



Intelligent Monitoring of Engineering Systems

Group 6: Intelligent Monitoring of a Bicycle Tire Pressure



Group 6

Intelligent Monitoring and Multiclass classification of a Bicycle Tire Pressure

- Introduction
 - Methods: Signal preprocessing
 - Methods: AI and network architecture
 - Methods: Cross validation and Testing
 - Results & Discussion
 - Conclusion & Outlook
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Our goal in this project

Problem Statement

Classifying tire pressure based on accelerometer data have limitations in accuracy and generalization

Challenges

Limited ability to accurately differentiate tire pressure levels

Motivation

Development of machine – learning based new tire pressure measurement methodology



Goal

To develop a classification model that can accurately predict tire pressure based on accelerometer data

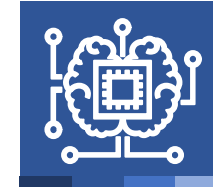


Team structure



Signal pre-processing

- Aakash Abhani
- Arnav Bhamburkar
- Yash Parab



Neural network

- Yash Patil
- Omkar Kunjir
- Rohit Jain

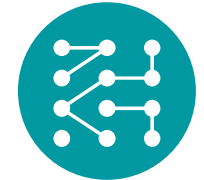
Deliverables



De-noised signal



Network architecture



Optimised network



Validation



Generalization



Use cases

Signal pre-processing for neural network input

Challenges	Processing technique
Different system response and noise frequencies	FFT analysis for noise and peak frequencies
Cover all signals required for processing	Butterworth bandpass filter 05 Hz to 40Hz of order 8
Isolate peaks for training neural network	Bump (peak) extraction
Datasets with different sampling frequency	Sampling frequency standardization (200 Hz)
Datasets recorded by different cyclists	Cyclist weight standardization
Paucity of training datasets	Individual bump as a single training set

