



Warning

Supervised learning for text mining Master Data Mining

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I won't mention deep learning in this course

Text classification

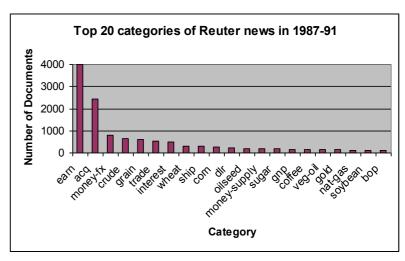
 Automatically classify documents into predefined classes

e.g., digital libraries



- Application areas:
 - Email SPAM filtering
 - Internet directory construction (ex.: Yahoo!)
 - Automatic indexing ...

A very classical dataset

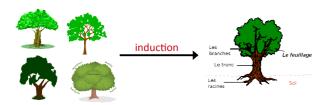


Basic ML approach

- Prepare a set of training data
 - Getting access to the data
 - Need of effective preprocessing
- Create a classifier
 - Apply a ML algorithm: NB, ANN, SVM etc.
- Classify new documents using the classifier

Inductive principle

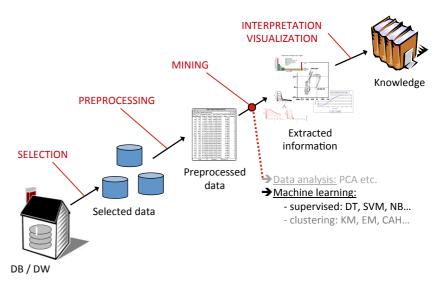
• Aristotle: knowledge comes from the (observable) world



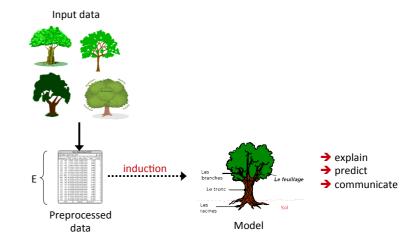
A tree = roots + trunk + branches + leaves

+ relations between: roots and ground, roots and trunk etc.

ML in data mining



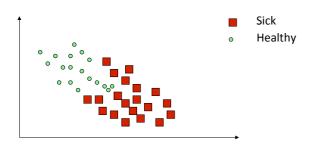
Induction using a machine



Supervised learning

- Inductive learning based on supervision
- Given:
 - o a representation language L,
 - o examples e_i∈E described using L,
 - o for each e_i , a class $\Phi(e_i)$ taken from $\{c_1, c_2 \dots c_p\}$
- The objective is to find:
 - a function (machine) h that relates each description built on L to a class in $\{c_1, c_2... c_p\} \rightarrow$ classifieur
 - a function h that relates each description built on L to a real value → régression

K-Nearest Neighbours



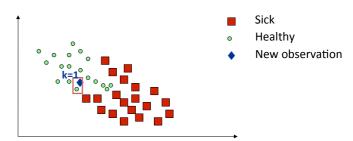
 Using a metric d(e_i,e_j) that calculates the dissimilarity between two individuals e_i and e_i.

A lot of existing algorithms

- K-Nearest Neighbours (KNN)
- Roccio's algorithm
- Decision Trees (DT)
- Artificial Neuronal Networks (ANN)
- Naive Bayes (NB)
- Support Vector Machines (SVM)
- Ensemble methods (bagging, boosting) etc.

K-Nearest Neighbours (cont'd)

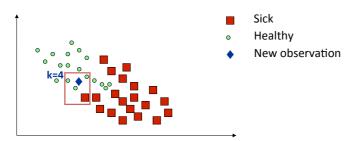
Given a new observation: ◆



Conclusion: we predict that this new person is healthy.

K-Nearest Neighbours (cont'd)

• With k=4:



• **Same conclusion:** we predict that this new person is healthy.

