1 Intro - Clustering

Clustering is the process of identifying 'similar' groups of data. The metric by which similarity is measured can vary, e.g. Euclidean distance, density, cosine similarity (to name a few.)

1.1 K-Means Clustering

Groups N data points into K clusters by Euclidean distance (12 norm).

- Initialise μ_k randomly for all $k \in K$
- For each x_n :

- for
$$k = argmin_k ||x_n - \mu_k||, r_{nk} = 1$$

• For each $k \in K$:

$$-\mu_k = \frac{\sum^N r_{nk} x_n}{\sum^N r_{nk}}$$

2 Gaussian Mixture Models

2.1 Model definition

Imagine now that points could partially belong to multiple clusters; a soft assignment. The probability of observing data point x_n in cluster k is proportional to its assignment weighting. One way to do this is to assume a Gaussian distribution for the points within each cluster, and a multinomial distribution for the clusters themselves. Using a generative process:

- 1. First pick a cluster by rolling a dice (with parameter ϕ)
- 2. Second generate a data point for this cluster based on its distribution (parameters μ_k , Σ_k)

$$p(x_n, C_k) = \phi_k N(x_n; \mu_k, \Sigma_k)$$

- Because we do not know what cluster x_n was actually generated from, we need to sum over the marginal probability to obtain the distribution. C_k is, in effect, a 'latent' ('hidden') variable.
- for convention sake let us denote $z_n k = C_k$ for data point x_n
- So our probability distribution becomes:

$$p(x_n) = \sum_{k=1}^{K} \phi_k N(x_n; \mu_k, \Sigma_k)$$

• The log likelihood is:

$$ln(\mathcal{L}) = \sum_{k=1}^{N} ln(\sum_{k=1}^{K} \phi_k N(x_n; \mu_k, \Sigma_k))$$

• (note the sum inside the log; it makes solving a bit tougher having a latent variable)

2.2 MLE Parameter Estimates

$$\mu_k = \frac{1}{N_k} \sum_{k=1}^{k} \gamma(z_{nk}) x_n \tag{1}$$

$$\Sigma_k = \frac{1}{N_k} \sum_{k=1}^k \gamma(z_{nk}) (x_n - \mu_k) (x_n - \mu_k)^T$$
(2)

$$\phi_k = \frac{N_k}{N} \tag{3}$$

where:

$$N_k = \sum_{n=1}^{N} \gamma(z_{nk}) \tag{4}$$

These all intuitively make sense for the MLE estimates; Considering $\gamma(z_{nk})$ as the portion of x_n that belongs to cluster k. μ_k and Σ_k estimates take this into account. ϕ_k is the relative fraction of each clusters mass.