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One Dimensional Thermal Analysis Model for Charring Ablative Materials

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Abstract. This paper presents a one-dimensional model for the analysis of the charring ablative materials used in spacecraft thermal protection systems. The numerical method is based on an implicit finite difference formulation of the governing equations written for a system of mobile coordinates that accounts for the possible presence of surface recession. The maximum allowable operating temperature for the adhesive layer of the junction between the heat shield and the substructure is used as a design parameter for determining the minimum heat shield thickness. A case study on the re-entry of the Stardust capsule is presented. The model proposed as a useful dimensioning tool for the preliminary design phase of the heat shields of spacecraft entering the atmosphere. The model was validated through a survey of the literature related to the dimensioning of thermal shields, but based on numeric programs of highly representative industrial standards.

Keywords. Thermal protection system, Ablative materials, Thermal analysis

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TERM REPORT

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1 Introduction

Thermal management is an important part of high speed vehicles like aircrafts, space shuttles and missiles. For high aerothermal loads, many different thermal protection systems(TPS) are developed. One easy and efficient way is to use ablative TPS materials to dissipate high entering heat flux which is widely used for aerospace systems as heat shield(covering main structure). Therefore, modelling of ablation phenomenon becomes very important while deciding the feasibility of design from thermal point of view. Ablation simply means degradation or removing of a material surface due to chemical reactions, erosion or vaporization and there are mainly two classes of ablative materials: "charring" and "non-charring". Ablative material called as non-charring if the material does not have any chemical reaction during removal process (like a simple change of state), it is called as charred if high heat causes a chemical reaction inside the material which leads to leakage of pyrolysis gases. Mainly, charring ablative materials contain resin which decomposes and generates gas when heated adequately, this is an endothermic reaction which is called as "pyrolysis". This reaction starts from the upper part of material where thermal loads are present and when this reaction is done remaining material called as "char" or "charred material". If material does not reach necessary temperature for pyrolysis reaction, it is called as "virgin ablative material". The outflow gases ,which are produced during pyrolysis reactions, pass through porous structure of charred ablative material and behaves like a barrier against aero-thermal heating (convective heating, radiative heating), this is another thermal protection effect of ablative materials. Lastly, during whole this process surface recession occurs due to mechanical erosion on charred part which causes a consistent decrease of material thickness. This general structure described is shown on Figure 1 as shematic[1].

Until 1950s no research was done about modeling or application of ablation phenomenon because there was no need for such a thermal protection system. Firstly space engineers and researchers began thinking about how to return from space, especially from thermal point of view since atmospheric reentry is an important thermal challenge due to high heat loads, . To overcome this challenge many different vehicle designs are tested through wind tunnels but just changing the design of the vehicle were not enough. Even they could cope with thermal loads weight increase became problem for trajectories due to using of high density metals such as copper as heat sink structure or using of very thick metal bodies then first considerations have started about ablative materials[2]. After committed assessments and analysis by researchers, using of ablative thermal protection system for atmospheric reentry became an important and logical choice due to its low density and high heat absorption properties. At this point, modelling of ablation became important of scientists and engineers. In 1965, a significant Nasa Technical Note is published by Donald M. Curry which gives a detailed mathematical model for charring ablation thermal protection system[5]. He used 1D implicit finite difference method to formulate differential equations and developed a FORTRAN IV code to make necessary calculations. That paper also showed the verification of the model by experimental results. These mathematical model and its verification enable engineers to calculate minimum thickness required for the

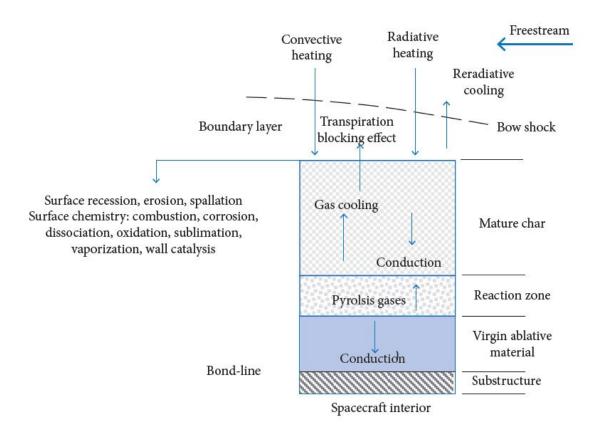


Figure 1: Shematic of charring ablative thermal protection system

missionans this leads to usign of ablative TPS for first successful controlled reentry mission of NASA[4](Gemini 6A, Figure Figure 2) which is a manned reentry mission and then it is used şb many space missions till today. It is still a commonly used TPS for atmospheric re-entry missions.

