

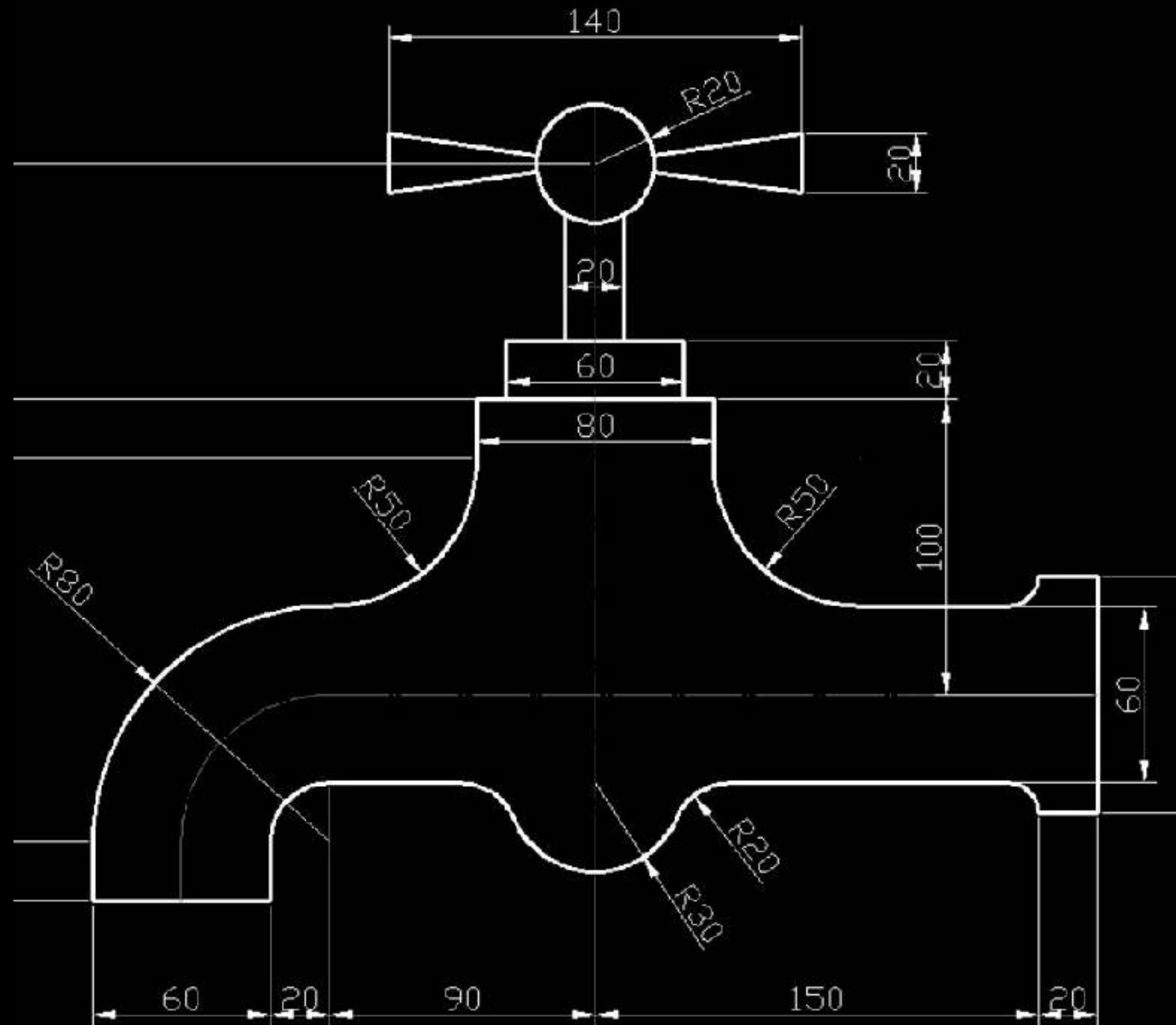
# Introduction to volume rendering

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## 2D drafting/drawing

Points + lines + curves + primitives (circle, rectangle ...)

Describes boundaries



## 2D image

Pixels

Describes the interior of a rectangle, a texture



2D drawings are constructed by various geometric primitives, but isn't suited to representing an image (except inefficiently as a very large number of coloured squares)



### 3D modelling

Points + lines + faces + texture + primitives (sphere, box ...)

Describes surfaces



Empty on the inside

### Volumetric, 3D image

Voxels

Describes interiors

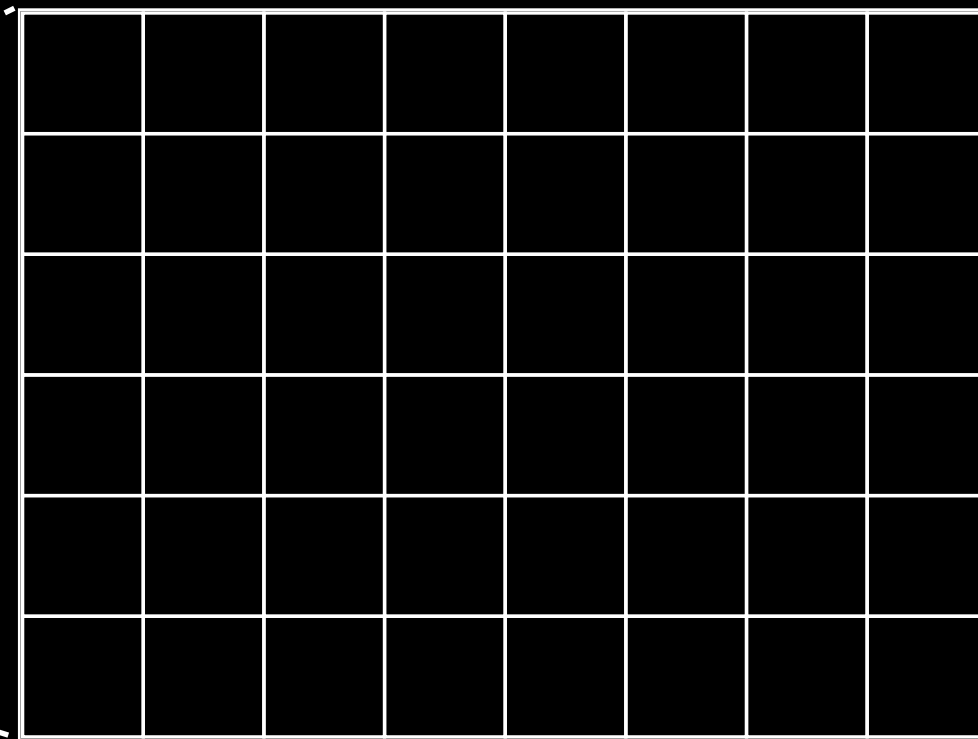
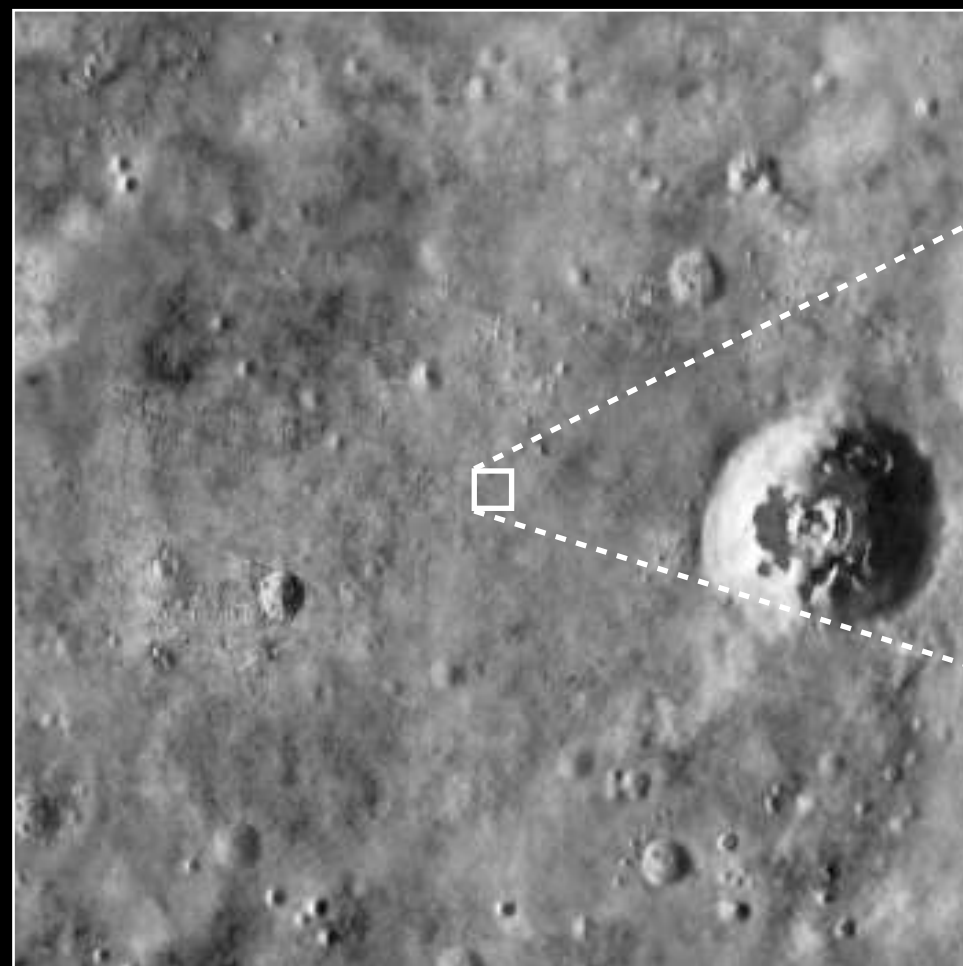


