

Q3)

$$\text{ca)} \quad L(y, \hat{y}) = e^{-(y \hat{y})} = e^{-(y, H_t(x_i))}$$

$\hat{y} = H_t(x_i)$

$$\begin{aligned} H_t(x) &= \sum_{i=1}^t \alpha_i h_i(x) \\ &= \sum_{i=1}^{t-1} \alpha_i h_i(x) + \alpha_t h_t(x) \end{aligned}$$

$H_t(x) = H_{t-1}(x) + \alpha_t h_t(x)$

$$\begin{aligned} L(y, \hat{y}) &= \frac{1}{n} \sum_{i=1}^n e^{-y_i H(x_i)} \\ &= \frac{1}{n} \sum_{i=1}^n e^{-y_i (H_{t-1} + \alpha_t h_t)} \\ &= \frac{1}{n} \sum_{i=1}^n e^{-y_i H_{t-1}} e^{-y_i \alpha_t h_t} \\ &= \frac{1}{n} \sum_{i=1}^n \underbrace{e^{-y_i H_{t-1}}}_{w_i^+} e^{-y_i \alpha_t h_t} \\ &= \frac{1}{n} \sum_{i=1}^n w_i^+ e^{-y_i \alpha_t h_t} \end{aligned}$$

To minimize loss, equate derivative to '0'.

$$\frac{\partial}{\partial \alpha} L(y, \hat{y}) = \frac{\partial}{\partial \alpha} \left(\frac{1}{n} \sum_{i=1}^n w_i^+ e^{-y_i \alpha h_t} \right) = 0$$

$$0 \Rightarrow -\frac{1}{n} \sum_{i=1}^n w_i^t y_i h_t e^{-y_i \alpha_t + h_t}$$

$e^{x+y} = e^x e^y$

$$\Rightarrow \frac{1}{n} \left[\sum_{i: h(x_i) = y_i} w_i^t e^{-\alpha_t} - \sum_{i: h(x_i) \neq y_i} w_i^t e^{\alpha_t} \right]$$

$y_i \cdot h_t = 1$ $y_i \cdot h_t = -1$

$$\Rightarrow -\frac{1}{n} \sum_{i: h(x_i) = y_i} w_i^t e^{-\alpha_t} + \frac{1}{n} \sum_{i: h(x_i) \neq y_i} w_i^t e^{\alpha_t}$$

$$\epsilon_t = \sum_{i: h(x_i) \neq y_i} w_i^t \quad 1 - \epsilon_t = \sum_{i: h(x_i) = y_i} w_i^t$$

$$\Rightarrow 0 = (1 - \epsilon_t) e^{-\alpha_t} - \epsilon_t e^{\alpha_t}$$

$$\Rightarrow (1 - \epsilon_t) e^{-\alpha_t} = \epsilon_t e^{\alpha_t}$$

$$\Rightarrow \frac{1 - \epsilon_t}{e^{\alpha_t}} = \epsilon_t e^{\alpha_t}$$

$$\Rightarrow \frac{1 - \epsilon_t}{\epsilon_t} = e^{2\alpha_t}$$

$$\Rightarrow \alpha_t = \frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right)$$

In this we proved that the α for a given iteration is $\frac{1}{2} \ln \left(\frac{1 - \epsilon_t}{\epsilon_t} \right)$ and we proved that this α_t minimizes the loss function.

So, an update, i.e. at the next step the empirical risk will indeed be reduced.