

# Derivation of the Energy-Balance Equations

in the DAFx-23 paper entitled

## TUNABLE COLLISIONS: HAMMER-STRING SIMULATION WITH TIME-VARIANT PARAMETERS

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### 1 Continuous-Domain Energy Balance: Equations (26) and (27)

We start with equation (21) in the paper:

$$d_t^2 \mathbf{u} + \mathbf{R} d_t \mathbf{u} + \mathbf{K} \mathbf{u} = \mathbf{h} \bar{F}_c,$$

and pre-multiply with  $(d_t \mathbf{u})^T$ , which yields

$$(d_t \mathbf{u})^T d_t^2 \mathbf{u} + (d_t \mathbf{u})^T \mathbf{R} d_t \mathbf{u} + (d_t \mathbf{u})^T \mathbf{K} \mathbf{u} = (\mathbf{h})^T d_t \mathbf{u} \bar{F}_c. \quad (1.1)$$

Now consider the following product-rule identities:

$$d_t [(d_t \mathbf{u})^T d_t \mathbf{u}] = 2(d_t \mathbf{u})^T d_t^2 \mathbf{u}, \quad (1.2)$$

$$d_t \bar{u}_s = d_t (\mathbf{h}^T \mathbf{u}) = \mathbf{h}^T d_t \mathbf{u} + (d_t \mathbf{h})^T \mathbf{u} \quad (1.3)$$

$$d_t (\mathbf{u}^T \mathbf{K} \mathbf{u}) = 2(d_t \mathbf{u})^T \mathbf{K} \mathbf{u} + \mathbf{u}^T (d_t \mathbf{K}) \mathbf{u}, \quad (1.4)$$

which we may use directly to substitute the relevant terms in (1.1):

$$d_t \underbrace{\left[ \left( \frac{1}{2} d_t \mathbf{u} \right)^T d_t \mathbf{u} + \frac{1}{2} (\mathbf{u}^T \mathbf{K} \mathbf{u}) \right]}_{\bar{H}_{\text{str}}} = -(d_t \mathbf{u})^T \mathbf{R} d_t \mathbf{u} + \frac{1}{2} \mathbf{u}^T (d_t \mathbf{K}) \mathbf{u} + [d_t \bar{u}_s - (d_t \mathbf{h})^T \mathbf{u}] \bar{F}_c, \quad (1.5)$$

where  $\bar{H}_{\text{str}}$  denotes the scaled-form energy of the string. Now consider equation (10) of the paper:

$$d_t \{ \bar{m}_h d_t \bar{u}_h \} = \bar{F}_e - \bar{F}_c,$$

and multiply with  $d_t \bar{u}_h$ , which gives

$$d_t \bar{u}_h d_t \{ \bar{m}_h d_t \bar{u}_h \} = d_t \bar{u}_h \bar{F}_e - d_t \bar{u}_h \bar{F}_c. \quad (1.6)$$

The following product-rule identities hold:

$$d_t \{ \bar{m}_h d_t \bar{u}_h \} = d_t \bar{m}_h d_t \bar{u}_h + \bar{m}_h d_t^2 \bar{u}_h \quad (1.7)$$

$$d_t [(d_t u_h)^2] = 2 d_t u_h d_t^2 u_h. \quad (1.8)$$

By substitution into (1.6) one obtains:

$$d_t \left[ \underbrace{\frac{1}{2} \bar{m}_h (d_t u_h)^2}_{\bar{H}_h} \right] = -d_t \bar{m}_h (d_t \bar{u}_h)^2 + d_t \bar{u}_h \bar{F}_e - d_t \bar{u}_h \bar{F}_c, \quad (1.9)$$

where  $\bar{H}_h$  denotes the scaled-form kinetic energy of the hammer. Now let's add equations (1.5) and (1.9) and obtain:

$$d_t [\bar{H}_{\text{str}} + \bar{H}_h] = -(d_t \mathbf{u})^T \mathbf{R} d_t \mathbf{u} + \frac{1}{2} \mathbf{u}^T (d_t \mathbf{K}) \mathbf{u} + d_t \underbrace{[\bar{u}_s - \bar{u}_h]}_{\bar{y}} \bar{F}_c - (d_t \mathbf{h})^T \mathbf{u} \bar{F}_c - d_t \bar{m}_h (d_t \bar{u}_h)^2 + d_t \bar{u}_h \bar{F}_e. \quad (1.10)$$

From equation (16) in the paper we have

$$\bar{F}_c = -\psi \partial_{\bar{y}} \psi = -\psi \frac{d_t \psi}{d_t \bar{y}} = -\frac{d_t (\frac{1}{2} \psi^2)}{d_t \bar{y}} + \psi \frac{(g_{\bar{\kappa}} d_t \bar{\kappa} + g_{\alpha} d_t \alpha)}{d_t \bar{y}}.$$