Full on the inside

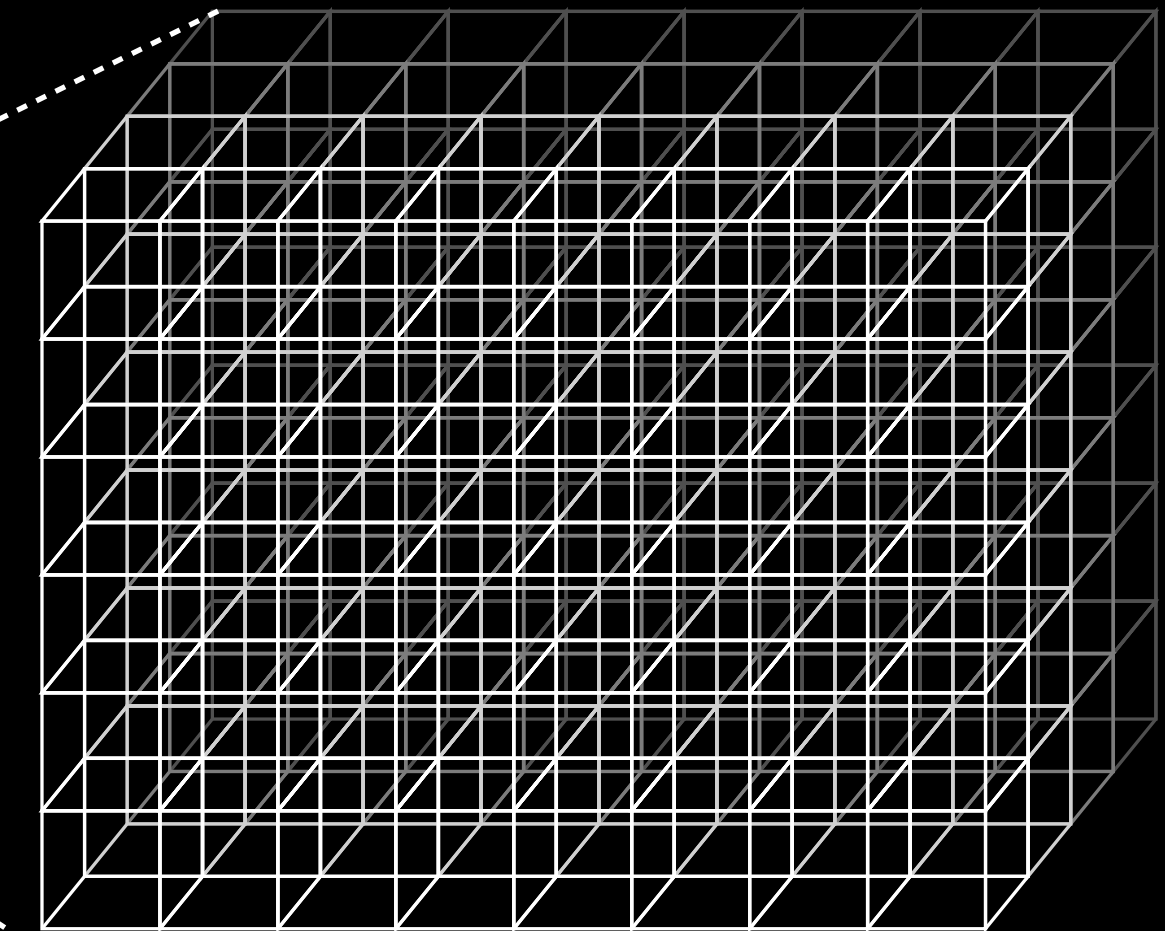
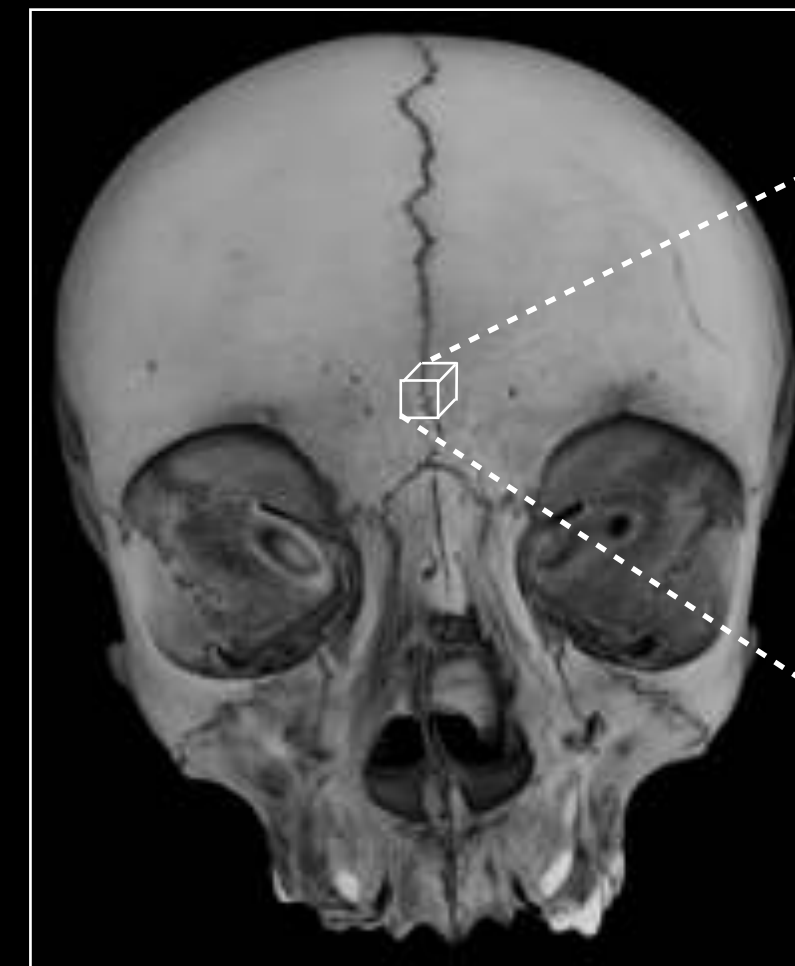
3D models are constructed by various geometric primitives, but not suited to representing a volume (except inefficiently as a very large number of coloured cubes)



**A digital image contains some quantity  
sampled on a regular grid on a 2D plane.**



**In a volumetric dataset there is some quantity  
sampled on a regular 3D grid. Each cell is  
called a VOXEL (VOlumatic piXEL)**



