
```

```
[]: # performing resize transformations on the two test data sets

test_data = datasets.ImageFolder(test_path, transform=test_transforms)

my_test_data=datasets.ImageFolder(my_test_path, transform=test_transforms)
```

#### 1.2.1 Mapping of labels

```
[]: class_labels=data.class_to_idx
    class_labels = {value:key for key, value in class_labels.items()}
    print(class_labels)
    print(f"Class to index mapping: {data.class_to_idx}")
```

# 1.3 Splitting of train and validation data set

```
[]: train_data_,val_data_= random_split(data, (69600, 17400), generator=torch.Generator().manual_seed(25)) #splits the dataset randomly
```

```
[]: print('Total images in Train data set:', len(train_data_))
print('Total images in Validation data set:', len(val_data_))
print('Total images in Test data set:', len(test_data))
```

#### 1.4 Loading images to data loaders

# 1.5 Checking if GPU is available

```
[]: # use GPU to accelerate the training if available
device = "cuda" if torch.cuda.is_available() else "cpu"
print("Currently used device:", device)
```

### 1.6 Common functions for generating plots

```
[]: def plot_accuracy(train_accuracy, validation_accuracy):
         Function to plot the accuracy for Training and Validation sets
         Parameters:
         train_accuracy: list of accuracy for training set
         validation_accuracy:list of accuracy for validation set
         Return:
         Plot of Train and Validation Accuracy
         111
          # accuracy plots
         plt.figure(figsize=(8,8))
         plt.plot(train_accuracy, color='green', label='Train Accuracy')# plot train_
      \rightarrowaccuracy
         plt.plot(validation_accuracy, color='orange', label='Validataion_⊔
      →Accuracy')# plot validation accuracy
         plt.xlabel('Epochs')
         plt.ylabel('Accuracy')
         plt.legend()
         plt.show()
```

```
[]: def plot_loss(train_loss, validation_loss):
         Function to plot the accuracy for Training and Validation sets
         Parameters:
         train_loss: list of loss for training set
         validation_loss:list of loss for validation set
         Return:
         Plot of Train and Validation Loss Curves
         111
         plt.figure(figsize=(8,8))
         plt.plot(train_loss, color='blue', label='Train Loss')# plot train loss
         plt.plot(validation_loss, color='red', label='Validataion Loss')# plot_
      \rightarrow validation loss
         plt.xlabel('Epochs')
         plt.ylabel('Loss')
         plt.legend()
         plt.show()
```

# 1.7 Common function for performing training on the model

```
[]: def train_model(model, dataloader,optimizer,criterion):
         Function to train the model on training set of images
         Parameters:
         model: the trained model
         dataloader: validation dataset
         optimizer: optimizer with a learning rate
         criterion: loss criterion
         Return:
         train_loss: train loss
         train_accuracy: train accuracy
         print('Training the model')
         model.train()
         batch_loss, batch_accuracy = [], []
         for k, (data, target) in tqdm(enumerate(dataloader), __
      →total=int(len(train_loader)/train_loader.batch_size)):
             data, target = data.to(device), target.to(device)
             outputs = model(data)
             loss = criterion(outputs, target)
             acc = (outputs.argmax(1) == target).type(torch.float)
             acc = torch.mean(acc)
             optimizer.zero_grad()
             loss.backward()
             optimizer.step()
             # Append to lists
             batch_loss.append(loss.item())
             batch_accuracy.append(acc.item())
         train_loss = sum(batch_loss)/len(batch_loss)
         train_accuracy = sum(batch_accuracy)/len(batch_accuracy)
         print(f"Train Loss: {train_loss:.4f}, Train Accuracy: {train_accuracy:.2f}")
         return train_loss, train_accuracy
```

# 1.8 Common function for performing validation on the model

