

Large deviations of affine processes

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Abstract

This is an abstract of the entire dissertation; summarize a history of large deviations and affine processes, then abstractly summarize our large deviations result.

Acknowledgment

This is where I acknowledge how I am useless without others.

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Introduction

This is where I give the reader a little more history and detail regarding affine processes and large deviations, should they read this paper without already being well-versed in the subject.

Notation and conventions

Throughout, unless specifically referenced elsewhere, all notions of this text are formally defined and explored in [Kal02] or [JS03]. Most of our notation will coincide with these texts (as well as most other literature), except in regards to some particular conventions. Let us establish some of these here. A stochastic process X with a marginal-index-set I and state space $(\mathbb{X}, \mathcal{X})$ will be indifferently recognized as:

- a collection $X = (X_t)_{t \in I}$ of marginals $X_t : \Omega \rightarrow \mathbb{X}$,
- a map $X : \Omega \times I \rightarrow \mathbb{X}$,
- or its curried version $X : \Omega \rightarrow \mathbb{X}^I$.

With this convention, we find it appropriate to denote filtrations $\mathcal{F} = (\mathcal{F}_t)_{t \geq 0}$ of increasing σ -algebras \mathcal{F}_t . Seeing as \mathcal{F} denotes the actual family of σ -algebras, we denote the joined algebra with an infinity subscript, $\mathcal{F}_\infty := \bigvee_{t \geq 0} \mathcal{F}_t$. The blackboard notation will generally correspond to a topological space, including those objects we typically introduce in analysis.

- The real \mathbb{R} , the complex $\mathbb{C} = \mathbb{R} \oplus i\mathbb{R}$, the and non-negative $\mathbb{R}_+ = [0, \infty)$ numbers with the usual Euclidean topologies.
- For real normed vector spaces \mathbb{V} , \mathbb{W} , the space $\mathbb{L}(\mathbb{V}, \mathbb{W})$ of real linear maps $\mathbb{V} \rightarrow \mathbb{W}$, equipped with operator norm.

$$|T| := \sup_{|v|=1} |Tv|$$

We also concisely denote $\mathbb{L}(\mathbb{V}) := \mathbb{L}(\mathbb{V}, \mathbb{V})$.

- For the a separable metric space \mathbb{X} and an interval $I \subseteq \mathbb{R}_+$, the space $\mathbb{D}(I, \mathbb{X})$ of càdlàg functions, equipped with the Skorokhod J1 topology.
- For topological spaces \mathbb{X}, \mathbb{Y} , the space $\mathbb{C}(\mathbb{X}, \mathbb{Y})$ of continuous functions, equipped with the supremum norm.

- For finite-dimensional normed vector spaces \mathbb{V}, \mathbb{W} and open $\mathbb{U} \subseteq \mathbb{V}$, the subspace $\mathbb{C}^1(\mathbb{U}, \mathbb{W})$ of functions $f \in \mathbb{C}(\mathbb{U}, \mathbb{W})$ in which there is a derivative map $Df \in \mathbb{C}(\mathbb{U}, \mathbb{L}(\mathbb{V}, \mathbb{W}))$.

$$\lim_{|v| \rightarrow 0} \frac{|f(u+v) - f(u) - Df(u) \cdot v|}{|v|} = 0$$

For $f \in \mathbb{C}^1(\mathbb{U}, \mathbb{R})$, we denote $\nabla f \in \mathbb{C}(\mathbb{U}, \mathbb{V})$ the gradient,

$$\langle v, \nabla f(u) \rangle := Df(u) \cdot v,$$

If there is some canonical ordered basis $(e_1, \dots, e_{\dim \mathbb{V}})$ of \mathbb{V} , denote $D_i f \in \mathbb{C}(\mathbb{U}, \mathbb{R})$ the i -th partial derivative.

$$D_i f(u) := Df(u) \cdot e_i, \quad i = 1, \dots, d$$

- For finite-dimensional normed vector space \mathbb{V} and open $\mathbb{U} \subseteq \mathbb{V}$, the subspace $\mathbb{C}^2(\mathbb{U}, \mathbb{R})$ of $f \in \mathbb{C}^1(\mathbb{U}, \mathbb{R})$ in which we also have $\nabla f \in \mathbb{C}^1(\mathbb{U}, \mathbb{V})$. In such a case, we denote $D^2 f \in \mathbb{C}(\mathbb{U}, \mathbb{L}(\mathbb{V}))$ the Hessian.

$$D^2 f(u) := D(\nabla f(u))$$

If there is some canonical ordered basis $(e_1, \dots, e_{\dim \mathbb{V}})$ of \mathbb{V} , denote $D_{ij} f \in \mathbb{C}(\mathbb{U}, \mathbb{R})$ the second-order ij -th partial derivative.

$$D_{ij} f(u) := \langle e_i, D^2 f(u) \cdot e_j \rangle, \quad i, j = 1, \dots, d$$

For any topological space \mathbb{X} and subset $A \subseteq \mathbb{X}$, we denote A° and \overline{A} its interior and closure, respectively. In the case that this topology on \mathbb{X} is induced by some metric d , we denote $B(x, \delta), \overline{B}(x, \delta) \subseteq \mathbb{X}$ the respectively open and closed balls centered at $x \in \mathbb{X}$ with radius $\delta > 0$.

$$B(x, \delta) := \{x' \in \mathbb{X} : d(x', x) < \delta\}, \quad \overline{B}(x, \delta) := \{x' \in \mathbb{X} : d(x', x) \leq \delta\}$$

When the topology on \mathbb{X} is canonical, we will denote the associated Borel algebra $\mathcal{B}(\mathbb{X})$. Particular examples of this convention are:

- the Borel algebra $\mathcal{B}(\mathbb{V})$ associated to the topology induced from a canonical inner-product $\langle \cdot, \cdot \rangle$ on a vector space \mathbb{V} .
- the Borel algebra $\mathcal{B}(\mathbb{X})$ associated to the relative topology of some subset \mathbb{X} of a space \mathbb{V} with itself some canonical topology.

In the case that we are dealing with a finite-dimensional real vector space \mathbb{V} with inner-product $\langle \cdot, \cdot \rangle$, we assume some canonical orthonormal basis $e_1, \dots, e_{\dim \mathbb{V}} \in \mathbb{V}$ and establish the associated isometric isomorphism $\mathbb{V} \equiv \mathbb{R}^d$.

$$v \in \mathbb{V} \quad \longleftrightarrow \quad (v^1, \dots, v^{\dim \mathbb{V}}); \quad v^i := \langle v, e_i \rangle, \quad i = 1, \dots, \dim \mathbb{V}$$

Similarly identify any map $f : \mathbb{A} \rightarrow \mathbb{V}$ with component maps $f_1, \dots, f_d : \mathbb{A} \rightarrow \mathbb{R}$.

$$f : \mathbb{A} \rightarrow \mathbb{V} \quad \longleftrightarrow \quad (f_1, \dots, f_d) : \mathbb{A} \rightarrow \mathbb{R}^d; \quad f_i(a) := \langle f(a), e_i \rangle$$

Extend the inner-product symmetrically to a bilinear form on $\mathbb{V} \oplus i\mathbb{V}$,

$$\langle v_1 + iw_1, v_2 + iw_2 \rangle = (\langle v_1, v_2 \rangle - \langle w_1, w_2 \rangle) + i(\langle v_1, w_2 \rangle + \langle w_1, v_2 \rangle),$$

and define the trace of an operator $T \in \mathbb{L}(\mathbb{V})$, as follows.

$$\text{tr}(T) = \sum_{i=1}^d \langle e_i, Te_i \rangle$$

We adopt that (Ω, Σ, P) is an abstract probability space that—through the process of enlargement via Kolmogorov’s extension theorem—we without loss of generality assume it is equipped with identifications of various quantities $X : \Omega \rightarrow \mathbb{X}$ into measurable spaces $(\mathbb{X}, \mathcal{X})$ associated with distributions μ on $(\mathbb{X}, \mathcal{X})$. We typically presume such maps X to be measurable without mention and will otherwise specify this fact explicitly by using the notation $X \in \Sigma/\mathcal{X}$. For each probability measure P on (Ω, Σ) , we denote the P -distribution of such X by P_X or pushforward notation, $X_{\#}P$.

$$P_X \Gamma := (X_{\#}P)(\Gamma) := P(X \in \Gamma) := P(X^{-1}\Gamma), \quad \Gamma \in \mathcal{X}$$

For intuition, we will also denote integration against this distribution as follows.

$$\int_{\mathbb{X}} P(X \in dx) f(x) := \int_{\mathbb{X}} P_X(dx) f(x) = \int_{\Omega} P(d\omega) f(X(\omega)) =: E_P f(X)$$

Just as E_P denotes the expectation operator of the measure P , we will denote $E_P(\cdot|\mathcal{G})$ the conditional expectation operator of P associated with a filtration \mathcal{G} . Should we choose a target space $(\mathbb{Y}, \mathcal{Y})$ and a natural σ -algebra $Y^{-1}\mathcal{Y}$ from some quantity $Y \in \Sigma/\mathcal{Y}$, we denote $E_P(\cdot|Y = \cdot)$ the factoring of $E_P(\cdot|Y^{-1}\mathcal{Y})$ through Y .

$$E_P(X|Y = y) = E_P(X|Y^{-1}\mathcal{Y}) \Big|_{Y=y}$$

Also, any quantity $X : \Omega \rightarrow \mathbb{X}$ will be identified with the identity map on its codomain, so that we may abusively use the convenient expectation notation.

$$E_{P_X} f(X) := E_{P_X} f = \int_{\mathbb{X}} f(x) P_X(dx) = \int_{\Omega} f(X(\omega)) P(d\omega) = E_P f(X)$$

This will particularly be useful for when we discuss Markov processes and their associated identities.

Chapter 1

Affine processes

Here I put a summary of chapter, along with a short history. It will include the following important notes.

- Chapter addresses important fundamental results of affine processes.
- Chapter addresses consequences of mgf results that are important for us, though not specified exactly much in the literature
- Chapter presents results in full generality, even though we have light-tails assumption; this helps for future extensions.

1.1 Formulation

We start by specifying our affine processes as in [KRM15]. That is to say, we fix a finite-dimensional real vector space \mathbb{V} with inner-product $\langle \cdot, \cdot \rangle$ and select a convex, closed $\mathbb{X} \subseteq \mathbb{V}$ satisfying $0 \in \mathbb{X}$ and $\text{span } \mathbb{X} = \mathbb{V}$. Associate this space with the finite exponentials.

$$\mathcal{U}_{\mathbb{X}} := \left\{ u \in \mathbb{V} \oplus i\mathbb{V} : \sup_{x \in \mathbb{X}} \exp \langle \Re(u), x \rangle < \infty \right\}$$

We may now define the notion of an affine process on \mathbb{X} .

Definition 1.1.1. *For a probability space (Ω, Σ, P) with filtration $\mathcal{F} = (\mathcal{F}_t)_{t \geq 0}$, an affine process X on \mathbb{X} is a stochastically continuous, time-homogeneous (P, \mathcal{F}) -Markov process on \mathbb{X} in which the bounded moments have the following log-affine dependence on the initial state.*

$$(1.1.2) \quad \begin{aligned} \mathbb{E}_{P_x} \exp \langle u, X_t \rangle &= \exp \Psi(t, u, x) \\ \Psi(t, u, x) &= \psi_0(t, u) + \langle \psi(t, u), x \rangle, \end{aligned} \quad t \geq 0, u \in \mathcal{U}_{\mathbb{X}}$$

Above, we are denoting $(P_x)_{x \in \mathbb{X}}$ the conditional P -distributions of X factored through the initial state $x \in \mathbb{X}$.

Remark 1.1.3. (a) See [KRM15, Remark 2.3] for an argument on how our assumptions on \mathbb{X} are at no loss of generality; \mathbb{X} may as well be any nonempty convex set.

- (b) Note how (1.1.2) specifies the characteristic function of each transition kernel of the Markov process X ; thus, should an affine process exist for choice of Ψ , only one will exist, up to distribution.
- (c) See how our notation (ψ_0, ψ) differs from that of [KRM15] and other papers, which typically use (ϕ, ψ) . We choose to do this because affine functions prevail throughout our investigation of affine processes, and we saw this an opportunity to have more cohesive notation of all such affine functions.

$$\alpha(x) = a_0 + \sum_{i=1}^d x^i a_i$$

- (d) If we have a vector space \mathbb{A} and affine map $\alpha : \mathbb{X} \rightarrow \mathbb{A}$ determined by $a_0, \dots, a_d \in \mathbb{A}$ via $\alpha(x) = a_0 + \sum_{i=1}^d x^i a_i$, then our linear assumptions $0 \in \mathbb{X}$ and $\text{span } \mathbb{X} = \mathbb{V}$ uniquely determine $a_0, \dots, a_d \in \mathbb{A}$. In particular, the map Ψ uniquely identifies its parts $\psi_i : \mathbb{R}_+ \times \mathcal{U}_{\mathbb{X}} \rightarrow \mathbb{C}$ for $i = 0, \dots, d$.

In [Cuc11, Theorem 1.2.7], it is shown that, without loss of generality on conditional distributions $(P_x)_{x \in \mathbb{X}}$, an affine process X can be chosen to have càdlàg paths. Thus, each distribution P_x may be recognized as a measure on the Borel algebra associated with the space $\mathbb{D}([0, \infty), \mathbb{X})$ of càdlàg functions equipped with the Skorokhod topology. By imposing this regularity, the following theorem tells us that an affine process X as in Definition 1.1.1 is a (P_x, \mathcal{F}) jump-diffusion for each $x \in \mathbb{X}$. For relevant definitions and results pertaining to jump-diffusions, we refer the reader to Appendix A.

Theorem 1.1.4. *An affine process X on \mathbb{X} is a (P_x, \mathcal{F}) jump-diffusion in which the differential χ -characteristics (β^x, α, μ) are affine maps of the following form.*

$$\beta^x(x) := b_0^x + \sum_{i=1}^d x^i b_i^x, \quad \alpha(x) := a_0 + \sum_{i=1}^d x^i a_i, \quad \mu(x, dv) := m_0(dv) + \sum_{i=1}^d x^i m_i(dv)$$

The associated Lévy-Khintchine map Λ then also affine,

$$\begin{aligned} \Lambda(u, x) &= \langle u, \beta^x(x) \rangle + \frac{1}{2} \langle u, \alpha(x) u \rangle + \int_{\mathbb{V}} \left(e^{\langle u, v \rangle} - 1 - \langle u, \chi(v) \rangle \right) \mu(x, dv) \\ &= L_0(u) + \sum_{i=1}^d x^i L_i(u) \\ L_i(u) &:= \langle u, b_i^x(x) \rangle + \frac{1}{2} \langle u, a_i(x) u \rangle + \int_{\mathbb{V}} \left(e^{\langle u, v \rangle} - 1 - \langle u, \chi(v) \rangle \right) m_i(x, dv), \end{aligned}$$

and each $u \in i\mathbb{V}$ induces the following differential equation.

$$(1.1.5) \quad \begin{cases} \psi_0(t, u) = L_0(\psi(t, u)) & t \geq 0 \\ \psi(t, u) = L(\psi(t, u)) & t \geq 0 \\ \psi_0(0, u) = 0 \\ \psi(0, u) = u \end{cases}$$

Proof. This is simply a restatement of [Cuc11, Theorem 1.5.4].

Remark 1.1.6. By Remark 1.1.3(d) and linearity of differentiation, the equation in (1.1.5) is equivalent to the following system of equations.

$$(1.1.7) \quad \forall x \in \mathbb{X}, \quad \begin{cases} \dot{\Psi}(t, u, x) = \Lambda(\psi(t, u), x) & t \geq 0 \\ \Psi(0, u, x) = \langle u, x \rangle \end{cases}$$

Henceforth, we fix X a càdlàg affine process with conditional distributions $(P_x)_{x \in \mathbb{X}}$ on $\mathbb{D}([0, \infty), \mathbb{X})$, induced filtration $\mathcal{F} = (\mathcal{F}_t)_{t \geq 0}$, and moment function Ψ as in Definition 1.1.1. We will use the truncation function $\chi(v) = v1_{|v| \leq 1}$ and fix the differential χ -characteristics $(\beta^\chi, \alpha, \mu)$ and Lévy-Khintchine map Λ as in Theorem 1.1.4.

1.2 Existence of real moments

This section elaborates upon the extension of the transform formula in (1.1.2) and equations (1.1.5) and (1.1.7) to real moments $u \in \mathbb{V}$. Clearly, should any extension exist for some $u \in \mathbb{V}$, the value $\Lambda(u, x) = \dot{\Psi}(0, u, x)$ should be well-defined. Throughout this section, we recall our exploration in Section A.4 of the Lévy-Khintchine map Λ and its essential domain of real moments.

$$\mathcal{D}_\Lambda := \left\{ u \in \mathbb{V} : \Lambda(u, x) \text{ is well-defined for all } x \in \mathbb{X} \right\}$$

These will allow us to establish existence results of $\Psi(\cdot, u, \cdot)$ for real moments $u \in \mathbb{V}$. The following definition will get us started.

Definition 1.2.1. For each $\tau \geq 0$ and $u \in \mathcal{D}_\Lambda$, we say a function $Q^u : [0, \tau] \times \mathbb{X} \rightarrow \mathbb{R}$ satisfies $\text{system}(\Lambda, \tau, u)$ if the following hold.

$$(1.2.2) \quad \begin{aligned} & \forall t \in [0, \tau], \ x \in \mathbb{X}, \quad Q^u(t, x) = q_0^u(t) + \langle q^u(t), x \rangle, \\ & \forall x \in \mathbb{X}, \quad \begin{cases} \dot{Q}^u(t, x) = \Lambda(q^u(t), x), & t \in [0, \tau] \\ Q^u(0, x) = \langle u, x \rangle \end{cases} \end{aligned}$$

Now define the following sets.

$$\begin{aligned} \mathcal{D}_\Psi(\tau) &:= \left\{ u \in \mathcal{D}_\Lambda : \text{there exists a solution to } \text{system}(\Lambda, \tau, u) \right\} \\ \mathcal{D}_\Psi &:= \bigcup_{\tau \geq 0} \left(\{\tau\} \times \mathcal{D}_\Psi(\tau) \right) \end{aligned}$$

Theorem 1.2.3. (a) There exists a map $\Psi : \mathcal{D}_\Psi \times \mathbb{X} \rightarrow \mathbb{R}$ of the form

$$\Psi(t, u, x) = \psi_0(t, u) + \langle \psi(t, u), x \rangle$$

such that, for each $(\tau, u) \in \mathcal{D}_\Psi$, $\Psi(\cdot, u, \cdot)$ is a solution to $\text{system}(\Lambda, \tau, u)$ dominated by all other such solutions. Moreover, this map satisfies the following for each $(\tau, u) \in \mathcal{D}_\Psi$ and $x \in \mathbb{X}$.

$$(1.2.4) \quad \mathbb{E}_{P_x} \exp \langle u, X_t \rangle = \exp \Psi(t, u, x), \quad t \in [0, \tau]$$

(b) If $\tau \geq 0$, $u \in \mathbb{V}$, and $x \in \mathbb{X}^\circ$ are such that $\mathbb{E}_{P_x} \exp \langle u, X_\tau \rangle < \infty$, then $(\tau, u) \in \mathcal{D}_\Psi$.

Proof. With Remark 1.1.6, this is the same as [KRM15, Theorem 2.14].

Now that we have two characterizations for the space \mathcal{D}_Ψ , we seek to understand properties of it and the associated moment map $\Psi : \mathcal{D}_\Psi \times \mathbb{X} \rightarrow \mathbb{R}$.

Proposition 1.2.5. (a) For each $\tau > 0$, $\mathcal{D}_\Psi(\tau)$ is open in $\mathcal{D}_\Lambda^\circ$,

(b) For each $\tau > 0$ and $u \in \mathcal{D}_\Psi(\tau) \cap \mathcal{D}_\Lambda^\circ$, $\Psi(\cdot, u, \cdot)$ from Theorem 1.2.3 is the unique solution to $\text{system}(\Lambda, \tau, u)$.

(c) Ψ is continuously differentiable on $\mathcal{D}_\Psi^\circ \times \mathbb{X}$.

Proof. Fix $\tau > 0$ and $u \in \mathcal{D}_\Psi(\tau) \cap \mathcal{D}_\Lambda^\circ$. Because $u \in \mathcal{D}_\Psi(\tau)$, $\Psi(\cdot, u, \cdot)$ exists on $[0, \tau] \times \mathbb{X}$ as a solution to $\text{system}(\Lambda, \tau, u)$. As mentioned in Remark 1.1.6, the function $\psi(\cdot, u)$ associated with $\Psi(\cdot, u, \cdot)$ is a solution to the following equation,

$$(1.2.6) \quad \begin{cases} \dot{\psi}(t, u) = f(t, \psi(t, u)) & t \in [0, \tau] \\ \psi(0, u) = u \end{cases}$$

where $f : \mathbb{R} \times \mathcal{D}_\Lambda^\circ \rightarrow \mathbb{V}$ is defined by $f(t, u) := L(u)$. Seeing as f is continuously differentiable on $\mathbb{R} \times \mathcal{D}_\Lambda^\circ$ by Lemma A.4.4, we may use [Wal98, III.13 Theorem X] to ensure some $\epsilon > 0$ such that the band

$$S_\epsilon := \left\{ (t, v) \in [0, \tau] \times \mathbb{V} : |v - \psi(t, u)| \leq \epsilon \right\}$$

is contained in $\mathbb{R} \times \mathcal{D}_\Lambda^\circ$ and provides us to each $(t_0, v) \in S_\epsilon$ a unique solution $q(\cdot, t_0, v)$ to the following initial value problem,

$$\begin{cases} \dot{q}(t, t_0, v) = f(t, q(t, t_0, v)) & t \in [t_0, \tau] \\ q(t_0, t_0, v) = v \end{cases}$$

which is continuously differentiable with derivatives $\partial_{t_0} q(t, t_0, v) \in \mathbb{V}$ and $Dq(t, t_0, v) \in \mathbb{L}(\mathbb{V})$ satisfying the following equations.

$$\partial_{t_0} q(t, t_0, v) = -f(t_0, u) + \int_{t_0}^t Df(s, q(s, t_0, v)) \partial_{t_0} q(s, t_0, v) ds$$

$$Dq(t, t_0, v) = \text{id}_\mathbb{V} + \int_{t_0}^t Df(s, q(s, t_0, v)) Dq(s, t_0, v) ds$$

In particular, for each $v \in B(u, \epsilon)$, we have $|v - \psi(0, u)| = |v - u| < \epsilon$, and so $(0, v) \in S_\epsilon$; this allows us to disregard the middle coordinate and have $q : [0, \tau] \times B(u, \epsilon) \rightarrow \mathbb{V}$ such that $q(\cdot, v)$ is the unique solution to

$$\begin{cases} \dot{q}(t, v) = L(q(t, v)), & t \in [0, \tau] \\ q(0, v) = v \end{cases}$$

and the derivative in the second coordinate $Dq(t, v) \in \mathbb{L}(\mathbb{V})$ satisfies the following equation.

$$Dq(t, v) = \text{id}_\mathbb{V} + \int_0^t DL(q(s, v)) Dq(s, v) ds$$

From here, we may define $Q : [0, \tau] \times B(u, \epsilon) \times \mathbb{X} \rightarrow \mathbb{R}$ as follows.

$$\begin{aligned} Q(t, v, x) &:= q_0(t, v) + \langle q(t, v), x \rangle \\ q_0(t, v) &:= \int_0^t L_0(q(s, v)) ds \\ L_0(v) &:= \Lambda(v, 0) \end{aligned}$$

Because the image of $q(\cdot, v)$ on $[0, \tau]$ remains in $\mathcal{D}_\Lambda^\circ$, on which L is continuously differentiable, q_0 is continuously differentiable with derivatives \dot{q}_0 and Dq_0 satisfying the following.

$$\begin{aligned} \dot{q}_0(t, v) &= L_0(q(s, v)) \\ Dq_0(t, v) &= \int_0^t DL_0(q(s, v)) Dq(s, v) ds \end{aligned}$$

By linearity, $Q(\cdot, v, \cdot)$ is a solution to $\text{system}(\Lambda, \tau, v)$ and so $v \in \mathcal{D}_\Psi(\tau)$. We now have $B(u, \epsilon) \subseteq \mathcal{D}_\Psi(\tau)$, concluding part (a). Meanwhile, any solution Q^u to $\text{system}(\Lambda, \tau, u)$ is such that the associated q^u solves (1.2.6) and so $q^u = q(\cdot, u)$. From here, it is thus the case that $Q^u = Q(\cdot, u, \cdot)$. This means Ψ from Theorem 1.2.3 is such that $\Psi(\cdot, u, \cdot)$ is the unique solution to $\text{system}(\Lambda, u, \tau)$, concluding part (b). Lastly, for each $x \in \mathbb{X}$, linearity also shows us that $\Psi(\cdot, \cdot, x)$ is continuously differentiable in a neighborhood of (t, u) , with derivative in the second coordinate $D\Psi(\cdot, \cdot, x)$ satisfying the following.

$$\begin{aligned} D\Psi(t, u, x) &= D\psi_0(t, u) + D\psi(t, u) \cdot x \\ &= Dq_0(t, u) + Dq(t, u) \cdot x \\ &= \int_0^t DL_0(q(s, u)) Dq(s, u) ds + \left(\text{id}_\mathbb{V} + \int_0^t DL(q(s, u)) Dq(s, u) ds \right) \cdot x \\ &= x + \int_0^t \left(DL_0(q(s, u)) Dq(s, u) + \sum_{i=1}^d x_i DL_i(q(s, u)) Dq(s, u) \right) ds \\ &= x + \int_0^t D \left(L_0 + \sum_{i=1}^d x_i L_i \right) (q(s, u)) Dq(s, u) ds \\ &= x + \int_0^t D\Lambda(q(s, u), x) Dq(s, u) ds \\ &= x + \int_0^t D\Lambda(\psi(s, u), x) D\psi(s, u) ds \end{aligned}$$

This concludes part (c).

Proposition 1.2.7. *For each compact set $K \subseteq \mathcal{D}_\Lambda^\circ$, there exists $\delta > 0$ such that $K \subseteq \mathcal{D}_\Psi(\delta)$. Moreover, $\Psi(\cdot, u, \cdot)$ from Theorem 1.2.3 is the unique solution to $\text{system}(\Lambda, \delta, u)$ for each $u \in K$.*

Proof. Firstly, we recognize that by virtue of $K \subseteq \mathcal{D}_\Lambda^\circ$ being compact, we have some $\epsilon > 0$ such that the associated open set

$$K^\epsilon := \left\{ u \in \mathbb{V} : \inf_{u' \in K} |u - u'| < \epsilon \right\}$$

has closure $\overline{K^\epsilon}$ contained in $\mathcal{D}_\Lambda^\circ$. Note in particular that this provides us with a buffer of radius ϵ around each point in $\mathcal{D}_\Lambda^\circ$.

$$\begin{aligned} \overline{B}(u, \epsilon) &:= \left\{ u' \in \mathbb{V} : |u' - u| \leq \epsilon \right\} \\ \bigcup_{u \in \mathcal{D}_\Lambda} \overline{B}(u, \epsilon) &\subseteq \overline{K^\epsilon} \subseteq \mathcal{D}_\Lambda^\circ \end{aligned}$$

With these sets established, we mitigate the task of finding a solution Q^u to $\text{system}(\Lambda, \delta, u)$ to that of finding a solution q^u to the related equation.

$$(1.2.8) \quad \begin{cases} \dot{q}^u(t) = L(q^u(t)) & t \in [0, \delta] \\ q^u(0) = u \end{cases}$$

For a fixed $u \in \mathcal{D}_\Lambda^\circ$, the existence of some $\delta_u > 0$ and solution q^u to (1.2.8) may be obtained from the usual fixed-point method (see [Wal98, II.6 Theorem III]). Indeed, Remark 1.1.3(d) and Lemma A.4.4 provide us a Lipschitz property for L on $\overline{B}(u, \epsilon)$,

$$\begin{aligned} |L(v) - L(w)| &\leq |v - w| C_{u, \epsilon}, & v, w \in \overline{B}(u, \epsilon) \\ C_{u, \epsilon} &:= \sup_{u' \in \overline{B}(u, \epsilon)} |DL(u', x)| \end{aligned}$$

and so a Banach space $(\mathbb{B}_u, \|\cdot\|_{\mathbb{B}_u})$ defined by

$$\begin{aligned} \delta_u &:= 1 \wedge \frac{\epsilon}{\sup_{u' \in \overline{B}(u, \epsilon)} |L(u')|} \\ \mathbb{B}_u &:= \mathbb{C}([0, \delta_u], \mathbb{V}) \\ \|f\|_{\mathbb{B}_u} &:= \sup_{t \in [0, \delta_u]} |f(t)| e^{-2C_{u, \epsilon} t} \end{aligned}$$

is partially equipped with a map $T : \mathbb{C}([0, \delta_u], K) \rightarrow \mathbb{C}([0, \delta_u], \overline{K^\epsilon})$ defined by

$$Tf(t) := u + \int_0^t L(f(s)) ds,$$

satisfying a contraction property,

$$\|Tf - Tg\|_{\mathbb{B}_u} \leq \frac{1}{2} \|f - g\|_{\mathbb{B}_u},$$

which induces a unique solution $q^u \in \mathbb{C}([0, \delta_u], \overline{K^\epsilon})$ to the associated fixed-point equation, $Tq^u = q^u$. This solution q^u is thus a unique solution to (1.2.8).