**In each case the value in the pixel or voxel is mapped onto colour and opacity.**

# Wide range of applications

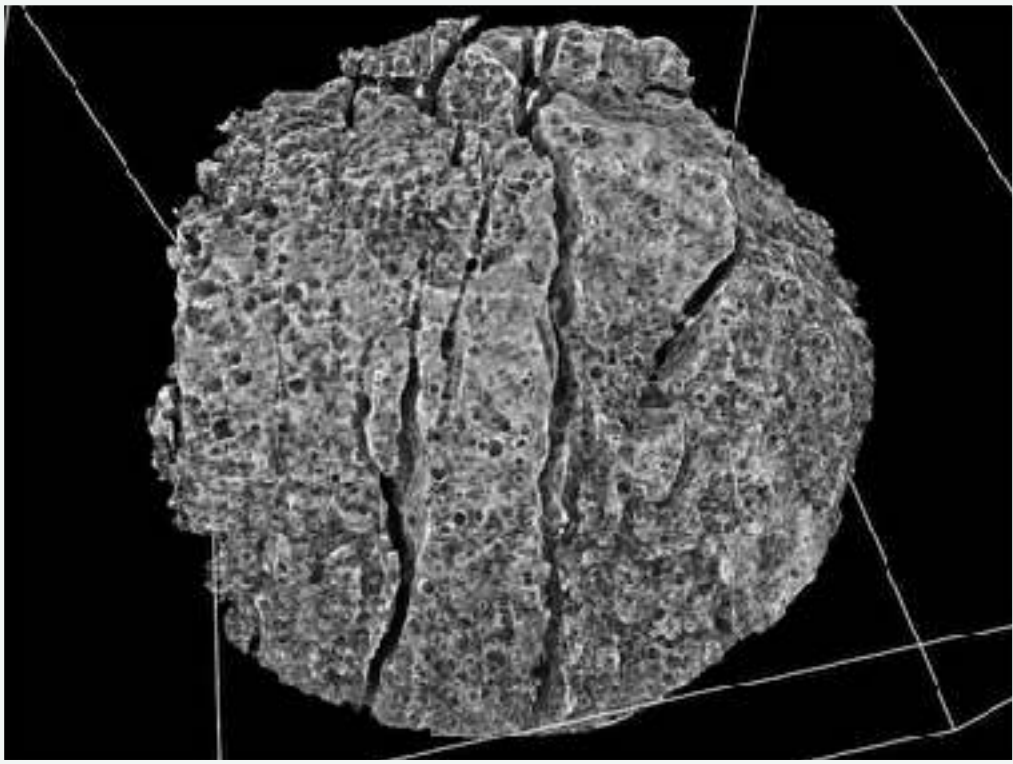
- Very common form of data in the sciences.
- Traditionally one thinks about medical data, for example MRI.  
Other scanning and 3D imaging technologies include CT (MicroCT) and CAT scans.
- Volumetric data also arises from many numerical simulations.  
Quite common in physics (simulations) and engineering (finite element calculations).
- In scanned volumetric datasets the quantity per voxel depends on the scanning technology. For example: MRI essentially gives water content, CT gives density.
- For volumetric datasets derived from simulation there can be multiple variables per voxel.