Neural network input parameters



11 Z-acceleration features about bump peak



Bump peak frequency & cyclist weight

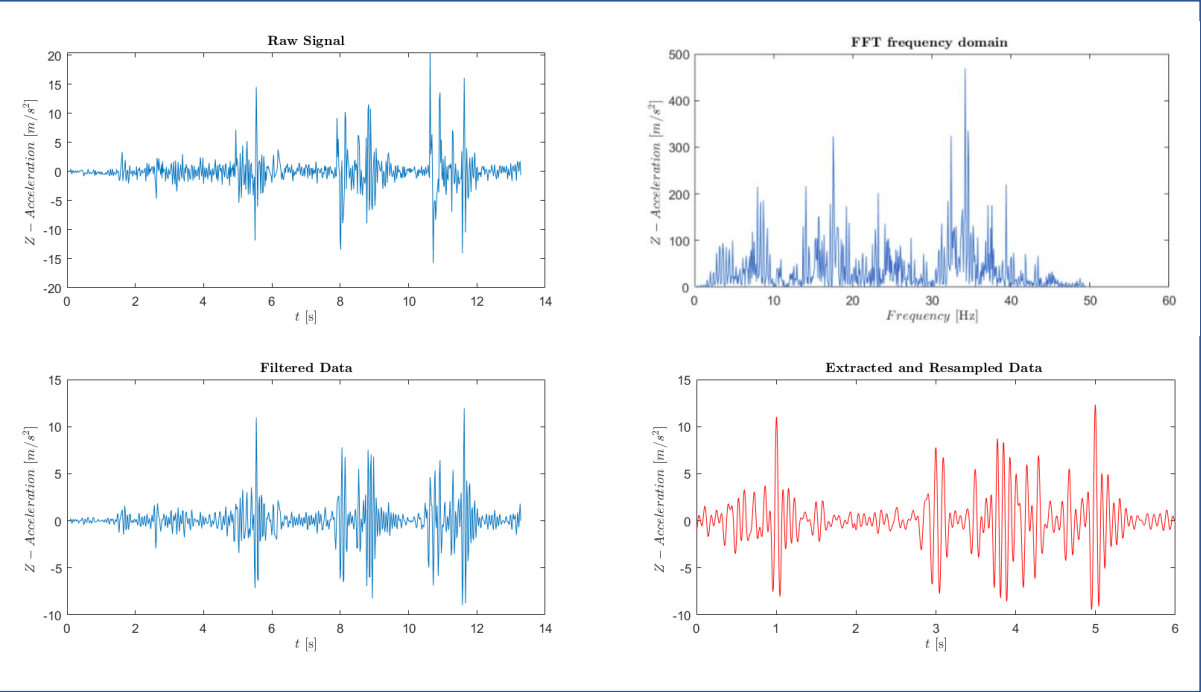


Chart 1: Illustrative signal processing for one group and one tire pressure

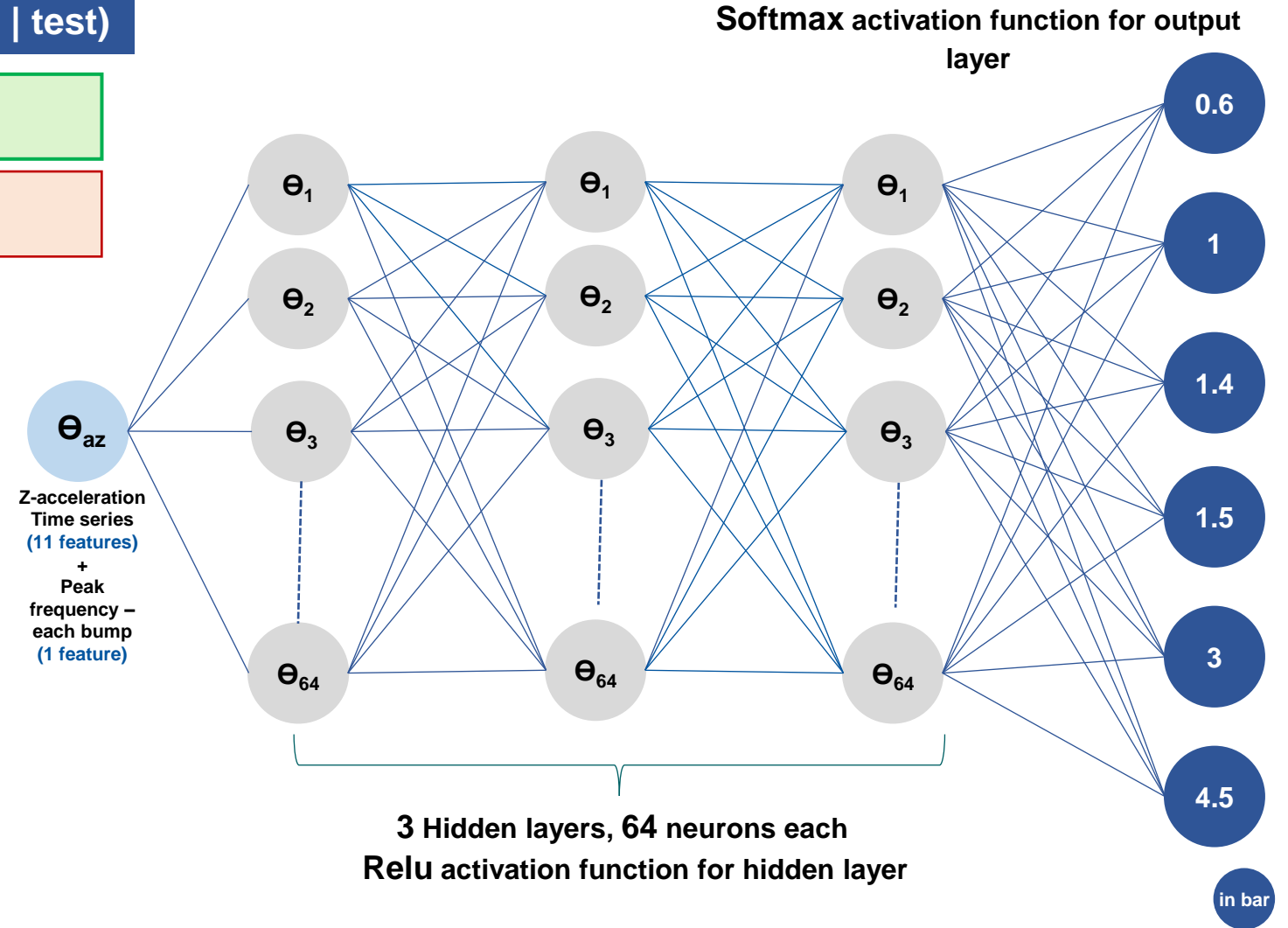
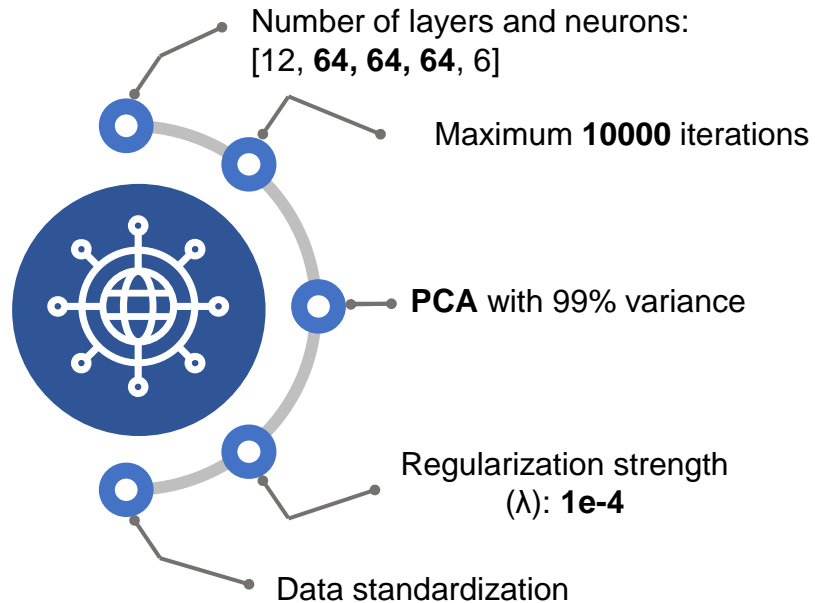
FF Neural network architecture is ~47% accurate, slightly better than SVM