From here, we define the following positive δ ,

$$\delta := \inf_{u \in K} \delta_u \geq 1 \wedge \inf_{u \in K} \frac{\epsilon}{\sup_{u' \in \overline{B}(u, \epsilon)} |L(u')|} \geq 1 \wedge \frac{\epsilon}{\sup_{u' \in \overline{K^\epsilon}} |L(u')|} > 0$$

so that each $u \in K$ has a unique solution q^u to (1.2.8). This induces the following map $Q^u : [0, \delta] \times \mathbb{X} \rightarrow \mathbb{R}$ for each $u \in K$.

$$Q^u(t, x) := q_0^u(t) + \langle q^u(t), x \rangle$$

$$q_0^u(t) := \int_0^t L_0(q^u(s)) ds$$

By linearity, Q^u is a solution to $\text{system}(\Lambda, \delta, u)$ for each $u \in K$, and so $K \subseteq \mathcal{D}_\Psi(\delta)$. For each $u \in K \subseteq \mathcal{D}_\Psi(\delta)$, a solution \tilde{Q}^u to $\text{system}(\Lambda, \delta, u)$ is such that the associated \tilde{q}^u solves (1.2.8) and so $\tilde{q}^u = q^u$. From here, it is thus the case that $\tilde{Q}^u = Q^u$. This means Ψ from Theorem 1.2.3 is such that $\Psi(\cdot, u, \cdot)$ is the unique solution to $\text{system}(\Lambda, u, \delta)$ for all $u \in K$.

Proposition 1.2.9. *For any compact subset $K \subseteq \mathcal{D}_\Psi^\circ$, there exists $C_K > 0$ such that the following holds for all $(t, u) \in K$.*

$$|\Psi(t, u, x) - \Psi(0, u, x)| \leq C_K \cdot t \cdot (1 + |x|)$$

Proof. Let $K \subseteq \mathcal{D}_\Psi^\circ$ be compact. By Remark 1.1.6 and Proposition 1.2.5(c), we have that the functions ψ_i for $i = 0, \dots, d$ are continuously differentiable on \mathcal{D}_Ψ° . Thus, we may define the following positive numbers.

$$C_{K,i} := \sup_{(t,u) \in K} |\dot{\psi}_i(t, u)|, \quad i = 0, \dots, d$$

$$C_K := \max \left\{ C_{K,0}, C_{K,1}\sqrt{d}, \dots, C_{K,d}\sqrt{d} \right\} < \infty$$

Using the fundamental theorem of calculus and that $\Psi(\cdot, u, \cdot)$ solves $\text{system}(\Lambda, \tau, u)$, we produce the following bound for all $(t, u) \in K$.

$$\begin{aligned} |\Psi(t, u, x) - \Psi(0, u, x)| &= \left| \psi_0(t, u) + \langle \psi(t, u) - u, x \rangle \right| \\ &\leq |\psi_0(t, u)| + |\psi(t, u) - u| \cdot |x| \\ &= \left| \int_0^t \dot{\psi}_0(s, u) ds \right| + \left| \int_0^t \dot{\psi}_i(s, u) ds \right| \cdot |x| \\ &\leq C_{K,0} \cdot t + \left(\sum_{i=1}^d C_{K,i}^2 \right)^{1/2} \cdot t \cdot |x| \\ &\leq C_K \cdot t \cdot (1 + |x|) \end{aligned}$$

1.3 Finite-dimensional distributions

With a good grasp of the finite real moments associated with our affine process X and their correspondence with Ψ , we now leverage these results to the finite-dimensional distributions. In other words, this section serves to lift Theorem 1.2.4 on marginals X_t to one on finite-dimensional distributions $(X_{t_1}, \dots, X_{t_n})$. Let us establish some notation.

For any space \mathbb{A} , positive integer $n \in \mathbb{N}$, and $\underline{a} \in \mathbb{A}^n$, adopt the convention of denoting $\underline{a} = (a_1, \dots, a_n)$ and

$$\underline{a}_{\ell:m} = (a_\ell, \dots, a_m) \in \mathbb{A}^{m-\ell+1}, \quad 1 \leq \ell \leq m \leq n.$$

For each $n \in \mathbb{N}$ and $\underline{t} \in [0, \infty)^n$, define the projection map $\pi_{\underline{t}} : \mathbb{X}^{[0, \infty)} \rightarrow \mathbb{X}^n$ by

$$\pi_{\underline{t}}(\xi) := \xi(\underline{t}) := (\xi(t_1), \dots, \xi(t_n)).$$

Denote $\underline{t} \vdash [0, \infty)$ to mean that \underline{t} is additionally a partition of the following form.

$$0 < t_1 < \cdots < t_n$$

For each such partition $\underline{t} \vdash [0, \infty)$, associate the following notation.

$$\begin{aligned} t_0 &:= 0 \\ \Delta t_k &:= t_k - t_{k-1}, & 1 \leq k \leq n \\ |\underline{t}| &:= n \end{aligned}$$

Lastly, for any $A \subseteq [0, \infty)$, denote $\underline{t} \vdash A$ to mean $\underline{t} \vdash [0, \infty)$ and $t_1, \dots, t_{|\underline{t}|} \in A$. For each $n \in \mathbb{N}$, extend the linear operations of \mathbb{V} to \mathbb{V}^n , componentwise. Similarly, extend the definition of our inner-product on $\mathbb{V} \oplus i\mathbb{V}$ to one on $(\mathbb{V} \oplus i\mathbb{V})^n$, like so.

$$\langle \underline{u}, \underline{v} \rangle := \sum_{k=1}^n \langle u_k, v_k \rangle$$

We now clearly specify the extension of Ψ to finite-dimensional projections from the perspective of Theorem 1.2.3 and equation (1.2.4). Note that this specifically *permits* infinite values.

Definition 1.3.1. To each $\underline{t} \vdash [0, \infty)$, define $\Psi(\underline{t}, \cdot, \cdot) : (\mathbb{V} \oplus i\mathbb{V})^{|\underline{t}|} \times \mathbb{X} \rightarrow (-\infty, \infty]$ as the cumulant generating function of $X_{\underline{t}}$.

$$\mathbb{E}_{\mathbb{P}_x} \exp \langle \underline{u}, X_{\underline{t}} \rangle =: \exp \Psi(\underline{t}, \underline{u}, x)$$

Note that this extends the definition of Ψ in that we may always consider some time $t > 0$ as a partition $\underline{t} \vdash [0, \infty)$.

Before we investigate real moments, let us establish the easier result on purely complex moments. This will give us intuition for the objects we create in the sequel.

Proposition 1.3.2. For any $\underline{t} \vdash [0, \infty)$, $\underline{u} \in i\mathbb{V}^{|\underline{t}|}$, and $x \in \mathbb{X}$, we have the following identity, where we denote $n := |\underline{t}|$ for brevity.

$$\begin{aligned} \theta_n &:= u_n \\ \theta_k &:= u_k + \psi(\Delta t_{k+1}, \theta_{k+1}), \quad k = n-1, \dots, 1 \\ \Psi(\underline{t}, \underline{u}, x) &= \sum_{k=1}^{|\underline{t}|} \psi_0(\Delta t_k, \theta_k) + \langle \psi(\Delta t_k, \theta_k), x \rangle \end{aligned}$$

Proof. We start by recognizing that $\underline{u} \in i\mathbb{V}$ means the following identity.

$$|e^{\langle u_k, x \rangle}| = \exp \langle \Re(u_k), x \rangle = 1, \quad k = 1, \dots, n$$

In particular, we have $\theta_n = u_n \in \mathcal{U}_{\mathbb{X}}$; we show $\theta_k \in \mathcal{U}_{\mathbb{X}}$ for $k = n-1, \dots, 1$ by induction.

$$\begin{aligned} \exp \langle \Re(\theta_k), x \rangle &= |e^{\langle \theta_k, x \rangle}| \\ &= |e^{\langle u_k + \psi(\Delta t_{k+1}, \theta_{k+1}), x \rangle}| \\ &= |e^{\langle u_k, x \rangle}| \cdot |e^{\langle \psi(\Delta t_{k+1}, \theta_{k+1}), x \rangle}| \end{aligned}$$

$$\begin{aligned}
&= \left| e^{-\psi_0(\Delta t_k, \theta_{k+1}) + \Psi(\Delta t_{k+1}, \theta_{k+1}, x)} \right| \\
&= \left| e^{-\psi_0(\Delta t_{k+1}, \theta_{k+1})} \right| \cdot \left| \mathbb{E}_{P_x} \exp \langle \theta_{k+1}, X_{\Delta t_{k+1}} \rangle \right| \\
&\leq \left| e^{-\psi_0(\Delta t_{k+1}, \theta_{k+1})} \right| \cdot \mathbb{E}_{P_x} \left| \exp \langle \theta_{k+1}, X_{\Delta t_{k+1}} \rangle \right| \\
&\leq \left| e^{-\psi_0(\Delta t_{k+1}, \theta_{k+1})} \right| \cdot \sup_{x' \in \mathbb{X}} \exp \Re \langle \theta_{k+1}, x' \rangle
\end{aligned}$$

Now observe the following identity.

$$\begin{aligned}
&\Psi(\underline{t}, \underline{u}, x) \\
&= \log \mathbb{E}_{P_x} \exp \langle \underline{u}, X_{\underline{t}} \rangle \\
(1.3.3) \quad &= \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-1} \langle u_k, X_{t_k} \rangle \cdot \exp \langle \theta_n, X_{t_n} \rangle \right) \\
&= \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-1} \langle u_k, X_{t_k} \rangle \cdot \mathbb{E}_{P_x} \left(\exp \langle \theta_n, X_{t_n} \rangle \middle| \mathcal{F}_{t_{n-1}} \right) \right) \\
&= \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-1} \langle u_k, X_{t_k} \rangle \cdot \exp \Psi(\Delta t_n, \theta_n, X_{t_{n-1}}) \right) \\
&= \psi_0(\Delta t_n, \theta_n) \\
&\quad + \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-1} \langle u_k, X_{t_k} \rangle \cdot \exp \left(\langle \psi(\Delta t_n, \theta_n), X_{t_{n-1}} \rangle \right) \right) \\
&= \psi_0(\Delta t_n, \theta_n) \\
&\quad + \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-2} \langle u_k, X_{t_k} \rangle \cdot \exp \left(\langle u_{n-1} + \psi(\Delta t_n, \theta_n), X_{t_{n-1}} \rangle \right) \right) \\
(1.3.4) \quad &= \psi_0(\Delta t_n, \theta_n) \\
&\quad + \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-2} \langle \theta_k - \psi(\Delta t_{k+1}, \theta_{k+1}), X_{t_k} \rangle \cdot \exp \left(\langle \theta_{n-1}, X_{t_{n-1}} \rangle \right) \right)
\end{aligned}$$

The final term of (1.3.3) is identical to that of (1.3.4) where we have reduced $k = n$ to $k = n - 1$. Repeating these equalities inductively $k = n - 1, \dots, 1$ will result in the desired identity.

$$\Psi(\underline{t}, \underline{u}, x) = \sum_{k=2}^n \psi_0(\Delta t_k, \theta_k) + \log \mathbb{E}_{P_x} \exp \langle \theta_1, X_{t_1} \rangle = \sum_{k=1}^n \psi_0(\Delta t_k, \theta_k) + \langle \psi(\Delta t_1, \theta_1), x \rangle$$

As the preceding result shows, the \mathbb{X} -affine structure of Ψ allows us to iteratively factor the exponentials in our expectation. The problem with extending this to real moments like in Theorem 1.2.3 is that each of the produced quantities θ_k need not produce an integrable exponential on which we apply the transform formula. The next result is our way of coercing such a property to occur; the map $U_{\underline{t}}$ serves to parameterize those moments $\underline{u} \in \mathbb{V}^{|\underline{t}|}$ which the resulting $\underline{\theta}$ is in $\prod_{k=1}^{|\underline{t}|} \mathcal{D}_{\Psi}(\Delta t_k)$, since this is precisely the set on which we may perform

the calculations between (1.3.3) and (1.3.4). This set turns out to be important in our discussion, so we will reserve it special notation.

$$\mathcal{D}_\Psi(\underline{t}) := \prod_{k=1}^{|\underline{t}|} \mathcal{D}_\Psi(\Delta t_k), \quad \underline{t} \vdash [0, \infty)$$

Proposition 1.3.5. *For each $\underline{t} \vdash [0, \infty)$, the following map $U_{\underline{t}}$ is a continuous injection, where we denote $n := |\underline{t}|$ for brevity.*

$$U_{\underline{t}} : \mathcal{D}_\Psi(\underline{t}) \rightarrow \mathbb{V}^{|\underline{t}|}, \quad U_{\underline{t}}(\underline{\theta}) := (\theta_1 - \psi(\Delta t_2, \theta_2), \dots, \theta_{n-1} - \psi(\Delta t_n, \theta_n), \theta_n)$$

Moreover, for each $x \in \mathbb{X}$ and $\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})$, we have the following (finite) identity.

$$(1.3.6) \quad \Psi(\underline{t}, U_{\underline{t}}(\underline{\theta}), x) = \sum_{k=1}^{|\underline{t}|} \psi_0(\Delta t_k, \theta_k) + \langle \psi(\Delta t_1, \theta_1), x \rangle$$

Proof. Fix $\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})$. By definition, this means that to each $k = 1, \dots, |\underline{t}|$, we have $\theta_k \in \mathcal{D}_\Psi(\Delta t_k)$, and so $\psi(\Delta t_k, \theta_k)$ is well-defined. This ensures that $U_{\underline{t}}$ is well-defined. Now select another point $\underline{\theta}' \in \mathcal{D}_\Psi(\underline{t})$ such that $U_{\underline{t}}(\underline{\theta}) = U_{\underline{t}}(\underline{\theta}')$. The final component of $U_{\underline{t}}$ ensures that $\theta_n = \theta'_n$; by means of induction, we then get $\theta_{k-1} = \theta'_{k-1}$ for $k = n, \dots, 2$, via the equality on the respective component map.

$$\theta_{k-1} - \psi(\Delta t_k, \theta_k) = U_{\underline{t}, k-1}(\underline{\theta}) = U_{\underline{t}, k-1}(\underline{\theta}') = \theta'_{k-1} - \psi(\Delta t_k, \theta'_k)$$

This indicates to us that $U_{\underline{t}}$ is an injection, and continuity comes simply from continuity of each $\psi(\Delta t_k, \cdot)$ via Proposition 1.2.5(c).

It now remains to show the identity in (1.3.6). This reduces down to repeatedly applying iterated expectations; fix $x \in \mathbb{X}$ and observe the following.

$$\begin{aligned} & \Psi(\underline{t}, U_{\underline{t}}(\underline{\theta}), x) \\ &= \log \mathbb{E}_{P_x} \exp \langle U_{\underline{t}}(\underline{\theta}), X_{\underline{t}} \rangle \\ (1.3.7) \quad &= \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-1} \langle \theta_k - \psi(\Delta t_{k+1}, \theta_{k+1}), X_{t_k} \rangle \cdot \exp \langle \theta_n, X_{t_n} \rangle \right) \\ &= \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-1} \langle \theta_k - \psi(\Delta t_{k+1}, \theta_{k+1}), X_{t_k} \rangle \cdot \mathbb{E}_{P_x} \left(\exp \langle \theta_n, X_{t_n} \rangle \middle| \mathcal{F}_{t_{n-1}} \right) \right) \\ &= \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-1} \langle \theta_k - \psi(\Delta t_{k+1}, \theta_{k+1}), X_{t_k} \rangle \cdot \exp \Psi(\Delta t_n, \theta_n, X_{t_{n-1}}) \right) \\ &= \psi_0(\Delta t_n, \theta_n) \\ &\quad + \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-1} \langle \theta_k - \psi(\Delta t_{k+1}, \theta_{k+1}), X_{t_k} \rangle \cdot \exp \left(\langle \psi(\Delta t_n, \theta_n), X_{t_{n-1}} \rangle \right) \right) \\ (1.3.8) \quad &= \psi_0(\Delta t_n, \theta_n) \\ &\quad + \log \mathbb{E}_{P_x} \left(\exp \sum_{k=1}^{n-2} \langle \theta_k - \psi(\Delta t_{k+1}, \theta_{k+1}), X_{t_k} \rangle \cdot \exp \left(\langle \theta_{n-1}, X_{t_{n-1}} \rangle \right) \right) \end{aligned}$$

The final term of (1.3.8) is identical to that of (1.3.7), where we have reduced $k = n$ to $k = n - 1$. Repeating these equalities inductively $k = n - 1, \dots, 1$ will result in the desired identity.

$$\Psi(\underline{t}, U_{\underline{t}}(\underline{\theta}), x) = \sum_{k=2}^n \psi_0(\Delta t_k, \theta_k) + \log E_{P_x} \exp \langle \theta_1, X_{t_1} \rangle = \sum_{k=1}^n \psi_0(\Delta t_k, \theta_k) + \langle \psi(\Delta t_1, \theta_1), x \rangle$$

We now turn to the analogue of Theorem 1.2.3(b), in which P_x -finite moments $\underline{u} \in \mathbb{V}^{|\underline{t}|}$ for initial points $x \in \mathbb{X}^\circ$ are precisely those $\underline{u} \in \mathcal{D}_\Psi(\underline{t})$.

Proposition 1.3.9. *Fix $\underline{t} \vdash [0, \infty)$ and denote $n := |\underline{t}|$ for brevity. If $\underline{u} \in \mathbb{V}^{|\underline{t}|}$ is such that $\Psi(\underline{t}, \underline{u}, x) < \infty$ for some $x \in \mathbb{X}^\circ$, then the following recursion holds.*

$$(1.3.10) \quad \begin{aligned} \theta_n &:= u_n \in \mathcal{D}_\Psi(\Delta t_n) \\ \theta_k &:= u_k + \psi(\Delta t_{k+1}, \theta_{k+1}) \in \mathcal{D}_\Psi(\Delta t_k), \quad k = n-1, \dots, 1 \end{aligned}$$

Proof. Consider $\underline{u} \in \mathbb{V}^{|\underline{t}|}$ from which we may not construct the recursion in (1.3.10). In other words, there exists maximal $j \in \{1, \dots, n\}$ in the recursion which fails; i.e. $\theta_k \in \mathcal{D}_\Psi(\Delta t_k)$ for all $k = n, \dots, j+1$ and $\theta_j \notin \mathcal{D}_\Psi(\Delta t_j)$. We now repeat the work as in (1.3.7)-(1.3.8) for a fixed $x \in \mathbb{X}^\circ$ to get the following identity.

$$\begin{aligned} & \log E_{P_x} \exp \langle \underline{u}, X_{\underline{t}} \rangle \\ &= \log E_{P_x} \left(\exp \left(\sum_{k=1}^{n-1} \langle u_k, X_{t_k} \rangle \right) \cdot E_{P_x} \left(\exp \langle u_n, X_{t_n} \rangle | \mathcal{F}_{t_{n-1}} \right) \right) \\ &= \psi_0(\Delta t_n, u_n) \\ & \quad + \log E_{P_x} \left(\exp \left(\sum_{k=1}^{n-2} \langle u_k, X_{t_k} \rangle \right) \cdot E_{P_x} \left(\exp \langle u_{n-1} + \psi(\Delta t_n, u_n), X_{t_{n-1}} \rangle | \mathcal{F}_{t_{n-2}} \right) \right) \\ &= \psi_0(\Delta t_n, \theta_n) \\ & \quad + \log E_{P_x} \left(\exp \left(\sum_{k=1}^{n-2} \langle u_k, X_{t_k} \rangle \right) \cdot E_{P_x} \left(\exp \langle \theta_{n-1}, X_{t_{n-1}} \rangle | \mathcal{F}_{t_{n-2}} \right) \right) \\ & \quad \vdots \\ &= \sum_{k=j+1}^n \psi_0(\Delta t_k, \theta_k) + \log E_{P_x} \left(\exp \left(\sum_{k=1}^{j-1} \langle u_k, X_{t_k} \rangle \right) \cdot E_{P_x} \left(\exp \langle \theta_j, X_{t_j} \rangle | \mathcal{F}_{t_{j-1}} \right) \right) \\ &= \sum_{k=j+1}^n \psi_0(\Delta t_k, \theta_k) + \log E_{P_x} \left(\exp \left(\sum_{k=1}^{j-1} \langle u_k, X_{t_k} \rangle \right) \cdot E_{P_{X_{t_{j-1}}}} \exp \langle \theta_j, X_{\Delta t_j} \rangle \right) \end{aligned}$$

By Theorem 1.2.3, since $\theta_j \notin \mathcal{D}_\Psi(\Delta t_j)$, we have $E_{P_{x'}} \exp \langle \theta_j, X_{\Delta t_j} \rangle = \infty$ for all $x' \in \mathbb{X}^\circ$, so the above integrand is infinite on the set $X_{t_{j-1}} \in \mathbb{X}^\circ$. Seeing as $x \in \mathbb{X}^\circ$, this set is P_x non-negligible, and so the quantity is infinite. We conclude that $\underline{u} \notin \mathcal{D}_\Psi(\underline{t})$, which finishes the proof by contrapositive.

Our final result of this section explores more on how finite moments \underline{u} of $X_{\underline{t}}$ relate to those $\underline{\theta}$ of the increments $X_{t_1} - X_{t_0}, X_{t_2} - X_{t_1}, \dots, X_{t_n} - X_{t_{n-1}}$. To see this, we define the following increment cumulant generating function,

$$\varphi(t, \theta, x) := \log E_{P_x} \exp \langle \theta, X_t - x \rangle = \Psi(t, \theta, x) - \langle \theta, x \rangle$$

Theorem 1.3.11. Fix $t \vdash [0, \infty)$ and $x_0 \in \mathbb{X}^\circ$. The map U_t is a homeomorphism from $\mathcal{D}_\Psi(t)$ to the collection of $\underline{u} \in \mathbb{V}^{[t]}$ for which $\Psi(t, \underline{u}, x_0) < \infty$. In particular, this means $\underline{u} \in \mathbb{V}^{[t]}$ satisfies $\Psi(t, \underline{u}, x_0) < \infty$ if and only if $\underline{u} = U_t(\underline{\theta})$. Moreover, we have the following identity for all $\underline{x} \in \mathbb{X}^{[t]}$.

$$\langle \underline{u}, \underline{x} \rangle - \Psi(t, \underline{u}, x_0) = \sum_{k=1}^{|t|} \left(\langle \theta_k, x_k - x_{k-1} \rangle - \varphi(\Delta t_k, \theta_k, x_{k-1}) \right), \quad \underline{u} = U_t(\underline{\theta})$$

Proof. By Proposition 1.3.5, we have that U is indeed a continuous map from $\mathcal{D}_\Psi(t)$ into the finite domain of $\Psi(t, \cdot, x_0)$. Conversely, Proposition 1.3.9 indicates to us that, on the finite domain of $\Psi(t, \cdot, x_0)$, a recursively-defined map T_t from (1.3.10) exists. Denoting $n := |t|$, we see that this map is continuous by induction and continuity of compositions.

$$\begin{aligned} T_t(\underline{u}) &= (T_{t,1}(\underline{u}_{1:n}), \dots, T_{t,n}(\underline{u}_{n:n})), & T_{t,n}(\underline{u}_{n:n}) &= u_n \\ & & T_{t,k}(\underline{u}_{k:n}) &= u_k + \psi(\Delta t_{k+1}, T_t(\underline{u}_{k+1:n})) \end{aligned}$$

Observe that T_t is the inverse of U_t . To see this, fix $\underline{\theta} \in \mathcal{D}_\Psi(t)$ and $\underline{u} := U_t(\underline{\theta})$. The final coordinate is obvious,

$$T_{t,n}(\underline{u}_{n:n}) = u_n = U_{t,n}(\underline{\theta}) = \theta_n,$$

while an inductive hypothesis $T_{t,k}(\underline{u}_{k:n}) = \theta_k$ gives us the next step.

$$T_{t,k-1}(\underline{u}_{k-1:n}) = U_{t,k-1}(\underline{\theta}) + \psi(\Delta t_k, T_{t,k}(\underline{u}_{k:n})) = \theta_{k-1} - \psi(\Delta t_k, \theta_k) + \psi(\Delta t_k, \theta_k) = \theta_{k-1}$$

Dual to this, fix $\underline{u} \in \mathbb{V}^{[t]}$ for which $\Psi(t, \underline{u}, x_0) < \infty$ and define $\underline{\theta} := T_t(\underline{u})$. Again, we immediately have

$$U_{t,n}(\underline{\theta}) = \theta_n = T_{t,n}(\underline{u}_{n:n}) = u_n,$$

and an inductive hypothesis of $U_{t,k}(\underline{\theta}) = u_k$ results in the next step.

$$U_{t,k-1}(\underline{\theta}) = \theta_{k-1} - \psi(\Delta t_k, \theta_k) = T_{t,k-1}(\underline{u}_{k-1:n}) - \psi(\Delta t_k, T_{t,k}(\underline{u}_{k:n})) = u_{k-1}$$

We have now showed that U_t is a homeomorphism with inverse T_t . It remains to show our identity for a pairing $\underline{u} = U_t(\underline{\theta})$.

$$\begin{aligned} \langle \underline{u}, \underline{x} \rangle - \Psi(t, \underline{u}, x_0) &= \langle U_t(\underline{\theta}), \underline{x} \rangle - \Psi(t, U_t(\underline{\theta}), x_0) \\ &= \sum_{i=1}^{n-1} \langle \theta_k - \psi(\Delta t_{k+1}, \theta_{k+1}), x_k \rangle + \langle \theta_n, x_n \rangle - \sum_{i=1}^n \psi_0(\Delta t_k, \theta_k) - \langle \psi(\Delta t_1, \theta_1), x_0 \rangle \\ &= \sum_{i=1}^n \left(\langle \theta_k, x_k \rangle - \psi_0(\Delta t_k, \theta_k) - \langle \psi(\Delta t_k, \theta_k), x_k \rangle \right) \\ &= \sum_{i=1}^n \left(\langle \theta_k, x_k \rangle - \Psi(\Delta t_k, \theta_k, x_k) \right) \\ &= \sum_{i=1}^n \left(\langle \theta_k, x_k - x_{k-1} \rangle - \varphi(\Delta t_k, \theta_k, x_{k-1}) \right) \end{aligned}$$

1.4 Affine jump-diffusions

This section shows how the notions of jump-diffusions explained in Appendix A apply in the affine case. Firstly, we prove the uniform-boundedness property for the affine jump kernel μ associated to our affine process.

Lemma 1.4.1. *The jump kernel μ satisfies the following uniform-boundedness property. Any function $f \in \mathcal{B}(\mathbb{V})/\mathcal{B}(\mathbb{R})$ that satisfies*

$$\int_{\mathbb{V}} |f(v)| \mu(x, dv) < \infty$$

for all $x \in \mathbb{X}$ then satisfies the following.

$$x \mapsto \int_{\mathbb{V}} |f(v)| \mu(x, dv) \text{ bounded on compact sets}$$

Proof. Seeing as $0 \in \mathbb{X}$ and $\text{span } \mathbb{X} = \mathbb{V}$, we can take appropriate linear combinations to get finite integrals for each of the parts m_0, \dots, m_d of μ .

$$F_i := \int_{\mathbb{V}} |f(v)| m_i(dv) < \infty, \quad i = 0, \dots, d$$

From here, the result is a simple effect of our affine property and boundedness of compact sets.

$$\sup_{|x| \leq M} \left| \int_{\mathbb{V}} |f(v)| \mu(x, dv) \right| = \sup_{|x| \leq M} \left| F_0 + \sum_{i=1}^d x^i F_i \right| \leq F_0 + M \sum_{i=1}^d F_i < \infty$$

With this result, we can state succinct versions of the results which exist for general jump-diffusions.

Proposition 1.4.2. *If $0 \in \mathcal{D}_\Lambda^\circ$, then X is a (P_x, \mathcal{F}) special jump-diffusion for each $x \in \mathbb{X}$. The resulting drift map $\beta : \mathbb{X} \rightarrow \mathbb{V}$ in the special semimartingale decomposition,*

$$X_t = x + \beta(X) \cdot \ell_t + X^c + \text{id}_{\mathbb{V}} * \tilde{q}_t^X$$

is also affine, making all the special differential characteristics (β, α, μ) affine.