Substitution into (1.10) yields

$$d_t \left[ \bar{H}_{\text{str}} + \bar{H}_h + \frac{1}{2} \psi^2 \right] = -(d_t \mathbf{u})^T \mathbf{R} d_t \mathbf{u} + \frac{1}{2} \mathbf{u}^T (d_t \mathbf{K}) \mathbf{u} - (d_t \mathbf{h})^T \mathbf{u} \bar{F}_c + d_t \bar{u}_h \bar{F}_e - (d_t \bar{u}_h)^2 d_t \bar{m}_h + \psi (g_{\bar{\kappa}} d_t \bar{\kappa} + g_{\alpha} d_t \alpha), \quad (1.11)$$

which is the result expressed in equations (25) and (26) of the paper.

## 2 Discrete-Domain Energy Balance: Equations (58) and (59)

Let's start with equation (38) of the paper:

$$\delta_t^2 \mathbf{u}^n + \hat{\mathbf{R}}^n \delta_t \mathbf{u}^n + \mu_t^2 \hat{\mathbf{K}}^n \mu_t^2 \mathbf{u}^n = \bar{F}_c^n \mu_t \mathbf{h}^n,$$

and pre-multiply with  $(\delta_t \mathbf{u}^n)^T$ , which yields:

$$(\delta_t \mathbf{u}^n)^T \delta_t^2 \mathbf{u}^n + (\delta_t \mathbf{u}^n)^T \hat{\mathbf{R}}^n \delta_t \mathbf{u}^n + (\delta_t \mathbf{u}^n)^T \mu_t^2 \hat{\mathbf{K}}^n \mu_t^2 \mathbf{u}^n = (\delta_t \mathbf{u}^n)^T \mu_t \mathbf{h}^n \bar{F}_c^n. \quad (2.1)$$

To make further useful manipulations, we must first consider the product identities articulated in equation (36) of the paper:

$$\delta_t \{ (\delta_t u^n)^2 \} = 2 \delta_t u^n \delta_t^2 u^n,$$

$$\delta_t \{(\mu_t u^n)^2\} = 2\delta_t \cdot u^n \mu_t^2 u^n.$$

From these we may derive that

$$\begin{aligned} \delta_t \cdot u^n \delta_t^2 u^n + \mu_t^2 k^n \delta_t \cdot u^n \mu_t^2 u^n &= \delta_t \left\{ \overbrace{\frac{1}{2}(\delta_t u^n)^2}^{T^n} \right\} + \mu_t^2 k^n \delta_t \left\{ \frac{1}{2}(\mu_t u^n)^2 \right\} \\ &= \delta_t T^n + \frac{1}{2\Delta_t} \left[ \mu_t^2 k^n (\mu_t u^{n+\frac{1}{2}})^2 - \mu_t^2 k^n (\mu_t u^{n-\frac{1}{2}})^2 \right] \\ &= \delta_t T^n + \frac{1}{2\Delta_t} \left[ \frac{\mu_t k^{n+\frac{1}{2}} + \mu_t k^{n-\frac{1}{2}}}{2} (\mu_t u^{n+\frac{1}{2}})^2 - \frac{\mu_t k^{n+\frac{1}{2}} + \mu_t k^{n-\frac{1}{2}}}{2} (\mu_t u^{n-\frac{1}{2}})^2 \right] \\ &= \delta_t T^n + \frac{1}{\Delta_t} \left[ \underbrace{\frac{1}{2} \mu_t k^{n+\frac{1}{2}} (\mu_t u^{n+\frac{1}{2}})^2}_{V^{n+\frac{1}{2}}} - \underbrace{\frac{1}{2} \mu_t k^{n-\frac{1}{2}} (\mu_t u^{n-\frac{1}{2}})^2}_{V^{n-\frac{1}{2}}} \right] \\ &\quad - \frac{1}{4\Delta_t} \left[ (\mu_t k^{n+\frac{1}{2}} - \mu_t k^{n-\frac{1}{2}}) (\mu_t u^{n+\frac{1}{2}})^2 - (\mu_t k^{n-\frac{1}{2}} - \mu_t k^{n+\frac{1}{2}}) (\mu_t u^{n-\frac{1}{2}})^2 \right] \\ &= \delta_t \{T^n + V^n\} - \underbrace{\frac{1}{2} \left[ \frac{\mu_t k^{n+\frac{1}{2}} - \mu_t k^{n-\frac{1}{2}}}{\Delta_t} \right]}_{\delta_t \cdot k^n} \underbrace{\left[ \frac{(\mu_t u^{n+\frac{1}{2}})^2 + (\mu_t u^{n-\frac{1}{2}})^2}{2} \right]}_{\mu_t \{(\mu_t u^n)^2\}} \\ &= \delta_t \{T^n + V^n\} - \left[ \frac{1}{4} \mu_t u^{n+\frac{1}{2}} \delta_t \cdot k^n \mu_t u^{n+\frac{1}{2}} + \frac{1}{4} \mu_t u^{n-\frac{1}{2}} \delta_t \cdot k^n \mu_t u^{n-\frac{1}{2}} \right]. \quad (2.2) \end{aligned}$$

