

CS 3305A

Memory Management

Lecture 15

Nov 13th 2023

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Memory Management: Lecture 15 - 19

□ Lecture 15

- Intro to Memory management
- Memory Hierarchy
- Memory Allocation Techniques
 - Contiguous allocation

□ Lecture 16

- Memory Allocation Techniques
 - Contiguous allocation

□ Lecture 17

- Memory Allocation Techniques
 - Distributed allocation or Paging
- Page Table

□ Lecture 18-19

- Virtual Memory & Page Replacement

Agenda

- ❑ Intro to Memory management
- ❑ Memory Hierarchy
- ❑ Memory Allocation Techniques
 - ❑ Contiguous Memory Allocation
 - ❑ Fixed Allocations
 - ❑ Variable or Dynamic Allocation

Introduction

- ❑ Our machines today have 10,000 times more memory than the IBM 7094 - leading edge machine of the 1960's
- ❑ Memory unit cost has dropped dramatically
- ❑ Operating systems must manage memory

Introduction

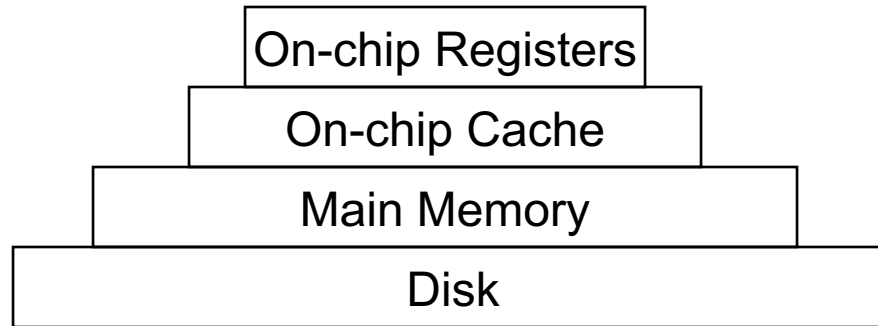
- ❑ Memory management requires
 - ❑ Allocate memory to processes when needed
 - ❑ Managing memory efficiently during runtime
 - ❑ Deallocate memory when processes are done

Introduction

- ❑ You can think of memory as a large array of bytes
 - ❑ Each byte has its own address

- ❑ Each of these operations require memory addresses and their management
 - ❑ Fetch an instruction from memory (reading)
 - ❑ Instruction is decoded
 - ❑ After instruction execution
 - ❑ Results may be stored back in memory (writing)

Memory Hierarchy



- ❑ A CPU waiting for data from main memory is not desired
- ❑ Remedy: Add fast memory between the CPU and main memory called a cache
- ❑ Typical average data transfer rate
 - ❑ SSD $\sim 4 \times$ faster than HDD
 - ❑ RAM is $\sim 30 \times$ faster than SSD
 - ❑ Cache is $\sim 100 \times$ faster than RAM

Memory Allocation Techniques

- ❑ Contiguous Memory allocation
 - ❑ Entire process has to be allocated in a memory in a contiguous manner
- ❑ Distributed memory allocation / Paging
 - ❑ Process can be allocated anywhere in the physical memory in a distributed manner

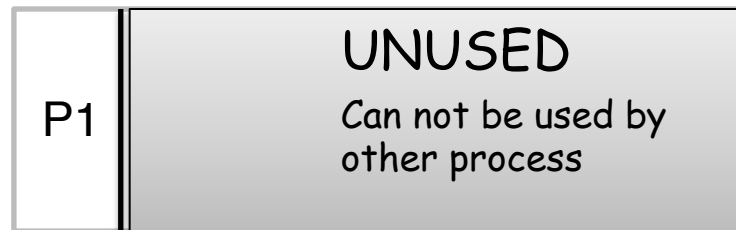
Contiguous Memory Allocation

Contiguous Memory Allocation

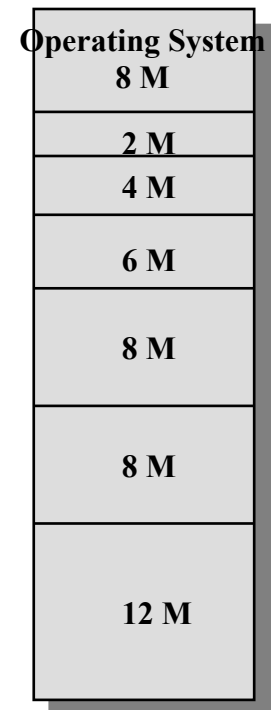
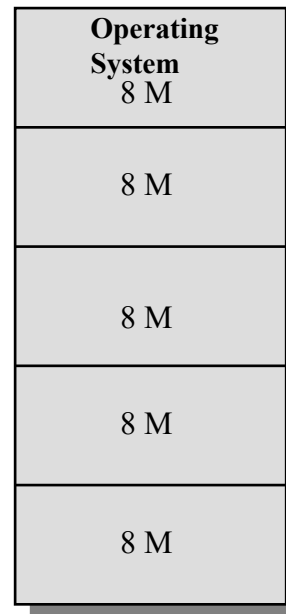
- ❑ We will start out with the most basic method used that allows multiple processes to reside in memory
- ❑ With **contiguous memory allocation** each process is contained in a single section of memory that is contiguous
 - ❑ Fixed partition
 - ❑ Variable / Dynamic Partition