Proof. By combining Lemma 1.4.1 and Proposition A.4.10, we get that X is special. Now, we perform the algebra to see the affine structure of β .

$$\begin{aligned} \beta(x) &= \beta^X(x) + \int_{\mathbb{V}} (v - \chi(v)) \mu(x, dv) \\ &= \left(b_0^X + \sum_{i=1}^d x^i b_i^X \right) + \int_{\mathbb{V}} (v - \chi(v)) \left(m_0(dv) + \sum_{i=1}^d x^i m_i(dv) \right) \\ &= \left(b_0^X + \int_{\mathbb{V}} (v - \chi(v)) m_0(dv) \right) + \sum_{i=1}^d x^i \left(b_i^X + \int_{\mathbb{V}} (v - \chi(v)) m_i(dv) \right) \end{aligned}$$

Proposition 1.4.3. *If the jump kernel satisfies $\mu(x, \mathbb{V}) < \infty$ for all $x \in \mathbb{X}$, then X is (P_x, \mathcal{F}) locally countable for all $x \in \mathbb{X}$. In the resulting factorization,*

$$\mu(x, dv) = \lambda(x) \kappa(x, dv),$$

the intensity λ is an affine map and the jump distribution κ is a convex mixture of probability distributions k_0, \dots, k_d whenever $\lambda(x) \neq 0$.

$$\lambda(x) = l_0 + \sum_{i=1}^d x^i l_i, \quad \kappa(x, dv) = \frac{l_0}{\lambda(x)} k_0(dv) + \sum_{i=1}^d \frac{x^i l_i}{\lambda(x)} k_i(dv),$$

Proof. By combining Lemmas 1.4.1 and A.3.2, we get the desired local countability. Because $0 \in \mathbb{X}$ and $\text{span } \mathbb{X} = \mathbb{V}$, we are able to take appropriate linear combinations to ensure finiteness of the quantities $l_i := m_i(\mathbb{V})$ for each $i = 0, \dots, d$. This allows us to define our intensity map.

$$\lambda(x) := l_0 + \sum_{i=1}^d x^i l_i = m_0(\mathbb{V}) + \sum_{i=1}^d x^i m_i(\mathbb{V}) = \mu(x, \mathbb{V})$$

Now, just as in Remark A.3.3, each non-zero l_i will produce a probability distribution $k_i(dv) := m_i(dv)/l_i$; otherwise, simply define $k_i(dv) := \delta_{e_1}$. This way, we have the factoring $m_i(dv) = l_i k_i(dv)$ for each $i = 0, \dots, d$. If $\lambda(x) \neq 0$, we see our other desired identity.

$$\begin{aligned} \kappa(x, dv) &:= \frac{1}{\lambda(x)} \mu(x, dv) \\ &= \frac{1}{\lambda(x)} \left(m_0(dv) + \sum_{i=1}^d x^i m_i(dv) \right) \\ &= \frac{1}{\lambda(x)} \left(l_0 k_0(dv) + \sum_{i=1}^d x^i l_i k_i(dv) \right) \\ &= \frac{l_0}{\lambda(x)} k_0(dv) + \sum_{i=1}^d \frac{x^i l_i}{\lambda(x)} k_i(dv) \end{aligned}$$

Theorem 1.4.4. *If $0 \in \mathcal{D}_\Lambda^\circ$, then any $h \in \mathbb{D}([0, \infty), \mathbb{V})$ of finite variation, compact support, and image contained in $\mathcal{D}_\Lambda^\circ$ makes $\exp(h \cdot X)$ a $(\mathbb{P}_x, \mathcal{F})$ special jump-diffusion and*

$$\exp \left(h \cdot X - \Lambda(h, X) \cdot \ell \right)$$

a martingale for every $x \in \mathbb{X}$.

Proof. The quantity $M = \exp(h \cdot X - \Lambda(h, X) \cdot \ell)$ is a $(\mathbb{P}_x, \mathcal{F})$ local martingale by our hypotheses and Theorem A.4.13. To get the remaining martingale property, we first note that the compact support of h means that there exists $\tau > 0$ such that $h(t) = 0$ for all $t > \tau$. This makes $M = M^\tau$, and so we only need to consider the martingale property on the interval $[0, \tau]$. For this, we use [SV10, Theorem 2.6], which requires the maps

$$(s, x) \mapsto \langle h(s), \alpha(x) h(s) \rangle, \quad (s, x) \mapsto \int_{\mathbb{V}} (e^{\langle h(s), v \rangle} - 1 - \langle h(s), v \rangle) \mu(x, dv)$$

are bounded on compact sets of points (s, x) . This comes from the fact that the image of h is contained in some compact subset of $\mathcal{D}_\Lambda^\circ$ and that Λ is uniformly bounded on compact subsets of $\mathcal{D}_\Lambda^\circ \times \mathbb{X}$ by Lemma A.4.4.

Chapter 2

Large deviations of affine processes

1. Summarize how multiple *frameworks* are utilized: Dembo, Feng, Puhalskii
2. Summarize history of works treating DG+EM differently

2.1 Asymptotic family

We will prove a large deviation principle for a family $(P_{x_0}^\epsilon)_{\epsilon>0}$ of distributions $P_{x_0}^\epsilon$ of affine processes ϵX^ϵ with initial point $x_0 \in \mathbb{X}^\circ$ in which the differential χ -characteristics $(\beta^{\chi,\epsilon}, \alpha^\epsilon, \mu^\epsilon)$ of each respective X^ϵ have the following parameterization.

$$(2.1.1) \quad \beta^{\chi,\epsilon}(x) = \frac{1}{\epsilon} \beta^{\chi,1}(\epsilon x), \quad \alpha^\epsilon(x) = \frac{1}{\epsilon} \alpha^1(\epsilon x), \quad \mu^\epsilon(x, dv) = \frac{1}{\epsilon} \mu^1(\epsilon x, dv), \quad x \in \mathbb{X}$$

In effect, the family $(P_x^\epsilon)_{\epsilon>0}$ is induced by a *base distribution* $P_x := P_x^1$ associated with *base affine process* $X := X^1$ and *base differential characteristics* $(\beta^\chi, \alpha, \mu) := (\beta^{\chi,1}, \alpha^1, \mu^1)$. This also implies a similar parameterization for the Lévy-Khintchine maps Λ^ϵ associated with $(\beta^{\chi,\epsilon}, \alpha^\epsilon, \mu^\epsilon)$ in terms of the base map Λ from $(\beta^\chi, \alpha, \mu)$.

$$(2.1.2) \quad \Lambda^\epsilon(u, x) = \frac{1}{\epsilon} \Lambda(u, \epsilon x), \quad u \in \mathbb{V}, \quad x \in \mathbb{X}$$

Using the notation of Appendix A.4, we see that the set $\mathcal{D}_\Lambda(x)$ of finite points of $\Lambda(\cdot, x)$ is identical to that $\mathcal{D}_{\Lambda^\epsilon}(\epsilon x)$ of $\Lambda^\epsilon(\cdot, \epsilon x)$. So long that \mathbb{X} is a cone—which is to say that \mathbb{X} an additive set, closed under non-negative-scalar multiplication—we have $\mathbb{X} = \epsilon \mathbb{X}$, and so the following sets agree.

$$\mathcal{D}_\Lambda = \bigcap_{x \in \mathbb{X}} \mathcal{D}_\Lambda(x) = \bigcap_{x \in \mathbb{X}} \mathcal{D}_{\Lambda^\epsilon}(\epsilon x) = \bigcap_{x \in \mathbb{X}} \mathcal{D}_{\Lambda^\epsilon}(x) = \mathcal{D}_{\Lambda^\epsilon}$$

Note that a parameterization like (2.1.1) or (2.1.2) may exist irrespective of the affine property on $(\beta^\chi, \alpha, \mu)$. However, affine processes are distinct in the existence (from Theorem 1.2.3) of an affine map $\Psi^\epsilon : \mathcal{D}_{\Psi^\epsilon} \rightarrow \mathbb{R}$ respective to X^ϵ ,

$$\Psi^\epsilon(t, u, x) = \psi_0^\epsilon(t, u) + \langle \psi^\epsilon(t, u), x \rangle,$$

in which $\Psi^\epsilon(\cdot, u, \cdot)$ is the minimal solution of $\text{system}(\Lambda^\epsilon, \tau, u)$ for each $(\tau, u) \in \mathcal{D}_{\Psi^\epsilon}$,

$$\forall x \in \mathbb{X}, \quad \begin{cases} \dot{\Psi}^\epsilon(t, u, x) = \Lambda^\epsilon(\psi^\epsilon(t, u), x), & t \in [0, \tau] \\ \Psi^\epsilon(0, u, x) = \langle u, x \rangle \end{cases}$$

and is the cumulant generating function of each marginal.

$$\mathbb{E}_{P_x^\epsilon} \exp \langle u, X_\tau^\epsilon \rangle = \exp \Psi^\epsilon(\tau, u, x/\epsilon), \quad (\tau, u) \in \mathcal{D}_\Psi, \quad x \in \mathbb{X}$$

Above, note that we are naturally denoting $(P_x^\epsilon)_{x \in \mathbb{X}}$ the other distributions P_x^ϵ of ϵX^ϵ in which it starts at various $x \in \mathbb{X}$ (hence why we have a x/ϵ in the last coordinate). The following result shows us that our parameterization in (2.1.1) and (2.1.2) applies these cumulant generating functions, where $\Psi := \Psi^1$ and $\mathcal{D}_\Psi := \mathcal{D}_\Psi^1$.

Proposition 2.1.3. *Assume \mathbb{X} is a cone satisfying $\text{span } \mathbb{X} = \mathbb{V}$. For each $\epsilon > 0$, we have $\mathcal{D}_\Psi = \mathcal{D}_{\Psi^\epsilon}$ and the following identities.*

$$\Psi^\epsilon(t, u, x) = \frac{1}{\epsilon} \Psi(t, u, \epsilon x), \quad \psi_0^\epsilon(t, u) = \frac{1}{\epsilon} \psi_0(t, u), \quad \psi^\epsilon(t, u) = \psi(t, u),$$

Proof. Start by selecting $(\tau, u) \in \mathcal{D}_\Psi$. This means that $u \in \mathcal{D}_\Psi(\tau)$ and $\Psi(\cdot, u, \cdot)$ is a solution to $\text{system}(\Lambda, u, \tau)$. Observe that this implies the following identity for all $x \in \mathbb{X}$.

$$\begin{aligned} \frac{\partial}{\partial t} \frac{1}{\epsilon} \Psi(t, u, \epsilon x) &= \frac{1}{\epsilon} \dot{\Psi}(t, u, \epsilon x) = \frac{1}{\epsilon} \Lambda(\psi(t, u), \epsilon x) = \Lambda^\epsilon(\psi(t, u), x), \quad t \in [0, \tau] \\ \frac{1}{\epsilon} \Psi(0, u, \epsilon x) &= \frac{1}{\epsilon} \langle u, \epsilon x \rangle = \langle u, x \rangle \end{aligned}$$

This means that $\frac{1}{\epsilon} \Psi(\cdot, u, \epsilon \cdot)$ is a solution to $\text{system}(\Lambda^\epsilon, \tau, u)$. By definition, existence of a solution means that $u \in \mathcal{D}_{\Psi^\epsilon}(\tau)$, and so $(\tau, u) \in \mathcal{D}_{\Psi^\epsilon}$. Theorem 1.2.3 then tells us $\Psi^\epsilon(\cdot, u, \cdot)$ exists and is dominated by the other solution.

$$\Psi^\epsilon(t, u, x) \leq \frac{1}{\epsilon} \Psi(t, u, \epsilon x), \quad t \in [0, \tau], \quad x \in \mathbb{X}$$

On the other hand, if we have $(\tau, u) \in \mathcal{D}_{\Psi^\epsilon}$, then $u \in \mathcal{D}_{\Psi^\epsilon}(\tau)$, and so $\Psi^\epsilon(\cdot, u, \cdot)$ is a solution to $\text{system}(\Lambda^\epsilon, \tau, u)$. Now, we have the following identity for all $x \in \mathbb{X}$,

$$\begin{aligned} \frac{\partial}{\partial t} \epsilon \Psi^\epsilon(t, u, x/\epsilon) &= \epsilon \dot{\Psi}^\epsilon(t, u, x/\epsilon) = \epsilon \Lambda^\epsilon(\psi^\epsilon(t, u), x/\epsilon) = \Lambda(\psi(t, u), x), \quad t \in [0, \tau] \\ \epsilon \Psi^\epsilon(0, u, x/\epsilon) &= \epsilon \langle u, x/\epsilon \rangle = \langle u, x \rangle, \end{aligned}$$

and so $\epsilon \Psi^\epsilon(\cdot, u, \cdot)$ is a solution to $\text{system}(\Lambda, \tau, u)$. Again, we may conclude from this that $(\tau, u) \in \mathcal{D}_\Psi$ and that $\Psi^\epsilon(\cdot, u, \cdot)$ exists and is dominated by the other solution.

$$\Psi(t, u, x) \leq \epsilon \Psi^\epsilon(t, u, x/\epsilon), \quad t \in [0, \tau], \quad x \in \mathbb{X}$$

In total, we have now shown that $\mathcal{D}_\Psi = \mathcal{D}_{\Psi^\epsilon}$, and inequalities (14) and (14) indicate to us that the following functions agree.

$$\Psi^\epsilon(t, u, x) = \frac{1}{\epsilon} \Psi(t, u, \epsilon x), \quad (t, u) \in \mathcal{D}_\Psi, \quad x \in \mathbb{X}$$

This means equality of the following affine expressions.

$$\begin{aligned}\psi_0^\epsilon(t, u) + \langle \psi^\epsilon(t, u), x \rangle &= \Psi^\epsilon(t, u, x) \\ &= \frac{1}{\epsilon} \Psi(t, u, \epsilon x) \\ &= \frac{1}{\epsilon} \psi_0(t, u) + \frac{1}{\epsilon} \langle \psi(t, u), \epsilon x \rangle = \frac{1}{\epsilon} \psi_0(t, u) + \langle \psi(t, u), x \rangle\end{aligned}$$

Seeing as $\text{span } \mathbb{X} = \mathbb{V}$, we may take appropriate linear combinations to show the remaining identities.

$$\psi_0^\epsilon(t, u) = \frac{1}{\epsilon} \psi_0(t, u), \quad \psi_i^\epsilon(t, u) = \psi_i(t, u), \quad i = 1, \dots, d$$

Remark 2.1.4. Note that the above proof can be applied to complex moments, since Theorem 1.1.4 and Remark 1.1.6 indicate to us that each $\Psi^\epsilon(\cdot, u, \cdot)$ is a solution to following equation, for each $u \in i\mathbb{V}$.

$$\forall x \in \mathbb{X}, \quad \begin{cases} \dot{\Psi}^\epsilon(t, u, x) = \Lambda^\epsilon(\psi^\epsilon(t, u), x), & t \geq 0 \\ \Psi^\epsilon(0, u, x) = \langle u, x \rangle \end{cases}$$

This parameterization also applies to the liftings $\Psi^\epsilon(\underline{t}, \cdot, \cdot)$ of Ψ^ϵ to finite-dimensional projections on partitions $\underline{t} \vdash [0, \infty)$.

$$\text{E}_{P_x^\epsilon} \exp \langle \underline{u}, \epsilon X_{\underline{t}}^\epsilon \rangle =: \exp \Psi(\underline{t}, \underline{u}, x/\epsilon), \quad \underline{u} \in \mathbb{V}^{|\underline{t}|}, \quad x \in \mathbb{X}$$

Denoting $\Psi(\underline{t}, \cdot, \cdot) := \Psi^1(\underline{t}, \cdot, \cdot)$, the below result shows just this.

Proposition 2.1.5. Assume \mathbb{X} is a cone satisfying $\text{span } \mathbb{X} = \mathbb{V}$. Fix $\underline{t} \vdash [0, \infty)$, $x_0 \in \mathbb{X}^\circ$, and $\epsilon > 0$ and define $U_{\underline{t}}$ as in Proposition 1.3.5. Each $\underline{u} \in \mathbb{V}^{|\underline{t}|}$ satisfying $\underline{u} = U_{\underline{t}}(\theta)$ for some $\theta \in \mathcal{D}_\Psi(\underline{t})$ satisfies

$$\Psi^\epsilon(\underline{t}, U_{\underline{t}}(\theta), x_0) = \frac{1}{\epsilon} \Psi(\underline{t}, U_{\underline{t}}(\theta), \epsilon x_0) < \infty,$$

and if no such $\theta \in \mathcal{D}_\Psi(\underline{t})$ exists, both are infinite.

$$\Psi^\epsilon(\underline{t}, \underline{u}, x_0) = \frac{1}{\epsilon} \Psi(\underline{t}, \underline{u}, \epsilon x_0) = \infty.$$

Proof. We start by recognizing two facts. Firstly, from Proposition 2.1.3, we have an identity of the following sets.

$$(2.1.6) \quad \mathcal{D}_{\Psi^\epsilon}(\underline{t}) = \prod_{k=1}^{|\underline{t}|} \mathcal{D}_{\Psi^\epsilon}(\Delta t_k) = \prod_{k=1}^{|\underline{t}|} \mathcal{D}_\Psi(\Delta t_k) = \mathcal{D}_\Psi(\underline{t}),$$

Secondly, Proposition 2.1.3 also shows us that the $U_{\underline{t}}^\epsilon$ associated with X^ϵ is identical to that $U_{\underline{t}}$ of X , as $\psi^\epsilon = \psi$. We now show the desired identity by fixing $\underline{u} \in \mathbb{V}^{|\underline{t}|}$ and considering each case.

First suppose $\underline{u} = U_{\underline{t}}(\theta)$ for some $\theta \in \mathcal{D}_\Psi(\underline{t})$. The identity of (2.1.6) tells us $\theta \in \mathcal{D}_{\Psi^\epsilon}(\underline{t})$ and so Propositions 1.3.5 and 2.1.3 give us the following.

$$\Psi^\epsilon(\underline{t}, \underline{u}, x_0) = \Psi^\epsilon(\underline{t}, U_{\underline{t}}(\theta), x_0)$$

$$\begin{aligned}
&= \sum_{k=1}^{|\underline{t}|} \psi_0^\epsilon(\Delta t_k, \theta_k) + \langle \psi^\epsilon(\Delta t_1, \theta_1), x_0 \rangle \\
&= \frac{1}{\epsilon} \left(\sum_{k=1}^{|\underline{t}|} \psi_0(\Delta t_k, \theta_k) + \langle \psi(\Delta t_1, \theta_1), \epsilon x_0 \rangle \right) \\
&= \frac{1}{\epsilon} \Psi(\underline{t}, U_{\underline{t}}(\underline{\theta}), \epsilon x_0) \\
&= \frac{1}{\epsilon} \Psi(\underline{t}, \underline{u}, \epsilon x_0)
\end{aligned}$$

On the other hand, suppose \underline{u} is not in the image of $\mathcal{D}_\Psi(\underline{t})$ under $U_{\underline{t}}$. Seeing as $x_0 \in \mathbb{X}^\circ$ and \mathbb{X} is a cone, we have $\epsilon x_0 \in \mathbb{X}^\circ$. Applying Theorem 1.3.11, we then have $\Psi(\underline{t}, \underline{u}, \epsilon x_0) = \infty$. The identity in (2.1.6) also tells us that \underline{u} is not in the image of $\mathcal{D}_\Psi(\underline{t})$ under $U_{\underline{t}}$. Theorem 1.3.11 now tell us $\Psi^\epsilon(\underline{t}, \underline{u}, x_0) = \infty$. We conclude our final identity.

$$\Psi^\epsilon(\underline{t}, \underline{u}, x_0) = \frac{1}{\epsilon} \Psi(\underline{t}, \underline{u}, \epsilon x_0) = \infty$$

Now that we have established parameterizations for just about every object that relates to an affine process, we establish some intuition on the relationship between these distributions $(P_x^\epsilon)_{\epsilon>0}$. The first of which is immediate from our preceding result, but it only makes sense when we consider the countable sequence $\epsilon_m := 1/m$ for $m \in \mathbb{N}$.

Proposition 2.1.7. *Assume \mathbb{X} is a cone with $\text{span } \mathbb{X} = \mathbb{V}$. For a fixed $x \in \mathbb{X}$, the family $(P_x^{\epsilon_m})_{\epsilon_m>0}$ corresponds to a mean-field regime. That is to say, if we fix a probability space (Ω, Σ, P) equipped with a sequence of independent quantities $(X^{(j)})_{j \in \mathbb{N}}$ each distributing according to P_x , then we may realize each $\epsilon_m X^{\epsilon_m}$ as follows.*

$$\epsilon_m X^{\epsilon_m} = \frac{1}{m} \sum_{j=1}^m X^{(j)}, \quad m \in \mathbb{N}$$

Proof. We will prove this by showing that the finite-dimensional distributions agree by identity of their characteristic functions. Fixing $\underline{t} \vdash [0, \infty)$ and $\underline{u} \in \mathbb{V}^{|\underline{t}|}$, we apply Proposition 1.3.2 and Remark 2.1.4.

$$\begin{aligned}
\log E_P \exp \left\langle i\underline{u}, \sum_{j=1}^m X_{\underline{t}}^{(j)} \right\rangle &= \log \left(E_{P_x} \exp \langle i\underline{u}, X_{\underline{t}} \rangle \right)^m \\
&= \log \left(\exp \Psi(\underline{t}, i\underline{u}, x) \right)^m \\
&= m \Psi(\underline{t}, i\underline{u}, x) \\
&= m \left(\sum_{k=1}^{|\underline{t}|} \psi_0(\Delta t_k, \theta_k) + \langle \psi(\Delta t_1, \theta), x \rangle \right) \\
&= \sum_{k=1}^{|\underline{t}|} \frac{1}{\epsilon_m} \psi_0(\Delta t_k, \theta_k) + \langle \psi(\Delta t_1, \theta), x/\epsilon_m \rangle \\
&= \sum_{k=1}^{|\underline{t}|} \psi_0^{\epsilon_m}(\Delta t_k, \theta_k) + \langle \psi^{\epsilon_m}(\Delta t_1, \theta), x/\epsilon_m \rangle
\end{aligned}$$

$$\begin{aligned}
&= \Psi^{\epsilon_m}(\underline{t}, \underline{u}, x/\epsilon_m) \\
&= \log \mathbb{E}_{P_x^{\epsilon_m}} \exp \langle \underline{u}, X_{\underline{t}} \rangle
\end{aligned}$$

We may also intuitively understand the relationship of $(P_x^\epsilon)_{x \in \mathbb{X}}$ from a dynamical system perspective. In Theorem A.1.14, we see how jump-diffusions X always correspond to a weak solution of some stochastic differential equation driven by standard Brownian motion W and Poisson random measure p .

$$\begin{aligned}
(2.1.8) \quad X_t &= X_0 + \beta^\chi(X) \cdot \ell_t + \sigma(X) \cdot W_t + \chi \circ c(X, \text{id}_\mathbb{V}) * \tilde{p}_t + \chi' \circ c(X, \text{id}_\mathbb{V}) * p_t \\
\forall x \in \mathbb{X}, \quad &\begin{cases} \mu(x, \Gamma) = \int_{\mathbb{V}} 1_\Gamma(c(x, v)) dv, & \Gamma \in \mathcal{B}(\mathbb{V} - \{0\}) \\ \alpha(x) = \sigma \sigma^*(x) \end{cases}
\end{aligned}$$

The following proposition gives perspectives on how the processes ϵX^ϵ may relate through these objects in two different perturbed dynamical systems.

Proposition 2.1.9. *Fix a probability space (Ω, Σ, P) equipped with standard Brownian motion W on \mathbb{V} and Poisson random measure p on $\mathcal{B}(\mathbb{R}_+ \times \mathbb{V})$. Let $\sigma : \mathbb{X} \rightarrow \mathbb{L}(\mathbb{V})$ and $c : \mathbb{X} \times \mathbb{V} \rightarrow \mathbb{V}$ satisfy (2.1.8) for the χ -differential characteristics $(\beta^\chi, \alpha, \mu)$, as granted by Theorem A.1.14. For each $x \in \mathbb{X}$, the family $(P_x^\epsilon)_{\epsilon > 0}$ of distributions P_x^ϵ may be recognized as each P_x^ϵ being a weak solution to the respective scaled stochastic dynamical system,*

$$\epsilon X_t^\epsilon = x + \beta^\chi(\epsilon X^\epsilon) \cdot \ell_t + \sqrt{\epsilon} \sigma(X) \cdot W_t + \chi \circ \epsilon c(\epsilon X^\epsilon, \sqrt[4]{\epsilon} \cdot \text{id}_\mathbb{V}) * \tilde{p}_t + \chi' \circ \epsilon c(\epsilon X^\epsilon, \sqrt[4]{\epsilon} \cdot \text{id}_\mathbb{V}) * p_t,$$

or the time-changed stochastic dynamical system.

$$\begin{aligned}
\epsilon X_t^\epsilon &= x + \beta^\chi(\epsilon X^\epsilon) \cdot \ell_t + \epsilon \sigma(X) \cdot W_t^\epsilon + \chi \circ \epsilon c(\epsilon X^\epsilon, \text{id}_\mathbb{V}) * \tilde{p}_t^\epsilon + \chi' \circ \epsilon c(\epsilon X^\epsilon, \text{id}_\mathbb{V}) * p_t^\epsilon, \\
W_t^\epsilon &:= W_{t/\epsilon} \\
p^\epsilon([0, t] \times \Gamma) &:= p([0, t/\epsilon] \times \Gamma)
\end{aligned}$$

Proof. By [JS03, III.2.26], it suffices to check if the characteristics of the above dynamical systems match those of ϵX^ϵ . We will instead match those of the scaled X^ϵ ; recall its characteristics, as specified by (2.1.1).

$$\langle X^{\epsilon, c, i}, X^{\epsilon, c, j} \rangle = \frac{1}{\epsilon} \alpha_{i, j}(\epsilon X^\epsilon) \cdot \ell, \quad \hat{q}^{X^\epsilon}(ds, dv) = \frac{1}{\epsilon} \mu(\epsilon X^\epsilon, dv) ds$$

Let us first address the first system. Note that for any $i, j = 1, \dots, d$, we use [JS03, Theorem I.4.40(d)] to resolve the predictable quadratic covariation of the continuous local martingale part $\frac{1}{\sqrt{\epsilon}} \sigma(\epsilon X^\epsilon) \cdot W$ of X^ϵ .

$$\begin{aligned}
\left\langle \left(\frac{1}{\sqrt{\epsilon}} \sigma(\epsilon X^\epsilon) \cdot W \right)^i, \left(\frac{1}{\sqrt{\epsilon}} \sigma(\epsilon X^\epsilon) \cdot W \right)^j \right\rangle &= \left\langle \sum_{l=1}^d \frac{1}{\sqrt{\epsilon}} \sigma_{i, l}(\epsilon X^\epsilon) \cdot W^l, \sum_{m=1}^d \frac{1}{\sqrt{\epsilon}} \sigma_{j, m}(\epsilon X^\epsilon) \cdot W^m \right\rangle \\
&= \frac{1}{\epsilon} \sum_{l, m=1}^d \sigma_{i, l}(\epsilon X^\epsilon) \sigma_{j, m}(\epsilon X^\epsilon) \cdot \langle W^l, W^m \rangle \\
&= \frac{1}{\epsilon} \sum_{l=1}^d \sigma_{i, l}(\epsilon X^\epsilon) \sigma_{j, l}(\epsilon X^\epsilon) \cdot \ell
\end{aligned}$$

$$\begin{aligned}
&= \frac{1}{\epsilon} \alpha_{i,j}(\epsilon X^\epsilon) \cdot \ell \\
&= \langle X^{\epsilon,c,i}, X^{\epsilon,c,j} \rangle
\end{aligned}$$

Note that the accumulated jump process associated from X^ϵ in these dynamics is the following process.

$$t \mapsto \sum_{0 < s \leq t} c(\epsilon X_{s-}^\epsilon, \sqrt[d]{\epsilon} \cdot \epsilon \Delta X_s^\epsilon)$$

This allows us to see that, for a non-negative predictable process $H : \Omega \times \mathbb{R}_+ \times \mathbb{V} \rightarrow \mathbb{R}$, we have the following identities, via changing coordinates.

$$\begin{aligned}
\mathbb{E}_P \left(H * q_\infty^{X^\epsilon} \right) &= \mathbb{E}_P \int_{\mathbb{R}_+ \times \mathbb{V}} H(\cdot, s, c(\epsilon X_{s-}^\epsilon, \sqrt[d]{\epsilon} \cdot v)) p(ds, dv) \\
&= \mathbb{E}_P \int_0^\infty \int_{\mathbb{V}} H(\cdot, s, c(\epsilon X_{s-}^\epsilon, \sqrt[d]{\epsilon} \cdot v)) dv ds \\
&= \mathbb{E}_P \int_0^\infty \int_{\mathbb{V}} H(\cdot, s, c(\epsilon X_{s-}^\epsilon, v)) \frac{1}{\epsilon} dv ds & v \leftarrow \sqrt[d]{\epsilon} \cdot v \\
&= \mathbb{E}_P \int_0^\infty \int_{\mathbb{V}} H(\cdot, s, v) \frac{1}{\epsilon} \mu(\epsilon X_{s-}^\epsilon, dv) ds & v \leftarrow c(X_{s-}, v)
\end{aligned}$$

Now we address the second system using the same calculations; the continuous local martingale term of X^ϵ in this case is $\sigma(\epsilon X^\epsilon) \cdot W$, and we have the following identity.

$$\begin{aligned}
\left\langle (\sigma(\epsilon X^\epsilon) \cdot W^\epsilon)^i, (\sigma(\epsilon X^\epsilon) \cdot W^\epsilon)^j \right\rangle &= \left\langle \sum_{l=1}^d \sigma_{i,l}(\epsilon X^\epsilon) \cdot W^{\epsilon,l}, \sum_{m=1}^d \sigma_{j,m}(\epsilon X^\epsilon) \cdot W^{\epsilon,m} \right\rangle \\
&= \sum_{l,m=1}^d \sigma_{i,l}(\epsilon X^\epsilon) \sigma_{j,m}(\epsilon X^\epsilon) \cdot \langle W^{\epsilon,l}, W^{\epsilon,m} \rangle \\
&= \sum_{l=1}^d \sigma_{i,l}(\epsilon X^\epsilon) \sigma_{j,l}(\epsilon X^\epsilon) \cdot (\epsilon^{-1} \ell) \\
&= \frac{1}{\epsilon} \alpha_{i,j}(\epsilon X^\epsilon) \cdot \ell \\
&= \langle X^{\epsilon,c,i}, X^{\epsilon,c,j} \rangle
\end{aligned}$$

Meanwhile, our time-change of the Poisson random measure immediately gives us our desired characteristic.

$$\begin{aligned}
\mathbb{E}_P \left(H * q_\infty^{X^\epsilon} \right) &= \mathbb{E}_P \int_{\mathbb{R}_+ \times \mathbb{V}} H(\cdot, s, c(\epsilon X_{s-}^\epsilon, v)) p^\epsilon(ds, dv) \\
&= \mathbb{E}_P \int_0^\infty \int_{\mathbb{V}} H(\cdot, s, c(\epsilon X_{s-}^\epsilon, v)) dv \cdot \frac{1}{\epsilon} ds \\
&= \mathbb{E}_P \int_0^\infty \int_{\mathbb{V}} H(\cdot, s, v) \frac{1}{\epsilon} \mu(\epsilon X_{s-}^\epsilon, dv) ds & v \leftarrow c(X_{s-}, v)
\end{aligned}$$

2.2 Assumptions

We now clearly spell out the assumptions we will need to prove our large deviation principle. The first of which concerns existence of our affine processes.