Rocchio's algorithm

- Build prototype vector for each class
- Prototype vector: average vector over all training document vectors that belong to class c_i

$$\vec{\mu}(c) = \frac{1}{|D_c|} \sum_{\vec{d} \in D_c} \vec{d}$$

- Calculate similarity between test document and each of prototype vectors
- Assign test document to the class with maximum similarity

K-Nearest Neighbours (cont'd)

- Pros:
 - Effective
 - Non-parametric
 - Pairwise (local) comparison of documents
- Cons:
 - Classification time is long (usually in O(n²))
 - Difficult to find an optimal value of k

Rocchio's algorithm (cont'd)

- Pros:
 - Easy to implement
 - Very fast learner
- Cons:
 - Low classification accuracy
 - Only for linear classification boundaries

Need of inductive bias in ML

- Bias = set of assumptions that the learner uses to predict outputs given inputs that it has not encountered [Mitchell, 80]
- Choices for reducing the solution (hypotheses) space; guide of the learning process
- In concept learning: way to favour a generalization rather than another one
- Absolut need of bias for learning [Mitchell, 80].
- Examples :
 - o Occam's razor,
 - o Conditional independance (cf. NB)
 - o Maximum margin (cf. SVM) etc.

Learning as search

- Choosing a family of concepts (hypotheses)
- Searching for the best hypothesis possible
- To do this, you need fixing biases
- Occam's razor addresses the trade-off:

simplicity / efficiency

Illustration of the Occam's razor

• Given the sequence: 1, 2, 3, 5 ..., a?

Statistical machine learning

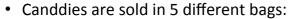
- Main concepts:
 - Data (examples, instances, observations)
 - Hypotheses (probabilistic theories on the process of data generation)
- Objective:
 - Explain the observed data
 - Predict new observations

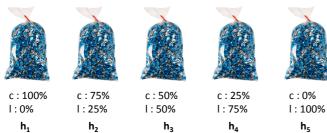
Example [Russel & Norvig, 2003]











Baysian learning

Hypothesis probability given the data:

$$P(h_i/D) = \frac{P(D/h_i)P(h_i)}{P(D)} \propto P(D/h_i)P(h_i)$$

• Making predictions:

$$P(X/D) = \sum_{i} P(X/D,h_{i})P(h_{i}/D)$$
$$= \sum_{i} P(X/h_{i})P(h_{i}/D)$$

Example (cont'd)

• Given a new "unknown" bag:



H can take 5 values:

 $H \in \{h1, h2, h3, h4, h5\}$

• Observations: opening the wrappers!

Ex.: d1, d2, d3, d4, d5, d6, d7, d8, d9, d10, etc.



Baysian learning (cont'd)

probability distribution $P(X/D) \propto \sum P(X/h_i)P(D/h_i)P(h_i)$

How to calculate the likelihood?

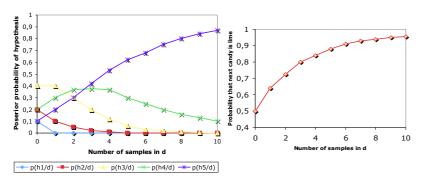
$$P(D/h) = \prod P(d_i/h)$$

i.i.d. hypothesis (independently identically distributed)

• Example of observed data:



Evolution of learning



Here are the priors: < 0,1; 0,2; 0,4; 0,2; 0,1>

Role of priors

- P(h_i) very important in Bayesian learning
- Bounding the complexity of models
- Complex models (hypotheses) are less likely a priori
- Trade-off between complexity and expressivity
- If you have no idea on priors: uniform

Decision in bayesian learning

- Given p(X/D) what decision make?
 - the simpliest way: taking the most likely solution
 - another solution: drawing a random number
- MAP = Maximum A Posteriori
 - here: h_5 . $\underset{i}{\operatorname{arg\,max}} P(h_i/d)$

$$P(X/D) \approx P(X/h_{MAP})$$

Link with information theory

• Choosing $\mathbf{h}_{\mathrm{MAP}}$ for maximizing $\mathbf{P}(\mathbf{D}/h_i)\mathbf{P}(h_i)$ means minimazing:

$$-\log_2 P(D/h_i) - \log_2 P(h_i)$$

• If you split this formula into 2 parts:

$$-\log_2 P(h_i)$$
 coding hypothis h_i $-\log_2 P(D/h_i)$ additional coding for D

MAP → maximum compression of the data!