2 The Ablative Thermophysical Model

Mathematical model presented here is also a 1D implicit model and specific for charring ablative materials. This model is suggested to be used in conceptual development phase since it gives faster result comparing to other detailed models. Here instead of using whole trajectory of a space vehicle, just stagnation point, where heat flux is maximum, is enough to find necessary results for conceptual development case. As it is described in section 1, the aim is to find minimum thickness required that keeps the body structure below maximum operating temperature.

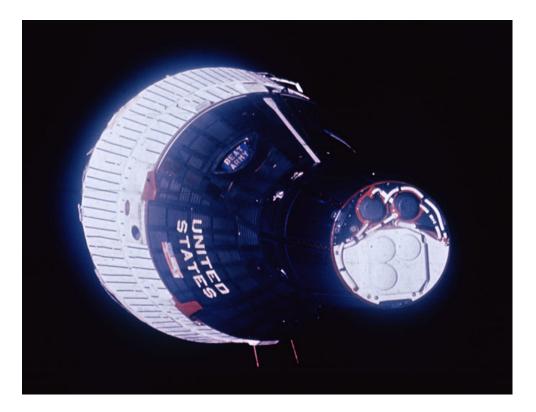


Figure 2: Gemini 6A spacecraft, black side is charring ablative TPS(painted)

2.1 Assumptions

Before explaining the governing equation of the model the assumptions made for ablation physics are described in this section. Seven main assumptions are explained below.

- 1. In fact it is not easy to know exactly where decomposition of virgin state material to char occurs but in this model it is assumed in a certain area which is called as reaction zone.
- 2. There are two important temperature values defining the reaction zone: T_{abl} , temperature where pyrolysis reactions start; T_{char} , temperature where fully charring occurs. These temperature values are found by assessing the thermogravimetric experiments. One sample graph is given in Figure 3. As it seen, these temperature points are estimated by looking at the behaviour of the curvature.
- 3. Pressure loss during upward flow of the gases generated in the reaction zone to upper parts is neglected. (It is assumed that gas instantenously passes to upper layers.)
- 4. Effects of thermal stress is neglected.
- 5. There is a local thermal equilibrium between the char zone and gases.

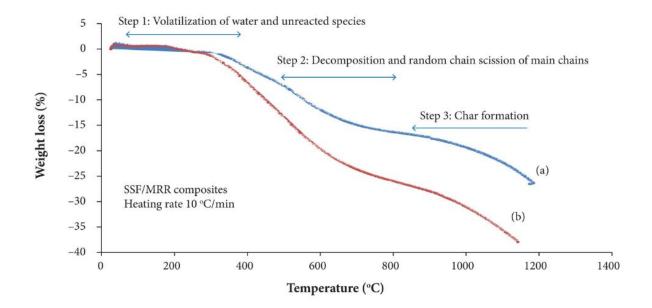


Figure 3: Thermogravimetric experiment data for short silica fiber, reinforced modified resole resin composites(SSF/MRR) under (a) nitrogen and (b) air flow. [3]

- 6. Rather than the reactions described in the model, there is no chemical reaction occurs betweeb gases and environment.
- 7. Thermal effects of internal part of spacecraft is neglected.

2.2 Governing Equations

Equations to estimate the physics of ablation are explained in this section. Main equations are: The internal energy equation which describes the accumulation rate of thermal energy, internal decomposition equation that the decomposition rate due to pyrolysis reactions, surface energy balance equation to calculate net total heat flux at the surface, surface recession that calculates the total char removal from surface.