As mentioned in the previous section, the base parameters (β^X, α, μ) parameterize those $(\beta^{X^\epsilon}, \alpha^\epsilon, \mu^\epsilon)$ for each $\epsilon > 0$. This means that selecting the base affine process X immediately imposes the laws ϵX^ϵ for all other $\epsilon > 0$, *should they exist*. Generally speaking, there exist functions (β^X, α, μ) for which there is no jump-diffusion that makes them differential characteristics. Proposition 2.1.7 indicated that, should distributions $(P_x)_{x \in \mathbb{X}}$ exist for an affine process X with differential characteristics (β^X, α, μ) , then we can construct distributions $P_x^{\epsilon_m}$ for each $m \in \mathbb{N}$ and $x \in \mathbb{X}$ by taking convolutions (recall, $\epsilon_m := 1/m$). However, we find it important to establish our large deviation principle over a continuously defined family $\epsilon > 0$. This now motivates the following assumption, which was already implicitly assumed in the previous section.

Assumption 2.2.1. *The affine parameters (β^X, α, μ) are chosen so that each $\epsilon \in (0, 1]$, affine processes X^ϵ exist which exhibit the parameters $(\beta^{X^\epsilon}, \alpha^\epsilon, \mu^\epsilon)$ as in (2.1.1).*

Remark 2.2.2. (a) *If we wanted to show a large deviation principle over only the family $(\epsilon_m X^{\epsilon_m})_{m \in \mathbb{N}}$, then this assumption is unnecessary.*

(b) *Selecting (β^X, α, μ) parameterizes each Λ^ϵ , which does specify the systems (1.1.7) and (1.2.2) associated with complex and real moments, respectively. There are already many results which allow one to say that X^ϵ exists in this scenario. For instance, if our state space is $\mathbb{X} = \mathbb{R}_+^m \times \mathbb{R}^n$, then [DFS03, Proposition 7.4] provides us the existence we require, so long as the parameters are chosen to be admissible. Otherwise, one can specify weaker assumptions on \mathbb{X} at the expense of choosing diffusions $(\mu(\cdot, dv) = 0)$ or pure-jump processes $(\alpha = 0)$ on certain factors of the space; see [Cuc11, Section 2.5, Section 3.4].*

Our proof ultimately comes from the parameterizations of our moment functions Ψ^ϵ in the previous section. These relied on \mathbb{X} being a cone, so we specifically mention that here.

Assumption 2.2.3. *The space \mathbb{X} is a cone and $\text{span } \mathbb{X} = \mathbb{V}$.*

Remark 2.2.4. *Note that $\text{span } \mathbb{X}$ is at no loss of generality, per Remark 1.1.3.*

Our last assumption is of key importance. Large deviations are best understood through moment generating functions, which serve no purpose if they are not finite. For an initial point $x_0 \in \mathbb{X}^\circ$, a large deviation principle holds for a family $(P_{x_0}^\epsilon)_{\epsilon > 0}$ on the projective limit space (i.e. the product topology), so long as $0 \in \mathcal{D}_\Lambda^\circ$. However, in order to strengthen this result to the Skorokhod topology—a step which is necessary for interesting asymptotics and an integral-form of our rate function—we need the full strength of $\mathcal{D}_\Lambda = \mathbb{V}$.

Assumption 2.2.5. *We have $\mathcal{D}_\Lambda = \mathbb{V}$; equivalently, by Lemma A.4.2,*

$$\int_{|v| > 1} e^{\langle u, v \rangle} \mu(x, dv) < \infty, \quad x \in \mathbb{X}, \quad u \in \mathcal{D}_\Psi$$

Remark 2.2.6. (a) *It is easy to see in the proofs where we assume $\mathcal{D}_\Lambda = \mathbb{V}$ versus simply using $0 \in \mathcal{D}_\Lambda^\circ$.*

- (b) By imposing even the simpler of the two assumptions that $0 \in \mathcal{D}_\Lambda^\circ$ immediately tells us that all X^ϵ are special, and so we proceed the rest of the chapter with a presentation in terms of special differential characteristics (β, α, μ) .

With this assumption in mind, we state versions of the propositions at the end of Section 1.2 in our scenario.

Proposition 2.2.7. (a) For each $\tau > 0$, $\mathcal{D}_\Psi(\tau)$ is open; in particular, there exists $\delta > 0$ such that $B(0, \delta) \subseteq \mathcal{D}_\Psi(\tau)$.

- (b) For each $\tau > 0$ and $u \in \mathcal{D}_\Psi(\tau)$, $\Psi(\cdot, u, \cdot)$ from Theorem 1.2.3 is the unique solution to system (Λ, τ, u) .

- (c) For each $M > 0$, there exists $\delta > 0$ such that $\overline{B}(0, M) \subseteq \mathcal{D}_\Psi(\delta)$.

- (d) For each $M > 0$, there exist $\delta > 0$ and C_M such that the following holds.

$$|\Psi(t, u, x) - \Psi(0, u, x)| \leq C_M \cdot t \cdot (1 + |x|), \quad t \in [0, \delta], \quad u \in \overline{B}(0, M), \quad x \in \mathbb{X}$$

Proof. (a) Proposition 1.2.5(a) tells us that $\mathcal{D}_\Psi(\tau)$ is open in $\mathcal{D}_\Lambda^\circ$, which is now \mathbb{V} by our assumption. Also, seeing as $\mathbb{E}_{P_x} \exp \langle 0, X_\tau \rangle = 1 < \infty$ for all $x \in \mathbb{X}$, $0 \in \mathcal{D}_\Psi(\tau)$. Openness of $\mathcal{D}_\Psi(\tau)$ now grants some $B(0, \delta) \subseteq \mathcal{D}_\Psi(\tau)$.

- (b) Proposition 1.2.5(b) gives us uniqueness of $\Psi(\cdot, u, \cdot)$ as a solution to system (Λ, τ, u) for any $u \in \mathcal{D}_\Psi(\tau) \cap \mathcal{D}_\Lambda^\circ$, which is now the same thing as $u \in \mathcal{D}_\Psi(\tau)$.

- (c) Seeing as $\mathcal{D}_\Lambda = \mathbb{V}$, we now have $\overline{B}(0, M) \subseteq \mathcal{D}_\Lambda^\circ$, so Proposition 1.2.7 gives us $\delta > 0$ such that $\overline{B}(0, M) \subseteq \mathcal{D}_\Psi(\delta)$.

- (d) Fix $M > 0$. By part (c), there exists $\delta > 0$ such that $\overline{B}(0, 2M) \subseteq \mathcal{D}_\Psi(2\delta)$. Now, $[0, \delta] \times \overline{B}(0, M)$ is a compact subset of \mathcal{D}_Ψ° , and so Proposition 1.2.9 gives us our desired C_M .

2.3 Dawson-Gärtner

This section proves our large deviation principle from a perspective similar to that of Dawson-Gärtner (see [DZ10, Theorem 4.6.1]), in which we prove the principle for the finite-dimensional projections, so that we get a principle on the projective space associated with $\mathbb{D}([0, \infty), \mathbb{X})$ that we may tighten to the Skorokhod space through exponential tightness. Though we attribute this approach to the names of Dawson and Gärtner, we specifically use results in [FK06] which instead use results which appeal more to weak convergence arguments that are comparable to Prokhorov on an exponential scale.

Theorem 2.3.1. For each $x \in \mathbb{X}^\circ$ and $\underline{t} \vdash [0, \infty)$, the family $(\pi_{\underline{t}\#} P_x^\epsilon)_{\epsilon > 0}$ satisfies a large deviation principle on $\mathbb{V}^{|\underline{t}|}$ with good convex rate function $\Psi^*(\underline{t}, \cdot, x)$, the Fenchel-Legendre transform of $\Psi(\underline{t}, \cdot, x)$.

$$\Psi^*(\underline{t}, \underline{x}, x) := \sup_{\underline{u} \in \mathbb{V}^{|\underline{t}|}} \left(\langle \underline{u}, \underline{x} \rangle - \Psi(\underline{t}, \underline{u}, x) \right)$$

Proof. We first prove a principle on the discrete family $(\pi_{t\#} P_x^{\epsilon_m})_{m \in \mathbb{N}}$ for $\epsilon_m := 1/m$. Note that Proposition 2.1.7 allows us to consider a space (Ω, Σ, P) equipped with an i.i.d. sequence $(X^{(j)})_{j \in \mathbb{N}}$ of elements distributing from P_x and realize each $\epsilon_m X^{\epsilon_m}$.

$$\epsilon_m X^{\epsilon_m} = \frac{1}{m} \sum_{j=1}^m X^{(j)}$$

We now use a specific instance of Cramér's theorem [DZ10, Corollary 6.1.6] to conclude that if $\underline{0}$ is an interior point in the finite domain of $\Psi(\underline{t}, \cdot, x)$, then our principle is satisfied with good rate function $\Psi^*(\underline{t}, \cdot, x)$. Note that Proposition 2.2.7(a) tells us that $\underline{0} \in \mathcal{D}_\Psi(\underline{t})$, an open set. Denoting some ball $B(\underline{0}, \delta) \subseteq \mathcal{D}_\Psi(\underline{t})$, Theorem 1.3.11 indicates that $U_{\underline{t}} B(\underline{0}, \delta)$ is an open set containing $\underline{0}$ in the finite domain of $\Psi(\underline{t}, \cdot, x)$.

Now that we have established a large deviation principle for $(\pi_{t\#} P_x^{\epsilon_m})_{m \in \mathbb{N}}$, we seek to establish one for $(\pi_{t\#} P_x^\epsilon)_{\epsilon > 0}$. We start by defining a map $\epsilon \mapsto \tilde{\epsilon}$ which discretizes the nature of $\epsilon > 0$; denoting $[r] \in \mathbb{Z}$ the integer part of $r \in \mathbb{R}$, define $\tilde{\epsilon} := [\epsilon^{-1}]^{-1}$. The following quick inequalities relating ϵ and $\tilde{\epsilon}$,

$$\tilde{\epsilon} - \tilde{\epsilon}^2 < \epsilon \leq \tilde{\epsilon}$$

make it easy to directly show $(\pi_{t\#} P_x^{\tilde{\epsilon}})_{\epsilon > 0}$ satisfies a large deviation principle; for each $\Gamma \in \mathcal{B}(\mathbb{V}^{|\underline{t}|})$,

$$\begin{aligned} - \inf_{\underline{x} \in \Gamma^\circ} \Psi^*(\underline{t}, \underline{x}, x) &\leq \liminf_{m \rightarrow \infty} \epsilon_m \log \pi_{t\#} P_x^{\epsilon_m} \Gamma \\ &= \liminf_{\epsilon \rightarrow 0} \tilde{\epsilon} \log \pi_{t\#} P_x^{\tilde{\epsilon}} \Gamma \\ &\leq \liminf_{\epsilon \rightarrow 0} (\epsilon + \tilde{\epsilon}^2) \log \pi_{t\#} P_x^{\tilde{\epsilon}} \Gamma \\ &= \liminf_{\epsilon \rightarrow 0} \epsilon \log \pi_{t\#} P_x^{\tilde{\epsilon}} \Gamma \\ &\leq \limsup_{\epsilon \rightarrow 0} \epsilon \log \pi_{t\#} P_x^{\tilde{\epsilon}} \Gamma \\ &\leq \limsup_{\epsilon \rightarrow 0} \tilde{\epsilon} \log \pi_{t\#} P_x^{\tilde{\epsilon}} \Gamma \\ &= \limsup_{m \rightarrow \infty} \epsilon_m \log \pi_{t\#} P_x^{\epsilon_m} \Gamma \leq - \inf_{\underline{x} \in \bar{\Gamma}} \Psi^*(\underline{t}, \underline{x}, x) \end{aligned}$$

To obtain a large deviation principle for our family $(\pi_{t\#} P_x^\epsilon)_{\epsilon > 0}$, we show regularity $\epsilon \rightarrow \pi_{t\#} P_x^\epsilon$ to lift the principle for the discretized family $(\pi_{t\#} P_x^{\tilde{\epsilon}})_{\epsilon > 0}$. This notion in the literature is known as an *exponential approximation*, which is explored in [DZ10, Section 4.2.2]. From [DZ10, Theorem 4.2.13], it suffices to construct a probability space (Ω, Σ, P) such that elements $(\epsilon X^\epsilon)_{\epsilon > 0}$ on this space with distributions $(P_x^\epsilon)_{\epsilon > 0}$ satisfy the following exponential equivalence property.

$$\limsup_{\epsilon \rightarrow 0} \epsilon \log P \left(|\epsilon X_t^\epsilon - \tilde{\epsilon} X_{\tilde{t}}^{\tilde{\epsilon}}| > \delta \right) = -\infty$$

The *scaled-dynamics* realization from Proposition 2.1.9 will do just this.

Cramér's theorem—the tool we leveraged to prove the above principle—is proven by using measure changes induced by densities of the following form.

$$\exp \left(\langle \underline{u}, X_{\underline{t}}^\epsilon \rangle - \Psi^\epsilon(\underline{t}, \underline{u}, X_0^\epsilon) \right)$$

Observe that Theorem 1.3.11 gives us a perspective of how this measure depends on the increments; a valid moment $\underline{u} \in \mathbb{V}^{|\underline{t}|}$ for the above expression must satisfy $\underline{u} = U_{\underline{t}}(\underline{\theta})$ for some $\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})$, and

$$\exp\left(\langle \underline{u}, X_{\underline{t}}^\epsilon \rangle - \Psi^\epsilon(\underline{t}, \underline{u}, X_0^\epsilon)\right) = \exp\sum_{k=1}^{|\underline{t}|} \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon)\right) =: \underline{Z}^{\epsilon, \underline{t}, \underline{\theta}}$$

We denote these changes of measure like so,

$$\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}(d\omega) := \underline{Z}^{\epsilon, \underline{t}, \underline{\theta}}(\omega) \cdot P(d\omega),$$

and observe the nature of how they make our increments distribute.

Proposition 2.3.2. *Fix $\epsilon > 0$, $x \in \mathbb{X}$, $\underline{t} \vdash [0, \infty)$, and $\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})$. For each $\ell = 1, \dots, |\underline{t}|$ and $\theta \in \mathbb{V}$ with $\theta_\ell + \theta \in \mathcal{D}_\Psi(\Delta t_\ell)$, we have the following moments.*

$$\begin{aligned} \mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\exp \langle \theta, X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon \rangle | \mathcal{F}_{t_{\ell-1}}^\epsilon \right) \\ = \exp \left(\varphi^\epsilon(\Delta t_\ell, \theta_\ell + \theta, X_{t_{\ell-1}}^\epsilon) - \varphi^\epsilon(\Delta t_\ell, \theta_\ell, X_{t_{\ell-1}}^\epsilon) \right) \end{aligned}$$

This furthermore means we have the following conditional expectations.

$$\mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\epsilon X_{t_\ell}^\epsilon - \epsilon X_{t_{\ell-1}}^\epsilon | \epsilon X_{\underline{t}_{1:\ell-1}}^\epsilon = \underline{x}_{1:\ell-1} \right) = \nabla_{\theta_\ell} \varphi(\Delta t_\ell, \theta_\ell, x_{\ell-1})$$

Proof. Denote $n := |\underline{t}|$ for brevity. We first show the following conditional expectation for any $m = n - 1, \dots, 1$.

$$(2.3.3) \quad \mathbb{E}_{P_x^\epsilon} \left(\underline{Z}^{\epsilon, \underline{t}, \underline{\theta}} | \mathcal{F}_{t_m}^\epsilon \right) = \prod_{k=1}^m \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right),$$

by iteratively projecting onto $\mathcal{F}_{t_n}^\epsilon, \dots, \mathcal{F}_{t_{m+1}}^\epsilon$. For any quantity $H \in \mathcal{F}_{t_m}/\mathcal{B}(\mathbb{R}_+)$, we have the following.

$$\begin{aligned} & \mathbb{E}_{P_x^\epsilon} \left(H \underline{Z}^{\epsilon, \underline{t}, \underline{\theta}} \right) \\ &= \mathbb{E}_{P_x^\epsilon} \left(H \prod_{k=1}^n \exp \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right) \right) \\ &= \mathbb{E}_{P_x^\epsilon} \left(H \prod_{k=1}^{n-1} \exp \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right) \right. \\ & \quad \left. \mathbb{E}_{P_x^\epsilon} \left(\exp \langle \theta_n, X_{t_n}^\epsilon - X_{t_{n-1}}^\epsilon \rangle | \mathcal{F}_{t_{n-1}}^\epsilon \right) \exp \left(- \varphi^\epsilon(\Delta t_n, \theta_n, X_{t_{n-1}}^\epsilon) \right) \right) \\ &= \mathbb{E}_{P_x^\epsilon} \left(H \prod_{k=1}^{n-1} \exp \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right) \right) \\ & \quad \vdots \\ &= \mathbb{E}_{P_x^\epsilon} \left(H \prod_{k=1}^m \exp \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right) \right) \end{aligned}$$

which indicates that (2.3.3) is true. Now choosing $H \in \mathcal{F}_{t_{\ell-1}}^\epsilon / \mathcal{B}(\mathbb{R}_+)$, we apply (2.3.3) for $m = \ell$ and $m = \ell - 1$ to see that the following holds.

$$\begin{aligned}
& \mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\exp \langle \theta, X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon \rangle H \right) \\
&= \mathbb{E}_{P_x^\epsilon} \left(\exp \langle \theta, X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon \rangle H \underline{Z}^{\epsilon, \underline{t}, \underline{\theta}} \right) \\
&= \mathbb{E}_{P_x^\epsilon} \left(\exp \langle \theta, X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon \rangle H \prod_{k=1}^{\ell} \exp \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right) \right) \\
&= \mathbb{E}_{P_x^\epsilon} \left(H \prod_{k=1}^{\ell-1} \exp \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right) \right. \\
&\quad \left. \mathbb{E}_{P_x^\epsilon} \left(\exp \langle \theta_\ell + \theta, X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon \rangle | \mathcal{F}_{t_{\ell-1}}^\epsilon \right) \exp \left(- \varphi^\epsilon(\Delta t_\ell, \theta_\ell, X_{t_{\ell-1}}^\epsilon) \right) \right) \\
&= \mathbb{E}_{P_x^\epsilon} \left(H \prod_{k=1}^{\ell-1} \exp \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right) \right. \\
&\quad \left. \exp \left(\varphi^\epsilon(\Delta t_\ell, \theta_\ell + \theta, X_{t_{\ell-1}}^\epsilon) - \varphi^\epsilon(\Delta t_\ell, \theta_\ell, X_{t_{\ell-1}}^\epsilon) \right) \right) \\
&= \mathbb{E}_{P_x^\epsilon} \left(\exp \left(\varphi^\epsilon(\Delta t_\ell, \theta_\ell + \theta, X_{t_{\ell-1}}^\epsilon) - \varphi^\epsilon(\Delta t_\ell, \theta_\ell, X_{t_{\ell-1}}^\epsilon) \right) H \underline{Z}^{\epsilon, \underline{t}, \underline{\theta}} \right) \\
&= \mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\exp \left(\varphi^\epsilon(\Delta t_\ell, \theta_\ell + \theta, X_{t_{\ell-1}}^\epsilon) - \varphi^\epsilon(\Delta t_\ell, \theta_\ell, X_{t_{\ell-1}}^\epsilon) \right) H \right)
\end{aligned}$$

This gives us our first desired identity.

$$\begin{aligned}
& \mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\exp \langle \theta, X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon \rangle | \mathcal{F}_{t_{\ell-1}}^\epsilon \right) \\
&= \exp \left(\varphi^\epsilon(\Delta t_\ell, \theta_\ell + \theta, X_{t_{\ell-1}}^\epsilon) - \varphi^\epsilon(\Delta t_\ell, \theta_\ell, X_{t_{\ell-1}}^\epsilon) \right)
\end{aligned}$$

Now that this identity is established, we appeal to Propositions 2.2.7(a), 1.2.9, and 2.1.3 in specifying an open ball $B(\theta_k, \delta) \subseteq \mathcal{D}_\Psi(\Delta t_k)$ on which we may apply derivatives to get the following identity.

$$\begin{aligned}
\mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\epsilon X_{t_\ell}^\epsilon - \epsilon X_{t_{\ell-1}}^\epsilon | \mathcal{F}_{t_{\ell-1}}^\epsilon \right) &= \epsilon \mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon | \mathcal{F}_{t_{\ell-1}}^\epsilon \right) \\
&= \epsilon \mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\nabla_\theta \exp \langle \theta, X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon \rangle |_{\theta=0} | \mathcal{F}_{t_{\ell-1}}^\epsilon \right) \\
&= \epsilon \nabla_\theta \mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\exp \langle \theta, X_{t_\ell}^\epsilon - X_{t_{\ell-1}}^\epsilon \rangle | \mathcal{F}_{t_{\ell-1}}^\epsilon \right) \Big|_{\theta=0} \\
&= \epsilon \nabla_\theta \exp \left(\varphi^\epsilon(\Delta t_\ell, \theta_\ell + \theta, X_{t_{\ell-1}}^\epsilon) - \varphi^\epsilon(\Delta t_\ell, \theta_\ell, X_{t_{\ell-1}}^\epsilon) \right) \Big|_{\theta=0} \\
&= \nabla_\theta \exp \left(\varphi^\epsilon(\Delta t_\ell, \theta_\ell + \theta, \epsilon X_{t_{\ell-1}}^\epsilon) - \varphi^\epsilon(\Delta t_\ell, \theta_\ell, \epsilon X_{t_{\ell-1}}^\epsilon) \right) \Big|_{\theta=0} \\
&= \nabla_{\theta_\ell} \varphi(\Delta t_\ell, \theta_\ell, \epsilon X_{t_{\ell-1}}^\epsilon)
\end{aligned}$$

Seeing as the above quantity is measurable with respect to the σ -algebra generated by $X_{\underline{t}_{1:\ell}}$, we have our desired identity.

$$\mathbb{E}_{\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}} \left(\epsilon X_{t_\ell}^\epsilon - \epsilon X_{t_{\ell-1}}^\epsilon | \epsilon X_{\underline{t}_{1:\ell-1}}^\epsilon = \underline{x}_{1:\ell-1} \right) = \nabla_{\theta_\ell} \varphi(\Delta t_\ell, \theta_\ell, \epsilon X_{t_{\ell-1}}^\epsilon)$$

Understanding these measures $\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}$ will be important for our next section, where we relate the seemingly alternative exponential martingale method to studying large deviations. We now proceed from that short tangent back to our large deviation principle.

Proposition 2.3.4. *For each $x \in \mathbb{X}$, the family $(P_x^\epsilon)_{\epsilon > 0}$ is exponentially tight on $\mathbb{D}([0, \infty), \mathbb{X})$.*

Proof. First note that each family $(\pi_{t\#} P_x^\epsilon)_{\epsilon > 0}$ of finite-dimensional distributions is exponentially tight by Theorem 2.3.1; for each $\alpha > 0$, $K_\alpha = \Psi^*(\underline{t}, \cdot, x)^{-1}[0, \alpha]$ is a compact subset of $\mathbb{V}^{|\underline{t}|}$ (by goodness of the rate function) clearly satisfying the following.

$$\limsup_{\epsilon \rightarrow 0} \epsilon \log \pi_{t\#} P_x^\epsilon(K_\alpha^c) \leq - \inf_{\underline{x} \in K_\alpha^c} \Psi^*(\underline{t}, \underline{x}, x) \leq -\alpha$$

By [FK06, Theorem 4.1] (rather, adapting to continuously parameterized family), our desired exponential tightness is obtained if we produce to each $\epsilon, \delta, \lambda, T > 0$ a random variable $\gamma_\epsilon(\delta, \lambda, T)$ with the following dominating property over all $t \in [0, T]$, $s \in [0, \delta]$,

$$(2.3.5) \quad \mathbb{E}_{P_x} \left(\exp \left(\epsilon^{-1} \lambda (|\epsilon X_{t+s}^\epsilon - \epsilon X_t^\epsilon| \wedge 1) \right) \middle| \mathcal{F}_t^\epsilon \right) \leq \mathbb{E}_{P_x} \left(\exp \gamma_\epsilon(\delta, \lambda, T) \middle| \mathcal{F}_t^\epsilon \right),$$

such that the following equalities are true for all $\lambda > 0$.

$$(2.3.6) \quad \lim_{\delta \rightarrow 0} \limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{E}_{P_x} \exp \left(\epsilon^{-1} \lambda (|\epsilon X_\delta^\epsilon - \epsilon X_0^\epsilon| \wedge 1) \right) = 0$$

$$(2.3.7) \quad \lim_{\delta \rightarrow 0} \limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{E}_{P_x} \exp \gamma_\epsilon(\delta, \lambda, T) = 0$$

To show this fact, first note that, by Proposition 2.2.7(d), to each $\lambda > 0$ there exist $\delta_\lambda > 0$ and $C_\lambda > 0$ such that the following inequality holds.

$$|\Psi(t, u, x) - \Psi(0, u, x)| \leq C_\lambda \cdot t \cdot (1 + |x|), \quad t \in [0, \delta_\lambda], \quad u \in \overline{B}(0, \lambda\sqrt{d}), \quad x \in \mathbb{X}$$

We then define the following function $f_\epsilon(\cdot, \delta, \lambda) : \mathbb{X} \rightarrow \mathbb{R}$ for each $\epsilon > 0$, $\lambda > 0$, and $\delta \in [0, \delta_\lambda]$.

$$f_\epsilon(x', \delta, \lambda) := \log 2d + \frac{1}{\epsilon} \cdot C_\lambda \cdot \delta \cdot (1 + |x|)$$

We now define $\gamma_\epsilon(\delta, \lambda, T) := f_\epsilon(\epsilon X_t^\epsilon, \delta, \lambda)$.

Note that for all $\lambda, \epsilon, t > 0$, $\delta \in [0, \delta_\lambda]$, and $s \in [0, \delta]$, we use Proposition 2.1.3 to get the following.

$$\begin{aligned} & \mathbb{E}_{P_x} \left(\exp \left(\epsilon^{-1} \lambda (|\epsilon X_{t+s}^\epsilon - \epsilon X_t^\epsilon| \wedge 1) \right) \middle| \mathcal{F}_t^\epsilon \right) \\ & \leq \mathbb{E}_{P_x} \left(\exp \left(\epsilon^{-1} \lambda |\epsilon X_{t+s}^\epsilon - \epsilon X_t^\epsilon| \right) \middle| \mathcal{F}_t^\epsilon \right) \\ & \leq \sum_{\ell=0}^1 \sum_{i=1}^d \mathbb{E}_{P_x} \left(\exp \left(\left\langle (-1)^\ell \epsilon^{-1} \lambda \sqrt{d} e^i, \epsilon X_{t+s}^\epsilon - \epsilon X_t^\epsilon \right\rangle \right) \middle| \mathcal{F}_t^\epsilon \right) \\ & = \sum_{\ell=0}^1 \sum_{i=1}^d \exp \left(\epsilon^{-1} \Psi \left(s, (-1)^\ell \lambda \sqrt{d} e^i, \epsilon X_t^\epsilon \right) - \epsilon^{-1} \left\langle (-1)^\ell \lambda \sqrt{d} e^i, \epsilon X_t^\epsilon \right\rangle \right) \\ & \leq 2d \cdot \exp \left(\frac{1}{\epsilon} \cdot C_\lambda \cdot \delta \cdot (1 + |\epsilon X_t^\epsilon|) \right) \end{aligned}$$

$$(2.3.8) \quad = \exp f_\epsilon(\epsilon X_t^\epsilon, \delta, \lambda)$$

Note that (2.3.8) makes (2.3.5) true.

$$\begin{aligned} \mathbb{E}_{P_x} \left(\exp \left(\epsilon^{-1} \lambda (|\epsilon X_{t+s}^\epsilon - \epsilon X_t^\epsilon| \wedge 1) \right) | \mathcal{F}_t^\epsilon \right) &\leq \exp f_\epsilon(\epsilon X_t^\epsilon, \delta, \lambda) \\ &= \exp \gamma_\epsilon(\delta, \lambda, T) \\ &= \mathbb{E}_{P_x} \left(\exp \gamma_\epsilon(\delta, \lambda, T) | \mathcal{F}_t^\epsilon \right) \end{aligned}$$

For (2.3.6), we also use (2.3.8).

$$\begin{aligned} &\lim_{\delta \rightarrow 0} \limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{E}_{P_x} \exp \left(\epsilon^{-1} \lambda (|\epsilon X_\delta^\epsilon - \epsilon X_0^\epsilon| \wedge 1) \right) \\ &= \lim_{\delta \rightarrow 0} \limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{E}_{P_x} \mathbb{E}_{P_x} \left(\exp \left(\epsilon^{-1} \lambda (|\epsilon X_\delta^\epsilon - \epsilon X_0^\epsilon| \wedge 1) \right) | \mathcal{F}_0^\epsilon \right) \\ &\leq \lim_{\delta \rightarrow 0} \limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{E}_{P_x} \exp f_\epsilon(\epsilon X_0^\epsilon, \delta, \lambda) \\ &= \lim_{\delta \rightarrow 0} \limsup_{\epsilon \rightarrow 0} \left(\epsilon \log 2d + C_\lambda \cdot \delta \cdot (1 + |x|) \right) \\ &= 0 \end{aligned}$$

Using Proposition 2.2.7(a), to each $\lambda > 0$, there exists $\delta'_\lambda > 0$ such that $B(0, \delta_\lambda) \subseteq \mathcal{D}_\Psi(\delta'_\lambda)$. Now, for any $\delta < \delta_\lambda \wedge \delta'_\lambda / (2C_\lambda \sqrt{d})$, we again use Proposition 2.1.3 to get the following.

$$\begin{aligned} &\epsilon \log \mathbb{E}_{P_x} \left(\exp \gamma_\epsilon(\delta, \lambda, T) \right) \\ &= \epsilon \log \mathbb{E}_{P_x} \left(\exp f_\epsilon(\epsilon X_t^\epsilon, \delta, \lambda) \right) \\ &= \epsilon \log 2d + C_\lambda \cdot \delta + \epsilon \log \mathbb{E}_{P_x} \exp \left(\epsilon^{-1} C_\lambda \delta |\epsilon X_t^\epsilon| \right) \\ &\leq \epsilon \log 2d + C_\lambda \cdot \delta + \epsilon \log \sum_{\ell=0}^1 \sum_{i=1}^d \mathbb{E}_{P_x} \exp \left\langle (-1)^\ell \epsilon^{-1} C_\lambda \delta \sqrt{d} e^i, \epsilon X_t^\epsilon \right\rangle \\ &\leq 2\epsilon \log 2d + C_\lambda \cdot \delta + \max_{\substack{\ell=0,1 \\ i=1,\dots,d \\ k=1,\dots,|t|}} \epsilon \log \mathbb{E}_{P_x} \exp \left\langle (-1)^\ell \epsilon^{-1} C_\lambda \delta \sqrt{d} e^i, \epsilon X_t^\epsilon \right\rangle \\ &\leq 2\epsilon \log 2d + C_\lambda \cdot \delta + \max_{\substack{\ell=0,1 \\ i=1,\dots,d \\ k=1,\dots,|t|}} \Psi \left(t, (-1)^\ell C_\lambda \delta \sqrt{d} e^i, x \right) \end{aligned}$$

This gives us (2.3.7).

