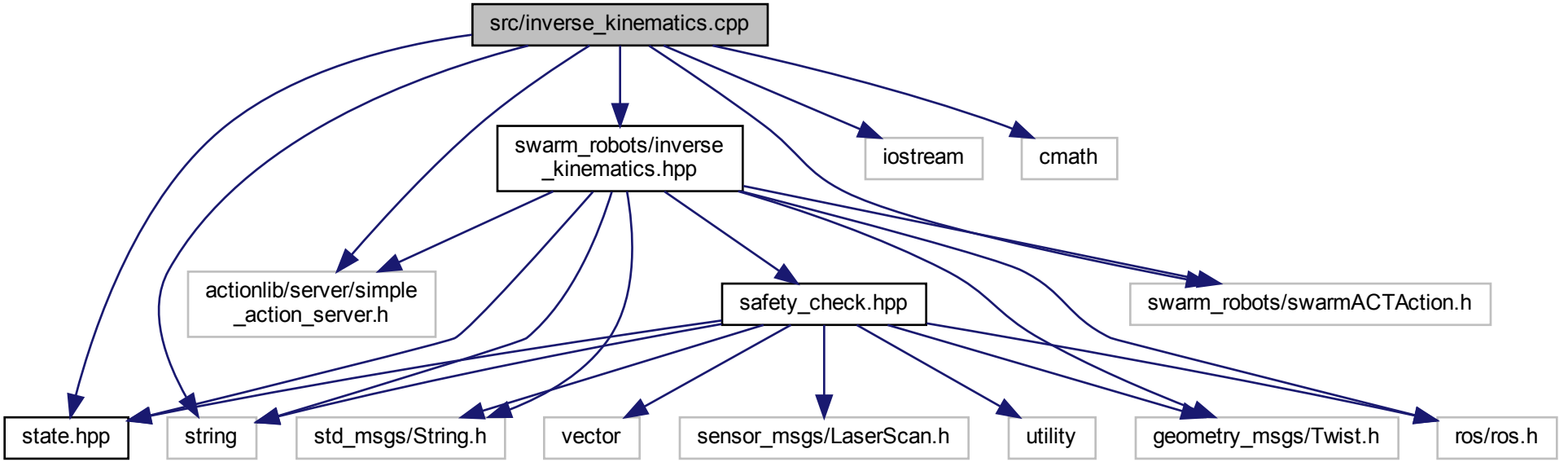
src/inverse_kinematics.cpp
swarm_robots/inverse
_kinematics.hpp
iostream
cmath
actionlib/server/simple
_action_server.h
safety_check.hpp
swarm_robots/swarmACTAction.h
state.hpp
string
std_msgs/String.h
vector
sensor_msgs/LaserScan.h
utility
geometry_msgs/Twist.h
ros/ros.h