Bayesian learning of parametric models

- To begin with: we assume that the data are complete (no missing values)
- The objective is to estimate the values of the parameters of a given model
- Classical approach: Maximum-Likelihood **Estimation** (MLE) for estimating the model parameters

Example (cont'd)

- N observations:
 - o c candies with cherry flavour
 - o I candies with lime flavour
- Estimating the likelihood:

$$P(D/h_{\theta}) = \prod_{i=1}^{N} P(d_{j}/h_{\theta}) = \theta^{c} . (1-\theta)^{l}$$

• $h_{MAP} \rightarrow taking \theta$ for maximazing this formula = maximizing the log-likelihood

Learning of discrete models

Example: Selling bags containing candies with two different flavours

 θ with the cherry flavour

 $1-\theta$ with the lime flavour

- The problem hypotethis = h₀.
- Assume uniform priors
- Just one random variable: Flavour.



Calculating h_e

- Likelihood: $P(D/h_{\theta}) = \prod_{j=1}^{N} P(d_{j}/h_{\theta}) = \theta^{c} . (1-\theta)^{l}$ Log-likelihood:

$$L(D/h_{\theta}) = \log P(D/h_{\theta}) = \sum_{j=1}^{N} \log P(d_{j}/h_{\theta}) = c \log \theta + l \log(1 - \theta)$$

Which θ maximizes this formula?

$$\frac{\partial L(D/h_{\theta})}{\partial \theta} = \frac{c}{\theta} - \frac{l}{1 - \theta} = 0 \qquad \Rightarrow \qquad \theta = \frac{c}{c + l} = \frac{c}{N}$$

First conclusion

$$\theta = \frac{c}{c+l} = \frac{c}{N}$$

- The real rate θ of cherry candies is estimated to the rate of observed cherry candies...
- Quite an obvious result! But we have:
 - written a (log)likelihood function,
 - derived this function wrt θ ,
 - found the best value for the parameter θ .

Estimating the likelihood

- Unwrapping N candies:
 - o c with cherry flavour, I with lime flavour,
 - o cherry candies: r_c red wrappers, g_c green wrappers,
 - o lime candies: r_I red wrappers, g_I green wrappers.

$$P(D/h_{\theta,\theta_1,\theta_2}) = \theta^c \cdot (1-\theta)^l \theta_1^{r_c} \cdot (1-\theta_1)^{g_c} \theta_2^{r_l} \cdot (1-\theta_2)^{g_l}$$

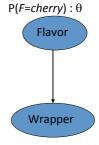
$$L = [c.\log\theta + l.\log(1 - \theta)] + [r_c \log\theta_1 + g_c \log(1 - \theta_1)]$$
$$+ [r_l \log\theta_2 + g_l \log(1 - \theta_2)]$$

New more complicated example

Adding wrappers: red and green

Model with 3 parameters:

 $\theta \text{, }\theta _{1}\text{, }\theta _{2}$



<i>V</i> =red/ <i>F</i>)

What is the likelihood of a cherry candy in a green wrapper?

$$\begin{split} &\mathbf{P}(F=c,W=g/h_{\theta,\theta_1,\theta_2})\\ &=\mathbf{P}(F=c/h_{\theta,\theta_1,\theta_2})\mathbf{P}(W=g/F=c,h_{\theta,\theta_1,\theta_2})=\theta.(1-\theta_1) \end{split}$$

Calculating $h_{\theta,\theta 1,\theta 2}$

• Derivations:

$$\frac{\partial L}{\partial \theta} = \frac{c}{\theta} - \frac{l}{1 - \theta} = 0 \quad \Rightarrow \quad \theta = \frac{c}{c + l}$$

$$\frac{\partial L}{\partial \theta_1} = \frac{r_c}{\theta_1} - \frac{g_c}{1 - \theta_1} = 0 \quad \Rightarrow \quad \theta_1 = \frac{r_c}{r_c + g_c}$$

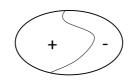
$$\frac{\partial L}{\partial \theta_2} = \frac{r_l}{\theta_2} - \frac{g_l}{1 - \theta_2} = 0 \quad \Rightarrow \quad \theta_2 = \frac{r_l}{r_l + g_l}$$

• Same conclusion...