```
[]: def validate_model(model, dataloader, criterion):
         Function to check performance on the validation dataset
         Parameters:
         model: the trained model
         dataloader: validation dataset
         criterion: loss criterion
         Return:
         val_loss: validation loss
         val_accuracy: validation accuracy
         111
         print('Validating the model')
         model.eval()
         with torch.no_grad():
             for data,target in dataloader:
                 data, target = data.to(device), target.to(device)
                 outputs = model(data)
                 val_loss = criterion(outputs, target)
                 val_accuracy = (outputs.argmax(1) == target).type(torch.float).
      →mean()
             print(f'Validation Loss: {val_loss.item():.4f}, Validation Accuracy: u
      →{val_accuracy.item():.2f}')
             return val_loss.item(), val_accuracy.item()
```

# 1.9 Common function for testing models

```
[]: def test_model(model,test_loader,x):

'''

Function to test model's performance on the test set. The function receives

two types of test_loaders.

One is the test set provided with the Kaggle dataset and the second one is

the dataset created by us.

Parameters:

model: the model to be used for testing

test_loader: contains the test set images

x: takes the value of 0 or 1. 0 indicates the test set sent to the function

was the Kaggle
```

```
test data. 1 indicates the test set was the one created by us.
Return:
Prints accuracy on the test dataset
true_labels=[] #correct labels
pred_labels=[] #labels which would be predicted my model
s=""
with torch.no_grad():
    total = 0
    correct = 0
    for image, labels in test_loader:
        model.eval()
        image=image.to(device)
        labels=labels.to(device)
        output=model(image)
        predictions=torch.max(output,1)[1]
        correct+=(predictions==labels).sum().cpu().numpy()
        total+=len(labels)
        labels=labels.cpu().detach().numpy()
        predictions=predictions.cpu().detach().numpy()
        true_labels.extend(labels)
        pred_labels.extend(predictions)
    acc = correct*100/total
    if(x==0):
        s='Kaggle'
    else:
        s='self generated'
    print('Accuracy on '+s+' test dataset: %f' %(acc))
```

# 1.9.1 Common Optimizer and Criterion functions

```
criterion: loss criterion

///

# optimizer

optimizer = torch.optim.Adam(model.parameters(), lr=learning_rate,
weight_decay = 0.0001)

# loss function

criterion = nn.CrossEntropyLoss()

return optimizer,criterion
```

# 1.10 Deep Neural Network

#### 1.10.1 Defining the NN class

```
[]: class NeuralNetwork(nn.Module):
         Defining a 4-layer Deep NN with Kaiming normal initialization and ReLU_{\sqcup}
      \hookrightarrow activation functions
         111
         def __init__(self):
             super(NeuralNetwork, self).__init__()
             self.flatten = nn.Flatten()
             #linear layers
             self.l1 = nn.Linear(3*96*96, 10000)# input image size is 96x96 and due_
      \rightarrow to RGB image there are 3 channels
             self.12 = nn.Linear(10000, 2000)
             self.13 = nn.Linear(2000, 250)
             self.14 = nn.Linear(250, 29)
             nn.init.kaiming_normal_(self.l1.weight, mode='fan_in',
                                       nonlinearity='relu')
             nn.init.kaiming_normal_(self.12.weight, mode='fan_in',
                                       nonlinearity='relu')
             nn.init.kaiming_normal_(self.13.weight, mode='fan_in',
                                       nonlinearity='relu')
             nn.init.kaiming_normal_(self.14.weight, mode='fan_in',
                                       nonlinearity='relu')
         def forward(self, x):
             #combining the entire model
             x = self.flatten(x)
             x = F.relu(self.l1(x))
             x = F.relu(self.12(x))
             x = F.relu(self.13(x))
```

```
output = self.14(x)

return output

nn_model = NeuralNetwork()
print('Layers of the updated pre-trained Neural Network model')
```