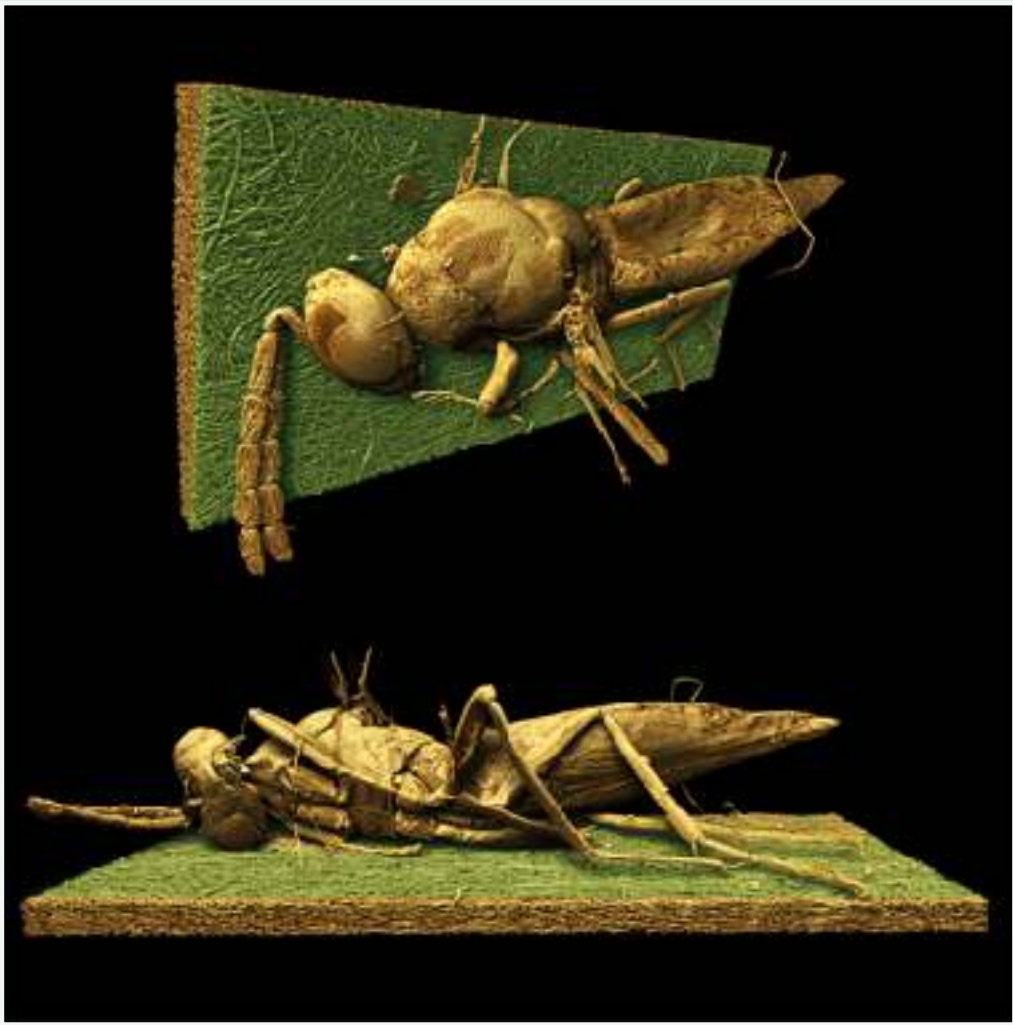
**Medical research (MRI)**



**Geology (CT)**

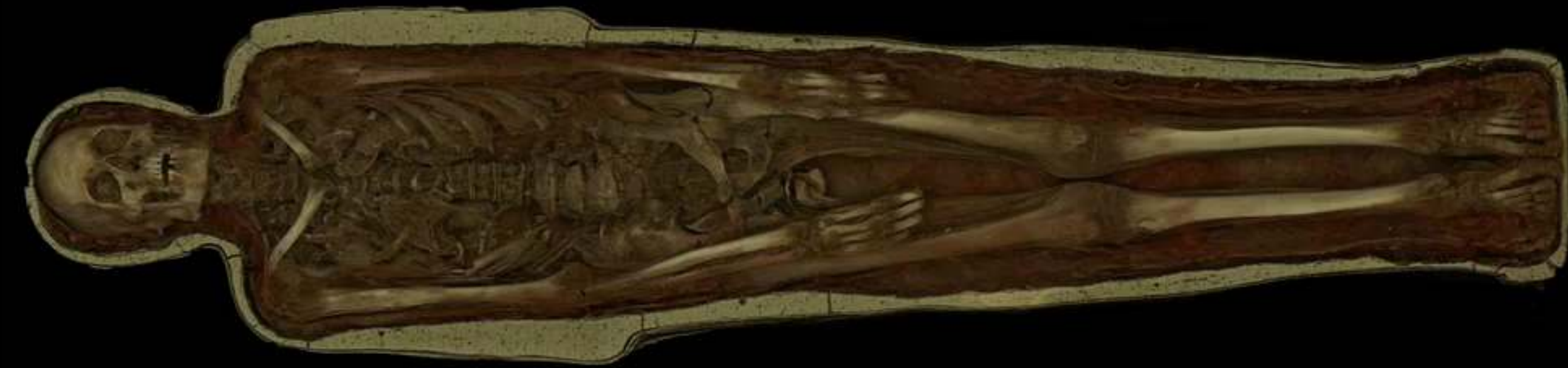


**Entomology**

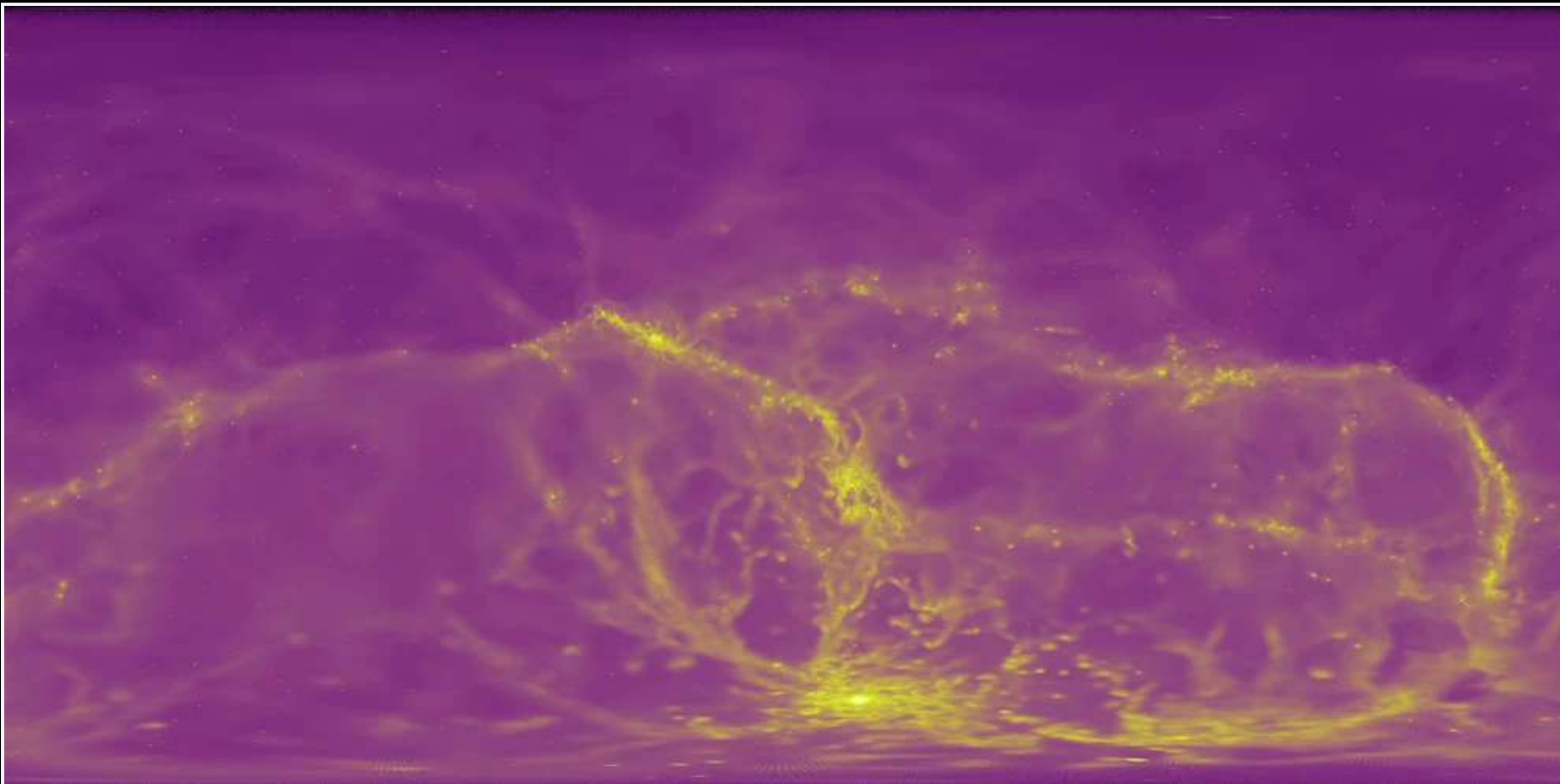


**Rabbits liver, medical research**



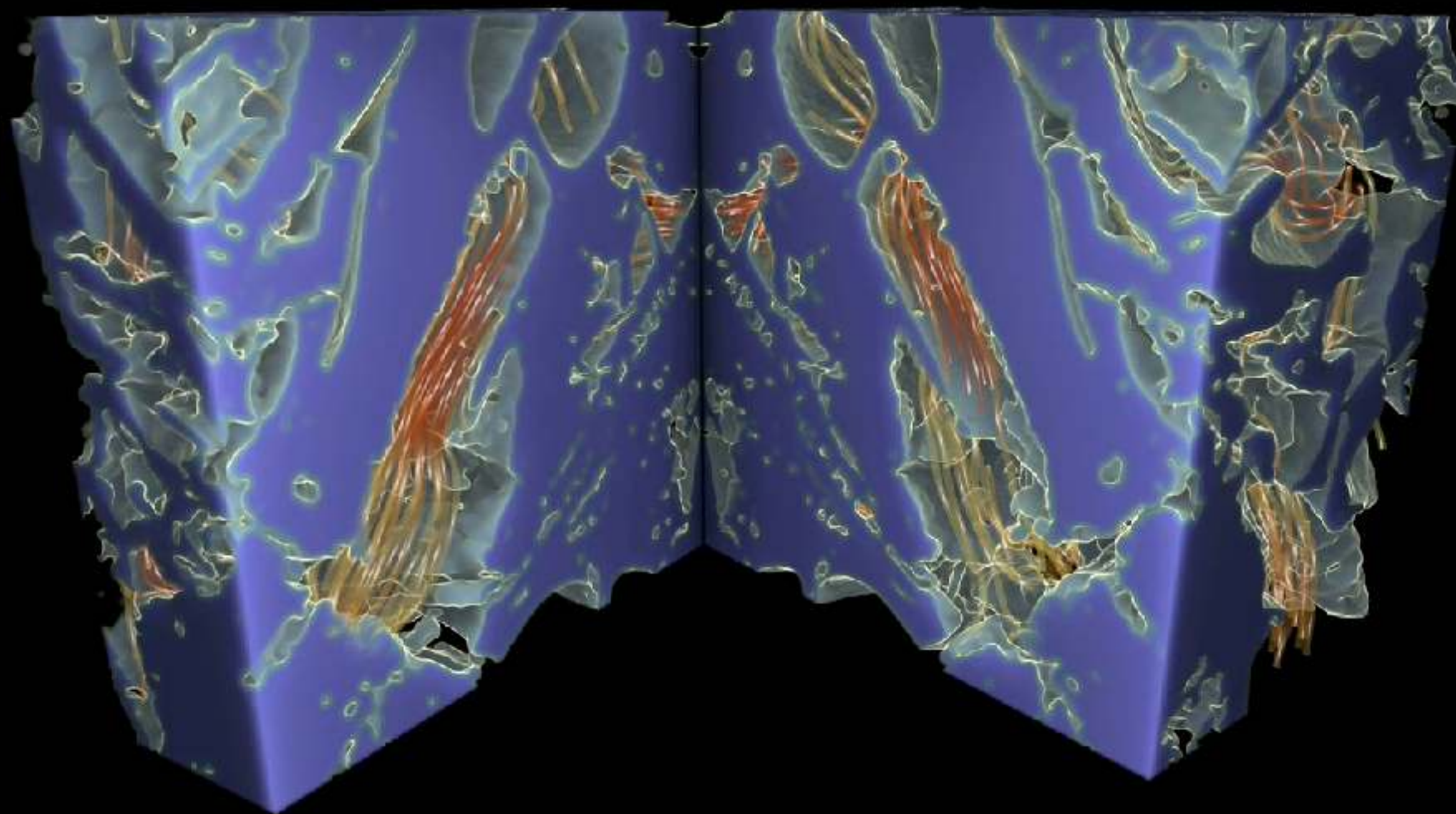