2.2.1 The Internal Energy Balance Equation

$$\rho c_p \frac{\partial T}{\partial t} \bigg|_x = \frac{\partial}{\partial x} \left(k \frac{\partial T}{\partial x} - \dot{q}_R \right) \bigg|_t + \left(H_d - \bar{h} \right) \frac{\partial \rho}{\partial t} \bigg|_y + \dot{S} \rho c_p \frac{\partial T}{\partial x} \bigg|_t + \dot{m}_g \frac{\partial h_d}{\partial x} \bigg|_t$$
 (1)

In this equation ρ : Density (kg/m^3) , c_p : Specific heat at constant temperature(J/(kg.K)), T: Temperature(K), k: Thermal conductivity(W(m.K)), \dot{q}_R : Internal radiative heat flux (W/m^2) , H_d : Pyrolysis enhalpy(J/kg), \bar{h} : Partial heat of charring(J/kg) given in Eq. , \dot{S} : Char

recession rate(m/s) \dot{m}_g : Pyrolysis gas mass flow rate(kg/m^2s)), x: Mobile coordinate system(m) that is moving with the surface recession and y: Fixed coordinate system at the beginning of the analysis these two systems are coincident.

As it is described before this equation gives the accumulation rate of thermal energy. The terms of rightern side represents respectively conduction and internal radiation, energy consumption due to pyrolysis, convective rate caused by surface recession and caonvective rate due to pyrolysis gases. It is clearly seen some material dependent properties (c_p, ρ) and (c_p, ρ) and (c_p, ρ) are used while modelling internal energy balance. During ablation the state of the material is between char and virgin states because of that these material properties have to be considered with some approximations given below. Here (c_p, ρ) is the mass fraction of the virgin material with respect to total weight given in Eq. 2. Subscript 'v' refers to virgin state and 'c' refers to char state. The equation of specific heat (c_p) and thermal conductivity (c_p, ρ) is given in Eq. 3 and Eq.4. For density linear relation with respect to temperature is considered (it is commonly used equation for reaction zone).

$$\tau = (1 - \rho_c/\rho)/(1 - \rho_c/\rho_v) \tag{2}$$

$$c_p = \tau c_{pv} + (1 - \tau)c_{pc} \tag{3}$$

$$k = \tau k_v + (1 - \tau)k_c \tag{4}$$

$$\rho = (\rho_v - \rho_c) \frac{T - T_{abl}}{T_{char} - T_{abl}} \tag{5}$$

Lastly, pyrolysis gas's enthalphy(h_d) is depend on temperature and pressure but the partial heat of charring(\bar{h}) can be defined as in Eq. 6.

$$\bar{h} = \frac{\rho_v h_v - \rho_c h_c)}{\rho_v - \rho_c} \tag{6}$$

2.2.2 The Internal Energy Balance Equation

This equation used for pyrolysis decomposition part of energy equation. It is developed based on Arrhenius relationship by adopting the coefficients for complete plastic ablative composite.

$$\frac{\partial \rho}{\partial t} = K(\frac{\rho - \rho_c}{\rho_v - \rho_c})^n e^{-B/T} \tag{7}$$

2.2.3 Internal Mass Balance Equation

This equation gives the mass flow rate of the pyrolysis gases. In this model it is approximated as equal to pyrolysis decomposition.

$$\frac{\partial \dot{m}_g}{\partial y} = \frac{\partial \rho}{\partial t} \tag{8}$$

2.2.4 Surface Energy Balance Equation

On the surface of the ablative material there is a high heat flux due to convective, radiative heat transfer and thermochemical interactions. This equation gives the net total heat flux at the surface which is also boundary.

$$\dot{Q}_{in} = \dot{q}_{c,blow} + \dot{q}_{rad} + \dot{q}_{comb} - F\sigma\epsilon(T_w^4 - T_{inf}^4) \tag{9}$$

Where \dot{Q}_{in} : Net total heat flux at the surface (W/m^2) , $\dot{q}_{c,blow}$: net hot wall convective heat flux (W/m^2) , \dot{q}_{rad} : Entering radiative heat flux (W/m^2) , \dot{q}_{comb} : Combustion heat flux (W/m^2) , F: View factor, σ : Stefan-Boltzmann constant (W/m^2K^4) , ϵ : Surface emissivity, T_w : Wall temperature(K), T_{inf} : Free stream temperature(K)