```
[]: nn_model = NeuralNetwork()
     print('Layers of the updated pre-trained Neural Network model')
     print(nn_model)
     # trainable parameters
     total_trainable_parameters = sum(para.numel() for para in nn_model.parameters()u
     →if para.requires_grad)
     print(f"{total_trainable_parameters:,} number of training parameters.")
[]: def neural_net_model():
         Function to train the model as well as check the performance on the \sqcup
      →validation dataset. Performs early stopping when the
         validation loss exceeds the previous loss twice.
         num_epoch=40 #setting total number of epochs to be 40
         prev_loss=100 #initial loss value for early stopping
         max_penalty=3
         best_acc=0
         parameter_learning_rate=[0.001,0.0001,0.00001] # different values for_
      \hookrightarrow learning rate
         for i,learning_rate in enumerate(parameter_learning_rate): #Looping through_
      → the learning rates
             train_loss , train_accuracy = [], []
             val_loss , val_accuracy = [], []
             counter=0
             model = NeuralNetwork().to(device)
             optimizer,criterion = model_optimizer_criterion(model, learning_rate)
             print("Training model on Learning Rate=",learning_rate)
             #model will train for a particular learning rate
             for epoch in range(num_epoch):# Looping through the epochs
                 print(f"Epoch number {epoch+1} of {num_epoch}")
                 #training the model
                 train_epoch_loss, train_epoch_accuracy = train_model(model,
                                                               train_loader,
                                                               optimizer,
                                                               criterion)
                 #checking the performance on validation
                 val_epoch_loss, val_epoch_accuracy = validate_model(model,
```

```
val_loader,
                                                          criterion)
           #append the loss and accuracy for every epoch for both train and
\rightarrow validation data set
           train_loss.append(train_epoch_loss)
           train accuracy.append(train epoch accuracy)
           val_loss.append(val_epoch_loss)
           val_accuracy.append(val_epoch_accuracy)
           # Early Stopping
           if val_epoch_loss>prev_loss: # checking if validation loss for the_
→current epoch is greater than the previous loss
               counter+=1
               if counter>= max_penalty: # if the validation loss exceeds the_
→previous loss twice begin the early stopping process
                   print('Early Stopping Initiated')
                   break
           else:
               counter = 0
           prev_loss = val_epoch_loss # update the threshold loss to the__
→previous validation loss of the epoch
       #saving the best performing model
       if(val_epoch_accuracy>best_acc):
           best_acc=val_epoch_accuracy
           best_model=model
       #saving the model for a particular learning rate
       torch.save(model.state_dict(),'/content/drive/MyDrive/ASL Project/
savedmodels/'+'model_neural_network'+str(learning_rate)+'.pth' )
       #plotting the accuracy and loss curves
       print('Plotting Validation and Training Accuracy Curves for Learning,
→Rate of ', learning_rate)
       plot_accuracy(train_accuracy, val_accuracy)
      print('Plotting Validation and Training Loss Curves for Learning Rate⊔
→of ', learning rate)
       plot_loss(train_loss,val_loss)
   return best_model
```

#### 1.10.2 Training the Neural Network model

```
[]: trained_neural_net_model=neural_net_model()
```

#### 1.10.3 Testing the Neural Network model

Testing the model on given test dataset

```
[]: test_model(trained_neural_net_model,test_loader,0)
```

Testing the model on our test dataset

```
[]: test_model(trained_neural_net_model,my_test_loader,1)
```

# 1.11 Convolutional Neural Network(CNN)

```
[]: class CustomCNN(nn.Module):
         ''' Creating a CNN model from scratch'''
         def __init__(self):
             super(CustomCNN, self).__init__()
             self.conv1 = nn.Conv2d(3, 8, 5)
             self.conv2 = nn.Conv2d(8, 16, 5)
             self.conv3 = nn.Conv2d(16, 32, 3)
             self.conv4 = nn.Conv2d(32, 64, 5)
             self.fc1 = nn.Linear(64, 128)
             self.fc2 = nn.Linear(128, 29) #output 29 classes
             self.pool = nn.MaxPool2d(2, 2)
         def forward(self, x):
             x = self.pool(F.relu(self.conv1(x)))
             x = self.pool(F.relu(self.conv2(x)))
             x = self.pool(F.relu(self.conv3(x)))
             x = self.pool(F.relu(self.conv4(x)))
             bs, _{,} _{,} _{-} = x.shape
             x = F.adaptive_avg_pool2d(x, 1).reshape(bs, -1)
             x = F.relu(self.fc1(x))
             x = self.fc2(x)
             return x
```