**Egyptology**

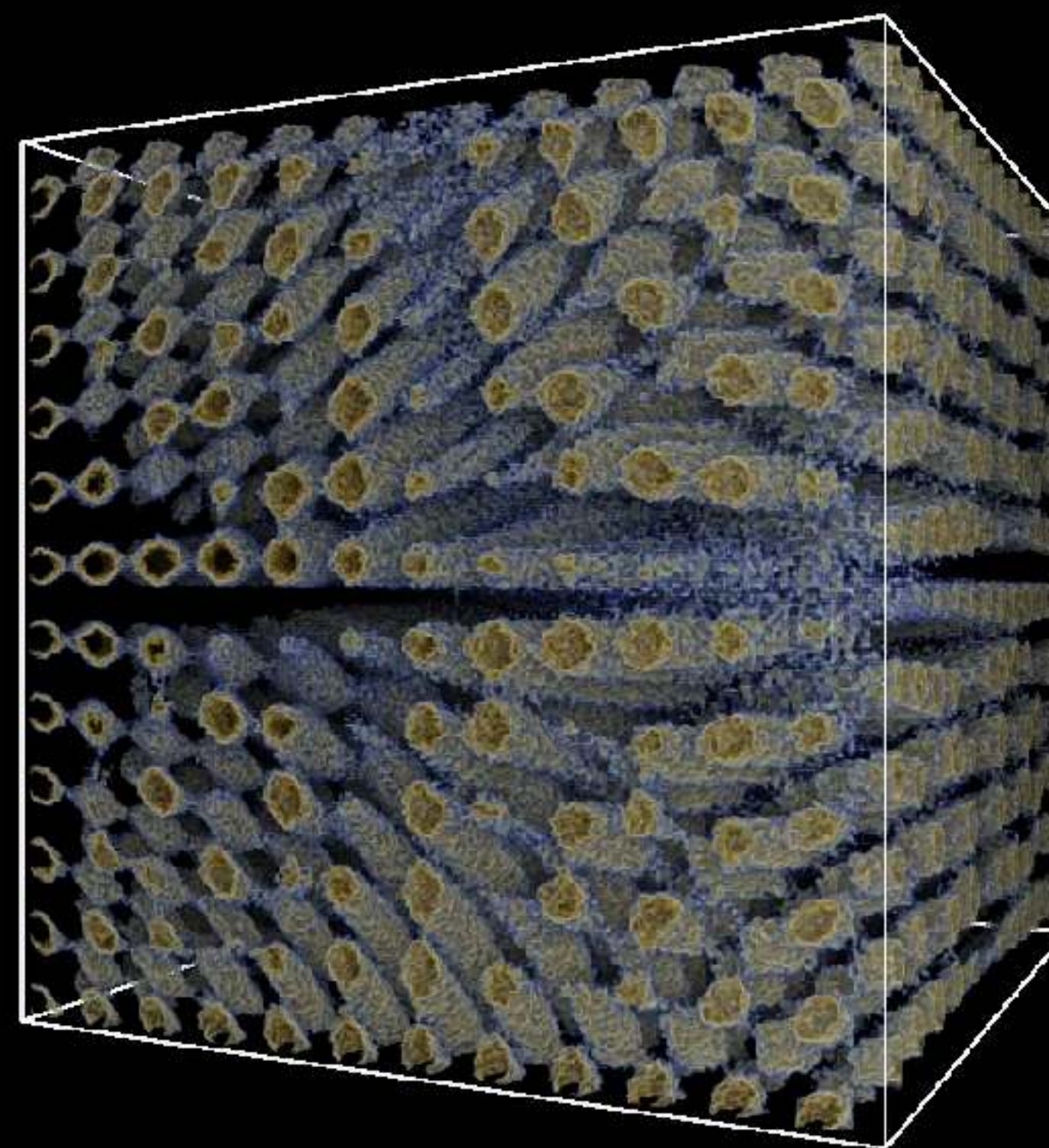


**Astrophysics**





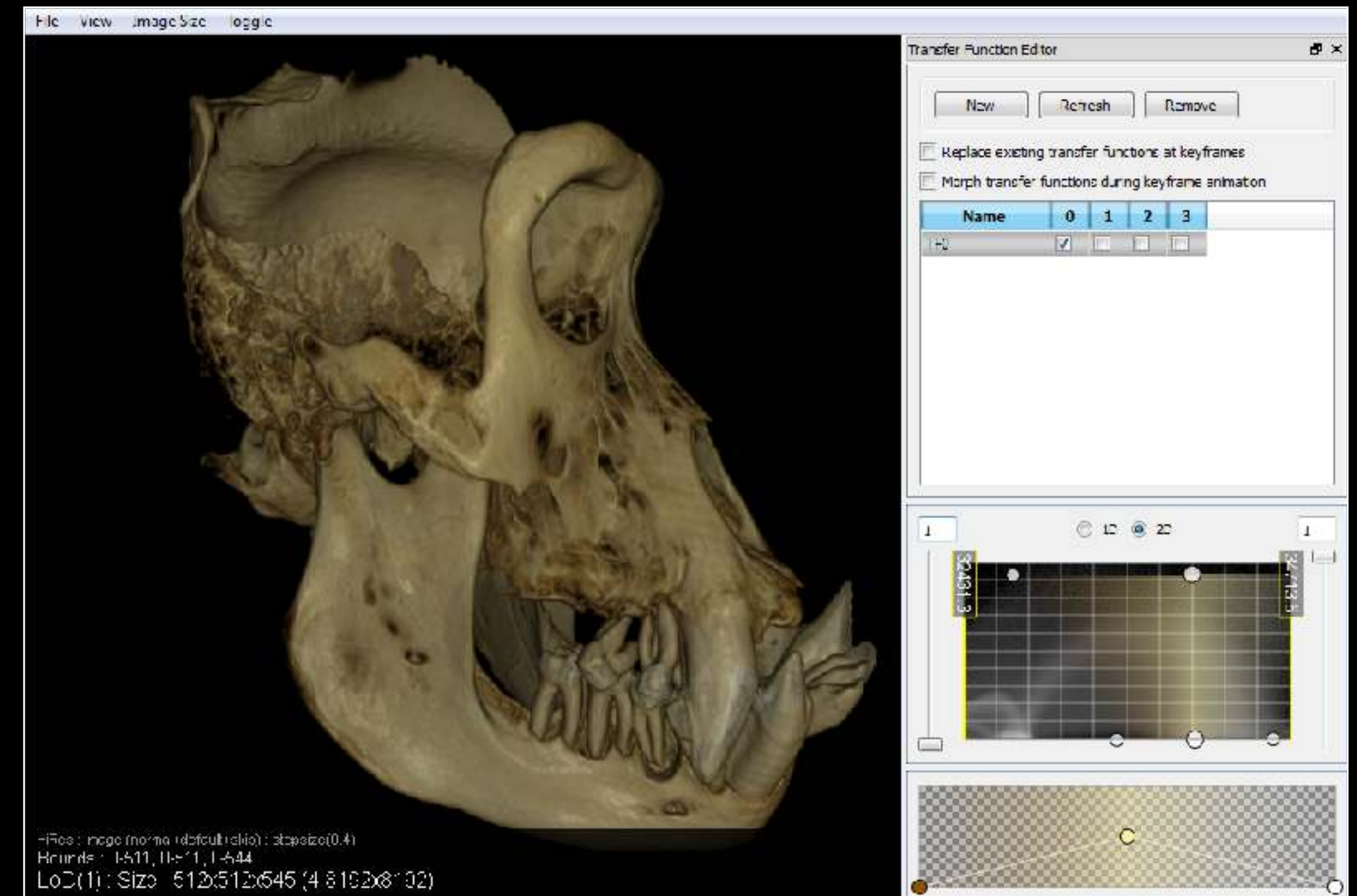
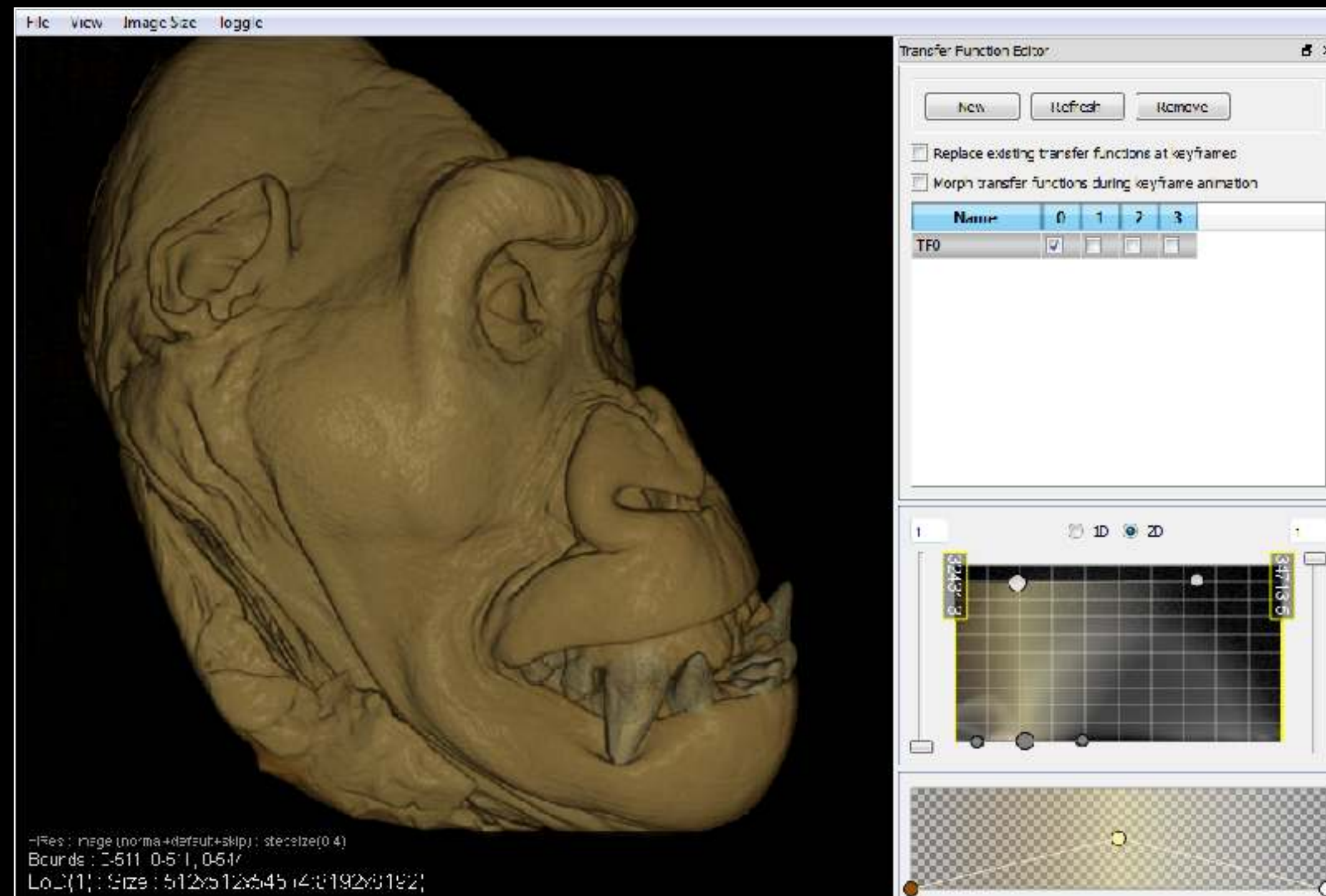
**Fluid flow in porous material, geology**



