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Q) Create a 4– way traffic control signal using arduino. Submit word file and simulation video

ANSWER:

```
void setup()
```

```
{
```

```
    pinMode(1, OUTPUT);
```

```
    pinMode(2, OUTPUT);
```

```
    pinMode(3, OUTPUT);
```

```
    pinMode(4, OUTPUT);
```

```
    pinMode(5, OUTPUT);
```

```
    pinMode(6, OUTPUT);
```

```
    pinMode(7, OUTPUT);
```

```
    pinMode(8, OUTPUT);
```

```
    pinMode(9, OUTPUT);
```

```
    pinMode(10, OUTPUT);
```

```
    pinMode(11, OUTPUT);
```

```
    pinMode(12, OUTPUT);
```

```
}
```

```
void loop()
```

```
{
```

```
    int r1=1;
```

```
    int y1=2;
```

```
    int g1=3;
```

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```
int r2=4;
```

```
int y2=5;
```

```
int g2=6;
```

```
int r3=7;
```

```
int y3=8;
```

```
int g3=9;
```

```
int r4=10;
```

```
int y4=11;
```

```
int g4=12;
```

```
digitalWrite(r1,HIGH);
```

```
digitalWrite(g2,HIGH);
```

```
digitalWrite(g3,HIGH);
```

```
digitalWrite(r4,HIGH);
```

```
delay(30000);
```

```
digitalWrite(r1,LOW);
```

```
digitalWrite(g1,LOW);
```

```
digitalWrite(y1,LOW);
```

```
digitalWrite(g2,LOW);
```

```
digitalWrite(r2,LOW);
```

```
digitalWrite(y2,LOW);
```

```
digitalWrite(r3,LOW);
```

```
digitalWrite(g3,LOW);
```

```
digitalWrite(y3,LOW);
```

```
digitalWrite(g4,LOW);
```

```
digitalWrite(r4,LOW);
```

```
digitalWrite(y4,LOW);
```

```
digitalWrite(y1,HIGH);
```

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```
digitalWrite(y2,HIGH);  
digitalWrite(y3,HIGH);  
digitalWrite(y4,HIGH);  
delay(10000);  
digitalWrite(r1,LOW);  
digitalWrite(g1,LOW);  
digitalWrite(y1,LOW);  
digitalWrite(g2,LOW);  
digitalWrite(r2,LOW);  
digitalWrite(y2,LOW);  
digitalWrite(r3,LOW);  
digitalWrite(g3,LOW);  
digitalWrite(y3,LOW);  
digitalWrite(g4,LOW);  
digitalWrite(r4,LOW);  
digitalWrite(y4,LOW);
```

```
digitalWrite(g1,HIGH);  
digitalWrite(r2,HIGH);  
digitalWrite(r3,HIGH);  
digitalWrite(g4,HIGH);  
delay(30000);  
digitalWrite(r1,LOW);  
digitalWrite(g1,LOW);  
digitalWrite(y1,LOW);  
digitalWrite(g2,LOW);  
digitalWrite(r2,LOW);  
digitalWrite(y2,LOW);  
digitalWrite(r3,LOW);
```

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```
digitalWrite(g3,LOW);  
digitalWrite(y3,LOW);  
digitalWrite(g4,LOW);  
digitalWrite(r4,LOW);  
digitalWrite(y4,LOW);  
  
digitalWrite(y1,HIGH);  
digitalWrite(y2,HIGH);  
digitalWrite(y3,HIGH);  
digitalWrite(y4,HIGH);  
delay(10000);  
digitalWrite(y1,LOW);  
digitalWrite(y2,LOW);  
digitalWrite(y3,LOW);  
digitalWrite(y4,LOW);  
  
}
```

Q) Differentiate between pull-up and pull-down resistor configuration

ANSWER:

PULL UP RESISTOR:

- Makes the default value of digital pin as HIGH.
- It's the most commonly used resistor.
- It provides current when the circuit is OPEN.

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PULL DOWN RESISTOR:

- Makes the default value of digital pin as LOW.
- It's the less commonly used resistor.
- It provides current when the circuit is CLOSED.