Theorem 2.3.9. *For each $x \in \mathbb{X}^\circ$, the family $(P_x^\epsilon)_{\epsilon > 0}$ satisfies a large deviation principle on $\mathbb{D}([0, \infty), \mathbb{X})$ with good rate function $I_x : \mathbb{D}([0, \infty), \mathbb{X}) \rightarrow [0, \infty]$ as follows.*

$$(2.3.10) \quad I_x(\xi) = \begin{cases} \sup_{t \in \Delta_\xi^c} \Psi^*(t, \xi(t), \xi(0)) & \xi(0) = x \\ \infty & \text{otherwise} \end{cases}$$

Above, $\Delta_\xi \subseteq [0, \infty)$ denotes the points of discontinuity of ξ .

Proof. Provided we have some $\underline{t} \vdash [0, \infty)$ the vector $\hat{\underline{t}}$ associated with prepending 0 to \underline{t} ,

$$\hat{\underline{t}} = (0, t_1, \dots, t_{|\underline{t}|}),$$

induces the following finite-dimensional distributions.

$$\pi_{\hat{\underline{t}}\#} \mathbf{P}_x^\epsilon = \delta_x \otimes \pi_{\underline{t}\#} \mathbf{P}_x^\epsilon$$

For these partitions, it is easy to see from Theorem 2.3.1 that the large deviations principle for $(\pi_{\hat{\underline{t}}\#} \mathbf{P}_x^\epsilon)_{\epsilon > 0}$ has good rate function as below.

$$(x_0, x_1, \dots, x_{|\underline{t}|}) \mapsto \begin{cases} \Psi^*(\underline{t}, \underline{x}, x_0), & x_0 = x \\ \infty & \text{otherwise} \end{cases}$$

By [FK06, Theorem 4.28], we now use Theorem 2.3.1 and Proposition 2.3.4 to get a large deviations principle for the family $(\mathbf{P}_x^\epsilon)_{\epsilon > 0}$ with good rate function I_x .

2.4 Exponential martingales

Now that we have our principle, we discuss how various exponential martingales $Z^{\epsilon, h}$ induce changes of measure alternative to those $\underline{Z}^{\epsilon, \underline{t}, \underline{\theta}}$ which themselves inspire a different flavor of proof. We start by defining the building blocks of these exponential martingales.

$$\begin{aligned} \mathcal{H}_\Lambda &:= \{h \in \mathbb{D}([0, \infty), \mathbb{V}) : h \text{ has compact support and finite-variation}\} \\ G : \mathbb{D}([0, \infty), \mathbb{X}) \times \mathcal{H}_\Lambda &\rightarrow \mathbb{R}, \end{aligned}$$

$$G(\xi, h) := \langle \xi(0), h(0) \rangle - \int_0^\infty \xi(s-) dh(s) - \int_0^\infty \Lambda(h(s), \xi(s)) ds$$

Proposition 2.4.1. *For each $\epsilon > 0$ and $h \in \mathcal{H}_\Lambda$, we have the following identities, where $\mathcal{E}(H)$ denotes the Doléans-Dade exponential of H .*

$$\begin{aligned} Z^{\epsilon, h} &:= \exp\left(\frac{1}{\epsilon} G(\epsilon X^\epsilon, h)\right) \\ &= \exp\left(\langle X_0^\epsilon, h(0) \rangle - \int_0^\infty X_{s-}^\epsilon dh(s) - \int_0^\infty \Lambda^\epsilon(h(s), X_s^\epsilon) ds\right) \\ &= \exp\left(h \cdot X_\infty^\epsilon - \Lambda^\epsilon(h, X^\epsilon) \cdot \ell_\infty\right) \\ &= \mathcal{E}\left(h \cdot X^{\epsilon, c} - (e^{\langle h, \text{id}_\mathbb{V} \rangle} - 1) * \tilde{q}^{X^\epsilon}\right)_\infty \end{aligned}$$

Furthermore, $Z^{\epsilon, h}$ is integrable and $t \mapsto \mathbb{E}_{\mathbf{P}_x}(Z^{\epsilon, h} | \mathcal{F}_t)$ is a martingale.

Proof. We start by establishing the first two identities. Realizing h as a predictable, finite-variation process, we apply integration by parts (see [JS03, Proposition I.4.49(b)]) to get the following identity.

$$\begin{aligned} \frac{1}{\epsilon} G(\epsilon X^\epsilon, h) &= \frac{1}{\epsilon} \left(\langle \epsilon X_0^\epsilon, h(0) \rangle - \int_0^\infty \epsilon X_{s-}^\epsilon dh(s) - \int_0^\infty \Lambda(h(s), \epsilon X_s^\epsilon) ds \right) \\ &= \langle X_0^\epsilon, h(0) \rangle - \int_0^\infty X_{s-}^\epsilon dh(s) - \int_0^\infty \Lambda^\epsilon(h(s), X_s^\epsilon) ds \end{aligned}$$

$$\begin{aligned}
&= \langle X_0^\epsilon, h(0) \rangle - X_-^\epsilon \cdot h_\infty - \Lambda^\epsilon(h, X_-^\epsilon) \cdot \ell_\infty \\
&= h \cdot X_\infty^\epsilon - \Lambda^\epsilon(\theta, X_-^\epsilon) \cdot \ell_\infty
\end{aligned}$$

The remaining identity is a special case of that from [JS03, Theorem III.7.24], but we will perform the Itô calculus here for completion's sake. Note that Theorem 1.4.4 tells us that $\exp(h \cdot X^\epsilon)$ is a (P_x, \mathcal{F}) jump-diffusion, and (A.4.15) from Theorem A.4.13 gives us its special semimartingale decomposition.

$$\begin{aligned}
\exp(h \cdot X_t^\epsilon) &= \left(\exp(h \cdot X^\epsilon) \cdot \Lambda(h, X^\epsilon) \right) \cdot \ell_t + \left(\exp(h \cdot X_-^\epsilon) \cdot h \right) \cdot X_t^{\epsilon, c} \\
&\quad + \exp(h \cdot X_-^\epsilon) \left(e^{\langle h, \text{id}_V \rangle} - 1 \right) * q_t^{X^\epsilon}
\end{aligned}$$

Note that this allows us to define the process H inside the alleged Doléans-Dade exponential.

$$H = h \cdot X^{\epsilon, c} + (e^{\langle h, \text{id}_V \rangle} - 1) * \tilde{q}^{X^\epsilon}$$

Observe that, by definition of the Doléans-Dade exponential and the special semimartingale decomposition of X^ϵ ,

$$\begin{aligned}
X_t^\epsilon &= \frac{1}{\epsilon} \beta(\epsilon X^\epsilon) \cdot \ell + X_t^{\epsilon, c} + \text{id}_V * \tilde{q}_t^{X^\epsilon}, \\
\langle X^{\epsilon, c, i}, X^{\epsilon, c, j} \rangle &= \frac{1}{\epsilon} \alpha(\epsilon X^\epsilon) \cdot \ell, \\
\hat{q}^{X^\epsilon}(\text{ds}, \text{dv}) &= \frac{1}{\epsilon} \mu(\epsilon X^\epsilon, \text{dv}) \text{ds},
\end{aligned}$$

we have the following.

$$\begin{aligned}
\log \mathcal{E}(H)_t &= H_t - H_0 - \frac{1}{2} \langle H^c, H^c \rangle_t + (\log(1 + \text{id}_\mathbb{R}) - \text{id}_\mathbb{R}) * q_t^H \\
&= h \cdot X_t^{\epsilon, c} + (e^{\langle h, \text{id}_V \rangle} - 1) * \tilde{q}_t^{X^\epsilon} \\
&\quad - \frac{1}{2} \langle h \cdot X^{\epsilon, c}, h \cdot X^{\epsilon, c} \rangle_t - (e^{\langle h, \text{id}_V \rangle} - 1 - \langle h, \text{id}_V \rangle) * q_t^{X^\epsilon} \\
&= h \cdot X_t^{\epsilon, c} - (e^{\langle h, \text{id}_V \rangle} - 1 - \langle h, \text{id}_V \rangle) * \hat{q}_t^{X^\epsilon} \\
&\quad - \frac{1}{2} \langle h, \alpha^\epsilon(X^\epsilon) h \rangle \cdot \ell_t + \langle h, \text{id}_V \rangle * \tilde{q}_t^{X^\epsilon} \\
&= h \cdot X_t^\epsilon - \beta^\epsilon(X^\epsilon) \cdot \ell_t - \langle h, \text{id}_V \rangle * \tilde{q}_t^{X^\epsilon} - (e^{\langle h, \text{id}_V \rangle} - 1 - \langle h, \text{id}_V \rangle) * \hat{q}_t^{X^\epsilon} \\
&\quad - \frac{1}{2} \langle h, \alpha^\epsilon(X^\epsilon) h \rangle \cdot \ell_t + \langle h, \text{id}_V \rangle * \tilde{q}_t^{X^\epsilon} \\
&= h \cdot X_t^\epsilon - \Lambda^\epsilon(h, X^\epsilon) \cdot \ell_t
\end{aligned}$$

Note that this is one argument that $Z^{\epsilon, h} = \mathcal{E}(H)_\infty$ corresponds to a (P, \mathcal{F}) local martingale, since H is (see [JS03, Theorem I.4.61(b)]). In any case, the martingale nature comes from Theorem 1.4.4.

The above proposition prescribes another change of measure. For each $\epsilon > 0$, $h \in \mathcal{H}_\Lambda$, and $x \in \mathbb{X}$, define

$$Q_x^{\epsilon, h}(\text{d}\omega) := Z^{\epsilon, h}(\omega) \cdot P_x^\epsilon(\text{d}\omega).$$

Let us explore the distribution of ϵX^ϵ over these spaces.

Proposition 2.4.2. Fix $\epsilon > 0$, $h \in \mathcal{H}_\Lambda$, and $x \in \mathbb{X}$. The process X^ϵ is a $(Q_x^{\epsilon,h}, \mathcal{F}^\epsilon)$ special semimartingale with the following decomposition.

$$X_t^\epsilon = x/\epsilon + \frac{1}{\epsilon} \beta^h(\cdot, \epsilon X_-^\epsilon) \cdot \ell_t + X_t^{\epsilon,c} + \text{id}_\mathbb{V} * \tilde{q}_t^{h,X^\epsilon},$$

where the drift β^h , diffusion α , and jump predictable compensator \hat{q}^{h,X^ϵ} (above, we have $\tilde{q}^{h,X^\epsilon} = q^{X^\epsilon} - \hat{q}^{h,X^\epsilon}$) are as follows.

$$\begin{aligned} \beta^h(s, x) &:= \beta(x) + \alpha(x)h(s) + \int_{\mathbb{V}} v(e^{\langle h(s), v \rangle} - 1) \mu(x, dv) \\ \langle X^{\epsilon,c,i}, X^{\epsilon,c,j} \rangle &= \frac{1}{\epsilon} \alpha_{i,j}(\epsilon X_-^\epsilon) \cdot \ell \\ \hat{q}^{h,X^\epsilon}(ds, dv) &:= e^{\langle h(s), v \rangle} \frac{1}{\epsilon} \mu(\epsilon X_{s-}^\epsilon, dv) ds \end{aligned}$$

Moreover the distributions $Q_x^{\epsilon,h}$ weakly converge to a degenerate measure δ_{ξ_h} at the solution ξ_h to the following dynamical system.

$$(2.4.3) \quad \begin{cases} \dot{\xi}_h(t) = \beta^h(t, \xi_h(t)) & t \geq 0 \\ \xi_h(0) = x \end{cases}$$

Proof. The $(Q_x^{\epsilon,h}, \mathcal{F}^\epsilon)$ dynamics of X^ϵ simply come from the Girsanov theorem (see [JS03, Theorem III.3.24 or Theorem III.7.23]). As far as weak convergence is concerned, this is immediate from the exponential tightness of our family and convergence of finite-dimensional distributions.

From here, a large deviation principle may be approached by concentrating probability on a ball and using Chebyshev-like bounds on $Z^{\epsilon,h}$.

$$\begin{aligned} \epsilon \log P_x^\epsilon(\epsilon X^\epsilon \in B(\xi, \delta)) &= \epsilon \log E_{Q_x^{\epsilon,h}}((Z^{\epsilon,h})^{-1} 1_{B(\xi, \delta)}(\epsilon X^\epsilon)) \\ &= \epsilon \log E_{Q_x^{\epsilon,h}}\left(\exp\left(-\frac{1}{\epsilon} G(\epsilon X^\epsilon, h)\right) 1_{B(\xi, \delta)}(\epsilon X^\epsilon)\right) \\ &\leq - \inf_{\xi' \in B(\xi, \delta)} G(\xi', h) \end{aligned}$$

Showing lower semi-continuity of $G(\cdot, h)$ would then result in us being able to say

$$\lim_{\delta \rightarrow 0} \epsilon \log P_x^\epsilon(\epsilon X^\epsilon \in B(\xi, \delta)) \leq -G(\xi, h),$$

for all $h \in \mathcal{H}_\Lambda$, and so we'd have

$$\lim_{\delta \rightarrow 0} \epsilon \log P_x^\epsilon(\epsilon X^\epsilon \in B(\xi, \delta)) \leq - \sup_{h \in \mathcal{H}_\Lambda} G(\xi, h)$$

Meanwhile, the lower bound would be approached by showing \mathcal{H}_Λ is suitably rich to have a dense family of limit functions ξ_h as in (2.4.3) of Proposition 2.4.2, on which $\sup_{h' \in \mathcal{H}_\Lambda} G(\xi_h, h') = G(\xi_h, h)$, and so a large deviations lower bound is attained from the following bound.

$$\begin{aligned} \epsilon \log P_x^\epsilon(\epsilon X^\epsilon \in B(\xi_h, \delta)) &= \epsilon \log E_{Q_x^{\epsilon,h}}((Z^{\epsilon,h})^{-1} 1_{B(\xi_h, \delta)}(\epsilon X^\epsilon)) \\ &= \epsilon \log E_{Q_x^{\epsilon,h}}\left(\exp\left(-\frac{1}{\epsilon} G(\epsilon X^\epsilon, h)\right) 1_{B(\xi_h, \delta)}(\epsilon X^\epsilon)\right) \end{aligned}$$

$$\begin{aligned}
&\geq - \sup_{\xi' \in B(\xi_h, \delta)} G(\xi', h) + \epsilon \log Q_x^{\epsilon, h}(\epsilon X^\epsilon \in B(\xi_h, \delta)) \\
&\geq -G(\xi_h, h) + \epsilon \log Q_x^{\epsilon, h}(\epsilon X^\epsilon \in B(\xi_h, \delta)) \\
&= - \sup_{h' \in \mathcal{H}_\Lambda} G(\xi_h, h') + \epsilon \log Q_x^{\epsilon, h}(\epsilon X^\epsilon \in B(\xi_h, \delta))
\end{aligned}$$

The benefit of this approach is that our rate function $\xi \mapsto \sup_{h \in \mathcal{H}_\Lambda} G(\xi, h)$ has an integral form. Instead of proving the large deviation principle in this alternative fashion, we reconcile the measure changes that appear in each of the approaches.

It is readily evident that $Q_x^{\epsilon, h}$ is a generalization of $\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}$, as we are replacing summations in $\underline{Z}^{\epsilon, \underline{t}, \underline{\theta}}$ with integrals in $Z^{\epsilon, h}$.

$$\begin{aligned}
(2.4.4) \quad \underline{Z}^{\epsilon, \underline{t}, \underline{\theta}} &= \exp \sum_{k=1}^{|\underline{t}|} \left(\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon) \right) \\
Z^{\epsilon, h} &= \exp \left(\int_0^\infty h(s) dX_s^\epsilon - \int_0^\infty \Lambda^\epsilon(h(s), X_s^\epsilon) ds \right)
\end{aligned}$$

The summand $\langle \theta_k, X_{t_k}^\epsilon - X_{t_{k-1}}^\epsilon \rangle$ relates to the integral term $h(s) dX_s^\epsilon$, while $\varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}^\epsilon)$ relates to $\Lambda^\epsilon(h(s), X_s^\epsilon) ds$. To explicitly resolve these two expressions, we disambiguate the operations in $\underline{Z}^{\epsilon, \underline{t}, \underline{\theta}}$ involving X^ϵ .

$$\underline{G}(\cdot, \underline{t}, \underline{\theta}) : \mathbb{D}([0, \infty), \mathbb{X}) \rightarrow \mathbb{R},$$

$$\underline{G}(\xi, \underline{t}, \underline{\theta}) := \sum_{k=1}^{|\underline{t}|} \left(\langle \theta_k, \xi(t_k) - \xi(t_{k-1}) \rangle - \Psi(\Delta t_k, \theta_k, \xi(t_{k-1})) \right)$$

We now have a common notation for factoring X^ϵ through each density.

$$\underline{Z}^{\epsilon, \underline{t}, \underline{\theta}} = \exp \left(\frac{1}{\epsilon} \underline{G}(\epsilon X^\epsilon, \underline{t}, \underline{\theta}) \right), \quad Z^{\epsilon, h} = \exp \left(\frac{1}{\epsilon} G(\epsilon X^\epsilon, h) \right)$$

We now state the main theorem of this section, which resolves the *twisting/tilting* approach of measure changes $\underline{Q}^{\epsilon, \underline{t}, \underline{\theta}}$ in Proposition 2.3.2 with the *exponential martingale* approach of measure changes $Q^{\epsilon, h}$ in Proposition 2.4.2. It relies on the following parameterization of maps $h(\cdot, \underline{t}, \underline{\theta})$ over $\underline{t} \vdash [0, \infty)$ and $\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})$.

$$(2.4.5) \quad h(\underline{t}, \underline{t}, \underline{\theta}) = \sum_{k=1}^{|\underline{t}|} 1_{[t_{k-1}, t_k)}(\underline{t}) \psi(\Delta t_k, \theta_k)$$

Theorem 2.4.6. *For each $\underline{t} \vdash [0, \infty)$ and $\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})$, we have $h(\cdot, \underline{t}, \underline{\theta}) \in \mathcal{H}_\Lambda$, and for any semimartingale H ,*

$$\underline{G}(H, \underline{t}, \underline{\theta}) = G(H, h(\cdot, \underline{t}, \underline{\theta})).$$

Thus, for any $\epsilon > 0$ and $x \in \mathbb{X}$, we have the following identities.

$$\underline{Z}^{\epsilon, \underline{t}, \underline{\theta}} = Z^{\epsilon, h(\cdot, \underline{t}, \underline{\theta})}, \quad \underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}} = Q_x^{\epsilon, h(\cdot, \underline{t}, \underline{\theta})}$$

Proof. It is clear that $h(\cdot, \underline{t}, \underline{h})$ is compactly supported on the intervals of \underline{t} . Meanwhile, Proposition 1.2.5(c) tells us that $h(\cdot, \underline{t}, \underline{\theta})$ is differentiable everywhere but potentially the nodes of \underline{t} , and so it is of finite variation. This concludes $h \in \mathcal{H}_\Lambda$.

Seeing as Ψ is \mathbb{X} -affine and stochastic integration is linear, we can use a simplified version of Itô's formula below (again using Proposition 1.2.5(c))

$$\begin{aligned}
\underline{G}(H, \underline{t}, \underline{\theta}) &= \sum_{k=1}^{|\underline{t}|} \left(\langle \theta_k, H_{t_k} - H_{t_{k-1}} \rangle - \varphi(\Delta t_k, \theta_k, H_{t_{k-1}}) \right) \\
&= \sum_{k=1}^{|\underline{t}|} \left(\Psi(t_k - t_k, \theta_k, H_{t_k}) - \Psi(t_k - t_{k-1}, \theta_k, H_{t_{k-1}}) \right) \\
&= \sum_{k=1}^{|\underline{t}|} \int_{t_{k-1}}^{t_k} d\Psi(t_k - \cdot, \theta_k, H_\cdot) \\
&= \sum_{k=1}^{|\underline{t}|} \left(- \int_{t_{k-1}}^{t_k} \dot{\Psi}(t_k - t, \theta_k, H_t) dt + \int_{t_{k-1}}^{t_k} \psi(t_k - t, \theta_k) dH_t \right) \\
&= \sum_{k=1}^{|\underline{t}|} \left(\int_{t_{k-1}}^{t_k} \psi(t_k - t, \theta_k) dH_t - \int_{t_{k-1}}^{t_k} \Lambda(\psi(t_k - t, \theta_k), H_t) dt \right) \\
&= \sum_{k=1}^{|\underline{t}|} \left(\int_{t_{k-1}}^{t_k} h(t, \underline{t}, \underline{\theta}) dH_t - \int_{t_{k-1}}^{t_k} \Lambda(h(t, \underline{t}, \underline{\theta}), H_t) dt \right) \\
&= h(\cdot, \underline{t}, \underline{\theta}) \cdot H_\infty - \Lambda(h(\cdot, \underline{t}, \underline{\theta}), H) \cdot \ell_\infty
\end{aligned}$$

From here, as we did in Proposition 2.4.1, we apply integration by parts to complete the equality.

$$\begin{aligned}
\underline{G}(H, \underline{t}, \underline{\theta}) &= h(\cdot, \underline{t}, \underline{\theta}) \cdot H_\infty - \Lambda(h(\cdot, \underline{t}, \underline{\theta}), H) \cdot \ell_\infty \\
&= \langle h(0, \underline{t}, \underline{\theta}), H_0 \rangle - \int_0^\infty H_{s-} dh(s, \underline{t}, \underline{\theta}) - \int_0^\infty \Lambda(h(\cdot, \underline{t}, \underline{\theta}), H_s) ds \\
&= G(H, h(\cdot, \underline{t}, \underline{\theta}))
\end{aligned}$$

Evaluating this identity at ϵX^ϵ now gives us the remaining equalities.

Remark 2.4.7. Note that a conditional cumulant φ and Lévy-Khintchine map Λ may be defined for any jump-diffusion, despite not generally being \mathbb{X} -affine.

$$\begin{aligned}
\varphi(t, \theta, x) &= \mathbb{E}_{P_x} \exp \langle \theta, X - x \rangle, \\
\Lambda(u, x) &= \langle u, \beta(x) \rangle + \frac{1}{2} \langle u, \beta(x) u \rangle + \int_{\mathbb{V}} \left(e^{\langle u, v \rangle} - 1 - \langle u, v \rangle \right) \mu(x, dv)
\end{aligned}$$

Furthermore, we may always construct (local) measure changes like $\underline{Z}^{\underline{t}, \underline{\theta}}$ and Z^h in (2.4.4) and postulate an equivalence like Theorem 2.4.6.

$$\exp \sum_{k=1}^{|\underline{t}|} \left(\langle \theta_k, X_{t_k} - X_{t_{k-1}} \rangle - \varphi^\epsilon(\Delta t_k, \theta_k, X_{t_{k-1}}) \right) = \exp \left(\int_0^\infty h(s) dX_{s-} - \int_0^\infty \Lambda^\epsilon(h(s), X_s) ds \right)$$

This is the very result which would generally prove that the approaches of twisting/tilting and martingales are in fact identical.

Corollary 2.4.8. *For each $\underline{t} \vdash [0, \infty)$ and $\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})$, the distributions $\underline{Q}_x^{\epsilon, \underline{t}, \underline{\theta}}$ converge weakly to the degenerate measure $\delta_{\xi_{\underline{t}, \underline{\theta}}}$ at the solution $\xi_{\underline{t}, \underline{\theta}}$ to the dynamical system in which $\xi_{\underline{t}, \underline{\theta}}(0) = x$ and for each $k = 1, \dots, |\underline{t}|$, we have the following equation.*

$$\begin{aligned} \dot{\xi}_{\underline{t}, \underline{\theta}}(t) &= \beta(\xi_{\underline{t}, \underline{\theta}}(t)) + \alpha(\xi_{\underline{t}, \underline{\theta}}(t))\psi(t_k - t, \theta_k) \\ &\quad + \int_{\mathbb{V}} v(e^{\langle \psi(t_k - t, \theta_k), v \rangle} - 1) \mu(\xi_{\underline{t}, \underline{\theta}}(t), dv), \end{aligned} \quad t \in [t_{k-1}, t_k)$$

Proof. This is simply substituting $h(\cdot, \underline{t}, \underline{\theta})$ for h in Proposition 2.4.2.

2.5 Integral representation of rate function

So far, for each $x \in \mathbb{X}^\circ$, Theorem 2.3.9 provides us a large deviation principle for $(P_x^\epsilon)_{\epsilon > 0}$ with good rate function I_x as in (2.3.10). This section is concerned with simplifying the nature of I_x to take a more explicit integral form, comparable to existing principles for other families of stochastic processes.

$$I_x(\xi) = \begin{cases} \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt & \xi(0) = x, \xi \in \mathbb{A}([0, \infty), \mathbb{X}) \\ \infty & \text{otherwise} \end{cases}$$

To show this, we start by defining a map I which composes the initial state through our rate functions $(I_x)_{x \in \mathbb{X}}$, to remove the finiteness condition of each I_x in (2.3.10).

$$I(\xi) := I_{\xi(0)}(\xi) = \sup_{\underline{t} \vdash \Delta_\xi} \Psi^*(\underline{t}, \xi(\underline{t}), \xi(0))$$

In the following results, we will—without mention—assume evaluations of $I(\xi)$ for $\xi(0) \in \mathbb{X}^\circ$, so that we can use Theorem 1.3.11. Note that this is at no loss of generality, since we are resolving our rate function I_x for a large deviation principle that already requires $x \in \mathbb{X}^\circ$.