**Standing waves, nano-science**



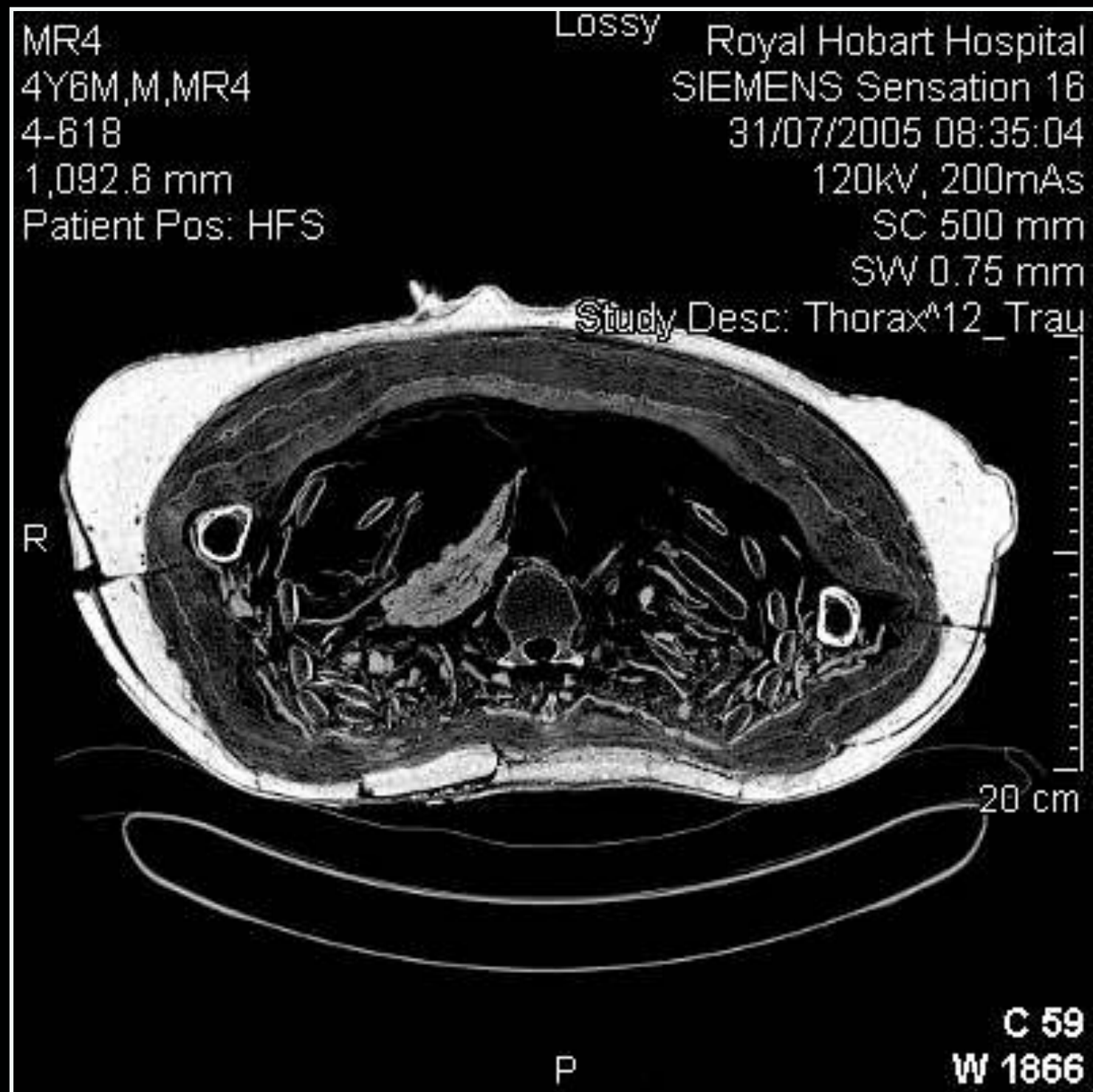
**Volumetric visualisation is the process of exploring and revealing the structure/interior of a volumetric dataset. The general approach involves a mapping between voxel values and colour/opacity.**