Network classifiers tried (accuracy: validation | test)

1 Feed forward neural network (46.9% | 46.7%)

2 Support vector machines (46% | 43.3%)

Selected neural network architecture (FFNN)



~47% accuracy is achieved for Training + Validation dataset



5-Fold Cross Validation

- 7 groups * 6 pressure classes * 3 Individual bumps each = 126 datasets → (~75%) 96 training & validation datasets

	Class	Precision	Recall	F1 score	Accuracy
Fat damped bike	0.6 bar	0.67	0.63	0.65	62.5%
	1.0 bar	0.27	0.25	0.26	25.0%
	1.4 bar	0.37	0.44	0.40	43.8%
Trekking undamped bike	1.5 bar	0.48	0.63	0.54	62.5%
	3.0 bar	0.43	0.38	0.40	37.5%
	4.5 bar	0.67	0.50	0.57	50.0%
Accuracy					46.9%

Confusion Matrix

Trilayered FFNN						
True Class	0.6	1	1.4	1.5	3	4.5
	10	2	3	1		
	5	4	5	1	1	
		7	7	2		
		2	2	10	2	
				6	6	4
Predicted Class			2	1	5	8
	0.6	1	1.4	1.5	3	4.5

Generalization ability can be measured to ~47% accuracy



Testing

- (~25 %) 30 testing datasets.
- Generalization accuracy similar to validation.

	Class	Precision	Recall	F1 score	Accuracy
Fat damped bike	0.6 bar	0.33	0.20	0.25	20.0%
	1.0 bar	0.40	0.40	0.40	40.0%
	1.4 bar	0.67	0.80	0.73	80.0%
Trekking undamped bike	1.5 bar	0.50	0.40	0.44	40.0%
	3.0 bar	0.33	0.40	0.36	40.0%
	4.5 bar	0.50	0.60	0.55	60.0%
Accuracy					46.7%

Confusion Matrix							
Trilayered FFNN							
True Class	0.6	1	1.4	1.5	3	4.5	
	0.6	1	1.4	1.5	3	4.5	
	0.6	1	1.4	1.5	3	4.5	
	0.6	1	1.4	1.5	3	4.5	
	0.6	1	1.4	1.5	3	4.5	
	0.6	1	1.4	1.5	3	4.5	
		0.6	1	1.4	1.5	3	4.5
		Predicted Class					

