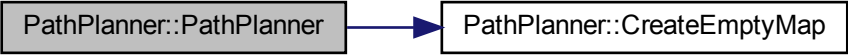


PathPlanner::PathPlanner



```
graph LR; A[PathPlanner::PathPlanner] --> B[PathPlanner::CreateEmptyMap]
```

The diagram consists of two rectangular boxes connected by a horizontal arrow. The left box is shaded gray and contains the text 'PathPlanner::PathPlanner'. The right box is white and contains the text 'PathPlanner::CreateEmptyMap'. A blue arrow points from the right side of the gray box to the left side of the white box.

PathPlanner::CreateEmptyMap