Solution Chapter 1: Grayscale







Excursion: Additional knowledge of cv::Mat

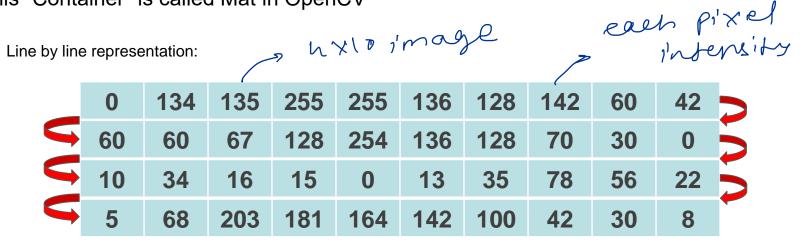






- Real world images are transformed into digital images e.g via digital cameras, scanners
- Every real world information (intensity) is stored in a list (called array)

- This "Container" is called Mat in OpenCV



Every single row is saved as individual object in memory

Continuous representation:

S tovel as single obj in mem->

Fast operation.

0 | 134 | 135 | 255 | 255 | 136 | 128 | 142 | 60 | 42 | 60 | 60 | 67 | 128 | 254 | 136 | 128 | 70 | 30 | 0 | ---

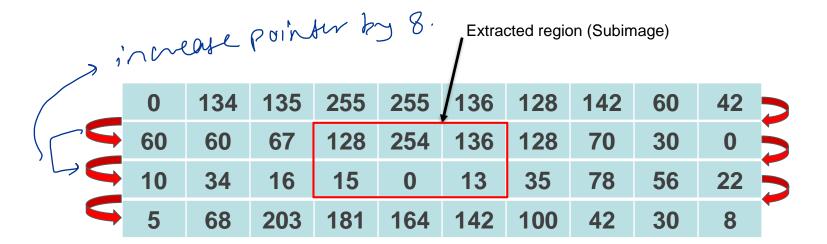
- The whole picture is saved as a single object in memory

viry image should be Continions? In mem by it not continions as wrong result.

To access the image in one now & survey Cols it should be continuous.



- Why is it important to check for continuity?
 - Extracted image is not continuous in cv::Mat



- Processing the extracted image needs pointer algorithms to get the first cell of the next row
- To get the next pixel after the cell with the value 136 the pointer has to be increased by 8 in this example

Some knowledge of cv::Mat and OpenCV is assumed, please brief yourself on the following website:

http://docs.opencv.org/2.4/doc/tutorials/core/mat_the_basic_image_container/mat_the_basic_image_container.ht ml

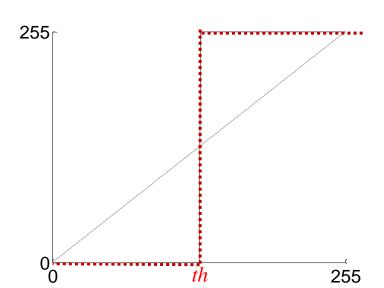
Chapter 2: Thresholding







$$J(m,n) = \begin{cases} 0, & \text{if } I(m,n)$$



- The result of thresholding an image is a binary image
- It can be used for simple segmentation tasks

$$th = 64$$

$$th = 128$$

$$th = 192$$





Second exercise

• Implement an image thresholding program





Expected Output

Original Grayscale Image



Thresholded Images (e.g. th = 128)





That is all for today.

