# Mokshith Voodarla

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#### **EDUCATION**

# **UC Berkeley**

Electrical Engineering and Computer Science B.S. Expected May 2022 | Berkeley, CA

#### LINKS

LinkedIn: linkedin.com/in/mokshith-voodarla

**GitHub:** github.com/mvoodarla **Personal Website:** mokshith.xyz

## SKILLS

LANGUAGES Python | Java | C++

**LIBRARIES** PyTorch | TensorFlow | Keras | ROS | NumPy | OpenCV | Eigen | PCL | Beautiful Soup

**OTHER** Stereo Cameras | LiDAR | PointCloud | Linux | Embedded Systems | Google Cloud

## COURSEWORK

MATH 53 | Multivariable Calculus
EE 16A/B | Device Information and Systems
CS 61A/B/C | Structure of Computer Programs + Data
Structures + Machine Architecture
CS 70 | Discrete Math and Probability
CS 170 | Efficient Algorithms and Intractable Problems

## **PROJECTS**

### **Jetson Home Security System**

Human-aware security system with live streaming feed and human alerts; used pose estimation in TensorFlow, OneSignal, Flask, FireBase, and Android

## <u>ClairVoyance: Spatio-temporal Deep</u> Learning Model for Weather Predection

Developed a model which can predict future frames in weather and traffic data; Used ConvLSTMs, Adversarial Networks, traditional CNNs and other 3D techniques

# **TionAl: Emotion Classification for Images**

Developed tri-CNNs ensemble to understand the emotions a picture is trying to convey with 90.2% accuracy

#### Picturize - Auto Note Taker

Developed an app that automatically takes notes on any textbook page seconds after taking a picture of it; used Google Cloud OCR and developed custom textcondensing algorithm; 20k+ downloads

#### EXPERIENCE

# Ford Motor Company | Computer Vision Research Intern March 2020 - August 2020 | Palo Alto, CA

- \* Developed novel weather and lighting invariant vision-based localization pipeline for autonomous vehicles
- Invented semantic birds-eye view PointCloud representation and trained deep learning autoencoder + regressor w/ PyTorch + Keras
- \* Filed invention disclosure patent and submitting paper (ICRA 2021)

# Placeware | Co-Founder

## May 2020 - Present | Berkeley, CA

- \* Bringing the data revolution to brick and mortar businesses through computer vision based human interaction analytics
- \* Developed model (PyTorch), frontend (ReactJS), and backend (GCP Functions + Firestore), and hardware (Flask)
- \* Expanding to 10+ businesses in Bay Area by end of September

# Cal Launchpad (UC Berkeley Student Club) | Project Leader August 2019 - Present | Berkeley, CA

- \* Managing a team of 6 working on a 3D camera tracking project
- Previous projects: <u>Image compression using genetic algorithms</u>,
   Spatio-temporal models for weather prediction

# Aceinna Inc | Embedded Software Engineering Intern June 2019 - August 2019 | Santa Clara, CA

- Developed self-balancing segway using Ninebot MiniPro chassis using Aceinna's OpenIMU as the control unit
- \* Tested various balancing strategies including a PID-controller
- Used VESC motor controllers and ARM-Cortex M4 timers to generate PWM signal for motor control on OpenIMU

# **LookyLoo Inc** | ML & Cloud Engineering Contractor September 2018 - May 2019 | San Francisco, CA

- \* Developed models for automatic recommendation of clothing based on body type, clothing style, and brand preferences
- \* Compiled dataset (~220k images) of clothing piece images and metadata using Beautiful Soup and saved to GCP storage buckets
- \* Trained CNN models using TensorFlow TPUs to predict metadata

# NVIDIA Corp | Computer Vision & Robotics Intern June 2018 - August 2018 | Santa Clara, CA

- \* Developed algorithms to replace 3D LiDAR w/ cheaper camera on indoor robot to avoid obstacles like glass, stairs, and railing
- \* Trained TensorFlow segmentation model for safe/unsafe area classification; <a href="Implemented">Implemented</a> on Jackal UGV using Jetson TX2 and ROS top-down PointCloud map