To be able to express the terms on the rightern side, equation of some coefficients should be declared (Eq. 10 - Eq. 12) . V is the velocity of spacecraft and c_{patm} is the specific heat of atmosphere.

$$h_w = c_{patm} T_w \tag{10}$$

$$h_0 = c_{patm} T_{\inf} + \frac{V^2}{2} \tag{11}$$

$$A = \frac{h_0}{\dot{q}_{c,w}} (\alpha_c \dot{m}_c + \alpha_g \dot{m}_g) \tag{12}$$

 $\dot{q}_{c,w}$: Cold wall convective heat flux (W/m^2) , \dot{m}_c : Removal rate of char due to surface recession $(kg/(m^2s))$, where the coefficients α_c and α_g are used to consider the molecular weight of gases in the boundary layer from that of the injected pyrolysis gases. The coefficient α_c also takes into account the part of the char that is mechanically removed rather than sublimated. Eq. 12 is needed to approximate blocking effect of pyrolysis gases in the boundary layer. Lastly, Eq. 13 gives the hot wall convective heat flux which will help for calculating net hot wall convective heat flux.

$$\dot{q}_{con} = \dot{q}_{c,w} \left(1 - \frac{h_w}{h_0}\right) \tag{13}$$

Now, the equations of the rightern side can be expressed. If coefficient A is smaller than 2.25 (A < 2.25) then Eq. 14 is used, otherwise($A \ge 2.25$) Eq. 15 is used for net how wall convective heat flux calculation.

$$\dot{q}_{c,blow} = (1 - 0.724A + 0.13A^2)\dot{q}_{con} \tag{14}$$

$$\dot{q}_{c,blow} = 0.04 \dot{q}_{con} \tag{15}$$

Secondly, heat flux effect of the combustion of the ablation products is expressed as in Eq. 17.

$$\dot{q}_{comb} = \dot{m}_c \Delta H_c \tag{16}$$

2.2.5 Surface Recession

Total recession due to surface material(char) removal can be easily defined as:

$$S = \int_0^t \dot{S}dt \tag{17}$$

3 Shematic of The Ablative Thermal Model

In introduction section the numerical approach of the paper is clearly indicated as 1D implicit difference formulation (backward time, centered space) which is used for governing equations explained in previous section. The advantage of this methodology is, especially in thermal field, by using parabolic partial differential equations, the resultant implicit scheme is unconditionally stable in both time and space. This approach is applied for the shematic given in Fig. 4. Upper boundary is exposed to surface recession (moving to bottom) so it is called as free surface and recession is modeled continuously. Ablative material part (char, reaction zone, virgin ablative) splits into a predefined and fixed number of nodes with size ΔX . Node number is increasing starting from upper node to bottom node. (In original paper there are three substructure but there is no need for extra two of them to express the main idea of the modelling)

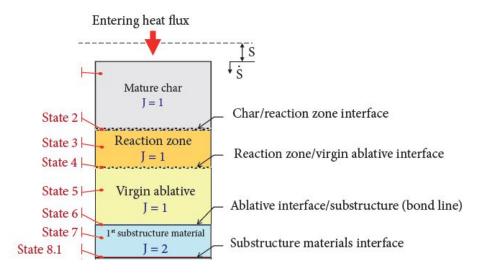


Figure 4: Schematic of the implemented model

The algorithm starts with estimation of ablative material thickness and determines the minimum thickness. The algorithm is basicly decreases the thickness values and stops when critical temperature values is reached (when temperature of the substructure material is higher than its operating temperature). While decreasing the thickness the secant method

is used for smooth convergence (10-15 iterations. Newton method was also a good choice but author did not prefer it because of difficulty of estimating derivative.