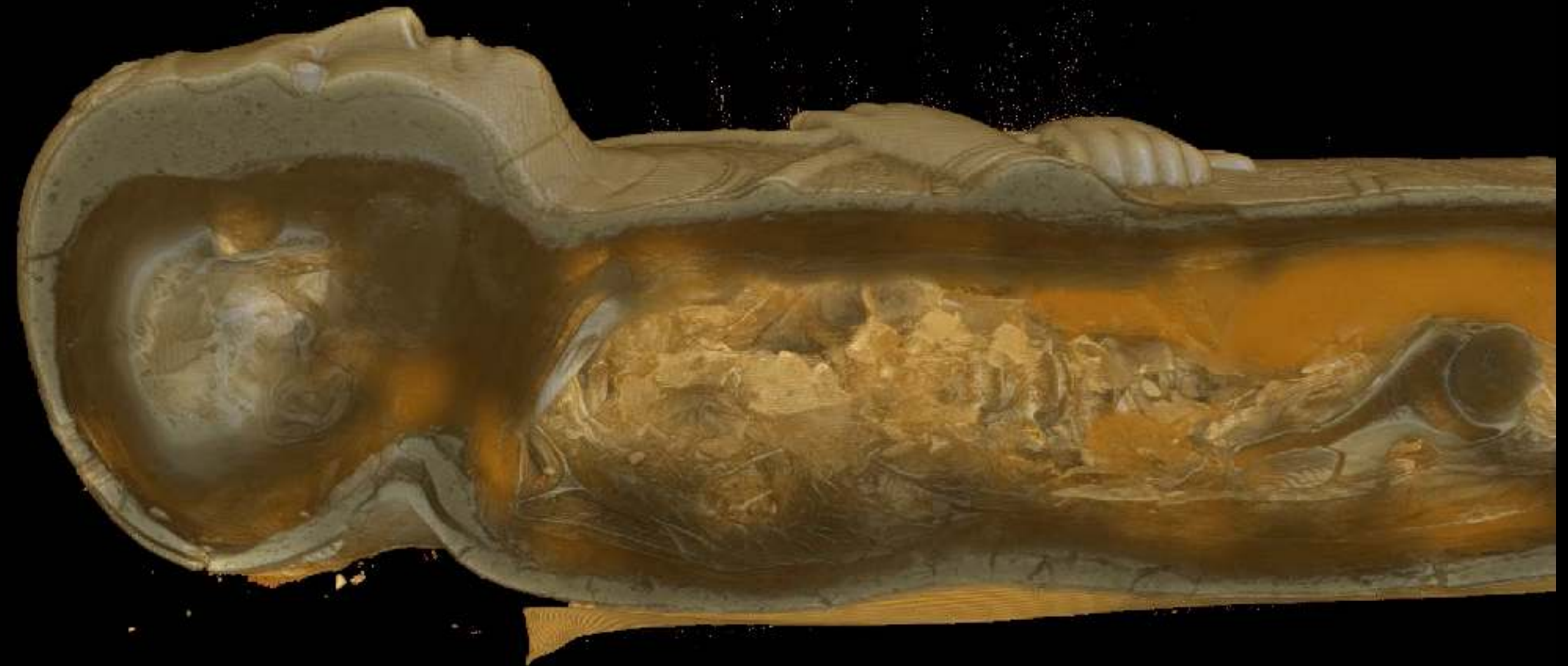
**Same data but different mappings**



**3D scanners typically create multiple 2D sections (bottom left).  
Voxels are not always cubes, often the within slice resolution is higher than between slice resolution.**