Fixed Partitioning

- Any program/process, no matter how small, occupies an entire partition of the memory partition



- Equal-size or unequal sized partitions



Fixed Partitions

- ❑ Leads to **internal fragmentation**
- ❑ Was used by OS/360 on large IBM mainframes for many years
- ❑ Today no modern OS uses fixed partitions
- ❑ Fixed Partition Memory Allocation Algorithms:
 - ❑ First Fit
 - ❑ Best Fit
- ❑ Operating system must decide which free block to allocate to a process
 - ❑ **Best-fit, and First-fit algorithms**

Fixed Partitioning Placement Algorithm

- ❑ **First-fit** algorithm

- ❑ Starts scanning memory from the beginning and chooses the first available block that is large enough.

Fixed Partitions First Fit

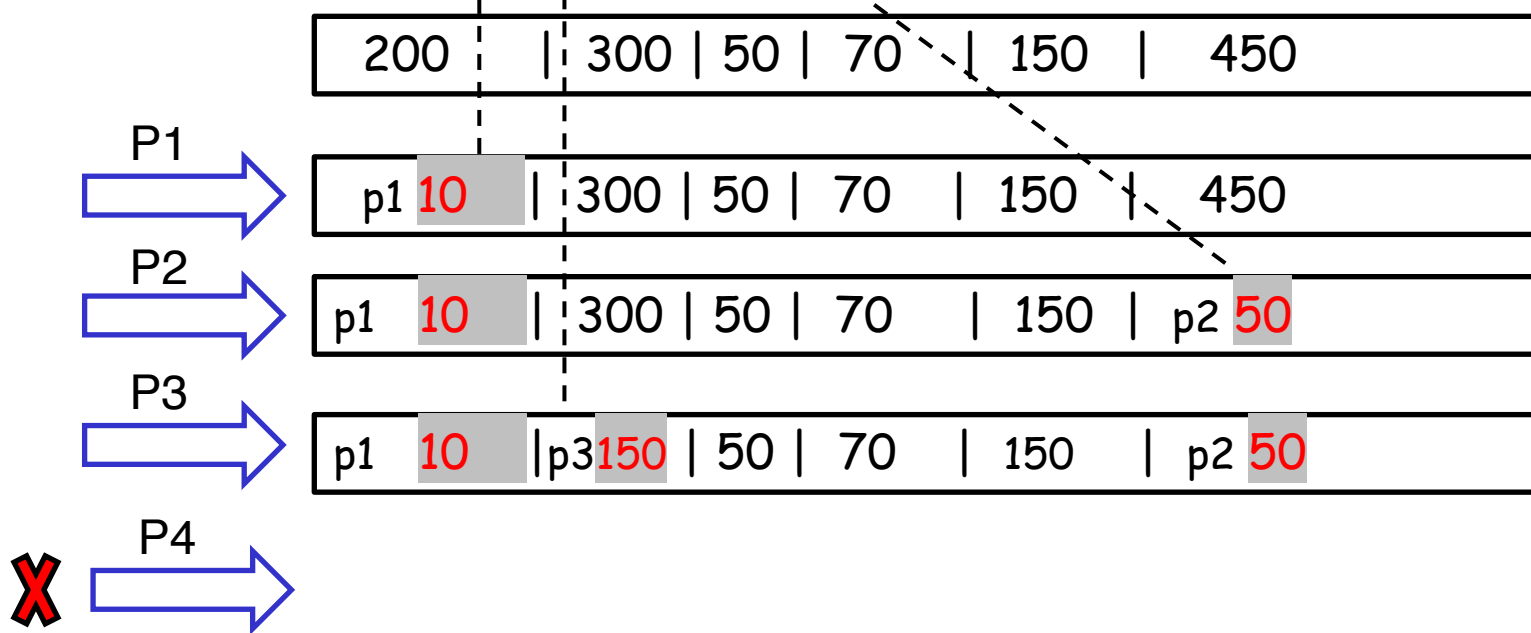
P1 = 190

P2 = 400

P3 = 150

P4 = 160

Internal Fragmentation (can NOT be used by any other process)



Internal Fragmentation = 10 + 50 + 150 = 210
Any External Fragmentation ? = 160

Fixed Partitioning Placement Algorithm

- ❑ **Best-fit** algorithm
 - ❑ Choose the block that is closest in size to the request
 - ❑ The smallest block is found for a process

- ❑ Can we compare the performance between the First-fit and the Best-fit?