```
[]: model_cnn = CustomCNN().to(device)
    print(model_cnn)
# total parameters and trainable parameters
total_params = sum(p.numel() for p in model_cnn.parameters())
print(f"{total_params:,} total parameters.")
total_trainable_params = sum(
    p.numel() for p in model_cnn.parameters() if p.requires_grad)
print(f"{total_trainable_params:,} training parameters.")
```

```
[]: def cnn_optimizer_criterion(model,learning_rate,wt_decay):
        Function to define the optimizer and criterion function for the CNN model
        Parameters:
        learning_rate: learning rate for optimizer
        Return:
        optimizer: optimizer with a learning rate
        criterion: loss criterion
        111
        #optimizer
        optimizer = torch.optim.Adam(model.parameters(),__
     →lr=learning_rate, weight_decay=wt_decay)
        # loss function
        criterion = nn.CrossEntropyLoss()
        return optimizer, criterion
[]: def my_cnn_model():
        →validation dataset using CNN Architecture. Performs early stopping when the
        validation loss exceeds the previous loss thrice.
        num epoch=40 #setting total number of epochs to be 40
        prev_loss=100 #initial loss value for early stopping
        max_penalty=3
        best acc=0
        param_learning_rate=[0.1,0.01,0.001]
        param_weight_decay=[0.001,0.0001]
        # Hyper parameter tuning begins
        for i,learning_rate in enumerate(param_learning_rate):#Looping through_
     → different learning rates values
            for j,wt decay in enumerate(param weight decay): #Looping through
     → different weight decay values
                model = CustomCNN().to(device)
     →optimizer,criterion=cnn_optimizer_criterion(model,learning_rate,wt_decay)
                train loss, train accuracy = [], []
                val_loss , val_accuracy = [], []
                for epoch in range(num_epoch):
                    print(f"Epoch {epoch+1} of {num_epoch}")
                    #training the model
                    train_epoch_loss, train_epoch_accuracy = train_model(model,
                                                            train_loader,
                                                            optimizer,
                                                            criterion)
```

```
#checking the performance on validation
               val_epoch_loss, val_epoch_accuracy = validate_model(model,
                                                         val_loader,
                                                         criterion)
               # Early Stopping
               if val_epoch_loss>prev_loss: # checking if validation loss for_
→ the current epoch is greater than the previous loss
                   counter+=1
                   if counter>= max_penalty: # if the validation loss exceeds⊔
→ the previous loss twice begin the early stopping process
                       print('Early Stopping Initiated')
                       break
               else:
                   counter = 0
               prev_loss = val_epoch_loss # update the threshold loss to the_
→previous validation loss of the epoch
           #saving the best performing model
           if(val_epoch_accuracy>best_acc):
               best_acc=val_epoch_accuracy
               best model=model
           #saving the model for a particular learning rate
           torch.save(model.state_dict(), '/content/drive/MyDrive/ASL_Project/
savedmodels/'+'model_cnn_lr'+str(learning_rate)+'_wt_decay_'+str(wt_decay)+'.
→pth' )
           *plotting the accuracy and loss curves
           print('Plotting Validation and Training Accuracy Curves for
→Learning Rate of ', learning_rate,' and Weight Decay of ',wt_decay)
           plot accuracy(train accuracy, val accuracy)
           print('Plotting Validation and Training Loss Curves for Learning
→Rate of ', learning_rate,' and Weight Decay of ',wt_decay)
           plot_loss(train_loss,val_loss)
   return best_model
```

#### 1.11.1 Training the CNN model

```
[]: trained_cnn_model=my_cnn_model()
```

#### 1.11.2 Testing the CNN model

Testing the model on given test dataset

```
[]: test_model(trained_cnn_model,test_loader,0)
```

Testing the model on our test dataset