After making necessary calculations and leave the unknown temperatures for nodes left-hand side and other values to right-hand side, Eq. 18 is obtained. Consequently, we had a tridiagonal system of N nodes where our problem becomes as Eq. 19.

$$A_i T'_{i-1} + B_i T'_i + C_i T'_{i+1} = D_i (18)$$

$$\begin{cases}
B_{1}T_{1}^{'} + C_{1}T_{2}^{'} & = D_{1} \\
A_{2}T_{1}^{'} + B_{2}T_{2}^{'} + C_{2}T_{3}^{'} & = D_{2} \\
A_{3}T_{2}^{'} + B_{3}T_{3}^{'} + C_{3}T_{4}^{'} & = D_{3} \\
& \vdots & \vdots & \vdots \\
A_{N}T_{N-1}^{'} + B_{N}T_{N}^{'} = D_{N}
\end{cases}$$
(19)

3.1 Assumptions of Thermal Model

While discretising the governing equations by finite differences, some key assumptions are done. In this section these assumptions, which are linearized radiation assumption, moving surface assumption and radiation between two parallel flat surfaces, will be explained.

3.1.1 Linearized Radiation

Radiation is calculated by using the fourth power of temperature and instead of taking fourth order of unknown temperature it is linearized and expression is adopted as Eq. 20.

$$(T_i')^4 = (T_i + \Delta T)^4 = T_i^4 \left(1 + \frac{\Delta T}{T_i} \right)^4 \cong T_i^4 \left(1 + 4\frac{\Delta T}{T_i} \right) = 4T_i^3 T_i' - 3T_i^4 \tag{20}$$

3.1.2 Moving Surface(Surface Recession)

Additional terms to the energy balance equations are used than by taking the derivative of thermal capacitive term(left-hand side term) surface recession rate is derived as seen in Eq. 22. NP means total number of nodes in the ablation material.

$$\frac{\partial}{\partial t} \left(\Delta X \rho c_p T \right) = \Delta X \rho c_p \frac{\partial T}{\partial t} + \rho c_p T \frac{\partial (\Delta X)}{\partial t}$$
(21)

where

$$\frac{\partial(\Delta X)}{\partial t} = \frac{\partial}{\partial t} \left(\frac{S_{init} - S}{NP - 1} \right) = -\frac{\dot{S}}{NP - 1}$$
 (22)

3.1.3 Radiation between two parallel flat surfaces

While considering radiative relations the form factor is taken as $1(F_{12} = 1)$ and equivalent emissivity is calculated as shown in Eq. 23.

$$\epsilon_{eq} = \left(\frac{1}{\epsilon_1} + \frac{1}{\epsilon_2} - 1\right)^{-1} \tag{23}$$

3.2 Nodal Schemes

Starting from the first node of surface nodal scheme for each part of the model is represented in Figure 5-Figure 13 [1]. Equations of each nodal scheme is also given in the figures. Red arrows mean energy addition and blue arrows mean removal of energy.

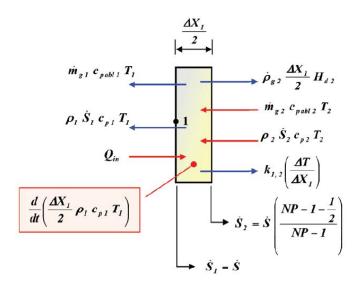


Figure 5: Nodal scheme of first node (upper surface)

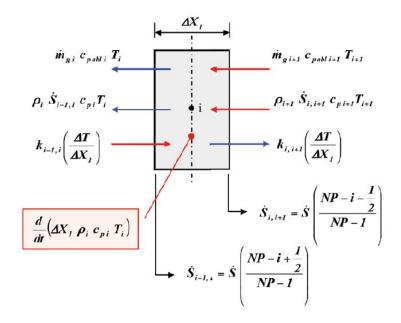


Figure 6: Nodal scheme of state 1(matur char zone)

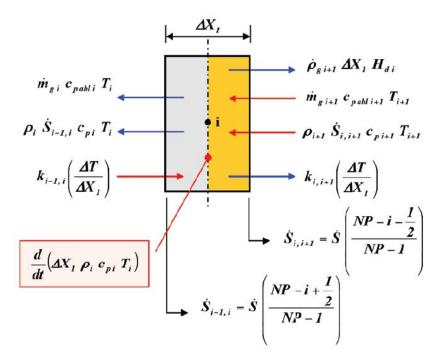


Figure 7: Nodal scheme of state 2 (matur char-reaction zone interface)