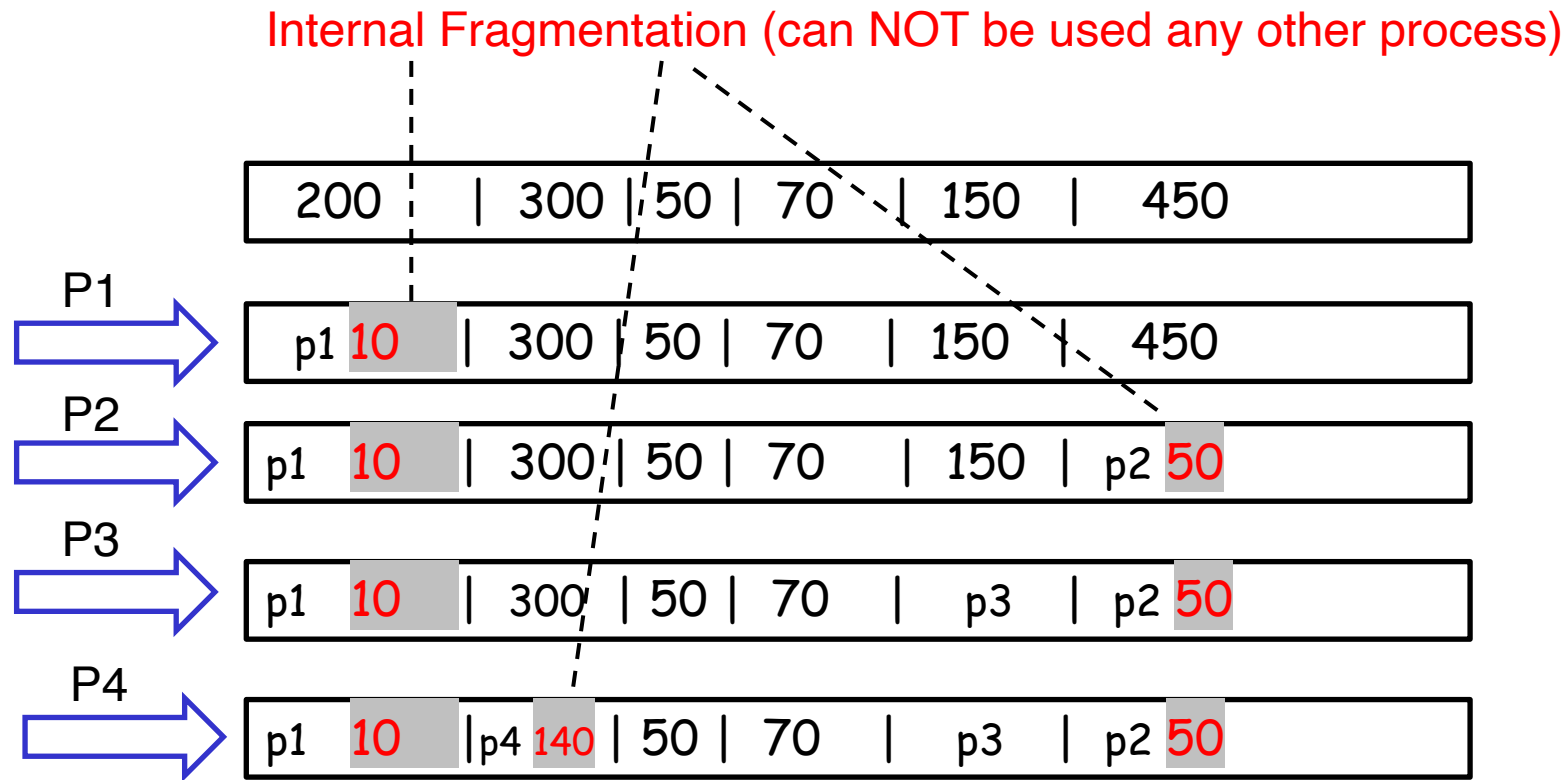
Fixed Partitions Best Fit

P1 = 190

P2 = 400

P3 = 150

P4 = 160



Internal Fragmentation = 10 + 50 + 140 = 200
Any External Fragmentation ? = 0