Lemma 2.5.1. *If $\xi \notin \mathbb{A}([0, \infty), \mathbb{X})$, then $I(\xi) = \infty$.*

Proof. Fix some $\xi \in \mathbb{D}([0, \infty), \mathbb{X})$ with $\xi \notin \mathbb{A}([0, \infty), \mathbb{X})$. That is to say, there exists some $\tau > 0$ for which $\xi \notin \mathbb{A}([0, \tau], \mathbb{X})$. For any $\rho > 0$, we now use Proposition 2.2.7(d) to produce some $\delta > 0$ and $C_{\delta, \rho} > 0$ such that the following bound holds.

$$|\Psi(t, u, x) - \Psi(0, u, x)| \leq C_{\delta, \rho} \cdot t \cdot (1 + |x|), \quad t \in [0, \delta], \quad u \in \overline{B}(0, \rho), \quad x \in \mathbb{X}$$

Because $\xi \notin \mathbb{A}([0, \tau], \mathbb{X})$, there exists $\epsilon > 0$ and a partition $\underline{t}^\rho \vdash [0, \tau]$ such that

$$\begin{aligned} \sum_{k=1}^{|\underline{t}^\rho|} \Delta t_k^\rho &< \delta \wedge \left(C_{\delta, \rho} \left(1 + \sup_{t \in [0, \tau]} |\xi(t)| \right) \right)^{-1} \\ \sum_{k=1}^{|\underline{t}^\rho|} |\xi(t_k^\rho) - \xi(t_{k-1}^\rho)| &\geq \epsilon \end{aligned}$$

The countable nature of Δ_ξ allows us to further impose that $\underline{t}^\rho \vdash \Delta_\xi^c$. This, along with Theorem 1.3.11, results in the following inequality.

$$\sup_{\underline{t} \vdash [0, \infty)} \Psi^*(\underline{t}, \xi(\underline{t}), \xi(0))$$

$$\begin{aligned}
&\geq \sup_{\rho>0} \Psi^*(\underline{t}^\rho, \xi(\underline{t}^\rho), \xi(0)) \\
&\geq \sup_{\rho>0} \sup_{\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})} \sum_{k=1}^{|\underline{t}^\rho|} \left(\langle \theta_k, \xi(t_k^\rho) - \xi(t_{k-1}^\rho) \rangle - \varphi(\Delta t_k^\rho, \theta_k, \xi(t_{k-1}^\rho)) \right) \\
&= \sup_{\rho>0} \sum_{k=1}^{|\underline{t}^\rho|} \sup_{\theta_k \in \mathcal{D}_\Psi(\Delta t_k^\rho)} \left(\langle \theta_k, \xi(t_k^\rho) - \xi(t_{k-1}^\rho) \rangle \right. \\
&\quad \left. - \left(\Psi(\Delta t_k^\rho, \theta_k, \xi(t_{k-1}^\rho)) - \Psi^*(0, \theta_k, \xi(t_{k-1}^\rho)) \right) \right) \\
&\geq \sup_{\rho>0} \sum_{k=1}^{|\underline{t}^\rho|} \left(\rho |\xi(t_k^\rho) - \xi(t_{k-1}^\rho)| - C_{\delta, \rho} \cdot \Delta t_k^\rho \cdot (1 + |\xi(t_{k-1}^\rho)|) \right) \\
&\geq \epsilon \cdot \sup_{\rho>0} \rho - 1 \\
&= \infty
\end{aligned}$$

Lemma 2.5.2. For each $\xi \in \mathbb{A}([0, \infty), \mathbb{X})$, $\underline{t} \vdash [0, \infty)$ and $\underline{\theta} \in \prod_{k=1}^{|\underline{t}|} \mathcal{D}_\Psi(\Delta t_k)$, we have an identity similar to that of Theorem 2.4.6.

$$\underline{G}(\xi, \underline{t}, \underline{\theta}) = G(\xi, h(\cdot, \underline{t}, \underline{\theta})) = \int_0^\infty \left(\langle h(t, \underline{t}, \underline{\theta}), \dot{\xi}(t) \rangle - \Lambda(h(t, \underline{t}, \underline{\theta}), \xi(t)) \right) dt.$$

Proof. Similar to as in Theorem 2.4.6, we use Propositions 1.2.5(c) and 2.2.7(a) and apply the fundamental theorem of calculus and integration by parts.

$$\begin{aligned}
\underline{G}(\xi, \underline{t}, \underline{\theta}) &= \sum_{k=1}^{|\underline{t}|} \left(\langle \theta_k, \xi(t_k) - \xi(t_{k-1}) \rangle - \varphi(\Delta t_k, \theta_k, \xi(t_{k-1})) \right) \\
&= \sum_{k=1}^{|\underline{t}|} \left(\Psi(t_k - t_k, \theta_k, \xi(t_k)) - \Psi(t_k - t_{k-1}, \theta_k, \xi(t_{k-1})) \right) \\
&= \sum_{k=1}^{|\underline{t}|} \int_{t_{k-1}}^{t_k} \frac{\partial}{\partial t} \Psi(t_k - t, \theta_k, \xi(t)) dt \\
&= \sum_{k=1}^{|\underline{t}|} \int_{t_{k-1}}^{t_k} \left(-\dot{\Psi}(t_k - t, \theta_k, \xi(t)) + \langle \psi(t_k - t, \theta_k), \dot{\xi}(t) \rangle \right) dt \\
&= \sum_{k=1}^{|\underline{t}|} \int_{t_{k-1}}^{t_k} \left(\langle \psi(t_k - t, \theta_k), \dot{\xi}(t) \rangle - \Lambda(\psi(t_k - t, \theta_k), \xi(t)) \right) dt \\
&= \int_0^\infty \left(\langle h(t, \underline{t}, \underline{\theta}), \dot{\xi}(t) \rangle - \Lambda(h(t, \underline{t}, \underline{\theta}), \xi(t)) \right) dt \\
&= \langle h(0, \underline{t}, \underline{\theta}), \xi(0) \rangle - \int_0^\infty \xi(t-) dh(t, \underline{t}, \underline{\theta}) - \int_0^\infty \Lambda(h(t, \underline{t}, \underline{\theta}), \xi(t)) dt \\
&= G(\xi, h(\cdot, \underline{t}, \underline{\theta}))
\end{aligned}$$

Proposition 2.5.3. For each $\xi \in \mathbb{A}([0, \infty), \mathbb{X})$, we have the following upper bound.

$$I(\xi) \leq \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt$$

Proof. Fix $\underline{t} \vdash [0, \infty)$ and $\underline{u} \in \mathbb{V}^{|\underline{t}|}$. Observe that if $\Psi(\underline{t}, \underline{u}, \xi(0)) = \infty$, we immediately have the following inequality.

$$\langle \underline{u}, \xi(\underline{t}) \rangle - \Psi(\underline{t}, \underline{u}, \xi(0)) = -\infty \leq 0 = \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt$$

Otherwise, Theorem 1.3.11 tells us that $\underline{u} = U_{\underline{t}}(\underline{\theta})$ for some $\underline{\theta} \in \mathcal{D}_\Psi(\underline{t})$. By Lemma 2.5.2, we now see the same inequality.

$$\begin{aligned} \langle \underline{u}, \xi(\underline{t}) \rangle - \Psi(\underline{t}, \underline{u}, \xi(0)) &= \sum_{k=1}^{|\underline{t}|} \left(\langle \theta_k, \xi(t_k) - \xi(t_{k-1}) \rangle - \varphi(\Delta t_k, \theta_k, \xi(t_{k-1})) \right) \\ &= \underline{G}(\xi, \underline{t}, \underline{\theta}) \\ &= \int_0^\infty \left(\langle h(t, \underline{t}, \underline{\theta}), \dot{\xi}(t) \rangle - \Lambda(h(t, \underline{t}, \underline{\theta}), \xi(t)) \right) dt \\ &\leq \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt \end{aligned}$$

Thus, we have the following upper bound.

$$\begin{aligned} I(\xi) &= \sup_{\underline{t} \vdash \Delta_\xi^c} \Psi^*(\underline{t}, \xi(\underline{t}), \xi(0)) = \sup_{\underline{t} \vdash [0, \infty)} \sup_{\underline{u} \in \mathbb{V}^{|\underline{t}|}} \left(\langle \underline{u}, \xi(\underline{t}) \rangle - \Psi(\underline{t}, \underline{u}, \xi(0)) \right) \\ &\leq \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt \end{aligned}$$

Lemma 2.5.4. Fix $\tau > 0$ and $h \in \mathbb{C}([0, \tau], \mathbb{X})$. For each $\epsilon > 0$, there exists a partition $\underline{t} \vdash [0, \tau]$ and $\underline{u} \in \mathcal{D}_\Psi(\underline{t})$ such that we have the following approximation.

$$\sup_{t \in [0, \tau)} |h(t, \underline{t}, \underline{u}) - h(t)| < \epsilon$$

Proof. Denote $M := \sup_{t \in [0, \tau]} |h(t)|$ and fix $\epsilon > 0$. We start by using Proposition 2.2.7(d) to guarantee $\delta_0 > 0$ and $C_M > 0$ such that the following bound holds.

$$|\Psi(t, u, x) - \Psi(0, u, x)| \leq C_M \cdot t \cdot (1 + |x|), \quad t \in [0, \delta_0], \quad u \in \overline{B}(0, M), \quad x \in \mathbb{X}$$

From here, we use the affine structure of Ψ to see the following inequality.

$$|\psi(t, u) - u| = 3C_M \sqrt{d} \cdot t, \quad (t, u) \in [0, \delta_0] \times \overline{B}(0, M)$$

Seeing as $h \in \mathbb{C}([0, \tau], \mathbb{V})$, it is uniformly continuous. Fix $\delta_1 > 0$ such that all $s, t \in [0, \tau]$ with $|t - s| < \delta_1$, we have the following inequality.

$$|h(t) - h(s)| < \epsilon/2$$

Fix an integer $N \in \mathbb{N}$ large enough to impose the following inequality.

$$\frac{\tau}{N} < \frac{\epsilon}{6C_M \sqrt{d}} \wedge \delta_0 \wedge \delta_1$$

Now define partition \underline{t} by $t_k = k\tau/N$ for $k = 1, \dots, N$. This way, for each $k = 1, \dots, N$, and $t \in [t_{k-1}, t_k)$, we have

$$|h(t, \underline{t}, h(\underline{t})) - h(t)| = |\psi(t_k - t, h(t_k)) - h(t)|$$

$$\begin{aligned}
&\leq \left| \psi(t_k - t, h(t_k)) - h(t_k) \right| + |h(t_k) - h(t)| \\
&< 3C_M \sqrt{d} \cdot (t_k - t) + \epsilon/2 \\
&< \epsilon.
\end{aligned}$$

Proposition 2.5.5. *For each $\xi \in \mathbb{A}([0, \infty), \mathbb{X})$, we have the following inequality.*

$$I(\xi) \geq \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt$$

Proof. We proceed in a way similar to that of [Puh01]. Define a map $f : [0, \infty) \times \mathbb{V} \rightarrow \mathbb{R}$ as below.

$$f(t, \theta) := \langle \theta, \dot{\xi}(t) \rangle - \Lambda(\theta, \xi(t))$$

For a fixed $\epsilon > 0$, $t \in [0, \infty)$, we define the following set.

$$\Gamma_t^\epsilon := \left\{ \theta \in \mathbb{V} : \left(\sup_{\theta' \in \mathbb{V}} f(t, \theta') - \epsilon \right)_+ \wedge \frac{1}{\epsilon} \leq f(t, \theta) \leq \frac{1}{\epsilon} \right\}$$

Continuity of $f(t, \cdot)$ and the least upper bound property guarantees Γ_t^ϵ is nonempty and measurable. Thus, we may construct a measurable selection $h : [0, \infty) \rightarrow \mathbb{V}$ for Γ^ϵ , which is to say h is Lebesgue measurable and the following holds.

$$(2.5.6) \quad f(t, h(t)) \in \Gamma_t^\epsilon, \quad t \in [0, \infty)$$

We now use Luzin's theorem to approximate $h|_{[0, 1/\epsilon]}$ with $\tilde{h} \in \mathbb{C}([0, 1/\epsilon], \mathbb{V})$ to the following extent.

$$(2.5.7) \quad \int_{\tilde{h} \neq h} dt < \epsilon^2$$

Now, we combine our inequalities from (2.5.6) and (2.5.7) to see that

$$\begin{aligned}
&\int_0^{1/\epsilon} \left(f(t, \tilde{h}(t)) \vee 0 \right) dt \\
&= \int_0^{1/\epsilon} f(t, h(t)) dt + \int_{\tilde{h} \neq h} \left(\left(f(t, \tilde{h}(t)) \vee 0 \right) - f(t, h(t)) \right) dt \\
&\geq \int_0^{1/\epsilon} \left(\left(\sup_{\theta \in \mathbb{V}} f(t, \theta) - \epsilon \right) \wedge \frac{1}{\epsilon} \right) dt - \int_{\tilde{h} \neq h} \frac{1}{\epsilon} dt \\
(2.5.8) \quad &= \int_0^{1/\epsilon} \left(\left(\Lambda^*(\dot{\xi}(t), \xi(t)) - \epsilon \right) \wedge \frac{1}{\epsilon} \right) dt - \epsilon
\end{aligned}$$

By Lemma 2.5.4, the fact that each $f(t, 0) = 0$, and continuity of each $f(t, \cdot)$, we may now use Fatou's lemma to guarantee some $\underline{t} \vdash [0, \infty)$ and $\underline{\theta} \in \prod_{k=1}^{\lfloor \underline{t} \rfloor} \mathcal{D}_\Psi(\Delta t_k)$ such that

$$(2.5.9) \quad \int_0^{1/\epsilon} f(t, h(t, \underline{t}, \underline{\theta})) dt \geq \int_0^{1/\epsilon} \left(f(t, \tilde{h}(t)) \vee 0 \right) dt - \epsilon$$

Combining (2.5.8) and (2.5.9), we now see that

$$\int_0^{1/\epsilon} f(t, h(t, \underline{t}, \underline{\theta})) dt \geq \int_0^{1/\epsilon} \left(\left(\Lambda^*(\dot{\xi}(t), \xi(t)) - \epsilon \right) \wedge \frac{1}{\epsilon} \right) dt - 2\epsilon.$$

By Theorem 1.3.11 and Lemmas 2.5.1 and 2.5.2, the above inequality gives us the following.

$$\begin{aligned}
I_x(\xi) &\geq \Psi^*(\underline{t}, \xi(\underline{t}), \xi(0)) \\
&\geq \sum_{k=1}^{|\underline{t}|} \left(\langle \theta_k, \xi(t_k) \rangle - \Psi(\Delta t_k, \theta_k, \xi(t_{k-1})) \right) \\
&= \sum_{k=1}^{|\underline{t}|} \int_{t_{k-1}}^{t_k} \left(\langle \psi(t_k - t, \theta_k), \dot{\xi}(t) \rangle - \Lambda(\psi(t_k - t, \theta_k), \xi(t)) \right) dt \\
&= \int_0^{1/\epsilon} f(t, h(t, \underline{t}, \underline{\theta})) dt \\
&\geq \int_0^{1/\epsilon} \left(\left(\Lambda^*(\dot{\xi}(t), \xi(t)) - \epsilon \right) \wedge \frac{1}{\epsilon} \right) dt - 2\epsilon
\end{aligned}$$

Taking $\epsilon \rightarrow 0$ now yields our desired result.

$$I_x(\xi) \geq \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt$$

Theorem 2.5.10. *For each $x \in \mathbb{X}$, the family $(P_x^\epsilon)_{\epsilon>0}$ satisfies a large deviation principle on $\mathbb{D}([0, \infty), \mathbb{X})$ with good rate function $I_x : \mathbb{D}([0, \infty), \mathbb{X}) \rightarrow [0, \infty]$ as follows.*

$$(2.5.11) \quad I_x(\xi) = \begin{cases} \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt & \xi \in \mathbb{A}([0, \infty), \mathbb{X}), \xi(0) = x \\ \infty & \text{otherwise} \end{cases}$$

Proof. Theorem 2.3.9 gives us our large deviation principle with rate function I_x as in (2.3.10). Fix $\xi \in \mathbb{D}([0, \infty), \mathbb{X})$. If $\xi(0) \neq x$, then we already have $I_x(\xi) = \infty$. Otherwise, $I_x(\xi) = I_{\xi(0)}(\xi) = I(\xi)$, and so Lemma 2.5.1 tells us $I_x(\xi) = \infty$ if $\xi \notin \mathbb{A}([0, \infty), \mathbb{X})$. If $\xi \in \mathbb{A}([0, \infty), \mathbb{X})$, then Propositions 2.5.3 and 2.5.5 tell us that

$$I_x(\xi) = \int_0^\infty \Lambda^*(\dot{\xi}(t), \xi(t)) dt.$$

This concludes that I can be written as in (2.5.11).

Chapter 3

Large deviation rate functions

3.1 Mogulskii's theorem

A surprisingly powerful theorem in the theory of large deviations of stochastic processes is that of Mogulskii (see [DZ10, Theorems 5.1.2 and 5.1.19 and Exercise 5.122]). Fixing a family $(V_j)_{j \in \mathbb{N}}$ of independent quantities distributing with common distribution κ with light tails,

$$(3.1.1) \quad \Lambda_\kappa(u) := \log \int_{\mathbb{V}} e^{\langle u, v \rangle} \kappa(dv) < \infty, \quad u \in \mathbb{V}$$

this theorem provides a large deviation principle for the laws associated to quantities Y^ϵ as below.

$$Y_t^\epsilon = \epsilon \sum_{j=1}^{\lfloor t/\epsilon \rfloor} V_j, \quad t \in [0, \tau]$$

It states that the associated laws $(P^\epsilon)_{\epsilon > 0}$ satisfy a large deviation principle on the space $\mathbb{L}^\infty[0, \tau]$ of bounded functions $[0, \tau] \rightarrow \mathbb{V}$, equipped with the supremum norm. The rate function, like ours, is an integral of the Fenchel-Legendre transform of Λ_κ .

$$\xi \mapsto \begin{cases} \int_0^\tau \Lambda_\kappa^*(\dot{\xi}(t)) dt & \xi(0) = 0, \xi \in \mathbb{A}([0, \tau], \mathbb{V}) \\ \infty & \text{otherwise} \end{cases}$$

Very minor adjustments can actually make this theorem similar to the context of our principle. Firstly, the principle may be lifted to the space $\mathbb{L}_{\text{loc}}^\infty[0, \infty)$ of locally bounded functions $[0, \infty) \rightarrow \mathbb{V}$, equipped with the weighted supremum norm,

$$(\xi, \xi') \mapsto \sup_{t \in [0, \infty)} e^{-t} |\xi(t) - \xi'(t)|,$$

for this metric is consistent with $\xi_n \rightarrow \xi$ if and only if $\xi_n|_{[0, \tau]} \rightarrow \xi|_{[0, \tau]}$ uniformly for all $\tau \geq 0$, which is the same as the projective limit space induced by the restriction maps.

$$(\xi_\tau)_{\tau > 0} \in \lim_{\leftarrow \tau} \mathbb{L}^\infty[0, \tau] \xleftrightarrow{\xi_\tau = \xi|_{[0, \tau]}} \xi \in \mathbb{L}_{\text{loc}}^\infty[0, \infty)$$

Applying Dawson-Gärtner [DZ10, Theorem 4.6.1], the rate function over this space is as follows.

$$\xi \mapsto \begin{cases} \sup_{\tau > 0} \int_0^\tau \Lambda_\kappa^*(\dot{\xi}(t)) dt & \xi(0) = 0, \xi \in \mathbb{A}([0, \tau], \mathbb{V}) \text{ for all } \tau > 0 \\ \infty & \text{otherwise} \end{cases}$$

From here, we recognize that each process Y^ϵ is càdlàg; if ν is supported on \mathbb{X} , the process takes values in $\mathbb{D}([0, \infty), \mathbb{X})$, and so we may restrict our principle (see [DZ10, Lemma 4.1.5(b)]). Our rate function then takes the same form (recall the local definition of absolute continuity $\mathbb{A}([0, \infty), \mathbb{X})$).

$$(3.1.2) \quad \xi \mapsto \begin{cases} \int_0^\infty \Lambda_\kappa^*(\dot{\xi}(t)) dt & \xi(0) = 0, \xi \in \mathbb{A}([0, \infty), \mathbb{X}) \\ \infty & \text{otherwise} \end{cases}$$

Example 3.1.3 (Brownian motion). Applying Mogulskii's theorem when our increment distribution κ is $\text{Normal}(0, \text{id}_\mathbb{V})$, the integral in our rate function in (3.1.2) becomes the following.

$$(3.1.4) \quad \int_0^\infty \frac{1}{2} |\dot{\xi}(t)|^2 dt$$

Furthermore, for a Brownian motion W , the process $\sqrt{\epsilon}W$ ends up being exponentially equivalent to Y^ϵ ,

$$\limsup_{\epsilon \rightarrow 0} \epsilon \log \mathbb{P}(|\sqrt{\epsilon}W - Y^\epsilon| \geq \delta) = -\infty,$$

which makes the family $\sqrt{\epsilon}W$ satisfy the large deviation principle with rate function (3.1.4); this result is known as Schilder's theorem (see [DZ10, Theorem 5.2.3]).

Note that $(\sqrt{\epsilon}W)_{\epsilon > 0}$ is a family of affine processes covered Theorem 2.5.10. We have $\epsilon X^\epsilon = \sqrt{\epsilon}W$, where the base process X has special differential characteristics $(0, \text{id}_\mathbb{V}, 0)$. The easiest way to see this is by considering Theorem ?? with initial state $x = 0$. Our theorem also immediately resolves (2.5.11) the same rate function.

$$\Lambda^*(\dot{x}, x) = \sup_{u \in \mathbb{V}} \left(\langle u, \dot{x} \rangle - \frac{1}{2} \langle u, \text{id}_\mathbb{V} \cdot u \rangle \right) = \frac{1}{2} |\dot{x}|$$

Example 3.1.5 (Poisson). One may apply a very similar argument for when our increment distribution κ is $\text{Poisson}(1)$. In this case, the integral in the rate function in (3.1.2) evaluates to

$$(3.1.6) \quad \int_0^\infty \left(\dot{\xi}(t) \log(\dot{\xi}(t)) - \dot{\xi}(t) + 1 \right) dt,$$

so long as $\xi(t) \geq 0$ for Lebesgue-almost-every $t \geq 0$ (otherwise, it is infinite). In the case that $\xi(t) = 0$, we are taking the continuous extension of the integrand, i.e. $0 \log(0) := 0$. Similar to the work of Schilder's theorem, we may show, for a standard Poisson process N , $\epsilon N_{\cdot/\epsilon}$ is exponentially equivalent to this Y^ϵ , which makes the family satisfy a large deviation principle with rate function (3.1.6). In fact and exercise of our reference text, [DZ10, Exercise 5.2.12], suggests the reader to show just this.

Again, such a family $(\epsilon N_{\cdot/\epsilon})_{\epsilon>0}$ is covered by Theorem 2.5.10. To see this, consider a base affine process X on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$ with special differential characteristics as below, where δ_1 denotes the degenerate distribution at $1 \in \mathbb{R}$.

$$\beta(x) = 1, \quad \alpha(x) = 0, \quad \mu(x, dv) = \delta_1(dv)$$

Setting the initial state $x = 0$ and looking at Theorem ??, we may say that ϵX^ϵ can be realized as follows.

$$\begin{aligned} \epsilon X_t^\epsilon &= t + \epsilon 1_{[0,1]}(\text{id}_{\mathbb{R}}) * \tilde{p}_t^\epsilon \\ &= t + \epsilon 1_{[0,1]}(\text{id}_{\mathbb{R}}) * p_t^\epsilon - \epsilon 1_{[0,1]}(\text{id}_{\mathbb{R}}) * \hat{p}_t^\epsilon \\ &= t + \epsilon p([0, t/\epsilon] \times [0, 1]) - \int_0^{t/\epsilon} \int_{\mathbb{R}} \epsilon 1_{[0,1]}(v) dv ds \\ &= \epsilon p([0, t/\epsilon] \times [0, 1]) \end{aligned}$$

As stated in [JS03, Theorem II.4.8], this Poisson random measure p is a Poisson point process with Lebesgue intensity. This means that, for each $t \geq 0$, $N_t := p([0, t] \times [0, 1])$ distributes $\text{Poisson}(t)$, and $N_t - N_s = p((s, t] \times [0, 1])$ is independent of $N_s = p([0, s], [0, 1])$ for each $0 \leq s < t$. In other words, N is a standard Poisson process and

$$\epsilon X_t^\epsilon = \epsilon p([0, t/\epsilon] \times [0, 1]) = \epsilon N_{t/\epsilon}.$$

As with the normal increments, our rate function (2.5.11) resolves this immediately.

$$\begin{aligned} \Lambda^*(\dot{x}, x) &= \sup_{u \in \mathbb{V}} \left(u\dot{x} - u - \int_{\mathbb{R}} (e^{uv} - 1 - uv) \delta_1(dv) \right) = \sup_{u \in \mathbb{V}} \left(u\dot{x} - e^u + 1 \right) \\ &= \begin{cases} \dot{x} \log \dot{x} - \dot{x} + 1 & \dot{x} \geq 0 \\ \infty & \text{otherwise} \end{cases} \end{aligned}$$

3.2 Transformations

While Mogulskii's theorem specifies that the processes $(Y^\epsilon)_{\epsilon>0}$ —by design—have independent increments, we may use the contraction principle [DZ10, Theorem 4.2.1] to develop a large deviation principle for families of processes with state-dependent increments. Indeed, by introducing a continuous map F , we will have a large deviation principle for the family $(F_\# P^\epsilon)_{\epsilon>0}$ of measures $F_\# P^\epsilon$ associated with respective quantities $F(Y^\epsilon)$, and F can be chosen so that each $F(Y^\epsilon)$ is a process with state-dependent increments. Seeing as this section serves as a survey for intuition on rate functions, we will digress from discussing the specifics of continuity of F on restricted spaces and/or exponentially equivalent families in our examples below.

Example 3.2.1 (Diffusions). We can leverage Example 3.1.3 to a family of processes $(\epsilon X^\epsilon)_{\epsilon>0}$,

$$(3.2.2) \quad \epsilon X^\epsilon = \beta(\epsilon X^\epsilon) \cdot \ell + \sqrt{\epsilon} \sigma(\epsilon X^\epsilon) \cdot W,$$

where the drift $\beta : \mathbb{V} \rightarrow \mathbb{V}$ and diffusion $\alpha = \sigma\sigma^* : \mathbb{V} \rightarrow \mathbb{L}(\mathbb{V})$ are bounded and Lipschitz and α is invertible. The details of this result, attributed to Freidlin-Wentzel [DZ10, Theorems

5.6.3 and 5.6.7], are rather complicated, so we will explain a heuristic. Having a map $F_{\beta,\alpha}$ which implicitly solves the equation,

$$F_{\beta,\alpha}(\omega) = \xi, \quad \xi(t) = \beta(\xi) \cdot \ell_t + \sigma(\xi) \cdot \omega_t,$$

will make $F_{\beta}(\sqrt{\epsilon}W) = \epsilon X^\epsilon$ for each $\epsilon > 0$, so the contraction principle states that the distributions of $(\epsilon X^\epsilon)_{\epsilon>0}$ satisfy a large deviation principle in which the rate function I_X is derived from that I_W from Example 3.1.3.

$$I_X(\xi) := \inf \left\{ I_W(\omega) : F_{\beta}(\omega) = \xi \right\},$$

$$I_W(\omega) := \begin{cases} \int_0^\infty \frac{1}{2} |\dot{\omega}(t)|^2 dt & \omega(0) = 0, \omega \in \mathbb{A}([0, \infty), \mathbb{V}), \\ \infty & \text{otherwise} \end{cases}$$

When $F_{\beta}(\omega) = \xi$, equation (3.2.2) tells us $\dot{\omega} = \sigma(\xi)^{-1}(\dot{\xi} - \beta(\xi))$, and so on the

$$\begin{aligned} I_X(\xi) &= \int_0^\infty \frac{1}{2} \left| \sigma(\xi(t))^{-1} (\dot{\xi}(t) - \beta(\xi(t))) \right|^2 dt \\ &= \int_0^\infty \frac{1}{2} \left\langle (\dot{\xi}(t) - \beta(\xi(t))), \alpha(\xi(t))^{-1} (\dot{\xi}(t) - \beta(\xi(t))) \right\rangle dt \end{aligned}$$

Note that this result does not apply to the general class of affine diffusions, for β, α are generally not bounded or Lipschitz, and α need not be invertible. However, [?]—a paper which inspires parts of our proof—first proved that affine diffusions with special characteristics (β, α) satisfy a large deviation principle with rate function similar to that above. Our rate function (2.5.11) from Theorem 2.5.10 immediately resolves an identical representation.

$$\begin{aligned} \Lambda^*(\dot{x}, x) &= \sup_{u \in \mathbb{V}} \left(\langle u, \dot{x} \rangle - \langle u, \beta(x) \rangle - \frac{1}{2} \langle u, \alpha(x)u \rangle \right) \\ &= \begin{cases} \frac{1}{2} \left\langle (\dot{x} - \beta(x)), \alpha(x)^\dagger (\dot{x} - \beta(x)) \right\rangle & \dot{x} - \beta(x) \in \text{image } \alpha(x) \\ \infty & \text{otherwise} \end{cases} \end{aligned}$$

Above, $a^\dagger \in \mathbb{L}(\mathbb{V})$ denotes the pseudoinverse of $a \in \mathbb{L}(\mathbb{V})$.

3.3 Coupling

1. **Mogulskii's theorem.** Purpose of section is to familiarize with rate functions we already have and set the stage for how we operate with our theorem.

- (a) Cite Mogulskii's theorem.
- (b) Brownian motion of our regime: achieved with Mogulskii's theorem with Normal increments and exponential tightness (Schilder).
- (c) Poisson process of our regime: achieved with Mogulskii's theorem with Poisson increments and use exponential tightness.

