Big picture
Rvalue references
Variadic templates
Rvalue references + variadic templates
Conclusion

C++11 tour What will change for library designers?

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24 July 2012

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Outline

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- Product value should increase

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- C++1x (C++17?) is already in the tubes

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- Copying a temporary might be very expensive
- No easy solution
- We have to hope that "return value optimisation" (RVO) kicks in
- What happens with complex formulas mixing a lot of operators?

Avoid deep-copying temporaries

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 Simply recompiling code with a move-enabled STL may increase performances Create a move constructor

```
template <typename T> class Matrix
{
  public:
    Matrix(int n, int m) : data(new T[n * m]) { }
    "Matrix() { delete data; }
    Matrix (Matrix & tmp)
    {
      data = tmp.data;
      tmp.data = 0;
    }
    T* data;
};
  Matrix < double > m(3, 3);
  // m.data == 0x9973008
  Matrix < double > n = std::move(m);
  // m.data == 0
  // n.data == 0x9973008
```

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Challenge: write a 'min' function which takes an arbitrary number of arguments of any type and returns the smallest in C++03.

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Challenge: write a 'min' function which takes an arbitrary number of arguments of any type and returns the smallest in C++03.

To support up to N arguments there needs to be N overloads...



Introducing variadic templates

 Combination of the old '...' (think of printf) and classic templates

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Introducing variadic templates

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```
template <typename T>
const T& min(const T& a, const T& b)
{
   return a < b ? a : b;
}

template <typename T, typename... Args>
const T& min(const T& a, const T& b, const Args&... args)
{
   return min(a, min(b, args...));
}
```

Very efficient thanks to inlining

A typesafe printf!

```
template <typename T>
void print(const T& t)
{
  std::cout << t;
}
template <typename T, typename... Ts>
void print(const T& t, const Ts&... tail)
{
  print(t);
 print(tail...);
print("There are ", 3, " arguments!", std::endl);
```

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Writing a generic "make_shared" function which **constructs** the object.

Either:

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- Add constraints on the type, typically being default constructible

Problem

Writing a generic "make_shared" function which **constructs** the object.

Either:

- Create a lot of overloads...
- Add constraints on the type, typically being default constructible
- ...don't construct the object but take a pointer to an already constructed object...

```
boost::shared_ptr <std::string > sptr =
boost::make_shared_ptr(new std::string("..."));
```



Perfect forwarding to the rescue!

• Rvalue references + variadic templates = perfect forwarding

```
template <typename T, typename... Args>
std::shared_ptr<T> make_shared(Args&&... args)
{
    std::shared_ptr<T> p(new T(std::forward<Args>(args)...));
    return p;
}
std::shared_ptr<std::string> sptr =
    make_shared<std::string>("...");
```

Perfect forwarding to the rescue!

Rvalue references + variadic templates = perfect forwarding

```
template <typename T, typename ... Args>
std::shared_ptr<T> make_shared(Args&&... args)
  std::shared_ptr<T> p(new T(std::forward<Args>(args)...));
  return p;
std::shared_ptr<std::string> sptr =
  make_shared < std :: string > (" . . . ");

    Used in the STL to create emplace_* methods

int main()
  std::vector<std::string> strings;
  strings.emplace_back("This is a test!");
```

strings.emplace_back(42, 'a');

}

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http://www2.research.att.com/~bs/C++0xFAQ.html

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As library designers:

- More powerful and safe interfaces
- Better performances with simpler designs
- And this with a better maintainability

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As library users:

- More powerful and safe interfaces
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There is much more!

• We only scratched the surface of C++11

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- Code bloat should decrease while features should increase
- We will see new paradigms emerge from the new core features

Bibliography

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- Bjarne Stroustrup: http://www2.research.att.com/~bs/
- C++Next: http://cpp-next.com/



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Questions?

Mixins

```
struct HasPosition
{
  double path_cost(int dest) const { /*...*/ }
  int position;
};
struct HasShape { /* ... */ };
template <typename... Mixins>
class Object : public Mixins...
{
};
int main()
{
  Object < HasPosition > waypoint;
  Object < HasPosition, HasShape > building;
}
```

Type inference

```
template <template <class...> class Cont,
          typename Fun, typename ... Args>
auto map(const Cont<Args...>& c, Fun f)
  -> Cont < decltype (f (*c.begin()))>
{
  typedef decltype(f(*c.begin())) map_type;
  Cont < map_type > out;
  for (const auto& e : c)
    out.emplace_back(f(e));
 return std::move(out);
}
int main()
{
  std::vector < int > v = {42, 51};
  auto s = map(v, [](int n) { return std::to_string(n); });
}
```