Pressure classes not sufficiently distinguishable

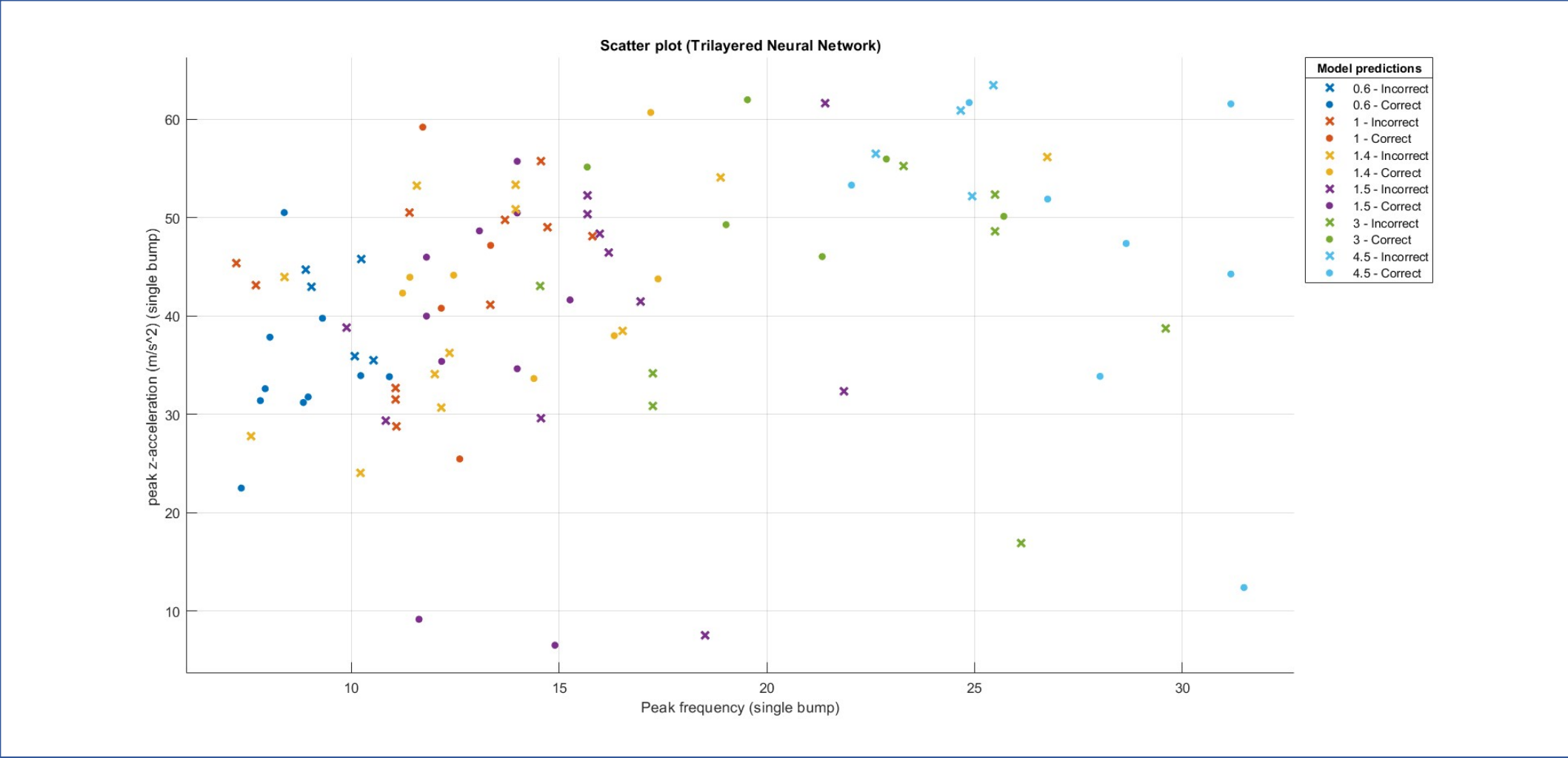


Chart 2: 2D visualization of model predictions with respect to peak z-acceleration and peak frequency for each bump.

What can be further done?

Conclusion

- With the available data, classification model is ill-equipped & accuracy (~47%) is insufficient. Thus, generalization isn't working in this case.
- Furthermore, robust sensor mounting would reduce noise & improve reproducibility



Potential improvements

- Creating additional run-time filters (dynamic) to eliminate noise due to different set-up, rider → standard & efficient filter strategy
- Regression/ Classification model with advanced network architecture – CNN, LSTM for higher accuracy. Open-source pre-trained networks - AlexNet, GoogLeNet, ResNet-50 can be used for this.



Direct applications



Automotive calibration

- Driver behavior analysis with data driven models.
- Road load prediction for design & analysis



Intelligent TPMS

- Real time monitoring: improve fuel efficiency & prevent accidents
- Tire wear & performance prediction

Extended applications



Smart Wearables

- Activity recognition
- Fall detection
- Sleep stage classification



Structural health monitoring

- Bridges, buildings, and other infrastructure to assess structural integrity, potential defects or damages



Biomedical

- Physiological signals like ECG, EEG, etc.
- Disease diagnosis, progression monitoring and treatment strategies



Material Characterization

- Analyze the response of materials to external stimuli and predict material properties.

REFERENCES

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Questions

Thank you for your attention!