2. **Simple contraction maps.**

- (a) Friedlin Wentzel (not so much our regime): use contraction mapping principles
 - (b) Birth rate process: Can we similarly contraction map Poisson to get this?
 - (c) Extension of Freidlin Wentzel to affine: KK
3. **Coupling states.** Indicate that when contraction mappings are not sufficient, we may *couple correlated states*, in the sense of looking at LDPs of joint processes.
- (a) Compound Poisson: Two *sources* of randomness; the arrivals and the jump sizes. Appeal to Duffy results for heuristical calculations.
 - (b) Compound linear Hawkes: Similarly two *sources* of randomness. Duffy also gives us the calculations. Note on Zhu paper for *sidestep*; less general jumps, more general nonlinear relationship of arrivals.
 - (c) The jumps of a general jump-diffusion do not have a well-posed notion of arrivals and jump sizes; we thus turn our focus to locally countable jump-diffusions, in which the three *sources* of randomness are the continuous local martingale, the arrival times, and the jump sizes. Note how this is discussed in next section.
4. **Locally countable affine processes.** Perform the necessary calculus and proceed to show our general formulation.
- (a) State result in numerous flavors, depending on which *base* quantities in which we choose to focus the large deviations.

$$\begin{aligned}
 X &= \beta(X) \cdot \ell + X^c + \text{id}_{\mathbb{V}} * \tilde{q}^X \\
 N^X &= 1 * q^X \\
 V^X &= \text{id}_{\mathbb{V}} * q^X
 \end{aligned}$$

- i. **overdetermined flavor.** (X, X^c, N^X, V^X) produces an overdetermined system which requires another condition for $I(\xi, \omega, \eta, \gamma)$ to be finite.

$$\dot{\xi}(t) = \beta(\xi(t)) + \dot{\omega}(t) + \dot{\eta}(t) \dot{\gamma}(t)$$

However, the rate function is very simple to understand.

- ii. **determine-continuous-noise flavor.** Normal term gets messy
 - iii. **determine-arrivals flavor.** Poisson and jump-term-denominator gets messy
 - iv. **determine-jumps flavor.** This is the one we have already presented; the jump-term-numerator gets messy.
- (b) Discuss how the deviations of X from the dynamical system $X = \beta(X) \cdot \ell$ are imposed from *continuous deviations* X^c and *discontinuous deviations* $\text{id}_{\mathbb{V}} * \tilde{q}^X$.
 - (c) Discuss how four quantities X, X^c, N^X, V^X heuristically relate in simple infinitesimal equality $(X, X^c, N^X, V^X) \approx (\xi, \omega, \eta, \gamma)$.

$$\dot{\xi}(t) = \beta(\xi(t)) + \dot{\omega}(t) + \dot{\eta}(t) \cdot \dot{\gamma}(t)$$

- (d) Each of the primitive deviations have a simple analogy, when we think of infinitesimals.

$$\dot{\omega}(t)$$

$$\text{normal deviations of covariance } \alpha(\xi(t))$$

$\dot{\eta}(t)$	<i>Poisson deviations of rate $\lambda(\xi(t))$</i>
$\dot{\gamma}(t)$	<i>jump deviations from $\kappa(\xi(t), dv)$</i>
$\xi(t) = \beta(\xi(t)) + \dot{\omega}(t) + \dot{\eta}(t) \cdot \dot{\gamma}(t)$	<i>all combined deviations</i>

- (e) Think of results from first section in this regard.
- i. birth is $\dot{\xi}(t) = \dot{\eta}(t)$, so we only need $\xi \approx X$.
 - ii. diffusion is $\dot{\xi}(t) = \beta(\xi(t)) + \dot{\omega}(t)$, and so we only need $\xi \approx X$ and rate function includes $\xi(t) - \beta(\xi(t))$ where $\dot{\omega}$ is.
 - iii. compound Poisson is $\dot{\xi}(t) = \dot{\eta}(t) \cdot \dot{\gamma}(t)$, so we choose one of the following pairs $(\xi, \eta) \approx (X, N^X)$, $(\xi, \gamma) \approx (X, V^X)$, or $(\eta, \gamma) \approx (N^X, V^X)$.
 - iv. compound linear Hawkes is $\dot{\xi}(t) = \beta(\xi(t)) + \dot{\eta}(t) \cdot \dot{\gamma}(t)$, so we can choose $(\xi, \eta) \approx (X, N^X)$ or $(\xi, \gamma) \approx (X, V^X)$.

Appendix A

Jump-diffusions

TODO:

- Motivate why I chose to put this in the appendix. Big point: I want to resolve abstractions and rigor of [JS03] to the digestible notions of special jump-diffusions.
- Point to the various papers we use that do not consolidate a similar set of assumptions.

In order to discuss jump-diffusions on a finite-dimensional real vector space, one must have a decent understanding of semimartingales. A great text for a comprehensive study of this is [JS03], which we will refer to in our proofs. In terms of notational differences, we choose our probability space (Ω, Σ, P) and filtration $\mathcal{F} = (\mathcal{F}_t)_{t \geq 0}$, where $\mathcal{F}_\infty \subseteq \Sigma$ denotes the joined space. Furthermore, we do not explicitly write processes to take values in \mathbb{R}^d , but rather some vector space \mathbb{V} with dimension $d := \dim \mathbb{V}$ and inner-product $\langle \cdot, \cdot \rangle$. Surely—due to our isometric isomorphism $\mathbb{V} \equiv \mathbb{R}^d$ —any componentwise or linear notion, such as integration or differentiation may be taken as equivalent. Furthermore, we sometimes specify that a stochastic process X has a Borel state space $\mathbb{X} \subseteq \mathbb{V}$, as this is the case when studying affine processes. We find it important to highlight the following important notation of objects introduced in [JS03, Chapters I-II].

- Given (P, \mathcal{F}) locally square-integrable martingales $M, N : \Omega \times \mathbb{R}_+ \rightarrow \mathbb{R}$, denote $\langle M, N \rangle$ the predictable quadratic covariation.
- Given $H, X : \Omega \times \mathbb{R}_+ \rightarrow \mathbb{R}$ with H being \mathcal{F} predictable and (P, \mathcal{F}) locally bounded and X a (P, \mathcal{F}) semimartingale, denote the stochastic integral process as follows.

$$H \bullet X_t = \int_0^t H_s dX_s$$

We may lift this concept componentwise and linearly. This allows us to choose the codomains of H, X to various combinations of \mathbb{V} and $\mathbb{L}(\mathbb{V}, \mathbb{W})$ when evaluating $H \bullet X$, so long as such a combination allows for $H_t \cdot X_t$ to make sense.

- Denote $\ell : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ the identity map to allow a concise notation for Lebesgue integration.

$$H \bullet \ell_t = \int_0^t H_s ds$$

- Given a random measure $q : \Omega \times \mathcal{B}(\mathbb{R}_+ \times \mathbb{V}) \rightarrow [0, \infty]$, denote the stochastic integral process against some suitably integrable process $H : \Omega \times \mathbb{R}_+ \times \mathbb{V} \rightarrow \mathbb{R}$ as follows.

$$H * q_t = \int_{[0,t] \times \mathbb{V}} H_s(v) q(ds, dv)$$

Denote its (P, \mathcal{F}) predictable projection by \hat{q} and the compensated measure $\tilde{q} = q - \hat{q}$. Also denote $H * \tilde{q}$ the compensated local martingale process for suitable $H \in G_{\text{loc}}(q)$, as constructed in [JS03, Definition II.1.27]. Lift these integration notions to vector-valued H componentwise. Instead of choosing a canonical variable for integrating expressions in this form, we use the identity maps $\text{id}_{\mathbb{V}}$ or ℓ .

$$f(\ell, \text{id}_{\mathbb{V}}) * q_t = \int_{[0,t] \times \mathbb{V}} f(s, v) q(ds, dv)$$

- Given (P, \mathcal{F}) semimartingales $X, Y : \Omega \times \mathbb{R}_+ \rightarrow \mathbb{R}$, denote $[X, Y]$ the quadratic covariation.
- Given a semimartingale X , denote X^c its continuous local martingale component and q^X its jump measure.

A.1 Formulation

As in [JS03, Definition III.2.18], a (P, \mathcal{F}) jump-diffusion X on state space $(\mathbb{X}, \mathcal{B}(\mathbb{X}))$ is a (P, \mathcal{F}) semimartingale in which the χ -characteristics (B^X, A, \hat{q}^X) have the following decompositions.

$$(A.1.1) \quad B_t^X = \int_0^t \beta^X(X_s) ds, \quad A_t = \int_0^t \alpha(X_s) ds, \quad \hat{q}^X(ds, dv) = \mu(X_s, dv) ds,$$

where the functions have the following properties.

- $\beta^X : \mathbb{X} \rightarrow \mathbb{V}$ is Borel measurable, $\beta^X \in \mathcal{B}(\mathbb{X})/\mathcal{B}(\mathbb{V})$.
- $\alpha : \mathbb{X} \rightarrow \mathbb{L}(\mathbb{V})$ is Borel measurable, $\alpha \in \mathcal{B}(\mathbb{X})/\mathcal{B}(\mathbb{L}(\mathbb{V}))$, and $\alpha(x)$ is self-adjoint and non-negative for each $x \in \mathbb{X}$.
- $\mu : \mathbb{X} \times \mathcal{B}(\mathbb{V}) \rightarrow [0, \infty]$ is a transition kernel from \mathbb{X} to \mathbb{V} , and it satisfies the following properties for each $x \in \mathbb{X}$.

$$(A.1.2) \quad \mu(x, \{0\}) = 0, \quad \int_{\mathbb{V}} (1 \wedge |v|^2) \mu(x, dv) < \infty$$

In other words, our jump-diffusion X has the following canonical semimartingale representation (see [JS03, Theorem II.2.34] for definition).

$$(A.1.3) \quad \begin{aligned} X &= X_0 + \beta^X(X) \cdot \ell + X^c + \chi * \tilde{q}^X + (\text{id}_{\mathbb{V}} - \chi) * q^X \\ \langle X^{c,i}, X^{c,j} \rangle &= \alpha_{ij}(X) \cdot \ell \\ \hat{q}^X(ds, dv) &= \mu(X_s, dv) ds \end{aligned}$$

Remark A.1.4. (a) Note that we differ slightly from the definition we reference by imposing a time-homogeneity formulation. There is no loss of generality in doing so, because we may always extend the state to $\mathbb{R}_+ \times \mathbb{X}$ via $\hat{X}_t = (t, X_t)$.

(b) Note that (A.1.1) can be written concisely by using the identity ℓ on \mathbb{R}_+ .

$$B_t^X = \beta^X(X) \cdot \ell_t, \quad A_t = \alpha(X) \cdot \ell_t, \quad \hat{q}^X([0, t], dv) = \mu(X, dv) \cdot \ell_t$$

(c) If we have a jump-diffusion with χ -characteristics in (A.1.1), we call (β^X, α, μ) the differential χ -characteristics. We see from (A.1.3) that β^X and $\beta^{\hat{X}}$ relate between different truncation functions $\chi, \hat{\chi}$ with the simple identity.

$$(A.1.5) \quad \beta^{\hat{X}}(x) = \beta^X(x) + \int_{\mathbb{V}} (\hat{\chi}(v) - \chi(v)) \mu(x, dv)$$

(d) The conditions on $\alpha(x)$ and $\mu(x, dv)$ are immediate consequences of (A.1.1). For the most general setting, see the corresponding result for any semimartingale, in [JS03, Proposition II.2.9].

Example A.1.6. Fix a probability space (Ω, Σ, P) and filtration $\mathcal{F} = (\mathcal{F})_{t \geq 0}$.

Just as with $(\mathbb{R}^d, \mathcal{B}(\mathbb{V}))$, we say that W is a standard (P, \mathcal{F}) Brownian motion on $(\mathbb{V}, \mathcal{B}(\mathbb{V}))$ if it is a continuous (P, \mathcal{F}) martingale with predictable quadratic covariation as follows.

$$\langle W^i, W^j \rangle_t = \begin{cases} t & i = j \\ 0 & \text{otherwise} \end{cases}$$

It is clear that W is a (P, \mathcal{F}) jump-diffusion with differential χ -characteristics $(0, \alpha, 0)$, where $\alpha(x) = \text{id}_{\mathbb{V}}$ for all $x \in \mathbb{X}$.

Similarly, we say that p is a standard (P, \mathcal{F}) Poisson random measure on $\mathcal{B}(\mathbb{R}_+ \times \mathbb{V})$ if its (P, \mathcal{F}) predictable projection is the Lebesgue measure $\hat{p}(ds, dv) = ds \otimes dv$ (identifying measures on $\mathcal{B}(\mathbb{R}^d)$ as those on $\mathcal{B}(\mathbb{V})$). By [JS03, Theorem II.4.8], this p is the same as a Poisson point process with Lebesgue intensity, which has infinitely many jumps on any nonempty interval of time. The accumulated jumps $\text{id}_{\mathbb{V}} * p$ form a (P, \mathcal{F}) jump-diffusion with parameters as follows.

$$\beta^X(x) = \int_{\mathbb{V}} \chi(v) dv, \quad \alpha(x) = 0, \quad \mu(x, dv) = dv,$$

because we have the following decomposition.

$$\begin{aligned} \text{id}_{\mathbb{V}} * p &= \chi * p + (\text{id}_{\mathbb{V}} - \chi) * p \\ &= \chi * \hat{p} + \chi * \tilde{p} + (\text{id}_{\mathbb{V}} - \chi) * p \\ &= \beta^X \cdot \ell + \chi * \tilde{p} + (\text{id}_{\mathbb{V}} - \chi) * p \end{aligned}$$

Note that the infinite activity of p means that the last term cannot be compensated.

We will see at the end of this section that these two objects W and p are the fundamental building blocks of all jump-diffusions.

The following Lemma will be repeatedly used as a shortcut of Itô's formula and various identities that always apply with jump-diffusions.

Lemma A.1.7. *Let X be a jump-diffusion with differential χ -characteristics (β^X, α, μ) and $f \in \mathbb{C}^2(\mathbb{V}, \mathbb{R})$. The composition $f(X)$ has the following semimartingale representation.*

$$\begin{aligned} f(X_t) = & f(X_0) + \left(Df(X) \cdot \beta^X(X) \right) \cdot \ell_t + \frac{1}{2} \operatorname{tr} \left(D^2 f(X) \circ \alpha(X) \right) \cdot \ell_t + Df(X_-) \cdot X^c \\ & + \left(Df(X_-) \cdot \chi \right) * \tilde{q}_t^X + \left(f(X_- + \operatorname{id}_{\mathbb{V}}) - f(X_-) - Df(X_-) \cdot \chi \right) * q_t^X \end{aligned}$$

Proof. Apply Itô's formula [JS03, Theorem I.4.57] and use the predictable covariation identity in (A.1.3) to get the following.

$$\begin{aligned} f(X_t) = & f(X_0) + \sum_{i=1}^d D_i f(X_-) \cdot X_t^i + \frac{1}{2} \sum_{i,j=1}^d D_{ij} f(X_-) \cdot \langle X^{c,i}, X^{c,j} \rangle_t \\ & + \sum_{0 \leq s \leq t} \left(f(X_s) - f(X_{s-}) - \sum_{i=1}^d Df_i(X_{s-}) \Delta X_s \right) \\ = & f(X_0) + Df(X_-) \cdot X_t + \frac{1}{2} \sum_{i,j=1}^d D_{ij} f(X_-) \cdot (\alpha_{ij}(X) \cdot \ell)_t \\ & + \left(f(X_- + \operatorname{id}_{\mathbb{V}}) - f(X_-) - Df(X_-) \cdot \operatorname{id}_{\mathbb{V}} \right) * q_t^X \end{aligned}$$

Using the iterated stochastic integral formula [JS03, Remark I.4.37], we may simplify the above equation to the following.

$$\begin{aligned} f(X_t) = & f(X_0) + Df(X_-) \cdot X_t + \frac{1}{2} \operatorname{tr} \left(D_{ij} f(X_-) \circ \alpha(X) \right) \cdot \ell_t \\ & + \left(f(X_- + \operatorname{id}_{\mathbb{V}}) - f(X_-) - Df(X_-) \cdot \operatorname{id}_{\mathbb{V}} \right) * q_t^X \end{aligned}$$

Now substitute our representation of (A.1.3) and repeat the iterated stochastic integral to get the following.

$$\begin{aligned} f(X_t) = & f(X_0) + Df(X_-) \cdot (X_0 + \beta^X(X) \cdot \ell + X^c + \chi * \tilde{q}^X + (\operatorname{id}_{\mathbb{V}} - \chi) * q^X)_t \\ & + \frac{1}{2} \operatorname{tr} \left(D^2 f(X_-) \circ \alpha(X) \right) \cdot \ell_t + \left(f(X_- + \operatorname{id}_{\mathbb{V}}) - f(X_-) - Df(X_-) \cdot \operatorname{id}_{\mathbb{V}} \right) * q_t^X \\ = & f(X_0) + \left(Df(X_-) \cdot \beta^X(X) \right) \cdot \ell_t + \frac{1}{2} \operatorname{tr} \left(D^2 f(X_-) \circ \alpha(X) \right) \cdot \ell_t + Df(X_-) \cdot X^c \\ & + Df(X_-) \cdot (\chi * \tilde{q}^X)_t + \left(f(X_- + \operatorname{id}_{\mathbb{V}}) - f(X_-) - Df(X_-) \cdot \chi \right) * q_t^X \end{aligned}$$

Furthermore, since $X_- = X$ on all but a countable amount of jumps, we may rewrite the Lebesgue integrals.

(A.1.8)

$$\begin{aligned} f(X_t) = & f(X_0) + \left(Df(X) \cdot \beta^X(X) \right) \cdot \ell_t + \frac{1}{2} \operatorname{tr} \left(D^2 f(X) \circ \alpha(X) \right) \cdot \ell_t + Df(X_-) \cdot X^c \\ & + Df(X_-) \cdot (\chi * \tilde{q}^X)_t + \left(f(X_- + \operatorname{id}_{\mathbb{V}}) - f(X_-) - Df(X_-) \cdot \chi \right) * q_t^X \end{aligned}$$

For the remaining equality, we construct localizing sequence $(T_n)_{n \in \mathbb{N}}$ of \mathcal{F} stopping times,

$$(A.1.9) \quad T_n(\omega) := \inf \{ t > 0 : X_t(\omega) > n \} \wedge n, \quad \omega \in \Omega, \quad n \in \mathbb{N},$$

to see that $Df(X_-)$ is (P, \mathcal{F}) locally bounded.

$$|Df(X_{s_n}^{T_n})| \leq \sup_{|x| \leq n} |Df(x)|$$

Thus, by [JS03, Proposition II.1.30], we may rewrite the following.

$$Df(X_-) \cdot (\chi * \tilde{q}^X)_t = (Df(X_-) \cdot \chi) * \tilde{q}_t^X,$$

which when substituted into (A.1.8) gives us our desired identity.

In the above lemma, the final term in the semimartingale decomposition of $f(X)$ is typically not able to be compensated into a local martingale. If we did have local integrability of the following quantity,

$$\left| f(X_- + \text{id}_{\mathbb{V}}) - f(X_-) + Df(X_-) \cdot \chi \right| * \tilde{q}^X,$$

then by [JS03, Proposition II.1.28] we could rewrite $f(X)$ into a canonical special semimartingale decomposition.

$$\begin{aligned} f(X_t) &= f(X_0) + \mathcal{L}f(X) \cdot \ell_t + Df(X_-) \cdot X^c + (f(X_- + \text{id}_{\mathbb{V}}) - f(X_-)) * \tilde{q}_t^X \\ \text{(A.1.10)} \quad \mathcal{L}f(x) &:= Df(x) \cdot \beta^x(x) + \frac{1}{2} \text{tr} \left(D^2 f(x) \circ \alpha(x) \right) \\ &\quad + \int_{\mathbb{V}} \left(f(x+v) - f(x) - Df(x) \cdot \chi(v) \right) \mu(x, dv) \end{aligned}$$

So long as f is bounded, we can guarantee this special semimartingale property.

Proposition A.1.11. *Let X and f as in Lemma A.1.7, and further impose f is bounded. Then the composition $f(X)$ is a special semimartingale with the decomposition as in (A.1.10).*

Proof. Seeing as f is bounded, [JS03, Lemma I.4.24] tells us that $f(X)$ is a special semimartingale. By [JS03, Proposition I.4.23], it is then the case that the following term is locally integrable.

$$\left(f(X_- + \text{id}_{\mathbb{V}}) - f(X_-) - Df(X_-) \cdot \chi \right) * q_t^X$$

By our discussion above, this suffices to conclude (A.1.10).

This operator \mathcal{L} in (A.1.10) gives a nice closed form for suitable $f(X)$, and so we reserve it the term of *generator* associated with X . Note that we do not mark dependence on χ , as any other truncation function $\hat{\chi}$ will produce the same operator; see Remark A.1.4(c) and note that the displacement from β^x and $\beta^{\hat{x}}$ would be the same as that in the integral term. One particular setting in which this result is useful is establishing a Lévy-Khintchine formula for jump-diffusions.

Proposition A.1.12. *Fix a jump-diffusion X with differential χ -characteristics (β^x, α, μ) . Then, for each $u \in i\mathbb{V}$, the process $\exp(\langle u, X \rangle - \Lambda(u, X) \cdot \ell)$ is a complex-valued (P, \mathcal{F}) local martingale, where $\Lambda : i\mathbb{V} \times \mathbb{X} \rightarrow \mathbb{R}$ is the associated Lévy-Khintchine map.*

$$\Lambda(u, x) = \langle u, \beta^x(x) \rangle + \frac{1}{2} \langle u, \alpha(x) \rangle + \int_{\mathbb{V}} (e^{\langle u, v \rangle} - 1 - \langle u, \chi(v) \rangle) \mu(x, dv),$$

Proof. For a fixed $u \in i\mathbb{V}$, note that the map f_u , defined by $f_u(v) = \exp \langle u, v \rangle$ is bounded. Thus, by Proposition A.1.11, we have

$$f_u(X_t) = f_u(X_0) + \mathcal{L}f_u(X) \cdot \ell_t + M_t,$$

where M is a $(\mathbb{P}, \mathcal{F})$ local martingale. Observe that the partial derivatives of f are as follows,

$$(A.1.13) \quad D_i f_u(x) = f_u(x) u_i, \quad D_{ij} f_u(x) = f_u(x) u_i u_j,$$

so we have the following equation.

$$\begin{aligned} \mathcal{L}f_u(x) &= Df_u(x) \cdot \beta^X(x) + \frac{1}{2} \operatorname{tr} \left(D^2 f_u(x) \circ \alpha(x) \right) \\ &\quad + \int_{\mathbb{V}} \left(f_u(x+v) - f_u(x) - Df_u(x) \cdot \chi(v) \right) \mu(x, dv) \\ &= f_u(x) \langle u, \beta^X(x) \rangle + \frac{1}{2} f_u(x) \langle u, \alpha(x) u \rangle + f_u(x) \int_{\mathbb{V}} \left(f_u(v) - 1 - \langle u, \chi(v) \rangle \right) \mu(x, dv) \\ &= f_u(x) \cdot \Lambda(u, x) \end{aligned}$$

Denoting $A = f_u(X) = \exp \langle u, X \rangle$ and $B = \exp(-\Lambda(u, X) \cdot \ell)$, we now use the fact that B is \mathcal{F} predictable and of finite-variation, so [JS03, Proposition I.4.49(b)] gives us the following.

$$\begin{aligned} &\exp \left(\langle u, X \rangle - \Lambda(u, X) \cdot \ell \right) \\ &= A_t B_t \\ &= A_0 B_0 + A_- \cdot B_t + B \cdot A_t \\ &= \exp \langle u, X_0 \rangle + A_- \cdot \left((-B \cdot \Lambda(u, X)) \cdot \ell \right)_t + B \cdot \left(f_u(X_0) + \mathcal{L}f_u(X) \cdot \ell + M \right)_t \\ &= \exp \langle u, X_0 \rangle - \left(A \cdot B \cdot \Lambda(u, X) \right) \cdot \ell_t + \left(B \cdot f_u(X) \cdot \Lambda(u, X) \right) \cdot \ell_t + B \cdot M_t \\ &= \exp \langle u, X_0 \rangle + B \cdot M_t \end{aligned}$$

This identity and [JS03, Remark I.4.34(b)] concludes the proof.

It turns out that each of the preceding results is sufficient in characterizing a semimartingale X as a jump-diffusion.

Theorem A.1.14. *The following statements are equivalent for a stochastic process X on state space $(\mathbb{X}, \mathcal{B}(\mathbb{X}))$.*

- (a) X is a $(\mathbb{P}, \mathcal{F})$ jump-diffusion with differential χ -characteristics (β^X, α, μ) .
- (b) For each bounded $f \in \mathbb{C}^2(\mathbb{V}, \mathbb{R})$, the process $f(X_t) - \mathcal{L}f(X_t) \cdot \ell_t$ is a $(\mathbb{P}, \mathcal{F})$ local martingale, where

$$\mathcal{L}f(x) := Df(x) \cdot \beta^X(x) + \frac{1}{2} \operatorname{tr} \left(D^2 f(x) \circ \alpha(x) \right) + \int_{\mathbb{V}} \left(f(x+v) - f(x) - Df(x) \cdot \chi(v) \right) \mu(x, dv)$$

- (c) For each $u \in i\mathbb{V}$, the process $\exp \left(\langle u, X \rangle - \Lambda(u, X) \cdot \ell \right)$ is a $(\mathbb{P}, \mathcal{F})$ local martingale, where Λ is our Lévy-Khintchine map.

$$\Lambda(u, x) = \langle u, \beta^X(x) \rangle + \frac{1}{2} \langle u, \alpha(x) \rangle + \int_{\mathbb{V}} \left(e^{\langle u, v \rangle} - 1 - \langle u, \chi(v) \rangle \right) \mu(x, dv),$$

(d) Denoting $(P_x)_{x \in \mathbb{X}}$ the P -conditional distributions of X factored through the initial state X_0 and selecting Borel functions σ, c to satisfy,

$$(A.1.15) \quad \begin{aligned} \sigma : \mathbb{X} &\rightarrow \mathbb{L}(\mathbb{V}) & \sigma \sigma^*(x) &= \alpha(x) \\ c : \mathbb{X} \times \mathbb{V} &\rightarrow \mathbb{V} & \mu(x, \Gamma) &= \int_{\mathbb{V}} 1_{\Gamma}(c(x, v)) dv \end{aligned}$$

each P_x is a solution to the equation associated with a standard Brownian motion W and Poisson random measure p , where $\chi' = \text{id}_{\mathbb{V}} - \chi$.

$$X_t = x + \beta^X(X) \cdot \ell_t + \sigma(X_-) \cdot W_t + (\chi \circ c(X_-, \text{id}_{\mathbb{V}})) * \tilde{p}_t + (\chi' \circ c(X_-, \text{id}_{\mathbb{V}})) * p_t$$

Proof. This is simply restating [JS03, Theorems II.2.42, II.2.49, and III.2.26] in terms of our identities from the previous propositions and lemmas. The choice of standard intensity $dt \otimes dv$ for the Poisson random measure is such that the jump factor dv satisfies the atom-free and infinite properties in [JS03, Remark III.2.28(3)].

Remark A.1.16. In the final part above, the push-forward map c may put mass on 0,

$$\int_{\mathbb{V}} 1_{\{0\}}(c(x, v)) dv > 0,$$

to thin or delete jumps coming from p (of which there are infinitely many). However, this contradicts the condition (A.1.2) that $\mu(x, \{0\}) = 0$ for all $x \in \mathbb{X}$. Explicitly, the push-forward in (A.1.15) happens on the space $\mathbb{V}_0 := \mathbb{V} - \{0\}$,

$$\mu(x, \Gamma) = \int_{\mathbb{V}} 1_{\Gamma}(c(x, v)) dv, \quad \Gamma \in \mathcal{B}(\mathbb{V}_0)$$

to allow for such thinning.

A.2 Special jump-diffusions

We now turn our focus to (P, \mathcal{F}) jump-diffusions which are additionally *special* in the sense of them having a semimartingale decomposition in which the finite-variation term is predictable. When looking at the canonical representation of a jump-diffusion X with χ -characteristics (β^X, α, μ) , it is clear how to make this predictable.

$$(A.2.1) \quad \begin{aligned} X_t &= X_0 + \beta^X(X) \cdot \ell_t + X_t^c + \chi * \tilde{q}^X + (\text{id}_{\mathbb{V}} - \chi) * q^X \\ &= X_0 + \beta^X(X) \cdot \ell_t + (\text{id}_{\mathbb{V}} - \chi) * \tilde{q}^X + X_t^c + \text{id}_{\mathbb{V}} * \tilde{q}^X \\ &= X_0 + \left(\beta^X(X) + \int_{\mathbb{V}} (v - \chi(v)) \mu(X, dv) \right) \cdot \ell_t + X_t^c + \text{id}_{\mathbb{V}} * \tilde{q}^X \end{aligned}$$

In such a case, it is nice to define the function $\beta : \mathbb{X} \rightarrow \mathbb{V}$,

$$(A.2.2) \quad \beta(x) := \beta^X(x) + \int_{\mathbb{V}} (v - \chi(v)) \mu(x, dv),$$

so that (A.2.1) may be simplified to a concise special semimartingale decomposition.

$$X_t = X_0 + \beta(X) \cdot \ell + X^c + \text{id}_{\mathbb{V}} * \tilde{q}_t^X$$

We call the triplet (β, α, μ) that results from (A.2.2) the *special differential characteristics* and its components β, α, μ the *drift*, *diffusion*, and *jump kernel*, respectively.

The calculus of (A.2.1) begs the question that $(\text{id}_{\mathbb{V}} - \chi) * q^X$ can be compensated which is not generally the case—otherwise, the term *special* would be a misnomer! The next result specifies conditions on which we may perform the above calculus.

Lemma A.2.3. *Let X be a (P, \mathcal{F}) jump-diffusion with differential χ -characteristics (β^X, α, μ) , such that μ satisfies the following condition.*

$$x \mapsto \int_{\mathbb{V}} |v - \chi(v)| \mu(x, dv) \text{ is bounded on compact subsets}$$

Then, X is special with drift β as in (A.2.2).