Please note how, if we replace  $k^n$  with  $\widehat{K}_{i,i}^n$ , the second term in the penultimate line is a consistent approximation to the components of the dot product  $\frac{1}{2} \mathbf{u}^T (d_t \mathbf{K}) \mathbf{u}$  appearing on the RHS of (1.11). In vector form, with  $\widehat{\mathbf{K}}$  being a diagonal matrix, we can write this as

$$\begin{aligned} (\delta_t \cdot \mathbf{u}^n)^T \delta_t^2 \mathbf{u}^n + (\delta_t \cdot \mathbf{u}^n)^T \mu_t^2 \widehat{\mathbf{K}}^n \mu_t^2 \mathbf{u}^n &= \delta_t \left\{ \frac{1}{2} (\delta_t \mathbf{u}^n)^T \delta_t \mathbf{u}^n + \frac{1}{2} (\mu_t \mathbf{u}^n)^T \mu_t \widehat{\mathbf{K}}^n \mu_t \mathbf{u}^n \right\} \\ &\quad - \left[ \frac{1}{4} (\mu_t \mathbf{u}^{n+\frac{1}{2}})^T \delta_t \cdot \widehat{\mathbf{K}}^n \mu_t \mathbf{u}^{n+\frac{1}{2}} + \frac{1}{4} (\mu_t \mathbf{u}^{n-\frac{1}{2}})^T \delta_t \cdot \widehat{\mathbf{K}}^n \mu_t \mathbf{u}^{n-\frac{1}{2}} \right]. \quad (2.3) \end{aligned}$$

Similar to the identities in equation (36) of the paper, we may derive a discrete product rule of the form:

$$\delta_t \cdot \{u^n q^n\} = \mu_t \cdot u^n \delta_t \cdot q^n + \delta_t \cdot q^n \delta_t \cdot u^n. \quad (2.4)$$

This allows writing

$$\begin{aligned} (\delta_t \cdot \mathbf{u}^n)^T \mu_t \cdot \mathbf{h}^n &= (\mu_t \cdot \mathbf{h}^n)^T \delta_t \cdot \mathbf{u}^n \\ &= \delta_t \cdot \underbrace{\{(\mathbf{h}^n)^T \mathbf{u}^n\}}_{\bar{u}_s^n} - \delta_t \cdot (\mathbf{h}^n)^T \mu_t \cdot \mathbf{u}^n. \quad (2.5) \end{aligned}$$

Using (2.3) and (2.5), we may now rewrite (2.1) as

$$\begin{aligned} \overbrace{\delta_t \left\{ \frac{1}{2} (\delta_t \mathbf{u}^n)^T (\delta_t \mathbf{u}^n) + \frac{1}{2} (\mu_t \mathbf{u}^n)^T \mu_t \widehat{\mathbf{K}}^n \mu_t \mathbf{u}^n \right\}}^{\bar{H}_{\text{str}}^n} &= \frac{1}{4} (\mu_t \mathbf{u}^{n+\frac{1}{2}})^T \delta_t \cdot \widehat{\mathbf{K}}^n \mu_t \mathbf{u}^{n+\frac{1}{2}} + \frac{1}{4} (\mu_t \mathbf{u}^{n-\frac{1}{2}})^T \delta_t \cdot \widehat{\mathbf{K}}^n \mu_t \mathbf{u}^{n-\frac{1}{2}} \\ &\quad - (\delta_t \cdot \mathbf{u}^n)^T \widehat{\mathbf{R}}^n \delta_t \cdot \mathbf{u}^n + \delta_t \cdot \bar{u}_s^n F_c^n - \delta_t \cdot (\mathbf{h}^n)^T \mu_t \cdot \mathbf{u}^n F_c^n, \quad (2.6) \end{aligned}$$

where  $\bar{H}_{\text{str}}^n$  denotes the numerical string energy. Now let's recall equation (50) of the paper:

$$\delta_t \{ \mu_t \bar{m}_h^n \delta_t \bar{u}_h^n \} = \bar{F}_e^n - \bar{F}_c^n$$

and pre-multiply with  $\delta_t \bar{u}_h^n$ :

$$\delta_t \bar{u}_h^n \delta_t \{ \mu_t \bar{m}_h^n \delta_t \bar{u}_h^n \} = \delta_t \bar{u}_h^n \bar{F}_e^n - \delta_t \bar{u}_h^n \bar{F}_c^n. \quad (2.7)$$

