# **GPU Computing with CUDA Lab 5 - Thrust**

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# **Objectives**

- ► Experiment with Thrust
- ▶ Outline
  - Walk through various examples
  - Implement "weld triangles" example

```
#include <thrust/device_vector.h>
#include <thrust/reduce.h>
#include <iostream>
int main(void)
  thrust::device_vector<int> data(4);
  data[0] = 10;
  data[1] = 20;
  data[2] = 30;
  data[3] = 40;
  int sum = thrust::reduce(data.begin(), data.end());
  std::cout << "sum is " << sum << std::endl;</pre>
  return 0;
```

```
#include <thrust/device_vector.h>
#include <thrust/transform.h>
struct triple
   host device
  int operator()(int x)
    return 3 * x;
};
int main(void)
 thrust::device_vector<int> input(4);
  input[0] = 10;
  input[1] = 20;
  input[2] = 30;
  input[3] = 40;
 thrust::device vector<int> output(4);
  thrust::transform(input.begin(), input.end(), output.begin(), triple());
  for (int i = 0; i < output.size(); i++)</pre>
    std::cout << output[i] << std::endl;</pre>
  return 0;
```

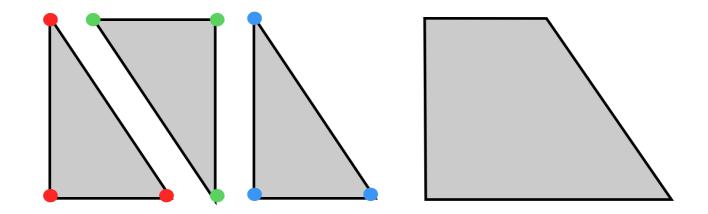
```
#include <thrust/device vector.h>
#include <thrust/sort.h>
#include <thrust/functional.h>
int main(void)
  thrust::device vector<int> data(8);
  data[0] = 6;
  data[1] = 3;
  data[2] = 7;
  data[3] = 5;
  data[4] = 9;
  data[5] = 0;
  data[6] = 8;
  data[7] = 1;
  thrust::sort(data.begin(), data.end());
  std::cout << "ascending" << std::endl;</pre>
  for (int i = 0; i < data.size(); i++)</pre>
    std::cout << data[i] << std::endl;</pre>
  thrust::sort(data.begin(), data.end(), thrust::greater<int>());
  std::cout << "descending" << std::endl;</pre>
  for (int i = 0; i < data.size(); i++)</pre>
    std::cout << data[i] << std::endl;</pre>
  return 0;
```

```
#include <thrust/device vector.h>
#include <thrust/count.h>
#include <thrust/copy.h>
struct is odd
  __host__ __device
 bool operator()(int x)
    return (x % 2) == 1;
int main(void)
 thrust::device_vector<int> data(8);
 data[0] = 6; data[1] = 3; data[2] = 7; data[3] = 5;
  data[4] = 9; data[5] = 0; data[6] = 8; data[7] = 1;
  int N = thrust::count if(data.begin(), data.end(), is odd());
  std::cout << "counted " << N << " odd values" << std::endl;</pre>
 thrust::device_vector<int> odds(N);
 thrust::copy if(data.begin(), data.end(), odds.begin(), is odd());
 for (int i = 0; i < odds.size(); i++)
    std::cout << odds[i] << std::endl;</pre>
  return 0;
```

```
#include <thrust/host vector.h>
#include <thrust/device vector.h>
#include <thrust/reduce.h>
#include <iostream>
int main(void)
  int N = 100000;
 thrust::host_vector<int> h_data(N);
  thrust::device_vector<int> d_data(N);
// // method 1: (one cudaMemcpy per element)
// for (int i = 0; i < N; i++)
// d data[i] = i;
// // method 2: one cudaMemcpy for entire array
// for (int i = 0; i < N; i++)
     h data[i] = i;
//
//
   thrust::copy(h_data.begin(), h_data.end(), d_data.begin());
  return 0;
```

## **Thrust - Weld triangles**

▶ Eliminate redundant vertices to form figure



- ▶ Procedure
  - Sort vertices
  - Collapse spans of like vertices
  - Search for each vertex's unique index

#### **Thrust - Weld triangles**

- ► Sort triangles:
  - Use sort with functor to sort respect to x and then to y
- ▶ Collapse spans of like vertices
  - Use unique: reorders array and points to the first repeated value

```
#include <thrust/unique.h>
...
const int N = 7;
int A[N] = {1, 3, 3, 3, 2, 2, 1};
int *new_end = thrust::unique(A, A + N);
// The first four values of A are now {1, 3, 2, 1}
// Values beyond new_end are unspecified.
\endcode
```

▶ Delete values beyond new iterator: vertices.erase()