Preliminary conclusions

- Results fit our expectations
- Using complete data and h_{MAP}, Bayesian learning split the problem into subproblems (one for each model parameter)
- Mind the "zero probability" situation (especially for small datasets)

Basics on NB



- Example: $e = tuple(x_1, x_2..., x_m) + class$
- Case of binary classification: $c \in \{+,-\}$
- Learning set:

$$E = \{(e_1,+),(e_2,+),(e_3,-)...,(e_n,+)\}$$

• We are looking for a function f_B so that:

$$f_B(e) = \frac{p(C = +/e)}{p(C = -/e)}$$

• If f_B ≥1 then h(e)=+ else h(e)=-

Naive Bayes



- Naive Bayes (NB) is a classical classifier in ML
- Based on the Bayes' Theorem
- Strong independence assumptions
- Easy and quick to implement
- Good results in practice

Calculating f_B

- How to calculate p(c/e)?
- Bayes' rule:

$$p(c/e) = \frac{p(e/c) \times p(c)}{p(e)}$$

• And now... p(e/c)?

$$p(e/c) = p(x_1, x_2, x_3..., x_m/c)$$

· What else?

conditional independence

We state the following fundamental hypothesis:

Hypothesis: We assume that all the attributes are **independent** given the associated class.

So:

Attributs | Pif

$$p(x_1/x_2, x_3..., x_m, c) = p(x_1/c)$$

$$p(e/c) = p(x_1, x_2, x_3..., x_m/c) = \prod_{i=1}^m p(x_i/c)$$

Illustration (Quinlan,83)

Temp



Golf

Valeurs	soleil, couvert, pluie	chaud, bon, frais	normale, haute	vrai, faux	jouer, ne_pas_jouer
1	soleil	chaud	haute	faux	ne_pas
2	soleil	chaud	haute	vrai	ne_pas
3	couvert	chaud	haute	faux	jouer
4	pluie	bon	haute	faux	jouer
5	pluie	frais	normale	faux	jouer
6	pluie	frais	normale	vrai	ne_pas
7	couvert	frais	normale	vrai	jouer
8	soleil	bon	haute	faux	ne_pas
9	soleil	frais	normale	faux	jouer
10	pluie	bon	normale	faux	jouer
11	soleil	bon	normale	vrai	jouer
12	couvert	bon	haute	vrai	jouer
13	couvert	chaud	normale	faux	jouer
14	pluie	bon	haute	vrai	ne_pas

Humid

Vent

class

The Naive Bayes classifier (NB)

• With this hypothesis, $f_B \rightarrow f_{NB}$:

$$f_{NB}(e) = \frac{p(C=+)}{p(C=-)} \prod_{i=1}^{m} \frac{p(x_i/C=+)}{p(x_i/C=-)}$$

with:

o p(C=+): proportion of positive instances,

o p(C=-): proportion of negative instances,

o $p(x_i/C=+)$: proportion of positive instances with $X=x_i$

o $p(x_i/C=-)$: proportion of negative instances with $X=x_i$

jouer = classe + (9 exemples sur 14)

1	soleil	chaud	haute	faux	ne_pas
2	soleil	chaud	haute	vrai	ne_pas
3	couvert	chaud	haute	faux	jouer
4	pluie	bon	haute	faux	jouer
5	pluie	frais	normale	faux	jouer
6	pluie	frais	normale	vrai	ne_pas
7	couvert	frais	normale	vrai	jouer
8	soleil	bon	haute	faux	ne_pas
9	soleil	frais	normale	faux	jouer
10	pluie	bon	normale	faux	jouer
11	soleil	bon	normale	vrai	jouer
12	couvert	bon	haute	vrai	jouer
13	couvert	chaud	normale	faux	jouer
14	pluie	bon	haute	vrai	ne_pas

Attributs	Pif	Temp	Humid	Vent	Golf
Valeurs	Soleil (2), couvert (4), pluie (3)	chaud (2), bon (4), frais (3)	normale (6), haute (3)	vrai (3), faux (6)	jouer, ne_pas_jouer

ne pas jouer = classe - (5 exemples sur 14)