Using the identity in equation (37) of the paper:

$$\delta_t \{ \mu_t q^n \delta_t u^n \} \delta_t u^n = \frac{1}{2} \delta_t \{ \mu_t q^n (\delta_t u^n)^2 \} + \delta_t q^n \delta_{t+} u^n \delta_{t-} u^n,$$

we may substitute the LHS of (2.7), and write this as

$$\underbrace{\delta_t \{ \frac{1}{2} \mu_t \bar{m}_h^n (\delta_t \bar{u}_h^n)^2 \}}_{\bar{H}_h^n} = \delta_t \bar{u}_h^n \bar{F}_e^n - \delta_t \bar{u}_h^n \bar{F}_c^n - \delta_t \bar{m}_h^n \delta_{t+} \bar{u}_h^n \delta_{t-} \bar{u}_h^n, \quad (2.8)$$

where  $\bar{H}_h^n$  denotes the numerical hammer energy. Adding equations (2.6) and (2.8) yields:

$$\begin{aligned} \delta_t \{ \bar{H}_{\text{str}}^n + \bar{H}_h^n \} &= \frac{1}{4} (\mu_t \mathbf{u}^{n+\frac{1}{2}})^T \delta_t \hat{\mathbf{K}}^n \mu_t \mathbf{u}^{n+\frac{1}{2}} + \frac{1}{4} (\mu_t \mathbf{u}^{n-\frac{1}{2}})^T \delta_t \hat{\mathbf{K}}^n \mu_t \mathbf{u}^{n-\frac{1}{2}} \\ &\quad - (\delta_t \mathbf{u}^n)^T \hat{\mathbf{R}}^n \delta_t \mathbf{u}^n - \delta_t (\mathbf{h}^n)^T \mu_t u^n F_c^n + \delta_t \bar{u}_h^n \bar{F}_e^n \\ &\quad + \delta_t \underbrace{[\bar{u}_s^n - \bar{u}_h^n]}_{\bar{y}^n} \bar{F}_c^n - \delta_t \bar{m}_h^n \delta_{t+} \bar{u}_h^n \delta_{t-} \bar{u}_h^n. \end{aligned} \quad (2.9)$$

From equation (54) of the paper, we may write:

$$\begin{aligned} \delta_t \bar{y}^n \bar{F}_c^n &= -\mu_t \psi^n \cdot (\delta_t \psi^n) + \mu_t \psi^n (g_{\bar{\kappa}}^n \delta_t \bar{\kappa}^n + g_{\alpha}^n \delta_t \alpha^n) \\ &= -\delta_t \{ \frac{1}{2} (\psi^n)^2 \} + \mu_t \psi^n (g_{\bar{\kappa}}^n \delta_t \bar{\kappa}^n + g_{\alpha}^n \delta_t \alpha^n). \end{aligned} \quad (2.10)$$

Substitution into (2.9) yields

$$\begin{aligned} \underbrace{\delta_t \{ \bar{H}_{\text{str}}^n + \bar{H}_h^n + \frac{1}{2} (\psi^n)^2 \}}_{\bar{H}^n} &= \frac{1}{4} (\mu_t \mathbf{u}^{n+\frac{1}{2}})^T \delta_t \hat{\mathbf{K}}^n \mu_t \mathbf{u}^{n+\frac{1}{2}} + \frac{1}{4} (\mu_t \mathbf{u}^{n-\frac{1}{2}})^T \delta_t \hat{\mathbf{K}}^n \mu_t \mathbf{u}^{n-\frac{1}{2}} \\ &\quad - (\delta_t \mathbf{u}^n)^T \hat{\mathbf{R}}^n \delta_t \mathbf{u}^n - \delta_t (\mathbf{h}^n)^T \mu_t u^n F_c^n + \delta_t \bar{u}_h^n \bar{F}_e^n \\ &\quad - \delta_t \bar{m}_h^n \delta_{t+} \bar{u}_h^n \delta_{t-} \bar{u}_h^n + \mu_t \psi^n (g_{\bar{\kappa}}^n \delta_t \bar{\kappa}^n + g_{\alpha}^n \delta_t \alpha^n), \end{aligned} \quad (2.11)$$

which is the result expressed in equations (58) and (59) of the paper.