```
[ ]: test_model(trained_cnn_model,my_test_loader,1)
```

#### 1.12 Resnet-50

1.12.1 Updating the fully connected layer of the pretrained Mobile Net V2 model

```
[]: def Resnet_50():
         '''Using the concept of transfer learning on the pre-trained Resnet-50<sub>\square</sub>
      →model and retraining the fully connected layer '''
         model = models.resnet50(pretrained=True)
         for param in model.parameters():
                                                              #freezing the pretrained_
      \rightarrow layers
             param.requires_grad = False
         model.fc = nn.Sequential(nn.Linear(2048, 1000), #redefining the fully_
      →connected classifier layer
                                    nn.ReLU(),
                                    nn.Dropout(0.3),
                                    nn.Linear(1000, 500),
                                    nn.ReLU(),
                                    nn.Dropout(0.2),
                                    nn.Linear(500, 29))
         return model
```

```
[]: def resnet_50_model():
         Function to train the model as well as check the performance on the \sqcup
      ⇒validation dataset. Performs early stopping when the
         validation loss exceeds the previous loss twice.
         num epoch=40 #setting total number of epochs to be 40
         prev_loss=100 #initial loss value for early stopping
         max penalty=3
         best_acc=0
         parameter_learning_rate=[0.1,0.01,0.001] # different values for learning_
      \hookrightarrow rate
         for i,learning_rate in enumerate(parameter_learning_rate): #Looping through_
      \hookrightarrow the learning rates
             train_loss , train_accuracy = [], []
             val_loss , val_accuracy = [], []
             counter=0
             model = Resnet_50().to(device)
             optimizer, criterion = model_optimizer_criterion_res(model,__
      →learning_rate)
             print("Training model on Learning Rate=",learning rate)
             #model will train for a particular learning rate
             for epoch in range(num_epoch):# Looping through the epochs
                 print(f"Epoch number {epoch+1} of {num_epoch}")
                 #training the model
                 train_epoch_loss, train_epoch_accuracy = train_model(model,
                                                                 train_loader,
```

```
optimizer,
                                                         criterion)
           #checking the performance on validation
           val_epoch_loss, val_epoch_accuracy = validate_model(model,
                                                          val_loader,
                                                          criterion)
           #append the loss and accuracy for every epoch for both train and
\rightarrow validation data set
           train_loss.append(train_epoch_loss)
           train_accuracy.append(train_epoch_accuracy)
           val_loss.append(val_epoch_loss)
           val_accuracy.append(val_epoch_accuracy)
           # Early Stopping
           if val_epoch_loss>prev_loss: # checking if validation loss for the_
→current epoch is greater than the previous loss
               counter+=1
               if counter >= max_penalty: # if the validation loss exceeds the_
→previous loss twice begin the early stopping process
                   print('Early Stopping Initiated')
                   break
           else:
               counter = 0
           prev_loss = val_epoch_loss # update the threshold loss to the__
→previous validation loss of the epoch
       #saving the best performing model
       if(val_epoch_accuracy>best_acc):
           best_acc=val_epoch_accuracy
           best_model=model
       #saving the model for a particular learning rate
       torch.save(model.state dict(), '/content/drive/MyDrive/ASL Project/
→savedmodels/'+'model_mobile_net'+str(learning_rate)+'.pth' )
       #plotting the accuracy and loss curves
       print('Plotting Validation and Training Accuracy Curves for Learning ⊔
→Rate of ', learning_rate)
       plot_accuracy(train_accuracy, val_accuracy)
       print('Plotting Validation and Training Loss Curves for Learning Rate⊔
→of ', learning rate)
       plot_loss(train_loss,val_loss)
   return best_model
```

#### 1.12.2 Training the Resnet 50 model

```
[]: trained_resnet_50_model = resnet_50_model()
```

# 1.12.3 Testing the Resnet 50 model

Testing the model on given test dataset

```
[]: test_model(trained_resnet_50_model,test_loader,0)
```

Testing the model on our test dataset

```
[]: test_model(trained_neural_net_model,my_test_loader,1)
```

#### 1.13 Mobile-Net V2

# 1.13.1 Updating the pretrained Mobile Net V2 model