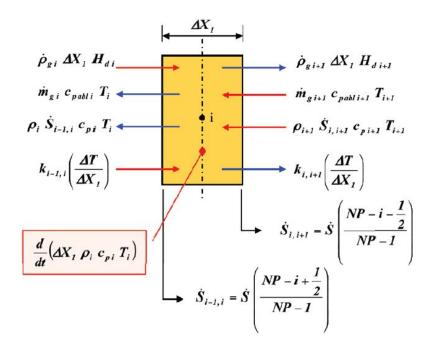


Figure 8: Nodal scheme of state 3(reaction zone)

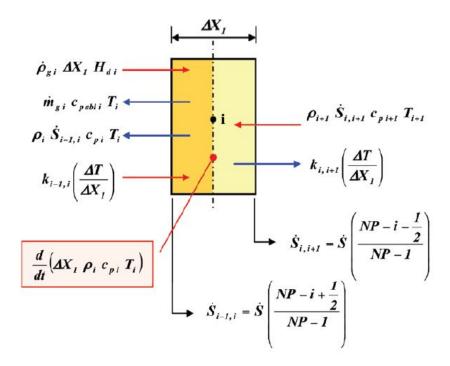


Figure 9: Nodal scheme of state 4(reaction zone-ablative virgin interface)

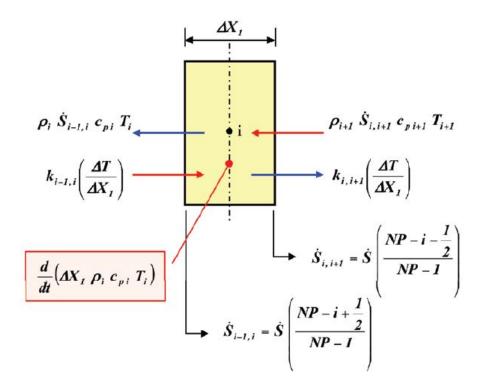


Figure 10: Nodal scheme of state 5(ablative virgin material)

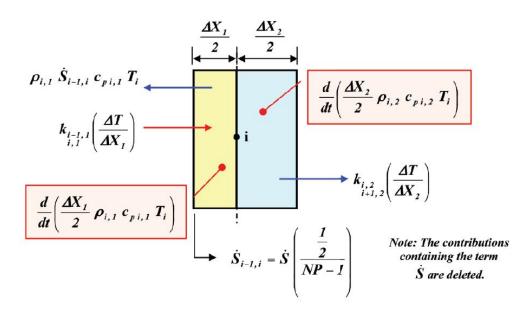


Figure 11: Nodal scheme of state 6(ablative virgin interface-substructure material interface)

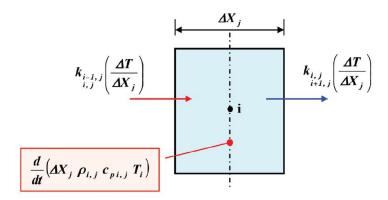


Figure 12: Nodal scheme of state 7(substructure material)

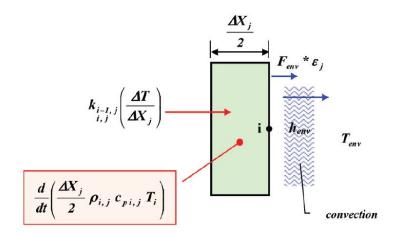


Figure 13: Nodal scheme last node(substructure material with radiation and convection to cabin interior)

4 Conclusion

In this paper Mazzarachio's paper[1] is summarized by explaining the one dimensional thermal analysis model for charring ablatives. This model is presented as a verified model and tried with Stardust return capsule as a case study. At the end of the paper Mazzarachio pointed the model's excellent agreement with similar literature data(especially with NASA's FIAT model). This result was very expected result because the numerical model Donald M. Curry proposed in 1965 [5] was nearly the same model(even the nodal scheme figures are same). As a further study of this research and ongoing researchs on this field, 2D model can be developed to see surface change of the TPS(since recession will be different depending on the thermal loads) and effects of this change to aerodynamic of the spacecraft can be investigated. Researches will continue for finite element models of this phenomena as well.

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