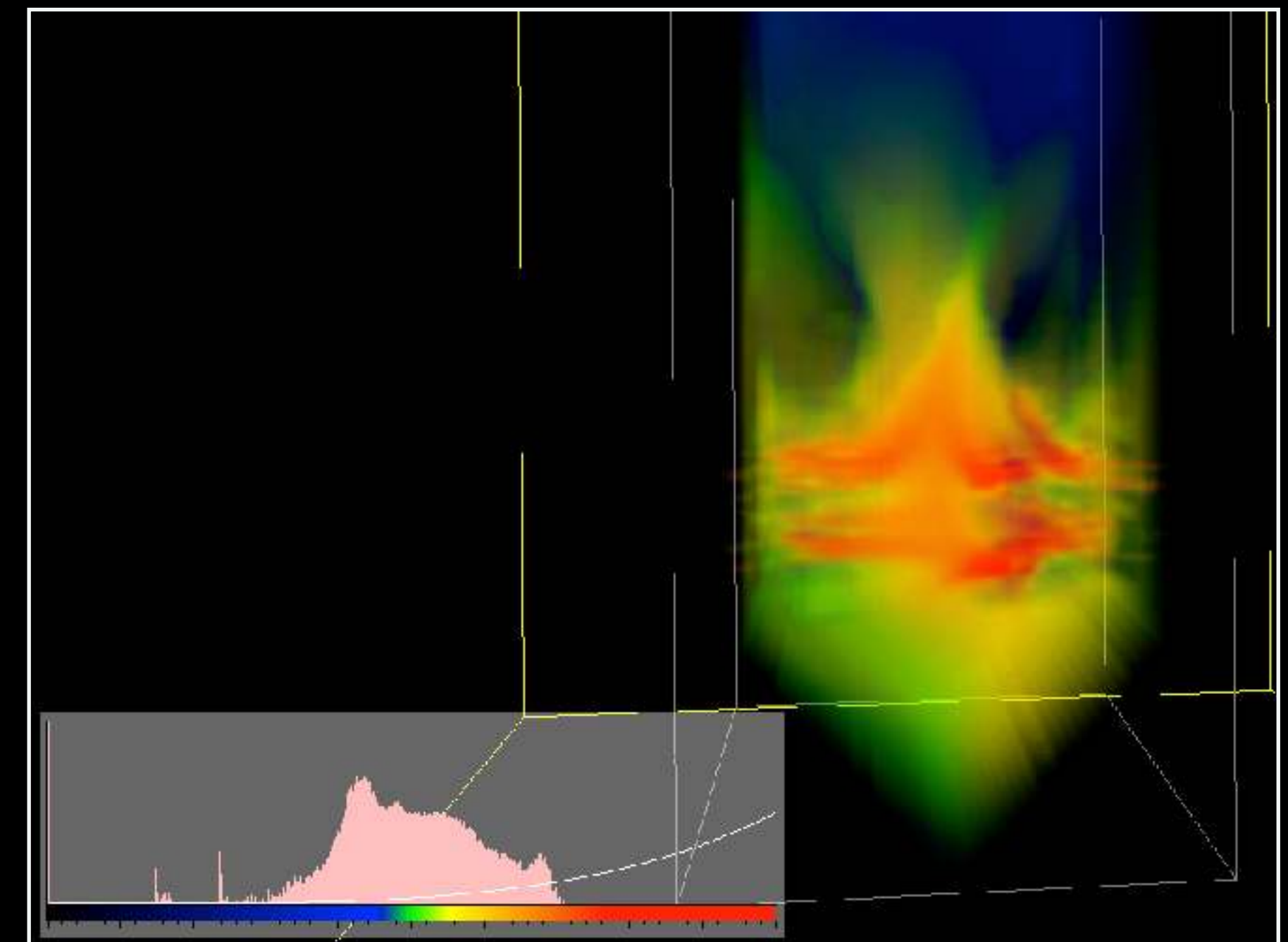
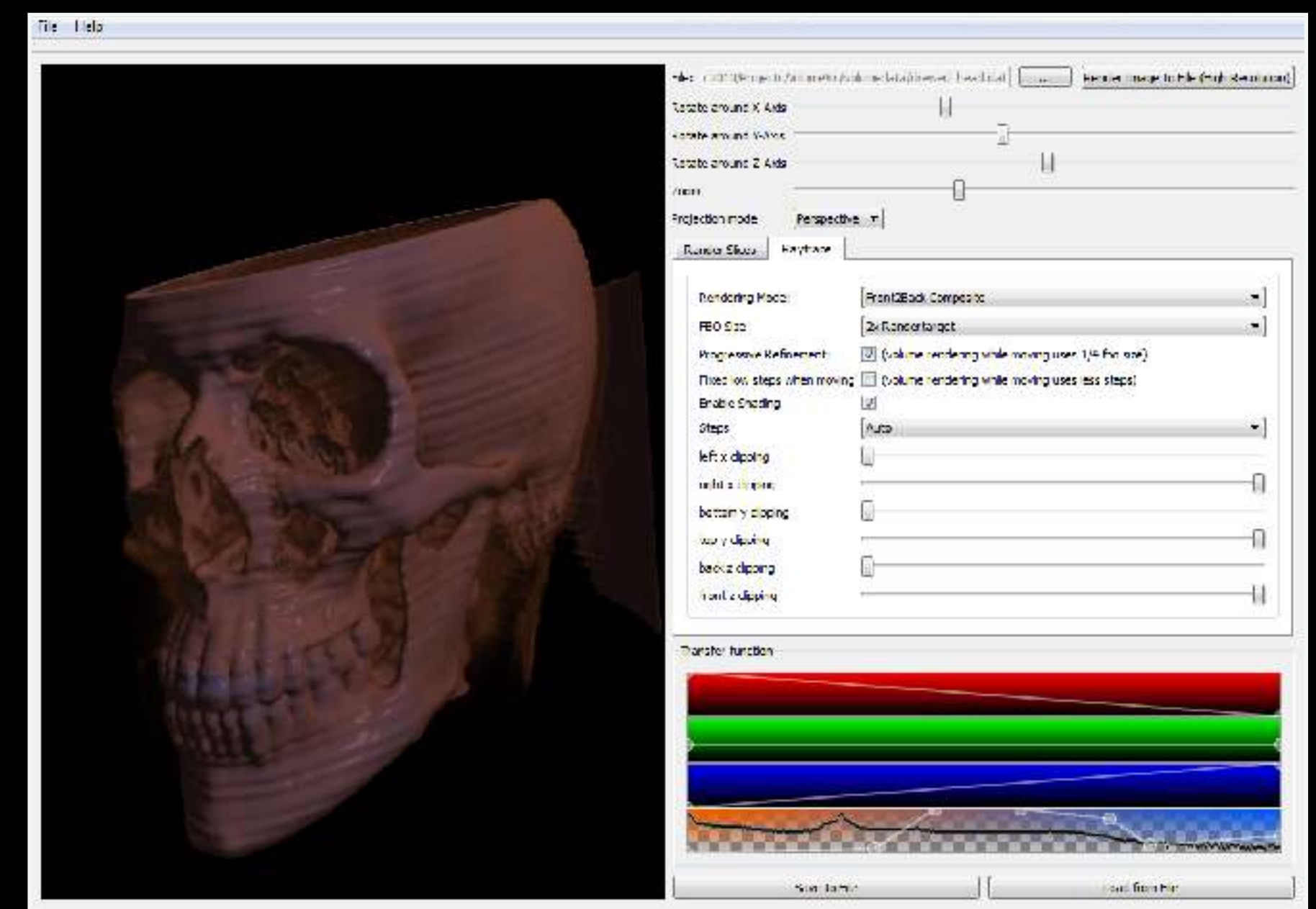
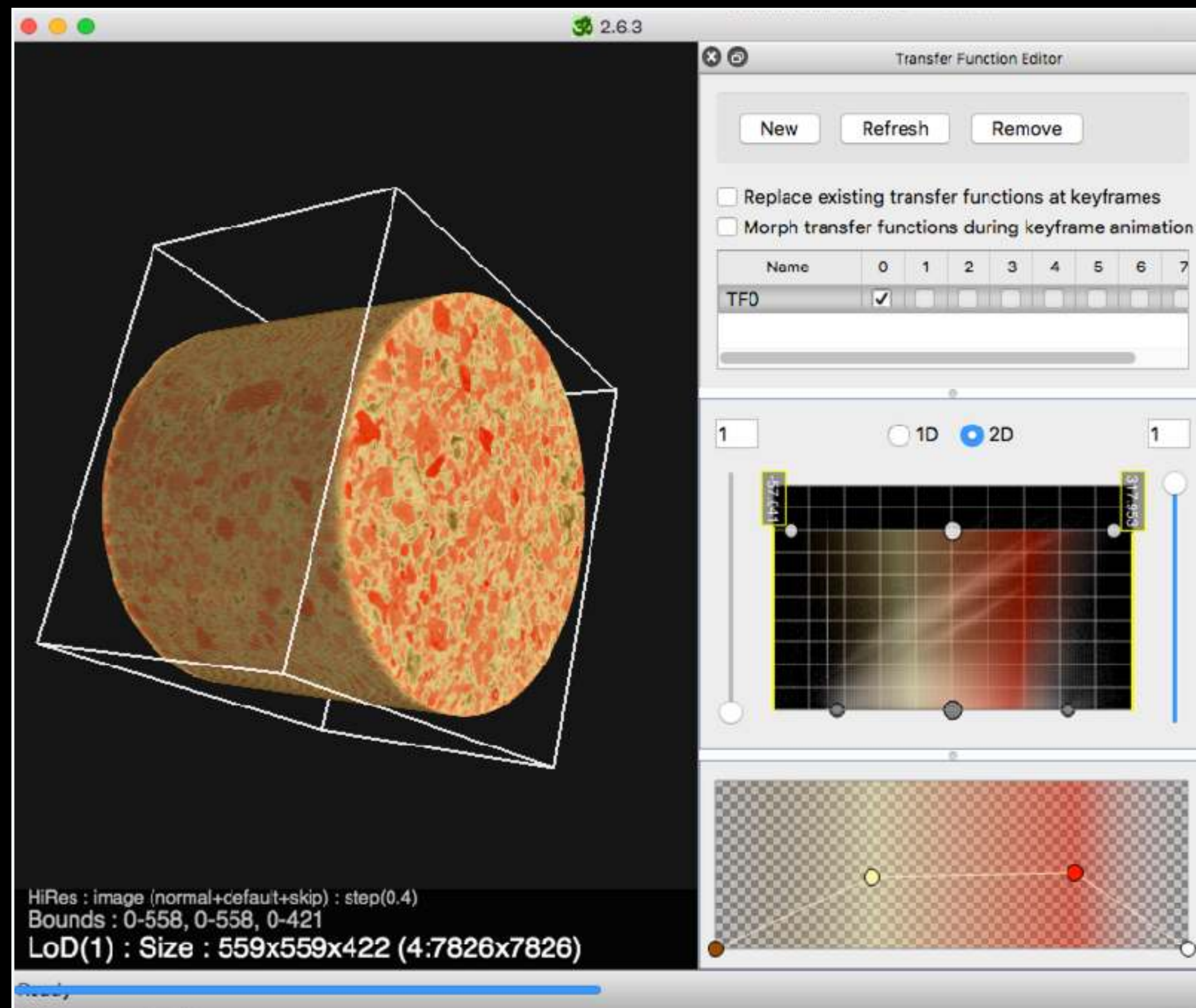
**Slice data from the CT scanner**



**Volume visualisation**



The details of the user interfaces vary but key is how to specify the mapping from voxel value to colour and opacity.





# Data formats

- Medical scanners (and others) generally create DICOM files.  
These are one file per slice but also contains metadata, for example, scanner make/model, date, scanner settings, size of the voxels in world units, subject identifiers, operator name, institution ... and so on.
- Other sources of volumetric data just provide the slices in some more standard image format, for example, jpg, tiff, png ...
- There are some single file containers for the whole volume.  
Typically they have a header giving at least the number of voxels on each axis, the size of the voxels in world units, and the size of the items per voxel (eg; byte, short, int ...)
- No good standards though, many people fall back to a single raw file and the above documented externally.



# Additional notes

- Voxels are rarely cubes except for volumetric data from physics or engineering simulations. Scanners typically create a higher density within each slice compared to the density between slices.
- Voxels are usually all the same size except for some physics and engineering simulations where it may be desirable to have a higher density of voxels in important regions.
- The most common voxel values are single bytes (256 states) or unsigned short integers. But can also be floating point and sometimes can be actual colour values (eg: sliced and photographed objects).
- Researchers have always, since the start of volumetric data visualisation, created volumes at a resolution that is hard to visualise interactively ... despite the advances in realtime computer graphics on the GPU.



**Demonstration**

**Dristhi**

**Means “vision” or “insight” in Sanskrit**

**Developed at the Australian National University by Ajay Limaye**