```
[]: def ModelMob():
         '''Using the concept of transfer learning on the pre-trained Mobile Net V2_{\sqcup}
      →model and retraining the fully connected layer '''
         model = models.mobilenet_v2(pretrained=True)
         for param in model.parameters():
                                                                      #freezing the
      \rightarrowpretrained layers
             param.requires_grad = False
         model.classifier = nn.Sequential(nn.Linear(1280, 128), #redefining the_
      → fully connected classifier layer
                                   nn.ReLU(),
                                   nn.Dropout(0.2),
                                   nn.Linear(128, 64),
                                   nn.ReLU(),
                                   nn.Dropout(0.2),
                                   nn.Linear(64, 29))
         return model
```

```
print(f"{total_trainable_parameters:,} number of training parameters.")
```

### 1.13.2 Training the Mobile Net V2 model

```
[]: def mobile_net_model():
         111
         Function to train the model as well as check the performance on the \sqcup
      ⇒validation dataset. Performs early stopping when the
         validation loss exceeds the previous loss twice.
         num_epoch=40 #setting total number of epochs to be 40
         prev_loss=100 # initial loss value for early stopping
         max_penalty=2
         best_acc=0
         parameter_learning_rate=[0.1,0.01,0.001]# different values for learning_
      \rightarrowrate
         for i,learning_rate in enumerate(parameter_learning_rate):#Looping through_
      → the learning rates
             train_loss , train_accuracy = [], []
             val_loss , val_accuracy = [], []
             counter=0
             model = ModelMob().to(device)
             optimizer,criterion=model_optimizer_criterion(model, learning_rate)
             print("Training model on Learning Rate=",learning rate)
             #model will train for a particular learning rate
             for epoch in range(num epoch): # Looping through the epochs
                 print(f"Epoch number {epoch+1} of {num_epoch}")
                 #training the model
                 train_epoch_loss, train_epoch_accuracy = train_model(model,
                                                                train_loader,
                                                                optimizer,
                                                                criterion)
                 #checking the performance on validation
                 val_epoch_loss, val_epoch_accuracy = validate_model(model,
                                                                val loader,
                                                                 criterion)
                 #append the loss and accuracy for every epoch for both train and
      \rightarrow validation data set
                 train_loss.append(train_epoch_loss)
                 train_accuracy.append(train_epoch_accuracy)
                 val_loss.append(val_epoch_loss)
                 val_accuracy.append(val_epoch_accuracy)
                 # Early Stopping
                 if val_epoch_loss>prev_loss:# checking if validation loss is_
      → greater than the previous loss
```

```
counter+=1
                     if counter >= max_penalty: # if the validation loss exceeds the_
      → threshold loss twice begin the early stopping process
                         print('Early Stopping Initiated')
                         break
                 else:
                     counter = 0
                 prev_loss=val_epoch_loss# update the previous loss to the previous_
     \rightarrow validation loss of the epoch
             #saving the best performing model
             if(val_epoch_accuracy>best_acc):
                 best_acc=val_epoch_accuracy
                 best_model=model
             #saving the model for a particular learning rate
             torch.save(model.state_dict(), '/content/drive/MyDrive/ASL_Project/

¬savedmodels/'+'model_mobile_net'+str(learning_rate)+'.pth' )

             #plotting the accuracy and loss curves
            print('Plotting Validation and Training Accuracy Curves for Learning⊔
      →Rate of ', learning_rate)
            plot accuracy(train accuracy, val accuracy)
            print('Plotting Validation and Training Loss Curves for Learning Rate⊔
     plot_loss(train_loss,val_loss)
        return best_model
[]: trained_mobile_net_model=mobile_net_model()
    1.13.3 Testing the Mobile Net V2 model
    Testing the model on given test dataset
[]: test_model(trained_mobile_net_model,test_loader,0)
    Testing the model on our test dataset
```

[]: test\_model(trained\_mobile\_net\_model,my\_test\_loader,1)