## Analysis 2 - Hausaufgabe 6

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## Aufgabe 1

## Aufgabe 2

$$\begin{aligned} \operatorname{Sei} \vec{v}(x,y,z) &= \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \operatorname{und} \vec{w}(x,y,z) = \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix}. \\ \operatorname{div} \left( \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \times \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix} \right) &= \begin{pmatrix} \operatorname{rot} \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \cdot \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix} - \begin{pmatrix} v_1 \\ v_2 \\ w_3 \end{pmatrix} \cdot \operatorname{rot} \left( \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix} \right) \\ \Leftrightarrow \operatorname{div} \left( \begin{pmatrix} v_2 w_3 - v_3 w_2 \\ -v_1 w_3 + v_3 w_1 \\ v_1 w_2 - v_2 w_1 \end{pmatrix} \right) &= \begin{pmatrix} \frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \\ \frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \\ \frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \end{pmatrix} \cdot \begin{pmatrix} w_1 \\ w_2 \\ w_3 \end{pmatrix} - \begin{pmatrix} v_1 \\ v_2 \\ v_3 \end{pmatrix} \cdot \begin{pmatrix} \frac{\partial w_3}{\partial y} - \frac{\partial w_2}{\partial z} \\ -\frac{\partial w_3}{\partial x} + \frac{\partial w_1}{\partial z} \\ \frac{\partial w_2}{\partial x} - \frac{\partial w_1}{\partial y} \end{pmatrix} \\ \Leftrightarrow \frac{\partial (v_2 w_3 - v_3 w_2)}{\partial x} + \frac{\partial (-v_1 w_3 + v_3 w_1)}{\partial y} + \frac{\partial (v_1 w_2 - v_2 w_1)}{\partial z} \\ &= w_1 \frac{\partial v_3}{\partial y} - w_1 \frac{\partial v_2}{\partial z} - w_2 \frac{\partial v_3}{\partial x} + w_2 \frac{\partial v_1}{\partial z} + w_3 \frac{\partial v_2}{\partial x} - w_3 \frac{\partial v_1}{\partial y} \\ &- v_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial z} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial z} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial y} \\ &= w_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial z} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial z} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial y} \\ &= w_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial z} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial z} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial y} \\ &= w_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial z} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial z} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial y} \\ &= w_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial z} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial z} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial y} \\ &= w_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial z} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial z} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial x} \\ &= w_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial z} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial x} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial y} \\ &= w_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial z} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial x} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial x} \\ &= w_1 \frac{\partial w_3}{\partial y} + v_1 \frac{\partial w_2}{\partial x} + v_2 \frac{\partial w_3}{\partial x} - v_2 \frac{\partial w_1}{\partial x} - v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial x} \\ &= w_1 \frac{\partial w_3}{\partial x} + v_3 \frac{\partial w_1}{\partial x} + v_3 \frac{\partial w_2}{\partial x} + v_3 \frac{\partial w_1}{\partial x} \\ &= w_1 \frac{\partial w_3}{\partial x} + v_3 \frac{\partial w_1}{\partial x} + v_3 \frac{$$

## Aufgabe 3