1	soleil	chaud	haute	faux	ne_pas
2	soleil	chaud	haute	vrai	ne_pas
3	couvert	chaud	haute	faux	jouer
4	pluie	bon	haute	faux	jouer
5	pluie	frais	normale	faux	jouer
6	pluie	frais	normale	vrai	ne_pas
7	couvert	frais	normale	vrai	jouer
8	soleil	bon	haute	faux	ne_pas
9	soleil	frais	normale	faux	jouer
10	pluie	bon	normale	faux	jouer
11	soleil	bon	normale	vrai	jouer
12	couvert	bon	haute	vrai	jouer
13	couvert	chaud	normale	faux	jouer
14	pluie	bon	haute	vrai	ne_pas

Attributs	Pif	Temp	Humid	Vent	Golf
Valeurs	Soleil (3), couvert (0), pluie (2)	chaud (2), bon (2), frais (1)	normale (1), haute (4)	vrai (3), faux (2)	jouer, nepas_jouer

Predicting the class of a new observation

 Bob would like to know whether he can go to play golf. He observes that the weather is sunny, the temperature is high, the humidity is normal and there is no wind.

o = {(Pif=soleil), (Temp=bon), (Humid=normal), (Vent=faux)}

$$f_{NB}(o) = \frac{p(C = +)}{p(C = -)} \prod_{i=1}^{m} \frac{p(x_i / C = +)}{p(x_i / C = -)}$$

Calculating the probabilities

$$p(C=+) = p(jouer) = 9/14 \approx 0,64$$

 $p(C=-) = p(ne_pas_jouer) = 5/14 \approx 0,36$

Attributs	Pif	Temp	Humid	Vent	Golf
Valeurs	Soleil (2), couvert (4), pluie (3)	chaud (2), bon (4), frais (3)	normale (6), haute (3)	vrai (3), faux (6)	jouer
n(x / C=+)	0.22 : 0.45 :	0.22 : 0.45 :	0.67 : 0.33	0.33 : 0.67	

$$p(X_i / C=-)$$
 0,6; 0; 0,4 0,4; 0,4; 0,2 0,2; 0,8 0,6; 0,4

0,33

 $o = \{(P=s), (T=b), (H=n), (V=f)\}$

Predicting the class of a new observation (cont'd)

$$f_{NB}(o) = \frac{p(C=+)}{p(C=-)} \prod_{i=1}^{m} \frac{p(x_i/C=+)}{p(x_i/C=-)} = \frac{9}{14} \frac{14}{5} \prod_{i=1}^{m} \frac{p(x_i/C=+)}{p(x_i/C=-)}$$

$$f_{NB}(o) = \frac{9}{5} \left[\frac{p(P = s/+)}{p(P = s/-)} \cdot \frac{p(T = b/+)}{p(T = b/-)} \cdot \frac{p(H = n/+)}{p(H = n/-)} \cdot \frac{p(V = f/+)}{p(V = f/-)} \right]$$

$$f_{NB}(o) \approx \frac{9}{5} \left[\frac{0.22}{0.6} \cdot \frac{0.45}{0.4} \cdot \frac{0.67}{0.2} \cdot \frac{0.67}{0.4} \right]$$

$$f_{NB}(o) \approx 1.8 \times [0.37 \times 1.13 \times 3.35 \times 1.68] \approx 4.24 \ge 1$$

Conclusion: Bob can go to play golf!

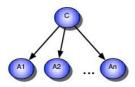
Pros of NB

- Simplicity of the theoretical background
- Memory complexity = probability tables
- Calculus are really fast: mainly x
- Often a good baseline for experiments
- Good results for real datasets

Link with Bayesian networks

• Very simple form of a Bayesian network

$$\forall X_i, p(X_i = x_{ij} / X_1, X_2..., X_m, C) = p(X_i = x_{ij} / C)$$



Cons of NB

- Strong hypotheses (e.g., the conditional independence)
- "Zero-probability" issue
 E.g., test with o = {(P=c), (T=ch), (H=h), (V=v)}
- Theoretical results not really well known

Managing continuous variables

- Basic NB deal only with discrete variables
- Possible solutions for continuous variables:
 - o discretizing the variables,
 - o adding an **hypothesis** on the data distribution (e.g., using a Gaussian distribution)

$$P(x) = \frac{1}{\sqrt{2\pi\sigma}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$