Proof. By choosing a \mathcal{F} localizing sequence $(T_n)_{n \in \mathbb{N}}$ as in (A.1.9), our hypothesis gives us the following integrability.

$$\mathbb{E}_P |\text{id}_{\mathbb{V}} - \chi| * \hat{q}_{T_n}^X = \mathbb{E}_P \int_0^{T_n} \int_{\mathbb{V}} |v - \chi(v)| \mu(X_t, dv) dt \leq n \cdot \sup_{|x| \leq n} \int_{\mathbb{V}} |v - \chi(v)| \mu(x, dv) < \infty$$

Now, [JS03, Proposition II.1.28] allows us to compensate as we did in (A.2.1)

Seeing as $(\text{id}_{\mathbb{V}} - \chi) * q^X$ may be compensated for special jump-diffusions X , all the characterizing objects of Theorem A.1.14 may be rewritten in terms of our drift β —effectively, χ becomes the identity.

$$\begin{aligned} \mathcal{L}f(x) &:= Df(x) \cdot \beta(x) + \frac{1}{2} \text{tr} \left(D^2 f(x) \circ \alpha(x) \right) + \int_{\mathbb{V}} \left(f(x+v) - f(x) - Df(x) \cdot v \right) \mu(x, dv) \\ \Lambda(u, x) &= \langle u, \beta(x) \rangle + \frac{1}{2} \langle u, \alpha(x) \rangle + \int_{\mathbb{V}} (e^{\langle u, v \rangle} - 1 - \langle u, v \rangle) \mu(x, dv), \\ X_t &= x + \beta(X) \cdot \ell_t + \sigma(X_-) \cdot W_t + c(X_-, \text{id}_{\mathbb{V}}) * \tilde{p}_t \end{aligned}$$

A.3 Locally countable jump-diffusions

We see that a (P, \mathcal{F}) jump-diffusion X is special if the accumulated large jumps $(\text{id}_{\mathbb{V}} - \chi) * q^X$ may be compensated. To this end, being special is a condition on the jumps *away* from the origin. We now turn our focus to jump-diffusions X in which the jumps *near* the origin behave nicely. For any jump-diffusion X , we may count the jumps with the jump process N^X .

$$(A.3.1) \quad N_t^X := \sum_{0 \leq s \leq t} 1_{\Delta X_s \neq 0} = 1 * q_t^X$$

For many jump diffusions, it may be the case that we P -almost-surely have $N_t^X = \infty$ for all $t > 0$. We say that X has (P, \mathcal{F}) *locally countable*, so long as N^X is (P, \mathcal{F}) locally integrable. Below, we state how to verify this using the differential characteristics.

Lemma A.3.2. *Fix a (P, \mathcal{F}) jump-diffusion X with differential χ -characteristics (β^X, α, μ) satisfying*

$$x \mapsto \mu(x, \mathbb{V}) \text{ is bounded on compact sets,}$$

then X is locally countable. Moreover, we may define $\lambda : \mathbb{X} \rightarrow \mathbb{R}_+$ and probability kernel $\kappa : \mathbb{X} \times \mathcal{B}(\mathbb{V}) \rightarrow [0, 1]$ by the following factoring.

$$\lambda(x) := \mu(x, \mathbb{V}), \quad \mu(x, dv) =: \lambda(x)\kappa(x, dv)$$

Also, N has (P, \mathcal{F}) intensity $\lambda(X)$.

Proof. Select the sequence $(T_n)_{n \in \mathbb{N}}$ as in (A.1.9). Note now that, since the constant function 1 is predictable,

$$\mathbb{E}_P N_{T_n}^X = \mathbb{E}_P 1 * q_{T_n}^X = \mathbb{E}_P 1 * \hat{q}_{T_n}^X = \mathbb{E}_P \int_0^{T_n} \mu(X_t, \mathbb{V}) dt \leq n \cdot \sup_{|x| \leq n} \mu(x, \mathbb{V}) < \infty$$

This means that N^X is locally integrable, making X locally countable. Moreover, by [JS03, Theorem II.1.8],

$$N^X - \int_0^t \lambda(X_s) ds = 1 * q^X - \int_0^t \int_{\mathbb{V}} \mu(X_s, dv) ds = 1 * q^X - 1 * \hat{q}^X$$

is a (P, \mathcal{F}) local martingale, which finishes the proof.

Remark A.3.3. (a) Such objects λ, κ always exist with our assumption of the Lemma. Seeing as μ is a transition kernel from $(\mathbb{X}, \mathcal{B}(\mathbb{X}))$ to $(\mathbb{V}, \mathcal{B}(\mathbb{V}))$, we have our desired measurability.

$$\lambda := \mu(\cdot, \mathbb{V}) \in \mathcal{B}(\mathbb{X}) / \mathcal{B}(\mathbb{R}_+)$$

Constructing κ should be obvious algebra, so long as we have no zero measures; otherwise, we may define

$$\kappa(x, \Gamma) := \delta_{e_1}(\Gamma) \cdot 1_{\lambda^{-1}\{0\}}(x) + \frac{\mu(x, \Gamma)}{\lambda(x)} 1_{\mathbb{X} - \lambda^{-1}\{0\}}(x),$$

where δ_{e_1} is the degenerate measure at $e_1 \in \mathbb{V}$. This ensures that any $\kappa(\cdot, \Gamma) \in \mathcal{B}(\mathbb{X}) / \mathcal{B}([0, 1])$ and any $\kappa(x, \cdot)$ a probability measure on $\mathcal{B}(\mathbb{V})$. Also, when $\mu(x, \cdot)$ is the zero measure,

$$\mu(x, dv) = 0 = \lambda(x) \cdot \delta_{e_1}(dv) = \lambda(x)\kappa(x, dv),$$

and otherwise,

$$\mu(x, dv) = \mu(x, \mathbb{V}) \frac{\mu(x, dv)}{\mu(x, \mathbb{V})} = \lambda(x)\kappa(x, dv).$$

(b) We call λ the intensity map and κ the (conditional) jump distribution

(c) As far as we know, there is no widely accepted source which explores jump-diffusions to the extent of declaring a notion like locally countable, as we have. This means that there is likely some clash of terminology, should such a concept already exist.

A.4 Real moments of jump-diffusions

We now turn our focus to the real moments of (P, \mathcal{F}) jump-diffusions and the extension of our Lévy-Khintchine map Λ to real moments.

$$\Lambda(u, x) = \langle u, \beta^x(x) \rangle + \frac{1}{2} \langle u, \alpha(x) \rangle + \int_{\mathbb{V}} (e^{\langle u, v \rangle} - 1 - \langle u, \chi(v) \rangle) \mu(x, dv), \quad u \in \mathbb{V}, \quad x \in \mathbb{X}$$

The above expression may be infinite, as the final term includes an unbounded integral over a possibly infinite measure. That said, we find it imperative to denote the following sets of finiteness.

$$(A.4.1) \quad \mathcal{D}_\Lambda(x) := \left\{ u \in \mathbb{V} : \Lambda(u, x) < \infty \right\}, \quad \mathcal{D}_\Lambda := \bigcap_{x \in \mathbb{X}} \mathcal{D}_\Lambda(x)$$

The following results will explore the nature of the maps $\Lambda(\cdot, x) : \mathcal{D}_\Lambda(x) \rightarrow \mathbb{R}$ for fixed differentiable χ -characteristics (β^x, α, μ) , where our truncation function χ is defined by $\chi(v) = v1_{|v| \leq 1}$. Note that there is no loss of generality in selecting this truncation function, since they all evaluate Λ identically.

Lemma A.4.2. *For any $x \in \mathbb{X}$, we have $u \in \mathcal{D}_\Lambda(x)$ if and only if $\int_{|v| > 1} e^{\langle u, v \rangle} \mu(x, dv) < \infty$.*

Proof. To each $u, v \in \mathbb{V}$, Taylor's theorem gives us $\gamma_{u,v} \in [0, 1]$ such that

$$e^{\langle u, v \rangle} = 1 + \langle u, v \rangle + \frac{1}{2} e^{\gamma_{u,v} \langle u, v \rangle} \langle u, v \rangle^2.$$

This allows us to see that, for each $x \in \mathbb{X}$, $\Lambda(u, x)$ and $\int_{|v| > 1} e^{\langle u, v \rangle} \mu(x, dv)$ differ by finite expressions.

$$\begin{aligned} & \left| \Lambda(u, x) - \int_{|v| > 1} e^{\langle u, v \rangle} \mu(x, dv) \right| \\ &= \left| \langle u, \beta^x(x) \rangle + \frac{1}{2} \langle u, \alpha(x) \rangle + \int_{|v| \leq 1} (e^{\langle u, v \rangle} - 1 - \langle u, v \rangle) \mu(x, dv) - \int_{|v| > 1} \mu(x, dv) \right| \\ &\leq \left| \langle u, \beta^x(x) \rangle + \frac{1}{2} \langle u, \alpha(x) \rangle \right| + \left| \int_{|v| \leq 1} \frac{1}{2} e^{\gamma_{u,v} \langle u, v \rangle} \langle u, v \rangle^2 \mu(x, dv) \right| + \int_{|v| > 1} \mu(x, dv) \\ &\leq \left| \langle u, \beta^x(x) \rangle + \frac{1}{2} \langle u, \alpha(x) \rangle \right| + \left(\frac{1}{2} e^{|u|} + 1 \right) \int_{\mathbb{V}} (1 \wedge |v|^2) \mu(x, dv) \end{aligned}$$

Thus, one can be defined as a finite displacement of the other.

Lemma A.4.3. *For each $x \in \mathbb{X}$, $\mathcal{D}_\Lambda(x)$ is convex.*

Proof. We use our characterization of $\mathcal{D}_\Lambda(x)$ from Lemma A.4.2. Let $u, u' \in \mathcal{D}_\Lambda(x)$, $\gamma \in (0, 1)$, and use Hölder's inequality to see the following.

$$\begin{aligned} & \int_{|v| > 1} e^{\langle u' + \gamma(u - u'), v \rangle} \mu(x, dv) \\ &= \int_{|v| > 1} |(e^{\langle u, v \rangle})^\gamma \cdot (e^{\langle u', v \rangle})^{1-\gamma}| \mu(x, dv) \end{aligned}$$

$$\begin{aligned}
&\leq \left(\int_{|v|>1} |(e^{\langle u,v \rangle})^\gamma|^{\frac{1}{\gamma}} \mu(x, dv) \right)^\gamma \left(\int_{|v|>1} |(e^{\langle u',v \rangle})^{1-\gamma}|^{\frac{1}{1-\gamma}} \mu(x, dv) \right)^{1-\gamma} \\
&= \left(\int_{|v|>1} e^{\langle u,v \rangle} \mu(x, dv) \right)^\gamma \left(\int_{|v|>1} e^{\langle u',v \rangle} \mu(x, dv) \right)^{1-\gamma} \\
&< \infty
\end{aligned}$$

An arbitrary convex combination now satisfies $\gamma u + (1 - \gamma)u' \in \mathcal{D}_\Lambda(x)$.

Lemma A.4.4. *For each $x \in \mathbb{X}$, the map $\Lambda(\cdot, x)$ is continuously differentiable on $\mathcal{D}_\Lambda(x)^\circ$, with derivative $D\Lambda(\cdot, x) : \mathcal{D}_\Lambda(x)^\circ \rightarrow \mathbb{L}(\mathbb{V}, \mathbb{R})$ as follows.*

$$(A.4.5) \quad D\Lambda(u, x)w = \left\langle \beta^\chi(x) + \alpha(x)u + \int_{\mathbb{V}} (e^{\langle u,v \rangle} v - \chi(v)) \mu(x, dv), w \right\rangle, \quad u \in \mathcal{D}_\Lambda(x)^\circ$$

Proof. Fix $x \in \mathbb{X}$, $u \in \mathcal{D}_\Lambda(x)^\circ$. Let $\epsilon > 0$ such that $B(u, \epsilon) \subseteq \mathcal{D}_\Lambda(x)$. For all $0 < \delta < \epsilon$ and $i = 1, \dots, d$, we now have the following identity

$$\begin{aligned}
(A.4.6) \quad \frac{\Lambda(u + \delta e_i, x) - \Lambda(u, x)}{\delta} &= \langle e_i, \beta^\chi(x) \rangle + \langle e_i, \alpha(x)u \rangle + \frac{1}{2} \langle \delta e_i, \alpha(x)u \rangle \\
&\quad + \int_{|v| \leq 1} \frac{1}{\delta} \left(e^{\langle u + \delta e_i, v \rangle} - e^{\langle u, v \rangle} - \langle \delta e_i, v \rangle \right) \mu(x, dv) \\
&\quad + \int_{|v| > 1} \frac{1}{\delta} \left(e^{\langle u + \delta e_i, v \rangle} - e^{\langle u, v \rangle} \right) \mu(x, dv)
\end{aligned}$$

Evaluating the limit of (A.4.6) as $\delta \rightarrow 0$ is now a matter of exchanging the limit with integration; we will do this by using the dominated convergence theorem.

For the first integral, Taylor's theorem provides us $\gamma_0, \gamma_1 \in [0, 1]$ such that the following hold.

$$\begin{aligned}
e^{\langle u + \delta e_i, v \rangle} &= 1 + \langle u + \delta e_i, v \rangle + \frac{1}{2} \langle u + \delta e_i, v \rangle^2 e^{\gamma_0 \langle u + \delta e_i, v \rangle} \\
e^{\langle u, v \rangle} &= 1 + \langle u, v \rangle + \frac{1}{2} \langle u, v \rangle^2 e^{\gamma_1 \langle u, v \rangle}
\end{aligned}$$

This shows us that, for all $0 < \delta < \epsilon$ and $|v| \leq 1$,

$$\begin{aligned}
\left| \frac{1}{\delta} \left(e^{\langle u + \delta e_i, v \rangle} - e^{\langle u, v \rangle} - \langle \delta e_i, v \rangle \right) \right| &= \left| \frac{1}{2} \langle u + \delta e_i, v \rangle^2 e^{\gamma_0 \langle u + \delta e_i, v \rangle} + \frac{1}{2} \langle u, v \rangle^2 e^{\gamma_1 \langle u, v \rangle} \right| \\
&\leq \left((|u| + \epsilon)^2 e^{|u| + \epsilon} \right) |v|^2.
\end{aligned}$$

This dominating function is integrable,

$$\int_{|v| \leq 1} \left((|u| + \epsilon)^2 e^{|u| + \epsilon} \right) |v|^2 \mu(x, dv) \leq \left((|u| + \epsilon)^2 e^{|u| + \epsilon} \right) \int_{\mathbb{V}} (1 \wedge |v|^2) \mu(x, dv) < \infty,$$

so we may apply the dominated convergence theorem.

$$\lim_{\delta \rightarrow 0} \int_{|v| \leq 1} \frac{1}{\delta} \left(e^{\langle u + \delta e_i, v \rangle} - e^{\langle u, v \rangle} - \langle \delta e_i, v \rangle \right) \mu(x, dv)$$

$$\begin{aligned}
&= \int_{|v| \leq 1} \lim_{\delta \rightarrow 0} \frac{1}{\delta} \left(e^{\langle u + \delta e_i, v \rangle} - e^{\langle u, v \rangle} - \langle \delta e_i, v \rangle \right) \mu(x, dv) \\
\text{(A.4.7)} \quad &= \int_{|v| \leq 1} \left(e^{\langle u, v \rangle} v_i - v_i \right) \mu(x, dv)
\end{aligned}$$

For the second integral, we again use Taylor's theorem to establish for each $0 < \delta < \epsilon/2$, some $\gamma_\delta \in [0, \delta]$ such that

$$e^{\langle u + \delta e_i, v \rangle} = e^{\langle u, v \rangle} + \langle \delta e_i, v \rangle e^{\langle u + \gamma_\delta e_i, v \rangle}$$

This way, we have the following dominating function.

$$\left| \frac{1}{\delta} \left(e^{\langle u + \delta e_i, v \rangle} - e^{\langle u, v \rangle} \right) \right| \leq \left| \langle e_i, v \rangle e^{\langle u + \gamma_\delta e_i, v \rangle} \right| \leq |v_i| e^{\langle u, v \rangle + \epsilon |v_i|/2}$$

The claim is that this dominating function is integrable. To see this, first note that because we have the following limit,

$$\lim_{|v| \rightarrow \infty} \frac{|v_i| e^{\langle u, v \rangle + \epsilon |v_i|/2}}{e^{\langle u, v \rangle + 2\epsilon |v_i|/3}} = \lim_{|v| \rightarrow \infty} \frac{|v_i|}{e^{\epsilon |v_i|/6}} = 0$$

There exists $M > 0$ such that for all $|v| > M$,

$$|v_i| e^{\langle u, v \rangle + \epsilon |v_i|/2} < e^{\langle u, v \rangle + 2\epsilon |v_i|/3}.$$

We now see that

$$\begin{aligned}
&\int_{|v| > 1} |v_i| e^{\langle u, v \rangle + \epsilon |v_i|/2} \mu(x, dv) \\
&= \int_{1 < |v| \leq M} |v_i| e^{\langle u, v \rangle + \epsilon |v_i|/2} \mu(x, dv) + \int_{|v| > M} |v_i| e^{\langle u, v \rangle + \epsilon |v_i|/2} \mu(x, dv) \\
&\leq \int_{1 < |v| \leq M} M e^{(|u| + \epsilon/2)M} \mu(x, dv) + \int_{|v| > M} e^{\langle u, v \rangle + 2\epsilon |v_i|/3} \mu(x, dv) \\
&\leq M e^{(|u| + \epsilon/2)M} \int_{\mathbb{V}} (1 \wedge |v|^2) \mu(x, dv) + \sum_{\ell=0}^1 \int_{|v| > 1} e^{\langle u + 2\epsilon e_\ell/3, v \rangle} \mu(x, dv) \\
&< \infty.
\end{aligned}$$

We again use the dominated convergence theorem to deduce the following.

$$\begin{aligned}
&\lim_{\delta \rightarrow 0} \int_{|v| > 1} \frac{1}{\delta} \left(e^{\langle u + \delta e_i, v \rangle} - e^{\langle u, v \rangle} \right) \mu(x, dv) \\
&= \int_{|v| > 1} \lim_{\delta \rightarrow 0} \frac{1}{\delta} \left(e^{\langle u + \delta e_i, v \rangle} - e^{\langle u, v \rangle} \right) \mu(x, dv) \\
\text{(A.4.8)} \quad &= \int_{|v| > 1} e^{\langle u, v \rangle} v_i \mu(x, dv)
\end{aligned}$$

Combining equations (A.4.6), (A.4.7), and (A.4.8) now yields our desired identity.

$$D_i \Lambda(u, x) = \left\langle e_i, \beta^X(x) + \alpha(x)u + \int_{\mathbb{V}} \left(e^{\langle u, v \rangle} v - \chi(v) \right) \mu(x, dv) \right\rangle$$

Continuity of $D_i \Lambda(u, x)$ for $u \in \mathcal{D}_\Lambda(x)^\circ$ involves very similar dominated convergence theorem arguments as above. From here, it is clear that Λ is continuously differentiable with the form in (A.4.5).

As we have seen in Lemmas A.2.3 and A.3.2, if we have local boundedness of certain integrals of a jump kernel μ , we can leverage these to (P, \mathcal{F}) local conditions of the associated jump-diffusion X . Throughout the remainder of this section, we impose the following uniform-boundedness principle for the kernel μ .

$$(A.4.9) \quad \begin{aligned} & f \in \mathcal{B}(\mathbb{V})/\mathcal{B}(\mathbb{R}), \quad \int_{\mathbb{V}} |f(v)| \mu(x, dv) < \infty \text{ for all } x \in \mathbb{X} \\ \implies & \quad x \mapsto \int_{\mathbb{V}} |f(v)| \mu(x, dv) \text{ bounded on compact sets} \end{aligned}$$

With this assumption, we get some nice results on finite exponential moments of X .

Proposition A.4.10. *Fix a (P, \mathcal{F}) jump-diffusion X with differential χ -characteristics $(\beta^\chi, \alpha, \mu)$. Suppose we have the regularity condition (A.4.9) above. If $0 \in \mathcal{D}_\Lambda^\circ$, then X is special.*

Proof. If $0 \in \mathcal{D}_\Lambda^\circ$, then there exists some $\delta > 0$ such that $\overline{B}(0, \delta) \subseteq \mathcal{D}_\Lambda$. Observe the following implication of this fact, for each $x \in \mathbb{X}$.

$$\begin{aligned} \int_{\mathbb{V}} |v - \chi(v)| \mu(x, dv) &= \int_{|v| > 1} |v| \mu(x, dv) \\ &\leq \int_{|v| > 1} \frac{\sqrt{d}}{\delta} \exp\left(\frac{\delta|v|}{\sqrt{d}}\right) \mu(x, dv) \\ &\leq \frac{\sqrt{d}}{\delta} \int_{|v| > 1} \exp\left(\max_{i=1}^d \max_{\ell=0}^1 \langle (-1)^\ell \delta e^i, v \rangle\right) \mu(x, dv) \\ &\leq \frac{\sqrt{d}}{\delta} \sum_{i=1}^d \sum_{\ell=0}^1 \int_{|v| > 1} \exp\langle (-1)^\ell \delta e^i, v \rangle \mu(x, dv) \\ &< \infty \end{aligned}$$

Our regularity condition (A.4.9) now allows us to apply Lemma A.2.3 to conclude X is special.

Proposition A.4.11. *Fix a (P, \mathcal{F}) jump-diffusion X with differential χ -characteristics $(\beta^\chi, \alpha, \mu)$. Suppose we have the regularity condition (A.4.9) above. If $u \in \mathcal{D}_\Lambda$, then $\exp \langle u, X \rangle$ is special, and $\exp \langle u, X \rangle - \Lambda(u, X) \cdot \ell$ is a (P, \mathcal{F}) local martingale.*

Proof. Using Lemma A.1.7 for the function $f_u(v) = \exp \langle u, v \rangle$ and its derivative identities as in (A.1.13), we get the following.

$$(A.4.12) \quad \begin{aligned} \exp \langle u, X_t \rangle &= \exp \langle u, X_0 \rangle + \exp \langle u, X_t \rangle \left(\langle u, \beta^\chi(X) \rangle + \frac{1}{2} \langle u, \alpha(X) u \rangle \right) \cdot \ell_t \\ &\quad + Df_u(X_-) \cdot X^c + \left(\exp \langle u, X_- \rangle \langle u, \chi \rangle \right) * \tilde{q}_t^X \\ &\quad + \exp \langle u, X_- \rangle \cdot \left(\exp \langle u, \text{id}_{\mathbb{V}} \rangle - 1 - \langle u, \chi \rangle \right) * q^X \end{aligned}$$

Note that localizing our final term on the sequence $(T_n)_{n \in \mathbb{N}}$ of stopping times in (A.1.9), we get the following.

$$\begin{aligned} & \mathbb{E}_P \left| \exp \langle u, X_- \rangle \left(\exp \langle u, \text{id}_V \rangle - 1 - \langle u, \chi \rangle \right) \right| * \tilde{q}_{T_n}^X \\ &= \mathbb{E}_P \int_0^{T_n} \int_V \left| \exp \langle u, X_s \rangle \left(\exp \langle u, v \rangle - 1 - \langle u, \chi(v) \rangle \right) \right| \mu(X_s, dv) ds \\ &\leq n \cdot \sup_{|x| \leq n} \left(e^{\langle u, x \rangle} \int_V |e^{\langle u, v \rangle} - 1 - \langle u, \chi(v) \rangle| \mu(x, dv) \right) \end{aligned}$$

Seeing as $u \in \mathcal{D}_\Lambda$, the integral in the above quantity is finite, and so (A.4.9) gives us finiteness of the supremum. Using [JS03, Proposition II.1.28] now allows us to compensate the jump term in (A.4.12).

$$\exp \langle u, X_t \rangle = \exp \langle u, X_0 \rangle + \left(\exp \langle u, X_t \rangle \cdot \Lambda(u, X) \right) \cdot \ell_t + \text{Df}_u(X_-) \cdot X^c + \left(\exp \langle u, X_- \rangle \langle u, \chi \rangle \right) * \tilde{q}_t^X$$

This is a representation of $\exp \langle u, X \rangle$ as an initial term, predictable term of finite variation, and a local martingale. Thus, it is a special semimartingale. From here, we may perform the product rule on $\exp(\langle u, X \rangle - \Lambda(u, X) \cdot \ell)$ as we did in Proposition A.1.12 to show that the process is a local martingale.

Theorem A.4.13. *Fix a (P, \mathcal{F}) jump-diffusion X with differential χ -characteristics $(\beta^\chi, \alpha, \mu)$. Suppose we have the regularity condition (A.4.9) above and that $0 \in \mathcal{D}_\Lambda^\circ$. For each $h \in \mathbb{D}([0, \infty), V)$ of finite-variation with image contained in $\mathcal{D}_\Lambda^\circ$, the process $\exp(h \cdot X)$ is special and*

$$\exp \left(h \cdot X - \Lambda(h, X) \cdot \ell \right)$$

is a (P, \mathcal{F}) local martingale.

Proof. We first note that Proposition A.4.10 allows us to conclude X is special. Perform Itô's formula [JS03, Theorem I.4.57] in addition to its jump-diffusion variant in Lemma A.1.7 and various stochastic integral identities [JS03, Remarks I.4.36, I.4.37, Theorem I.4.40(d), Proposition II.1.30(b)].

$$\begin{aligned} & \exp(h \cdot X_t) \\ &= \exp(h \cdot X_-) \cdot (h \cdot X)_t + \frac{1}{2} \exp(h \cdot X_-) \cdot \langle (h \cdot X)^c, (h \cdot X)^c \rangle_t \\ &\quad + \sum_{0 < s \leq t} \left(\exp(h \cdot X_{s-} + \Delta(h \cdot X)_s) - \exp(h \cdot X_{s-}) - \exp(h \cdot X_{s-}) \Delta(h \cdot X)_s \right) \\ &= \left(\exp(h \cdot X_-) \cdot h \right) \cdot X_t + \frac{1}{2} \exp(h \cdot X) \langle h, \alpha(X) h \rangle \cdot \ell_t \\ &\quad + \exp(h \cdot X_-) \left(e^{\langle h, \text{id}_V \rangle} - 1 - \langle h, \text{id}_V \rangle \right) * \tilde{q}_t^X \\ (A.4.14) \quad &= \left(\exp(h \cdot X) \cdot \langle h, \beta \rangle + \frac{1}{2} \exp(h \cdot X) \langle h, \alpha(X) h \rangle \right) \cdot \ell_t + \left(\exp(h \cdot X_-) \cdot h \right) \cdot X_t^c \\ &\quad + \exp(h \cdot X_-) \langle h, \text{id}_V \rangle * \tilde{q}_t^X \\ &\quad + \exp(h \cdot X_-) \left(e^{\langle h, \text{id}_V \rangle} - 1 - \langle h, \text{id}_V \rangle \right) * \tilde{q}_t^X \end{aligned}$$

Now, choosing our (P, \mathcal{F}) localizing sequence $(T_n)_{n \in \mathbb{N}}$ as in A.1.9, we have the following bound.

$$\begin{aligned} & \mathbb{E}_P \left| \exp(h \cdot X_-) \left(e^{\langle h, \text{id}_V \rangle} - 1 - \langle h, \text{id}_V \rangle \right) * \hat{q}_{T_n}^X \right| \\ &= \mathbb{E}_P \int_0^{T_n} \int_V \left| \exp(h \cdot X_s) \left(e^{\langle h(s), v \rangle} - 1 - \langle h(s), v \rangle \right) \right| \mu(X_s, dv) ds \\ &\leq n \cdot \sup_{|x| \leq n} \sup_{s \in [0, n]} e^{|x| \cdot |h(s)|} \int_V |e^{\langle h(s), v \rangle} - 1 - \langle h(s), v \rangle| \mu(x, dv) \end{aligned}$$

Seeing as $\Lambda(\cdot, x)$ is continuously differentiable, it is uniformly bounded on $\mathcal{D}_\Lambda^\circ$. This, along with assumption (A.4.9) allow us to conclude that the preceding expression is finite. Thus, we may compensate the final jump integral in (A.4.14).

$$\begin{aligned} \text{(A.4.15)} \quad \exp(h \cdot X_t) &= \left(\exp(h \cdot X) \cdot \Lambda(h, X) \right) \cdot \ell_t + \left(\exp(h \cdot X_-) \cdot h \right) \cdot X_t^c \\ &\quad + \exp(h \cdot X_-) \left(e^{\langle h, \text{id}_V \rangle} - 1 \right) * q_t^X \end{aligned}$$

The decomposition of $\exp(h \cdot X)$ into a predictable finite-variation process and a local martingale implies that it is special. Now, we write M as the local martingale term above, $A = \exp(h \cdot X)$, and $B = \exp(-\Lambda(h, X) \cdot \ell)$. We now recognize that B is predictable and finite-variation and use [JS03, Proposition I.4.49(b)] to conclude our proof.

$$\begin{aligned} \exp(h \cdot X_t - \Lambda(h, X) \cdot \ell_t) &= A_t B_t \\ &= A_- \cdot B_t + B \cdot A_t \\ &= (A \cdot B - \Lambda(h, X)) \cdot \ell_t + B \cdot \left((\exp(h \cdot X) \cdot \Lambda(h, X)) \cdot \ell + M \right)_t \\ &= (A \cdot B - \Lambda(h, X)) \cdot \ell_t + (B \cdot A \cdot \Lambda(h, X)) \cdot \ell_t + B \cdot M_t \\ &= B \cdot M_t \end{aligned}$$

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